

Geodesic Divergence in Certain Riemannian Manifolds

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Attempts to generalise the Gromov boundary

Ever since Gromov defined his notion of hyperbolicity in [Gromov] and topologised the space of geodesic rays in the Gromov boundary, there has been various generalisations of the Gromov boundary to a broader class of spaces such as the Morse boundary [Cordes] or the Bowditch boundary for relatively hyperbolic groups by [Bowditch]. One of these generalisations is the quasi-redirecting boundary by Qing and Rafi [Qing-Rafi] which is well-defined for a much broader class of metric spaces and is invariant under quasi-isometries. It is quite well-behaved in the sense that it coincides with the Gromov boundary for a δ -hyperbolic space, with the Bowditch boundary if G is relatively hyperbolic and is a point when G exhibits linear divergence.

Definitions

- **Quasi-geodesic** - A map $f : I \rightarrow X$ where $I \subseteq \mathbb{R}$ is said to be a quasi-geodesic if there exists (q, Q) such that
$$\frac{|x-y|}{q} - Q \leq d(f(x), f(y)) \leq q|x-y| + Q .$$
- **Quasi-redirection** - Let $\alpha, \beta : [0, \infty) \rightarrow X$ be two quasi-geodesic rays. We say that α redirects to β (denoted by $\alpha \preceq \beta$) if for every $r > 0$, there is a (q, Q) -quasigeodesic ray γ_r such that $\gamma_r \equiv \alpha$ in $B(a(0), r)$ and γ_r eventually coincides with β . We say that $\alpha \sim \beta$ if $\alpha \preceq \beta$ and $\beta \preceq \alpha$. Denote by $P(X)$ the resulting equivalence classes of quasi-geodesic rays.

Some assumptions on X to make it "well-behaved"

Assumptions

- **Assumption 0-** X is a proper geodesic metric space. Furthermore, there exists a (q_0, Q_0) such that every $x \in X$ lies on a (q_0, Q_0) -ray.
- **Assumption 1-** For (q_0, Q_0) as in the previous assumption, every $\alpha \in P(X)$ contains a (q_0, Q_0) ray. Call that ray the central element and denote it as $\mathbf{a} \in \alpha$.
- **Assumption 2-** For every $\alpha \in P(X)$, there is a function $f_\alpha : [1, \infty) \times [0, \infty) \rightarrow [1, \infty) \times [0, \infty)$ such that if $\mathfrak{b} \preceq \alpha$, then any (q, Q) -ray $\beta \in \mathfrak{b}$ can be $f_\alpha((q, Q))$ -quasiredirected to \mathbf{a} .

Topologising the boundary

Defining a topology

Recall that points in $P(X)$ are equivalence classes of quasi-geodesic rays. To unify the treatment, define $\mathbf{x} \in X$ as follows. $\mathbf{x} = \{ \text{quasi-geodesic rays in } X \text{ which pass through } x \}$. We can then define $\mathcal{U}(\mathbf{a}, r) = \{ \mathbf{b} \in X \cup P(X) : \text{every } q\text{-ray in } \mathbf{b} \text{ can be } F_{\mathbf{a}}(q) \text{ redirected to } \mathbf{a} \text{ at radius } r \}$ and these along with open sets in X comprise the basis of open sets in X .

Uniformization

Let (M, g) be a complete, simply connected Riemannian manifold of dimension 2, then (M, g) is conformally equivalent/biholomorphic to -

- S^2
- \mathbb{R}^2
- \mathbb{H}^2

From [Grigoryan], we see that Brownian motion a simply connected Riemannian surface is transient if and only if it is conformally equivalent to \mathbb{H}^2 .

Some preliminaries in Riemannian geometry

Preliminaries

- Laplace-Beltrami operator - $\Delta_M f = \text{Tr}(\text{Hess}(f))$
- Green's function- Let $p(t, x, y) : (0, \infty) \times M \times M \rightarrow \mathbb{R}$ be the fundamental solution of $\frac{dp}{dt} - \frac{1}{2}\Delta_M(p) = 0$. Then we define $G(x, y) = \int_0^\infty p(t, x, y) dt$ to be the Green's function. We note that $G(x, y)$ is finite for some $x, y \in M$ if and only if it is finite for all $x, y \in M$ if and only if it is transient.
- Bounded geometry- A Riemannian manifold (M, g) is said to exhibit bounded geometry if there exists $(\kappa, \chi) \in [0, \infty) \times (0, \infty)$ such that at all points $p \in M$, $-\kappa \leq \text{sec}_p(\Pi) \leq \kappa$ for all two-dimensional subspaces of $T_p M$ and $\text{inj}(p) > \chi$.

Triangulating planes with bounded geometry

Theorem - [Boissonant, Dyer, Ghosh]

Let (M, g) be a plane with bounded geometry. Then there exists a triangulation τ of M with its path metric ρ such that τ quasi-isometrically embeds into M .

As (M, g) is a Riemannian plane exhibiting bounded geometry, we get a triangulation (τ, ρ) with bounded degree whose path metric makes it quasi-isometric to (M, g) . Furthermore, as (τ, ρ) is a one-ended graph, we can construct a rotationally symmetric plane (N, h) with its pole at o such that there exists a $p \in V(\tau)$

$V_N(B(o, n)) = |B(p, n)|$ and

$l(\partial B(p, n)) = |w \in V(\tau) : d(w, p) = n|$ for all $n \in \mathbb{N}$. We see that (N, h) is quasi-isometric to (M, g) and that they have the same conformal type.

