Integrable stochastic interacting systems

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Abstract

Stochastic interacting particle systems show many intriguing phenomena due to the interaction among particles and have wide applications in various fields of science, but in general it is quite difficult to study their properties in detail. Over the last few decades, however, it has been gradually recognized that certain stochastic interacting particle systems can be "solved exactly", meaning that they admit explicit calculations of various probabilities and expectation values, and behind this tractability lies the integrability of these systems. In particular there have been remarkable progress in the understanding of growth and transport models in the Kardar-Parisi-Zhang (KPZ) universality class, which have turned out to have deep connections with random matrix theory, representation theory, special functions and so on.

In these lectures, we will explain these developments, mainly focusing on the models in the KPZ class. In the first lecture, we introduce one of the most fundamental models on the subject, the asymmetric simple exclusion process (ASEP) and explain the connection between its totally asymmetric version (TASEP) and random matrix theory[1]. In the second lecture we introduce various models and discuss their integrability [2]. In the third lecture we introduce the notion of stochastic duality and explain its relation to the replica approach of using moments [3]. Then we elucidate how an exact formula for ASEP can be obtained by combining the duality and integrability of the model. In the fourth lecture we explain our approach introduced in [4], which does not rely on the moment calculation. We emphasize that the method can be applied to many models in parallel, including the stationary situation. In the last lecture we discuss our recent extension of the techniques to study a two species exclusion process [5]. The implications to the nonlinear fluctuating hydrodynamics, which was proposed recently by H. van Beijren and H. Spohn, is also explained. Lastly we discuss some outstanding problems.

Contents

0 Introduction

In nature all matters consist of huge number of atoms and molecules, exhibiting various intriguing phenomena such as phase transitions, turbulence and so on. To have better understanding of such systems, we often construct models which should retain essential ingredients of the original systems. In many cases, one can model a system as a stochastic process of many particles which are interacting with each other, namely, a stochastic interacting system. Mathematical foundation of stochastic interacting systems had been set long time ago [17]. See Appendix A for a short explanation about the formulation.

There have been extensive amount of results on such systems [18], but it is often difficult to study their properties in detail. Recently, it has been realized that certain stochastic interacting systems allow quite exact and explicit analysis from which one can obtain very fine properties of the systems and there have been remarkable progress on the subject. In this development, a particularly important role was played by the asymmetric exclusion process and the Kardar-Parisi-Zhang (KPZ) equation.

The Asymmetric simple exclusion process (ASEP) is a stochastic process of many (infinite number of) particles on $\mathbb{Z}$ in which each particle tries to perform asymmetric random walk, with hopping rate to the right p and to the left q, under the volume exclusion interaction. The special case of the ASEP in which either $p = 0$ or $q = 0$ is called TASEP (Totally ASEP). When $p > q$, there is a net particle current to the right.
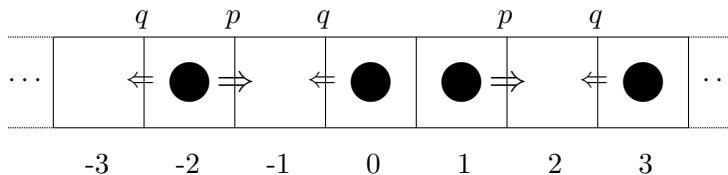

Figure 1: ASEP

By replacing empty sites by the upward slope / and occupied sites by the downward slope \, the ASEP is mapped to a surface growth model, called the single step model.

In the studies of surface growth, the standard model is the KPZ equation, which was introduced in 1986 [15]. In the case of one dimension, for the height of the surface $h(x,t)$ at position $x \in \mathbb{R}$ and at time $t \geq 0$, it reads,

$$\partial_t h(x,t) = \tfrac{1}{2}(\partial_x h(x,t))^2 + \tfrac{1}{2}\partial_x^2 h(x,t) + \eta(x,t)$$

where $\eta(x,t)$ is a Gaussian white noise with $\langle \eta(x,t)\eta(x',t')\rangle = \delta(x-x')\delta(t-t')$. Here $\langle \cdot \rangle$ means the average wrt η. In their original paper [15], Kardar, Parisi and Zhang applied a dynamical version of the renormalization group analysis to show that the height fluctuations scale like $O(t^{1/3})$ as $t \to \infty$. There have been a lot of (physical) analysis of this equation, but there had not been much information available for the height distribution until recently.

In 2010, the first explicit distribution has been found for special initial condition called the narrow wedge initial condition $e^{h(x,0} = \delta(x) = \lim_{\delta \to 0} c_\delta e^{-|x|/\delta}$ [2, 24–27]. The formula takes a simple form for a particular expectation:

$$\left\langle e^{-e^{h(x,t)+\frac{x^2}{2t}+\frac{t}{24}-\gamma_t s}} \right\rangle = \det(1 - K_{s,t})_{L^2(\mathbb{R}_+)} \tag{0.1}$$

where $\gamma_t = (t/2)^{1/3}$ and the kernel $K_{s,t}$ is

$$K_{s,t}(x,y) = \int_{-\infty}^{\infty} d\lambda \frac{\mathrm{Ai}(x+\lambda)\mathrm{Ai}(y+\lambda)}{e^{\gamma_t(s-\lambda)}+1}. \tag{0.2}$$

In the long time limit, we get

$$\lim_{t\to\infty} \mathbb{P}\left[\frac{h(x,t) + \frac{x^2}{2t} + \frac{t}{24}}{\gamma_t} \leq s\right] = F_2(s) \tag{0.3}$$

where F_2 is the GUE Tracy-Widom distribution from random matrix theory, see Appendix B. The result (0.3) says that the height of an interface for large t and the largest eigenvalue of GUE of large matrix dimension share the same distribution in the limit. Long time and large scale behaviors of a wide variety of systems are expected to be the same, constituting the KPZ universality class.

In the last decade, many generalizations and related results have been found. Behind their solvability lies the integrability of the systems, which means that generators of stochastic process have certain high symmetries. The theory of integrable systems also have a long history and there have been remarkable accumulation of knowledge on them. Whereas a lot of methods and results which have been developed in integrable system community are useful for studying stochastic interacting systems, the integrability for stochastic systems have some novel feature and provide new direction for the studies of integrable systems as well.

In this series of lectures, we discuss the integrable stochastic interacting systems, by mainly focusing on how the formulas above can be found and generalized.

Some notations. $\mathbb{N} = \{0, 1, 2, \cdots\}, \mathbb{Z}_+ = \{1, 2, \cdots\}, \mathbb{T} = \{e^{i\theta}, 0 \leq \theta < 2\pi\}$ Z is used as a normalization in general. For q-notation, see Appendix E.

1 TASEP

The main goal of this section is to get the result about the limiting distribution like (0.3) for the case of the TASEP with step initial condition in which all sites on $x \leq 0$ are occupied and all the rest are empty at $t =$. For the integrated current $N(t)$ at the origin, which is the same as the number of particles at t on $x \geq 1$ for our setting, the result reads

$$\lim_{t\to\infty} \mathbb{P}\left[\frac{N(t) - t/4}{2^{-4/3}t^{1/3}} \geq -s\right] = F_2(s). \tag{1.1}$$

What we actually try to show in the following is

$$\mathbb{P}[N(t) \geq N] = \frac{1}{Z} \sum_{\substack{x_i=N \\ 1\leq i\leq N}}^{\infty} \prod_{1\leq j<k\leq N} (x_j - x_k)^2 \prod_{j=1}^{N} \frac{t^{x_j}e^{-t}}{x_j!} \tag{1.2}$$

This formula looks very similar to (B.3) with $\beta = 2$ for the largest eigenvalue of GUE. One can follow the same steps (by replacing Hermite polynomials with Chariler polynomials) to show (1.1). The result (1.1) was first established by Johansson [14], by considering a discrete time version of TASEP and using combinatorial arguments. Here we show (1.2) by using the transition probability (or Green's function). A reference for this section is [23].

1.1 Time evolution equation for the transition probability

The transition probability for ASEP with N particles on $\mathbb{Z}$ is the probability that N particles starting from $y_1, \ldots, y_N$ at time 0 are on sites $x_1, \ldots, x_N$ at time t. (We assume $x_i < x_{i+1}, y_i < y_{i+1}, 1 \le i \le N-1$.) Let $X_i(t), 1 \le i \le N$ be the position of the i th particle at time t. Then the transition probability is

$$G(x_1, \ldots, x_N; t | y_1, \ldots, y_N; 0) = \mathbb{P}[X_i(t) = x_i, 1 \le i \le N | X_i(0) = y_i, 1 \le i \le N]. \qquad (1.3)$$

We often omit the dependence on y. In this section we take the time scale s.t. $p + q = 1$.

First let us write down the time evolution (Kolmogorov forward equation, master equation) satisfied by the transition probability. The equation for one particle ($N = 1$) case reads

$$\frac{d}{dt}G(x; t) = pG(x - 1; t) + qG(x + 1; t) - G(x; t). \qquad (1.4)$$

Next for $N = 2$, we have to consider two cases separately. When $x_2 - x_1 \ge 2$, the forward equation reads

$$\frac{d}{dt}G(x_1, x_2; t) = pG(x_1 - 1, x_2; t) + qG(x_1 + 1, x_2; t) + pG(x_1, x_2 - 1; t)$$
$$+ qG(x_1, x_2 + 1; t) - 2G(x_1, x_2; t). \qquad (1.5)$$

When $x_2 = x_1 + 1$, due to the exclusion rule, the equation is

$$\frac{d}{dt}G(x_1, x_1 + 1; t) = pG(x_1 - 1, x_1 + 1; t) + qG(x_1, x_1 + 2; t) - G(x_1, x_2; t). \qquad (1.6)$$

The initial condition for the transition probability is

$$G(x_1, x_2; t | y_1, y_2; 0) = \delta_{x_1 y_1} \delta_{x_2 y_2}. \qquad (1.7)$$

The transition probability is determined as the solution to (1.5),(1.6),(1.7). It is a little cumbersome that one has to deal with the two equations (1.5),(1.6) separately. But the second one can be replaced by a boundary condition for $G(x_1, x_2; t)$. Setting $x_2 = x_1 + 1$ in (1.5) one gets

$$\frac{d}{dt}G(x_1, x_1 + 1; t) = pG(x_1 - 1, x_1 + 1; t) + qG(x_1 + 1, x_1 + 1; t) + pG(x_1, x_1; t)$$
$$+ qG(x_1, x_1 + 2; t) - 2G(x_1, x_1 + 1; t). \qquad (1.8)$$

Comparing (1.8) with (1.6), we have

$$pG(x_1, x_1, t) + qG(x_1 + 1, x_1 + 1; t) = G(x_1, x_1 + 1; t). \qquad (1.9)$$

This means that instead of considering (1.5),(1.6) for $x_1 < x_2$, one can consider (1.5) with the boundary condition (1.9) for $x_1 \le x_2$ and focus on the case $x_1 < x_2$.

For general N the situation is similar to the $N = 2$ case. The main forward equation reads

$$\frac{d}{dt}G(x_1, \ldots, x_N; t) = \sum_{i=1}^{N} \Big(pG(\ldots, x_i - 1, \ldots; t) + qG(\ldots, x_i + 1, \ldots, t)$$
$$- G(\ldots, x_i, \ldots; t) \Big). \qquad (1.10)$$

One has to solve this with the boundary condition

$$pG(\ldots, x_i, x_i, \ldots; t) + qG(\ldots, x_i + 1, x_i + 1, \ldots; t) = G(\ldots, x_i, x_{i+1}, \ldots; t) \tag{1.11}$$

and the initial condition,

$$G(x_1, \ldots, x_N; t = 0) = \prod_{i=1}^{N} \delta_{x_i y_i}. \tag{1.12}$$

1.2 Bethe ansatz for ASEP

Formally the time evolution equation can be written in a form

$$\frac{d}{dt}G = L^*G \tag{1.13}$$

with L the time evolution generator of the process. For solving the eigenvalue problem for L^*,

$$L^*\Psi = \Lambda\Psi, \tag{1.14}$$

for ASEP, we apply the Bethe ansatz [7], in which assume the form of the eigenfunction to be in the form

$$\Psi_z(x) = \sum_{\sigma \in S_N} A_\sigma \prod_{j=1}^{N} z_{\sigma_j}^{x_j}. \tag{1.15}$$

When $N = 1$, the equation is

$$p\Psi(x - 1) + q\Psi(x + 1) - \Psi(x) = \Lambda\Psi(x), \ x \in \mathbb{Z}. \tag{1.16}$$

The solution is, with $z \in \mathbb{C}$,

$$\Psi(x) = \Psi_z(x) \tag{1.17}$$

with the eigenvalue

$$\Lambda = p/z + qz - 1 =: \epsilon(z). \tag{1.18}$$

When $N = 2$, we wand to solve

$$p\Psi(x_1 - 1, x_2) + q\Psi(x_1, x_2 - 1) - 2\Psi(x_1, x_2) = \Lambda\Psi(x_1, x_2), \tag{1.19}$$

$$p\Psi(x, x) + q\Psi(x + 1, x + 1) = \Psi(x, x + 1). \tag{1.20}$$

According to the Bethe ansatz (1.15), we make an ansatz that the eigenfunction is given in the form,

$$\Psi(x_1, x_2) = \Psi_{z_1, z_2}(x_1, x_2) = A_{12} z_1^{x_1} z_2^{x_2} + A_{21} z_2^{x_1} z_1^{x_2}. \tag{1.21}$$

From (1.19) one sees $\Lambda = \epsilon(z_1) + \epsilon(z_2)$. From (1.20), one can determine

$$\frac{A_{21}}{A_{12}} = -\frac{p + qz_1 z_2 - z_2}{p + qz_1 z_2 - z_1}. \tag{1.22}$$

This ratio is called the two particle scattering matrix.

For $N = 3$, there are six terms in the Bethe ansatz eigenfunction (1.15). The corresponding six coefficients should satisfy the boundary conditions when $x_2 = x_1 + 1 \ll x_3$ and when $x_1 \ll x_3 = x_2 + 1$. In addition they should satisfy the condition when $x_1 + 1 = x_2 = x_3 - 1$

but one can check that this condition is simply a sum of the previous two condition and does not create a new condition. One can check that the six coefficients can be written as a product of two particle scattering matrix and A_{123}.

For general N, A_σ can also be written as

$$A_\sigma = \text{sgn}\sigma \frac{\prod_{i<j}(p + q\xi_{\sigma(i)}\xi_{\sigma(j)} - (p+q)\xi_{\sigma(i)})}{\prod_{i<j}(p + q\xi_i\xi_j - (p+q)\xi_i)} \tag{1.23}$$

up to a constant factor.

Remark: when we consider ASEP on a period lattice of size L, we also have to put the periodic boundary condition on the eigenfunction, from which we get some conditions which z_i's should satisfy. It reads

$$z_i^L = (-1)^N \prod_{j(\neq i)=1}^{N} \frac{p + qz_iz_j - z_i}{p + qz_iz_j - z_j} \quad 1 \leq i \leq N. \tag{1.24}$$

This is called the Bethe ansatz equation (BAE). This is a set of coupled algebraic equations which are usually unsolvable. In these lectures, we mostly consider ASEP on $\mathbb{Z}$ for which one does not have to worry about it.

The transition probability for ASEP can be constructed by taking a linear combination of eigenfunctions appropriately. It is given by [34]

$$G(x_1, \ldots, x_N; t | y_1, \ldots, y_N; 0) = \sum_{\sigma \in S_N} \int_{C_r} \cdots \int_{C_r} d\xi_1 \ldots d\xi_N A_\sigma \prod_{i=1}^{N} \xi_{\sigma(i)}^{x_i - y_{\sigma(i)} - 1} e^{\sum_{i=1}^{N} \epsilon(\xi_i)t}$$

$$\tag{1.25}$$

where C_r is a contour enclosing the origin anticlockwise with a radius small enough that all the poles in A_σ are not included in C_r. $\epsilon(\xi)$ is defined in (1.18). It is highly nontrivial to utilize this formula to study asymptotic behavior of ASEP [33–35].

Remark: it is usually difficult to try to check the completeness of the Bethe ansatz wave functions. But in our case, we don't have to worry about such issues because one can check the conditions for the transition probability directly.

1.3 Determinantal formula for TASEP

For TASEP, the Bethe eigenfunction simplifies a lot and the transition probability can be written as a single determinant [29].

Proposition 1.1.

$$G(x_1, \ldots, x_N; t | y_1, \ldots, y_N; 0) = \det \left(F_{k-j}(x_k - y_j; t) \right)_{1 \leq j, k \leq N} \tag{1.26}$$

Here the function $F_n(x, t)$ appearing as a matrix element of the determinant is

$$F_n(x, t) = \frac{1}{2\pi i} \int_{0,1} dz \frac{1}{z^{x+1}} \left(1 - 1/z\right)^{-n} e^{-(1-z)t}$$

where the contour enclosing the poles at $z = 0, 1$ of the integrand anticlockwise

The formula is found by using Bethe ansatz, one can prove it directly. To prove the formula it is useful to list a few properties of $F_n(x, t)$ [excercise].