Statement

Let (M, g) be a simply connected Riemannian 2-manifold with bounded geometry. Then

- If (M, g) is conformally equivalent to S^2 , then quasi-redirecting boundary of (M, g) is empty
- If (M, g) is conformally equivalent to \mathbb{R}^2 with the Euclidean metric, then the quasi-redirecting boundary of (M, g) is a single point.
- If (M, g) is conformally equivalent to \mathbb{H}^2 , then the quasi-redirecting boundary of (M, g) is homeomorphic to S^1 .

When (M, g) is conformally equivalent to \mathbb{R}^2

Proof

As quasi-redirectedness is a quasi-isometry invariant and as compact metric spaces lack quasi-geodesic rays, we can restrict our attention to rotationally symmetric planes (M, g) with its pole at o where $g = dr^2 + f(r)^2 d\theta^2$. Recall that (M, g) is conformally equivalent to \mathbb{R}^2 if and only if $\int_0^\infty \frac{dr}{2\pi f(r)} = \infty$ (from [Grigor'yan]) which in turn implies that $\limsup_{r \rightarrow \infty} \frac{f(r)}{r} < \infty$ which implies that geodesic rays in (M, g) diverge linearly. Therefore, if (M, g) is conformally equivalent to \mathbb{R}^2 , then ∂M has a single point.

When (M, g) is conformally equivalent to \mathbb{H}^2

Proof

Just like the previous slide, we do not lose any generality if we suppose that (M, g) is a rotationally symmetric plane with its pole at p and $g = dr^2 + f(r)^2 d\theta^2$. As (M, g) is conformally equivalent to \mathbb{H}^2 , we get that $\int_0^\infty \frac{dr}{f(r)} < \infty$ (see [Grigor'yan]). From bounded geometry, we get that there exists a superlinear function κ such that $0 < \liminf_{r \rightarrow \infty} \frac{f(r)}{\kappa(r)} < \infty$ so we can make (M, g) to be quasi-isometric (and conformally equivalent) to a Cartan-Hadamard manifold such that $\lim_{r \rightarrow \infty} \frac{l(\partial B(o, r))}{\kappa(r)} \in (0, \infty)$. As geodesic balls in Cartan-Hadamard manifolds are convex, geodesic rays diverge superlinearly and therefore if α, β are two distinct geodesic rays with $\alpha(o) = \beta(o) = o$, then $\alpha \not\sim \beta$ and $\beta \not\sim \alpha$. Therefore, we get that $\partial M = \mathbb{S}^1$.

Martin boundary

Let (M, g) be a complete Riemannian manifold and assume that Brownian motion on it is transient. We recall that this is equivalent to Δ_g admitting a Green's function $G : M \times M \rightarrow (0, \infty)$. Choose $x_0 \in M$ and consider the function $K(\cdot; x) = \frac{G(\cdot; x)}{G(x, x_0)}$ which are harmonic on $M \setminus \{x\}$ and is 1 at x_0 . Consider all sequences $\{x_n\}_{n \in \mathbb{N}}$ with $d(x_0, x_n) \rightarrow \infty$ such that $K(\cdot; x_n)$ also converge to a positive harmonic function and deem two sequences going off to infinity equivalent if their limits coincide. The space of such equivalence classes $\partial_\Delta M$ is called the Martin boundary of (M, g) and the resulting compactification of (M, g) is called the Martin compactification. If Brownian motion is recurrent on (M, g) , then Δ_g does not admit a Green's function and therefore we can deem all sequences going off to infinity to get a one-compactification of (M, g) if non-compact or leaving (M, g) as it is if it is compact.

Martin Boundary and the Quasi-Redirecting Boundary

As positive harmonic functions are preserved under conformal mappings, we can just consider the case when (M, g) is conformally equivalent to \mathbb{H}^2 . As conformal mappings $f : M \rightarrow N$ induce a homeomorphism of their Martin boundaries and quasi-isometries $h : M \rightarrow N$ induce a homeomorphism between quasi-redirecting boundaries, we can once again work with rotationally symmetric planes (M, g) without losing any generality. As geodesic rays do not redirect to each other, we get that quasi-geodesic rays converge to a unique point in the geodesic boundary (i.e. $\lim_{r \rightarrow \infty} \frac{\exp_p^{-1}(\alpha(r))}{d(p, \alpha(r))}$ exists in $UT_p M$) and Theorem 6 of [Ancona] which ensures that geodesic rays diverge to a point in the Martin boundary, we get that the quasi-redirecting boundary is indeed the Martin boundary for rotationally symmetric planes.

Homogenous spaces

We say that a Riemannian n -manifold (M, g) is homogenous if $\text{Isom}(M)$ acts transitively on M . It is clear that every homogenous manifold is quasi-isometric to a Lie group G and from [Cornulier], we see that M has a unique asymptotic cone (denote it as $\text{Con}_\omega(M)$). We further see that $\text{Con}_\omega(M)$ is also a homogenous space and therefore, either every point is a cut-point or none is. If the former holds true, then M is quasi-isometric to a non-compact rank 1 symmetric space with $\partial M = \mathbb{S}^{n-1}$. If the latter holds true then M exhibits linear divergence and therefore ∂M has a single point.

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