Lemma 1.2. *(i)*

$$F_{n+1}(x,t) = \sum_{y=x}^{\infty} F_n(y,t) \tag{1.27}$$

(ii)

$$\frac{d}{dt}F_n(x,t) = F_n(x-1,t) - F_n(x,t) \tag{1.28}$$

Proof of Prop. 1.1 It is enough to check the forward equation and the initial conditions. Here we only consider the $N=2$ case in which (1.26) reads

$$G(x_1, x_2; t) = \begin{vmatrix} F_0(x_1-y_1;t) & F_1(x_2-y_2;t) \\ F_{-1}(x_1-y_2;t) & F_0(x_2-y_2;t) \end{vmatrix}. \tag{1.29}$$

For our special case where $p=1, q=0$, (1.5),(1.9), (1.7) read

$$\frac{d}{dt}G(x_1,x_2;t) = G(x_1-1,x_2;t) + G(x_1,x_2-1;t) - 2G(x_1,x_2;t), \tag{1.30}$$

$$G(x_1,x_1,t) = G(x_1,x_1+1;t), \tag{1.31}$$

$$G(x_1,x_2;t|y_1,y_2;0) = \delta_{x_1 y_1}\delta_{x_2 y_2}. \tag{1.32}$$

We check (1.29) satisfies them. First about (1.30), we see

$$\frac{d}{dt}G(x_1,x_2;t) = \begin{vmatrix} \frac{d}{dt}F_0(x_1-y_1;t) & F_1(x_2-y_1;t) \\ \frac{d}{dt}F_{-1}(x_1-y_2;t) & F_0(x_2-y_2;t) \end{vmatrix} + \begin{vmatrix} F_0(x_1-y_1;t) & \frac{d}{dt}F_1(x_2-y_1;t) \\ F_{-1}(x_1-y_2;t) & \frac{d}{dt}F_0(x_2-y_2;t) \end{vmatrix}$$

$$= \begin{vmatrix} F_0(x_1-y_1-1;t) - F_0(x_1-y_1;t) & F_1(x_2-y_1;t) \\ F_{-1}(x_1-y_2;t) - F_{-1}(x_1-y_2-1;t) & F_0(x_2-y_2;t) \end{vmatrix}$$

$$+ \begin{vmatrix} F_0(x_1-y_1;t) & F_1(x_2-y_1;t) - F_1(x_2-y_1-1;t) \\ F_{-1}(x_1-y_2;t) & F_0(x_2-y_2;t) - F_0(x_2-y_2-1;t) \end{vmatrix}$$

$$= G(x_1-1,x_2;t) + G(x_1,x_2-1;t) - 2G(x_1,x_2;t). \tag{1.33}$$

For (1.31), we see

$$G(x_1,x_1;t) = \begin{vmatrix} F_0(x_1-y_1;t) & F_1(x_1-y_1;t) \\ F_{-1}(x_1-y_2;t) & F_0(x_1-y_2;t) \end{vmatrix}$$

$$= \begin{vmatrix} F_0(x_1-y_1;t) & F_1(x_1-y_1;t) - F_0(x_1-y_1;t) \\ F_{-1}(x_1-y_2;t) & F_0(x_1-y_2;t) - F_{-1}(x_1-y_2;t) \end{vmatrix}$$

$$= G(x_1,x_1+1;t) \tag{1.34}$$

where in the second last equality we used (1.27).

About the initial condition, one sees

$$G(x_1,x_2;t=0) = \begin{vmatrix} F_0(x_1-y_1;0) & F_1(x_2-y_2;0) \\ F_{-1}(x_1-y_2;0) & F_0(x_2-y_2;0) \end{vmatrix} = \begin{vmatrix} \delta_{x_1 y_1} & \sum_{z=x_2}^{\infty}\delta_{x_2 y_1} \\ \delta_{x_1 y_2} - \delta_{x_1,y_2+1} & \delta_{x_2 y_2} \end{vmatrix}. \tag{1.35}$$

Since $x_2 \geq y_2 > y_1$, the second term is zero.

Using these one can show that the determinant in (1.26) satisfies (1.5),(1.9), (1.7), i.e. it gives the transition probability for TASEP.

$\square$

1.4 Charlier ensemble representation

In this section we get (1.2). First note that the distribution of the current can be obtained by taking an appropriate sum of the transition probability.

$$\mathbb{P}[N(t) \geq N] = \mathbb{P}[x_1(t) \geq 1] = \sum_{1 \leq x_1 < \cdots < x_N} G(x, t) \tag{1.36}$$

For $N = 2$, we see

$$\mathbb{P}[x_1(t) \geq 1] = \sum_{1 \leq x_1 < x_2} \begin{vmatrix} F_0(x_1 + 1; t) & F_1(x_2 + 1; t) \\ F_{-1}(x_1; t) & F_0(x_2; t) \end{vmatrix}$$

$$= \sum_{1 \leq x_1 < x_2} \sum_{y_2 = x_2}^{\infty} \begin{vmatrix} F_0(x_1 + 1; t) & F_0(y_2 + 1; t) \\ F_{-1}(x_1; t) & F_{-1}(y_2; t) \end{vmatrix} \tag{1.37}$$

Writing the determinant in the last expression as $f(x_1, y_2)$, this is calculated as

$$\sum_{x_1=1}^{\infty} \sum_{x_2=x_1+1}^{\infty} \sum_{y_2=x_2}^{\infty} f(x_1, y_2) = \sum_{x_1=1}^{\infty} \sum_{y_2=x_1+1}^{\infty} \sum_{x_2=x_1+1}^{y_2} f(x_1, y_2) \tag{1.38}$$

$$= \sum_{x_1=1}^{\infty} \sum_{y_2=x_1+1}^{\infty} (y_2 - x_1) f(x_1, y_2) = \sum_{x_1=1}^{\infty} \sum_{x_2=x_1+1}^{\infty} (x_2 - x_1) f(x_1, x_2). \tag{1.39}$$

Here

$$f(x_1, x_2) = \begin{vmatrix} F_0(x_1 + 1; t) & F_0(x_2 + 1; t) \\ F_{-1}(x_1; t) & F_{-1}(x_2; t) \end{vmatrix} = \begin{vmatrix} F_0(x_1 + 1; t) & F_0(x_2 + 1; t) \\ F_0(x_1; t) - F_0(x_1 + 1; t) & F_0(x_2; t) - F_0(x_2 + 1; t) \end{vmatrix}$$

$$= \begin{vmatrix} \frac{t^{x_1+1}}{(x_1+1)!} e^{-t} & \frac{t^{x_2+1}}{(x_2+1)!} e^{-t} \\ \frac{t^{x_1}}{(x_1)!} e^{-t} & \frac{t^{x_2}}{(x_2)!} e^{-t} \end{vmatrix} = \frac{t^{x_1+x_2+1}}{(x_1+1)!(x_2+1)!} e^{-2t}. \tag{1.40}$$

Substituting this into (1.39) one finds

$$\mathbb{P}[N(t) \geq 2] = \sum_{x_1=1}^{\infty} \sum_{x_2=x_1+1}^{\infty} (x_1-x_2)^2 \frac{t^{x_1+x_2+1}}{(x_1+1)!(x_2+1)!} e^{-2t} = \frac{1}{2t} \sum_{x_1=2}^{\infty} \sum_{x_2=2}^{\infty} (x_1-x_2)^2 \frac{t^{x_1+x_2}}{x_1! x_2!} e^{-2t}, \tag{1.41}$$

which is nothing but the $N = 2$ case of (1.2). Generalization to general N is left as an exsersize.

1.5 Schur measure and process

The Schur measure is a measure on the set of partitions, in the form

$$\frac{1}{Z} s_\lambda(a_1, \cdots, a_N) s_\lambda(b_1, \cdots, b_M). \tag{1.42}$$

Here s_λ is the Schur function, see Appendix C. By the Cauchy identity (C.23), the normalization here is

$$Z = \prod_{j,k} \frac{1}{1 - a_j b_k}. \tag{1.43}$$

The Schur process is a measure on GT_N, in the form

$$\frac{1}{Z} s_{\lambda^{(1)}}(a_1) s_{\lambda^{(2)}/\lambda^{(1)}}(a_2) \cdots s_{\lambda^{(N)}}(a_N) s_{\lambda^{(N)}}(b_1, \cdots, b_M) \tag{1.44}$$

By (C.21), the marginal measure about $\lambda^{(N)}$ is nothing but the Schur measure (1.42).

There are various variants of the Schur measure and process, in which $s_\lambda(b_1, \cdots, b_M)$ is replaced by a Schur function related to a more general specialization ρ. Such measures appear for Markov dynamics on GT_N and TASEP can be realized as a marginal dynamics on the left diagonal $\lambda_i^i, 1 \le i \le N$.

Because the Schur function is written as a determinant by the Jacobi-Trudi formula (C.19), the Schur measure can be studied by the same methods as for GUE.

2 Various models and integrability

2.1 Stochastic and quantum correspondence

Before going into our main subject of this section, we briefly discuss the relationship between stochastic systems and quantum systems.

Prop. Let H be an $N \times N$ real symmetric matrix with non-negative off-diagonal entries. The matrix H is diagonalizable. Without loss of generality one can assume that the minimum eigenvalue is zero by subtracting the minimum eigenvalue times the unit matrix of size N if necessary. By the Perron-Frobenius theorem, all components of the corresponding eigenvector $g \in \mathbb{R}^N$ satisfies $g(i) > 0, 1 \le i \le N$. Define a diagonal matrix $G = \mathrm{diag}(g(1), \cdots, g(N))$. Then the matrix $L = G^{-1}HG$ is a generator of a Markov process. This is sometimes called the ground state transformation.

2.2 q-TASEP, q-Hahn TASEP and zero range processes

As a generalization of TASEP studied in the last section, we introduce q-TASEP. For the continuous time version, the jth particle hops to the right nearest neighboring site with rate $a_j(1 - q^{x_{j-1}-x_j-1})$ with $a_j > 0, 0 \le q < 1$. The dynamics of the gaps of particle positions $x_j - x_{j+1} - 1$ is the q-TAZRP (totally asymmetric zero range process). When $q = 0$, this reduces to the standard TASEP. By rescaling time, the rate can be taken to be $a_j(1 - q^{x_{j-1}-x_j-1})/(1-q)$. Then one can take the nontrivial $q \to 1$ limit. When all a_i's are the same, the dynamics is equivalent to the one of independent walkers.
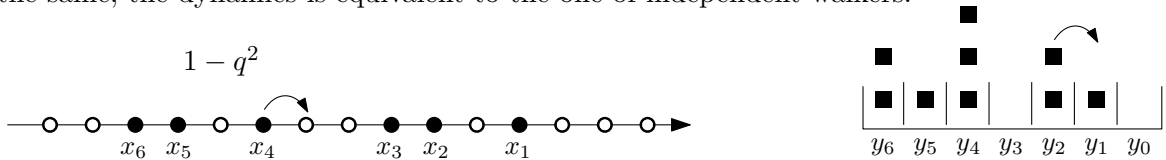
The model was introduced in [8] as a marginal process of the Macdonald process which we mention below but the corresponding zero-range process had already been introduced in [28]. There are also discrete time versions.

As a further generalization, we mention the q-Hahn TASEP. This was introduced by Povolotsky in [22]. The hopping probability is described in terms of a function $\varphi_{q,\mu,\nu}(j|m) = \mu^j \frac{(\nu/\mu;q)_j (\mu;q)_{m-j} (q;q)_m}{(\nu;q)_j (q;q)_j (q;q)_{m-j}}$ with $0 \le \nu < \mu < 1$. This is related to the measure with respect to which the q-Hahn polynomials are orthogonal, hence the name of the process.
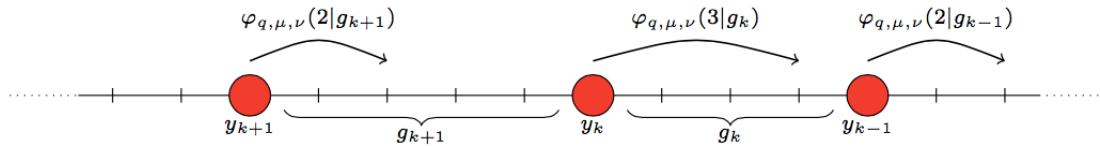
2.3 Six vertex model and its integrability

In equilibrium statistical mechanics, a central objectectiv is to compute the partition function,

$$Z = \sum_{C:\text{configurations}} e^{-\beta E(C)}, \tag{2.1}$$

where $E(C)$ is the energy associated with a configuration of the system and $\beta = 1/(k_B T)$ with k_B the Boltzmann constance and T the temperature of the system. For the famous Ising model, the energy is written as

$$E(C) = -J \sum_{\langle ij \rangle} s_i s_j \tag{2.2}$$

where $J > 0$ is the coupling constant, $s_i = \pm 1$ is the spin variable sitting on sites and the sum is over all nearest neighbor pairs of sites. From the partition function, one can calculate the free energy (per unit volume) f of the system and study various macroscopic properties of the system. For the case of two dimensional square lattice with sizes L, L' with periodic boundary conditions, it is defined as

$$f = -\kappa_B T \lim_{L,L' \to \infty} \frac{1}{LL'} \log Z. \tag{2.3}$$

Vertex models are originally introduced as statistical mechanical models for which the weight of a configuration of the system is given by a product of weights on all vertices of a lattice. As an example let us consider the two dimensional square lattice, suppose that a configuration is specified by some values on all edges, and assign some weight on each vertex denoted by $R_{lj}^{l'k}$ as a matrix for values l, j, l', k on four edges [Fig]. The partition function of this vertex model is defined to be the product of weights at all vertices,

$$Z = \sum_{\{j_e\}} \prod_{v:\text{vertices}} R_{j_1,j_2}^{j'_1,j'_2}. \tag{2.4}$$

Let us define the transfer matrix as the product of the weights in one direction as,

$$T_{j_1 \cdots j_L}^{k_1 \cdots k_L} = \sum_{l_1, \cdots, l_L} R_{l_1,j_1}^{l_2,k_1} \cdots R_{l_L,j_L}^{l_1,k_1}, \tag{2.5}$$

the partition function is written as $Z = \text{Tr } T^{L'}$. The transfer matrix is a $2^L \times 2^L$ matrix. We are interested in eigenvalues and eigenfunctions of this transfer matrix. For example, the free energy is the logarithm of the largest eigenvalue. Finding eigenvalues and eigenfunctions of a transfer matrix is in general difficult but becomes possible when the weight satisfies a certain condition [5].

Let us assign nonzero weights to the following six cases of vertices [Fig]. The weight is represented as a matrix

$$R_{l,j}^{l',k} = \begin{bmatrix} a & 0 & 0 & 0 \\ 0 & b & c & 0 \\ 0 & c & b & 0 \\ 0 & 0 & 0 & a \end{bmatrix}. \tag{2.6}$$

This is a (rather general) six vertex model. In particular when the weight is written as a matrix $R = R(x,y)$ of the form

$$a = a(x/y) = Qx/y - Q^{-1}y/x, \ b = b(x/y) = x/y - y/x, \ c = c(x/y) = Q - 1/Q, \tag{2.7}$$

it satisfies the following relation,

$$R_{12}(x,y)R_{13}(x,z)R_{23}(y,z) = R_{23}(y,z)R_{13}(x,z)R_{12}(x,y). \tag{2.8}$$

This is the Yang-Baxter equation and can be represented graphically [Fig]. Now using this R matrix, let us define the transfer matrix with a parameter ζ as (2.5) with parameters ζ and 1 for all R in the product. The main point of this YBE is that the transfer matrices with two parameters values commute:

$$[T(\zeta), T(\eta)] = 0. \tag{2.9}$$

To show this, let us introduce the monodromy matrix as

$$\mathcal{T}_{l;j_1\cdots j_L}^{l';k_1\cdots k_L}(\zeta, \{\xi\}) = \sum_{l_2,\cdots,l_L} R_{l,j_1}^{l_2,k_1}(\zeta, \xi_1) \cdots R_{l_L,j_L}^{l',k_1}(\zeta, \xi_L) = \begin{bmatrix} A(\zeta) & B(\zeta) \\ C(\zeta) & D(\zeta) \end{bmatrix} \tag{2.10}$$

This is also written as

$$\mathcal{T}(\zeta, \{\xi\}) = R_{01}(\zeta, \xi_1) \cdots R_{0L}(\zeta, \xi_L). \tag{2.11}$$

We mainly consider $\mathcal{T}(\zeta) = \mathcal{T}(\zeta, \{\xi_i = 1\})$.

By the Yang-Baxter equation, one can show

$$R_{12}(\zeta, \eta)\mathcal{T}_1(\zeta)\mathcal{T}_2(\eta) = \mathcal{T}_2(\eta)\mathcal{T}_1(\zeta)R_{12}(\zeta, \eta) \tag{2.12}$$

which is sometimes called the fundamental commutation relation (FCR). This can be understood graphically. The transfer matrix is

$$T(\zeta) = \text{Tr}_0\mathcal{T}(\zeta) = A(\zeta) + D(\zeta). \tag{2.13}$$

From (2.12) one can show (2.9). One can expand the transfer matrix $T(\zeta)$ in ζ around 1 as

$$T(\zeta) = \sum_{n=0}^{L-1} I_n(\zeta - 1)^n. \tag{2.14}$$

The coefficients I_n commute with each other: $[I_n, I_m] = 0$ and $I_0 = P$, the shift operator, and

$$I_1 = H_{XXZ} = \frac{1}{2}\sum_{j=1}^{L}(\sigma_j^x\sigma_{j+1}^x + \sigma_j^y\sigma_{j+1}^y + \Delta\sigma_j^z\sigma_{j+1}^z) \tag{2.15}$$

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with $\Delta = (Q + 1/Q)/2$ modulo a factor and additive constant. In particular one has $[H, I_n] = 0$, implying that I_n's are conserved quantities.

There is a standard procedure to find the eigenvalues and eigenvectors of the transfer matrix, called the algebraic Bethe ansatz [9,11,36]. First let us let us consider L two dimensional vector spaces $V_i = \mathbb{C}^2, 1 \le i \le L$, where each V_i has basis $|0\rangle$ and $|1\rangle$, corresponding to two possible states at each column of the six vertex model. Set $|\Omega\rangle = |0\ldots0\rangle$, which we call the pseudo vacuum. One can easily check

$$A(\zeta)|\Omega\rangle = (a(\zeta))^L|\Omega\rangle, \ D(\zeta)|\Omega\rangle = (d(\zeta))^L|\Omega\rangle \tag{2.16}$$

and hence from (2.13) it is immediate to see that the pseudo vacuum is an eigen vector of the transfer matrix with the eigenvalue $\Lambda(\zeta) = (a(\zeta))^L + (d(\zeta))^L$. Next from the FCR (2.12), one has

$$[B(\zeta), B(\eta)]] = 0, \tag{2.17}$$
$$A(\eta)B(\zeta) = f(\eta, \zeta)B(\zeta)A(\eta) + g(\zeta, \eta)B(\eta)A(\zeta), \tag{2.18}$$
$$D(\eta)B(\zeta) = f(\zeta, \eta)B(\zeta)A(\eta) + g(\eta, \zeta)B(\eta)A(\zeta) \tag{2.19}$$

with $f(\eta, \zeta) = a(\eta/\zeta)/b(\eta/\zeta), g(\eta, \zeta) = c(\eta/\zeta)/b(\eta/\zeta)$. Using this commutation relations, one can check that the vector of the form $\prod_{j=1}^N B(\zeta_j)\Omega\rangle$ is the eigenvector of the transfer matrix $T(\zeta)$ with the eigenvalue

$$\Lambda(\zeta) = (a(\zeta))^L \prod_{j=1}^N f(\zeta, \zeta_i) + (d(\zeta))^L \prod_{j=1}^N f(\zeta_{,i} \zeta), \tag{2.20}$$

provided that ζ_k's satisfy

$$\left(\frac{a(\zeta_k)}{d(\zeta_k)}\right)^L = \prod_{j(\neq k)=1}^N \frac{f(\zeta_j, \zeta_k)}{f(\zeta_k, \zeta_j)}, \ 1 \le k \le N. \tag{2.21}$$

By expanding (2.20) around $\zeta = 1$, one can also find the eigenvalue for the Hamiltonian (2.15). In particular, one can find an exact solution for the free energy of the six vertex model.

2.4 Stochastic six vertex model

The above "standard" six vertex model is not directly associated with a Markov process. Now let us introduce the stochastic version, which was studied in [16]. Let us replace the weight of the six vertex model by the 4×4 matrix of the form,

$$\tilde{R} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \delta_1 & 1 - \delta_2 & 0 \\ 0 & 1 - \delta_1 & \delta_2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \tag{2.22}$$

with $0 \le \delta_1, \delta_2 \le 1$. Obviously this is a stochastic matrix (nonzero elements and sum of each column gives one) and also the transfer matrix constructed from this matrix is also stochastic. This is the stochastic six vertex model.

With a certain parametrization, the matrix can be represented as

$$\tilde{R}(x,y) = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \frac{q(x-y)}{qx-y} & \frac{(q-1)y}{qx-y} & 0 \\ 0 & \frac{(q-1)y}{qx-y} & \frac{x-y}{qx-y} & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \tag{2.23}$$

This R matrix also satisfies the Yang-Baxter equation. This can be checked directly, but also as a consequence of the Yang-Baxter equation for the six vertex model because the $\tilde{R}$ for the stochastic six vertex model is related to the one for the standard six vertex model by a "gauge" transformation.

Since the $\tilde{R}$ matrix satisfies the YBE, one can apply the standard procedure in the previous subsection again to the stochastic six vertex model. By expanding the transfer matrix around $\zeta = 1$ as (2.14), what we find as I_1 is now

$$^t L_{\text{ASEP}} = \sum_j \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & -q & 1 & 0 \\ 0 & q & -1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}_{j,j+1} \tag{2.24}$$

which is nothing but the (adjoint) generator of the (continuous time) ASEP (with $p = 1$ normalization). One can also understand the appearance of the (continuous time) ASEP from the stochastic six vertex model by looking at the lattice of the six vertex model diagonally. Put in the opposite way, the stochastic six vertex model can be interpreted as a discrete time analogue of the ASEP.

By applying the standard method of the algebraic Bethe ansatz, one can construct the eigenvaue and eigenvector of the stochastic six vertex model and the ASEP at the same time. By an appropriate change of variables one can recover the result from the coordinate Bethe ansatz in the last section. On the finite lattice with periodic boundary condition, one has the condition (2.21) which is equivalent to (1.24), one does not have to impose this for a system on $\mathbb{Z}$.

2.5 Stochastic higher spin six vertex model

Let us consider a generalization of the six vertex model in which there could be more than one thick lines on edges, with the condition that the number of thick lines are conserved at each vertex. First we consider a case where horizontally there could be up to one thick line, but vertically there could be any number of lines. Then there are four possible type of configurations
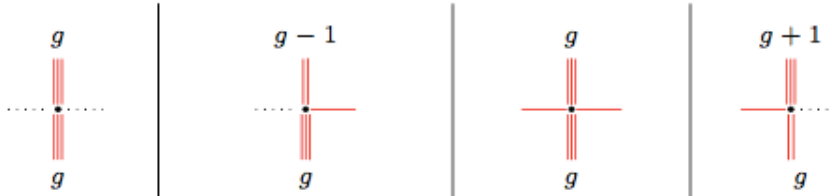

Figure 2: Configuration at a vertex of HS6VM

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From the left to right, the weight of the configurations are given by

$$\frac{1+\beta q^g}{1+\beta}, \; \frac{\beta(1-q^g)}{1+\beta}, \; \frac{\beta+\alpha q^g}{1+\beta}, \; \frac{1-\alpha q^g}{1+\beta}, \tag{2.25}$$

where $g \in \mathbb{N}$ is the number of incoming lines vertically. Let us denote this weight by a matrix L. One can define the transfer matrix $T(\zeta)$ as a product of this L matrices. The vertex model with this weight is called the stochastic higher spin six vertex model (HS6VM). We can regard the second axis to be time direction, the lines can be considered as time step evolution of particle positions and the weight is represented by the transfer matrix T. One can regard them as discrete time TASEP and can also consider corresponding TAZRP. When $\alpha = 0$, it reduces to a discrete time version of the q-TASEP, the Bernoulli q-TASEP.

Exercise: Set $\alpha = 1/q, \beta = -\kappa/q, 0 < q < 1 < \kappa$. Check that the stochastic HS6VM becomes the stochastic six vertex model with $q = \delta_1/\delta_2, \kappa = (1-\delta_1)/(1-\delta_2)$.

One can check that this satisfies the relation,

$$RLL = LLR, \tag{2.26}$$

with the R matrix for the six vertex model. Then one can apply the same arguments as for the six vertex model, and find the eigenvalues and eigenvectors of the HS6VM. In fact for the model on $\mathbb{Z}$, the only difference is the eigenvalue.

One can further introduce a more general model in which there could be up to $J(\in \mathbb{Z}_+)$ thick lines horizontally, by the procedure called the fusion. By setting $\mu = \nu q^J$ in this model (with analytic continuation wrt J), one gets the q-Hahn TASEP.

In the stochastic context the model was introduced in [10]. The HS6VM had been introduced much earlier.

Finding a R matrix satisfying the Yang Baxter equation is nontrivial. There are often related to quantum group. In particular the R matrix associated with the HS6VM is related to the higher spin representation of $U_q(sl_2)$ symmetry. One can consider other quantum group as $U_q(sl_N)$. This corresponds to multi-species models.

A   Formulation of lattice gases

In this section we explain the formulation of the lattice gas on $\mathbb{Z}$ for the case of exclusion process. We do not give the details but refer the readers to existing literature [17–19, 30].

Let us introduce a notation,

$$\eta(x) = \begin{cases} 0, & \text{site } x(\in \mathbb{Z}) \text{ is empty,} \\ 1, & \text{site } x(\in \mathbb{Z}) \text{ is occupied.} \end{cases} \tag{A.1}$$

Our state space is $X = \{0,1\}^{\mathbb{Z}}$, which is compact in the product topology. $\eta(\in X)$ is called a configuration (of particles). We set

$$\eta^{xy}(u) = \begin{cases} \eta(y), & \text{if } u = x, \\ \eta(x), & \text{if } u = y, \\ \eta(u), & \text{if } u \neq x, y. \end{cases} \tag{A.2}$$

Let us set $C(X)$ to be the space of continuous functions on X. Let us consider a Feller process $\eta_t \colon [0, \infty) \to X$ for which $E^{\eta} f(\eta_t) \in C(X)$ for any $f \in C(X)$. Let P^{μ} be the

distribution of the process with initial measure μ and E^μ be the corresponding expectation. We sometimes consider the situation in which the process starts from a single configuration η for which case we abuse the notation like P^η and E^η. For η_t, one can define the semigroup $S(t)$ on $C(X)$ by

$$S(t)f(\eta) = E^\eta f(\eta_t), \quad f \in C(X). \tag{A.3}$$

It is known that there is a one-to-one correspondence between the semigroup $S(t)$ and the generator L defined by

$$Lf = \lim_{t \to 0} \frac{S(t)f - f}{t}. \tag{A.4}$$

The lattice gas can be constructed by giving its generator. Let $c(x, y, \eta)$ be the rate of exchange of the occupancies at x and y. The generator of the process is given by introducing an operator

$$Lf(\eta) = \frac{1}{2} \sum_{x,y \in \mathbb{Z}} c(x, y, \eta)[f(\eta^{xy}) - f(\eta)] \tag{A.5}$$

for f a cylinder function (which depends only on finitely many coordinates) and then taking its closure. For this construction to work the rate $c(x, y, \eta)$ should satisfy certain conditions but here we simply assume that they are satisfied.

In the $t \to \infty$ limit, the system approaches the stationary measure μ, which is defined by

$$E^\mu[Lf] = 0 \tag{A.6}$$

For the ASEP the operator L on the cylinder set is given by

$$Lf(\eta) = \frac{1}{2} \sum_{x \in \mathbb{Z}} (p\eta(x)(1 - \eta(x+1)) + q(1 - \eta(x))\eta(x+1)) \left[f(\eta^{xy}) - f(\eta)\right]. \tag{A.7}$$

For ASEP on $\mathbb{Z}$, there are two series of the stationary measures. One is the product measure with $E[\eta(x)] = 1/(1 + (q/p)^x)$ and its translations. The other is the Bernoulli measure with density $\rho, 0 \leq \rho \leq 1$. It is known that these exhaust the all extremal stationary measures.

B   GUE and Tracy-Widom distribution [3, 12, 20]

In random matrix theory, Gaussian ensembles play a prominent role.

Definition B.1. *(Gaussian ensembles)*
   In Gaussian ensembles, the measure for $N \times N$ matrix H is given in the form,

$$P(H)dH = \frac{1}{Z} e^{-\frac{\beta}{2} \text{Tr} H^2} dH, \quad \beta = 1, 2, 4. \tag{B.1}$$

For GOE($\beta = 1$, Gaussian orthogonal ensemble(GOE)), H is taken to be a real symmetric matrix and the measure dH is $dH = \prod_{j=1}^{N} dH_{jj} \prod_{j<l} dH_{jl}$. For GUE($\beta = 2$, Gaussian unitary ensemble(GUE)), H is taken to be a hermitian matrix and the measure dH is $dH = \prod_{j=1}^{N} dH_{jj} \prod_{j<l} dH_{jl}^R \prod_{j<l} dH_{jl}^I$ where H_{jl}^R and H_{jl}^I denotes the real and imaginary part of H_{jl} respectively. GSE($\beta = 4$) means the Gaussian symplectic ensemble(GSE)). For a precise definition see a reference.

For Guassian ensembles, the joint eigenvalue density can be written down explicitly.

Proposition B.2. *The probability density of eigenvalues, $x_i, 1 \leq i \leq N$, ($x_i \leq x_{i+1}, 1 \leq i \leq N-1$) is*

$$P(x_1, \ldots, x_N) = \frac{1}{Z} \prod_{j<l} |x_l - x_j|^{\beta} \prod_{j=1}^{N} e^{-\frac{\beta}{2}x_j^2}, \quad \beta = 1, 2, 4. \tag{B.2}$$

For a proof see for instance [3].

By using this joint distribution one can in principle study all properties of the eigenvalues of Gaussian ensembles. For example, the Wigner's semin-circle law can be derived. In our discussions, the probabilistic properties of the largest eigenvalue are important. From the above joint distribution, one finds that the distribution function of the largest eigenvalue of GUE can be written in the following N fold integral.

Corollary B.3. *The distribution function of the largest eigenvalue $x_{\max}$*

$$\mathbb{P}_{N2}[x_{\max} \leq u] = \frac{1}{Z} \int_{(-\infty, u]^N} \prod_{1 \leq j<l \leq N} |x_l - x_j|^{\beta} \prod_{j=1}^{N} e^{-\frac{\beta}{2}x_j^2} dx_1 \cdots dx_N. \tag{B.3}$$

We are interested in the large N asymptotics of this quantity. This N fold integral expression is not very suited for doing this. We rewrite it into the Fredholm determinant. For the moment let us focus on the $\beta = 2$ case.

By rewriting the determinant (using Heine identity below and $\det(1+AB) = \det(1+BA)$), one can show

Proposition B.4.
$$\mathbb{P}_{N2}[x_{\max} \leq u] = \det(1 - \chi_u K_{N2} \chi_u) \tag{B.4}$$

where

$$K_{N2}(x, y) = e^{-\frac{x^2+y^2}{2}} \sum_{n=0}^{N-1} \frac{H_n(x)H_n(y)}{\sqrt{\pi}2^n n!}. \tag{B.5}$$

Here $H_n(x)$ is the n th Hermite polynomial

$$H_n(x) = (-1)^n e^{x^2} \frac{d^n}{dx^n} e^{-x^2}. \tag{B.6}$$

Note that the kernel (B.5) can be written in the form $K(x,y) = \sum_{n=0}^{N-1} \phi_n(x)\psi_n(y)$ if we set $\phi_n(x) = \psi_n(x) = \frac{e^{-x^2/2}}{\pi^{1/4}\sqrt{2^n n!}} H_n(x)$. In addition, by using the integral representations of the Hermite polynomial,

$$H_n(x) = \frac{e^{x^2} 2^n}{\sqrt{\pi} i} \int_{i\mathbb{R}} dz e^{z^2 - 2xz} z^n = \frac{n!}{2\pi i} \int_0 \frac{dz}{z^{n+1}} e^{2xz - z^2}, \tag{B.7}$$

one can find a double contour integral formula of the kernel,

$$K_{N2}(x, y) = 2e^{-y^2} \int_{i\mathbb{R}} dz \int_0 dw \frac{z^N}{w^N} \frac{e^{z^2 - 2zx - w^2 + 2wy}}{z - w} \tag{B.8}$$

Now it has become easier to consider the large N asymptotics. The basic asymptotics we need is that of the Hermite polynomials [31]. The Airy function $\mathrm{Ai}(x)$ is defined by

$$\mathrm{Ai}(x) = \frac{1}{2\pi} \int_{-\infty+i\epsilon}^{+\infty+i\epsilon} e^{ixz + \frac{iz^3}{3}} dz, \ \epsilon > 0. \tag{B.9}$$

Let us write

$$\phi_n(x) = \frac{H_n(x)e^{-x^2/2}}{\pi^{1/4}\sqrt{2^n n!}}. \tag{B.10}$$

Then for the scaling $n = N - N^{1/3}\lambda, x = \sqrt{2N} + \frac{\xi}{\sqrt{2}N^{1/6}}$, we have

$$\phi_N(x) \sim 2^{1/4} N^{-1/12} \mathrm{Ai}(\xi + \lambda). \tag{B.11}$$

This asymptotics can be shown by applying saddle point method to the integral representations (B.7).

To describe the results we introduce a kernel and the corresponding distribution.

Definition B.5. *The* Airy *kernel* $K_2(x,y)$ *is defined by*

$$K_2(x,y) = \frac{\mathrm{Ai}(x)\mathrm{Ai}'(y) - \mathrm{Ai}(y)\mathrm{Ai}'(x)}{x - y} = \int_0^\infty \mathrm{Ai}(x+\lambda)\mathrm{Ai}(y+\lambda)d\lambda. \tag{B.12}$$

The GUE Tracy-Widom *distribution* $F_2(s)$ *[32] is defined by*

$$F_2(s) = \det(1 - \chi_s K_2 \chi_s)_{L^2(\mathbb{R})}. \tag{B.13}$$

This is the limiting distribution for the appropriately scaled largest eigenvalue in GUE.

Theorem B.6.
$$\lim_{N\to\infty} \mathbb{P}_{N2}\left[(x_{\max} - \sqrt{2N})\sqrt{2}N^{1/6} \leq s\right] = F_2(s). \tag{B.14}$$

This follows from

Proposition B.7.

$$\lim_{N\to\infty} \frac{1}{\sqrt{2}N^{1/6}} K_{N2}\left(\sqrt{2N} + \frac{\xi_1}{\sqrt{2}N^{1/6}}, \sqrt{2N} + \frac{\xi_2}{\sqrt{2}N^{1/6}}\right) = K_2(\xi_1, \xi_2), \tag{B.15}$$

which in turn is a consequence of (B.11).

So far our discussions are only for the GUE. One can generalize the discussions to other two cases, GOE,GSE. The limiting distribution is denoted by F_1, F_4

Theorem B.8.

$$\lim_{N\to\infty} \mathbb{P}_{N\beta}\left[(x_{\max} - \sqrt{2N})\sqrt{2}N^{1/6} \leq s\right] = F_\beta(s), \quad \beta = 1, 4. \tag{B.16}$$

Before ending the section we state

Proposition B.9. *(Heine identity)*

$$\int \det\left(\Phi_j(x_{l+1})\right)_{0\leq j,l\leq N-1} \det\left(\Psi_j(x_{l+1})\right)_{0\leq j,l\leq N-1} dx_1 \cdots dx_N$$

$$= N! \det\left(\int \Phi_j(x)\Psi_l(x)dx\right)_{0\leq j,l\leq N-1}. \tag{B.17}$$

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This is seen as follows

$$\det\left(\int \Phi_j(x)\Psi_l(x)dx\right)_{0\leq j,l\leq N-1} = \int dx_1 \cdots dx_N \det\left(\Phi_i(x_j)\Psi_j(x_i)\right)$$

$$= \int dx_1 \cdots dx_N \prod_i \Phi_i(x_i) \det\left(\Psi_j(x_i)\right) = \int dx_1 \cdots dx_N \prod_i \Phi_i(x_{\sigma(i)}) \det\left(\Psi_j(x_{\sigma(i)})\right)$$

$$= \int dx_1 \cdots dx_N \mathrm{sgn}\sigma \prod_i \Phi_i(x_{\sigma(i)}) \det\left(\Psi_j(x_i)\right)$$

$$= \frac{1}{N!} \int dx_1 \cdots dx_N \sum_\sigma \mathrm{sgn}\sigma \prod_i \Phi_i(x_{\sigma(i)}) \det\left(\Psi_j(x_i)\right)$$

$$= \int dx_1 \cdots dx_N \det\left(\Phi_i(x_j)\right) \det\left(\Psi_i(x_j)\right). \tag{B.18}$$

C   Partition, Schur function, etc

First a partition is an n-tuple $\lambda = (\lambda_1, \ldots, \lambda_n)$ with $n \in \mathbb{N}, \lambda_j \in \mathbb{Z}_+, 1 \leq j \leq n$ s.t. $\lambda_1 \geq \ldots \geq \lambda_n$. n is called the length of the partition and is denoted as $\ell(\lambda)$. The set of all partitions of length n is denoted by $\mathcal{P}_n$. A partition λ can also be represented (and identified) as a Young diagram with n rows of length $\lambda_1, \ldots, \lambda_n$. The transpose λ' is the partition of length λ_1 defined as $\lambda'_i = \#\{j \in \mathbb{Z}_+ | \lambda_j \geq i\}, 1 \leq i \leq \lambda_1$. For two partitions $\lambda \in \mathcal{P}_n, \mu \in \mathcal{P}_m$ s.t. $m \leq n$ and $\lambda_i - \mu_i \geq 0, 1 \leq i \leq n$ (with the understanding $\mu_i \equiv 0, m < i \leq n$), a pair (λ, μ) is called a skew diagram and is denoted by λ/μ, with $|\lambda/\mu| = |\lambda| - |\mu|$. We say that λ/μ is a horizontal strip iff in each column λ/μ has at most one box, i.e., $\mu_i \leq \lambda_i \leq \mu_{i-1}$. A column-strict (skew) Young tableaux is a sequence of partitions

$$(\mu =)\lambda^{(0)} \subset \lambda^{(1)} \subset \cdots \subset \lambda^{(N)}(= \lambda)$$

such that $\lambda^{(i)}/\lambda^{(i-1)}, 1 \leq i \leq N$ is a horizontal strip. If $\mu = \phi$, this is equivalent to the semi-standard Young tableaux with entries from $\{1, \cdots, N\}$. Put i to the horizontal strip of $\lambda^{(i)}/\lambda^{(i-1)}$.

(Skew) Schur function with N variables $x = (x_1, \ldots, x_N)$ for a skew Young diagram λ/μ is defined as

$$s_{\lambda/\mu}(x_1, \ldots, x_N) = \sum_T x^T, \quad x^T = \prod_{i=1}^N x_i^{|\lambda^{(i)} - \lambda^{(i-1)}|}$$

where the sum over T is wrt column strict tableaux with $\lambda^{(0)} = \mu, \lambda^{(N)} = \lambda$.

When $N = 1$

$$s_{\lambda/\mu}(x_1) = \begin{cases} x_1^{|\lambda-\mu|} & \text{If } \mu_i \leq \lambda_i \leq \mu_{i-1} \\ 0 & \text{otherwise} \end{cases}$$

$$s_{\lambda'/\mu'}(x_1) = \begin{cases} x_1^{|\lambda'-\mu'|} & \text{If } (\lambda_j = \mu_j \text{ or } \lambda_j = \mu_j + 1) \text{ \& } \lambda_i \geq \mu_i \\ 0 & \text{otherwise} \end{cases}$$

The (skew) Schur function can be written as a single determinant by the Jacobi-Trudi formula,

$$s_{\lambda/\mu}(x) = \det(h_{\lambda_i - \mu_j - i + j}(x))_{1 \leq i,j \leq \ell(\lambda)} \tag{C.19}$$

where $h_k(x) = \sum_{1 \le i_1 \le \ldots \le i_k \le N} x_{i_1} \cdots x_{i_k}$ is the complete homogeneous symmetric function. For the case of one variable $h_k(x_1) = x_1^k 1_{k \ge 0}$.

Properties of Schur function.

$$\sum_\mu s_{\mu/\lambda}(x) s_{\mu/\nu}(y) = \sum_\tau s_{\nu/\tau}(x) s_{\lambda/\tau}(y) \Pi(x, y) \tag{C.20}$$

$$\sum_\lambda s_\lambda(x) s_{\mu/\lambda}(y) = s_\mu(x, y) \tag{C.21}$$

where

$$\Pi(x, y) = \prod_{i=1}^{N} \prod_{j=1}^{M} \frac{1}{1 - x_i y_j} \tag{C.22}$$

Setting $\lambda = \nu = \phi$ in the first equality, we get the Cauchy identity,

$$\sum_\mu s_\mu(x) s_\mu(y) = \Pi(x, y). \tag{C.23}$$

The Gelfand-Tsetlin cone is defined to be

$$\mathrm{GT}_N := \{\lambda_i^{(j)}, 1 \le i \le j \le N | \lambda_i^{(j)} \in \mathbb{N}, \lambda_i^{(j-1)} \le \lambda_i^{(j)} \le \lambda_{i-1}^{(j-1)}\}$$

Each $\lambda^{(j)} = \{\lambda_i^{(j)}, 1 \le i \le j\}, 1 \le j \le N$ is a Young diagram and an element of GT_N denoted by $\underline{\lambda}$ is considered as consisting of these N Young diagrams $\underline{\lambda} = (\lambda^{(1)}, \ldots, \lambda^{(N)})$ and is represented as an array of a triangular shape.

$$
\begin{array}{ccccccc}
\lambda_N^{(N)} & \lambda_{N-1}^{(N)} & & \cdots & & \lambda_2^{(N)} & \lambda_1^{(N)} \\
& \ddots & & \vdots & & \cdot\cdot & \\
& & \lambda_3^{(3)} & & \lambda_2^{(3)} & & \lambda_1^{(3)} \\
& & & \lambda_2^{(2)} & & \lambda_1^{(2)} & \\
& & & & \lambda_1^{(1)} & &
\end{array}
$$

Figure 3: Gelfand-Tsetlin cone

D   LUE formula for TASEP with step initial condition

In [14], the following LUE formula was shown.

Proposition D.1.

$$\mathbb{P}[N(t) \ge N] = \frac{1}{Z'_{N2}} \int_{[0,t]^N} \prod_{1 \le j < k \le N} (x_j - x_k)^2 \prod_{j=1}^{N} e^{-x_j} dx_1 \ldots dx_N. \tag{D.24}$$

Z'_{N2} is a normalization.

The similarity of this expression to (B.3) is obvious.

The formula can be derived using the transition probability [1, 21] One can show [21]

Proposition D.2. *Under the condition $M > y_N - y_1$,*

$$\mathbb{P}[X_1(t) \geq y_1 + M]$$

$$= \sum_{y_1+M \leq x_1 < x_2 < \cdots < x_N} G(x_1, x_2, \cdots, x_N; t | y_1, y_2, \cdots, y_N; 0)$$

$$= \frac{1}{\prod_{j=1}^N j!} \int_{[0,t]^N} dt_1 \cdots dt_N \prod_{1 \leq j < k \leq N} (t_k - t_j) \det\left(F_{-j+1}(y_1 - y_j + M - 1; t_{N-k+1})\right). \quad \text{(D.25)}$$

The step initial condition corresponds to setting $y_j = -j + 1, j = 1, \cdots, N$. In this case (D.25) reduces to (D.24). Here we only see how the computation proceeds for $N = 2$ with step i.c.

$$\mathbb{P}[N(t) \geq 2] = \sum_{1 \leq x_1 < x_2} G(x_1, x_2; t | y_1 = -1, y_2 = 0; 0)$$

$$= \begin{vmatrix} F_1(2;t) & F_2(3;t) \\ F_0(1;t) & F_1(2;t) \end{vmatrix} = \int_0^t dt_2 \int_0^t ds \begin{vmatrix} F_0(1;t_2) & F_1(2;s) \\ F_{-1}(0;t_2) & F_0(1;s) \end{vmatrix}$$

$$= \int_0^t dt_2 \int_0^t ds \int_0^s dt_1 \begin{vmatrix} F_0(1;t_2) & F_0(1;t_1) \\ F_{-1}(0;t_2) & F_{-1}(0;t_1) \end{vmatrix}$$

$$= \int_0^t dt_2 \int_0^t ds(t-t_1) \begin{vmatrix} F_0(1;t_2) & F_0(1;t_1) \\ F_{-1}(0;t_2) & F_{-1}(0;t_1) \end{vmatrix}$$

$$= \frac{1}{2} \int_0^t dt_2 \int_0^t ds(t_2-t_1) \begin{vmatrix} F_0(1;t_2) & F_0(1;t_1) \\ F_{-1}(0;t_2) & F_{-1}(0;t_1) \end{vmatrix}$$

$$= \frac{1}{2} \int_0^t dt_2 \int_0^t ds(t_2-t_1) \begin{vmatrix} F_0(1;t_2) & F_0(1;t_1) \\ F_0(0;t_2) & F_0(0;t_1) \end{vmatrix}$$

$$= \frac{1}{2} \int_0^t dt_2 \int_0^t ds(t_2-t_1) \begin{vmatrix} t_2 e^{-t_2} & t_1 e^{-t_2} \\ e^{-t_2} & e^{-t_1} \end{vmatrix}$$

$$= \frac{1}{2} \int_0^t dt_2 \int_0^t ds(t_2-t_1)^2 e^{-t_1-t_2}. \quad \text{(D.26)}$$

The computation can be generalized to arbitrary N and in this way one can arrive at (D.24).

E   Some q-functions and q-formulas

In this appendix, we summarize a few q-notations, q-functions and q-formulas. The first is the q-Pochhammer symbol, or the q shifted factorial. For $|q| < 1$ and $n \in \mathbb{N}$,

$$(a;q)_\infty = \prod_{n=0}^\infty (1 - aq^n), \quad (a;q)_n = \frac{(a;q)_\infty}{(aq^n;q)_\infty}. \quad \text{(E.27)}$$

The q-binomial theorem will be useful in various places in the discussions,

$$\sum_{n=0}^\infty \frac{(a;q)_n}{(q;q)_n} z^n = \frac{(az;q)_\infty}{(z;q)_\infty}, \quad |z| < 1. \quad \text{(E.28)}$$

In particular the $a = 0$ case appears in many applications. Another q-binomial formula reads (see e.g. Cor.10.2.2.(b) in [4])

$$\sum_{n=0}^{\infty} \frac{(-1)^n q^{n(n-1)/2}}{(q;q)_n} z^n = (z;q)_\infty. \tag{E.29}$$

There is yet another version of the q-binomial theorem (see e.g. Cor.10.2.2.(c) in [4]),

$$\sum_{k=0}^{\ell} \frac{(-1)^k q^{k(k-1)/2}(q;q)_\ell}{(q;q)_k(q;q)_{\ell-k}} x^k = (1-x)(1-xq)\cdots(1-xq^{\ell-1}). \tag{E.30}$$

The q-exponential function, denoted as $e_q(z)$ is defined to be

$$e_q(z) := \frac{1}{((1-q)z;q)_\infty} = \sum_{n=0}^{\infty} \frac{(1-q)^n}{(q;q)_n} z^n. \tag{E.31}$$

The second equality is by the above q-binomial theorem (E.28). From the series expansion expression, it is easy to see that this tends to the usual exponential function in the $q \to 1$ limit.

The q-Gamma function $\Gamma_q(x)$ is defined by

$$\Gamma_q(x) = (1-q)^{1-x} \frac{(q;q)_\infty}{(q^x;q)_\infty}. \tag{E.32}$$

The q-digamma function is defined by $\Phi_q(z) = \partial_z \log \Gamma_q(z)$. In the $q \to 1$ limit, they tends to the usual Γ function and the digamma function respectively.

Ramanujan's summation formula (cf [4] p502, [13] p138) is a two-sided generalization of the above q-binomial theorem (E.28). For $|q| < 1, |b/a| < |z| < 1$,

$$\sum_{n\in\mathbb{Z}} \frac{(a;q)_n}{(b;q)_n} z^n = \frac{(az;q)_\infty(\frac{q}{az};q)_\infty(q;q)_\infty(\frac{b}{a};q)_\infty}{(z;q)_\infty(\frac{q}{a};q)_\infty(b;q)_\infty(\frac{b}{az};q)_\infty}. \tag{E.33}$$

F   Pauli matrices, Tensor product

Pauli matrices are
$$\sigma^x = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \ \sigma^y = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}, \ \sigma^z = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}. \tag{F.34}$$

Tensor product notation. Suppose there are m dimensional vector spaces $V_i, 1 \le i \le N$. For an $m \times m$ matrix A, A_i acts nontrivially only on V_i. Similarly, for $m^2 \times m^2$ matrix B, $B_{i,j}$ acts nontrivially only on V_i, V_j.

For example, when there are three two-dimensional vector spaces $V_1 = V_2 = V_3 = \mathbb{C}^2$ and 4×4 matrix A, $\sigma_1^x = \sigma^x \otimes 1_2 \otimes 1_2, \sigma_2^z = 1_2 \otimes \sigma^z \otimes 1_2, A_{12} = A \otimes 1_2$, where 1_2 means the 2×2 identity matrix.

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