

Structure Preserving Discretizations
of Wasserstein Gradient Flows
Part IV of IV: Discretization on a grid

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“A school on gradient flows”
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Where do we need to go today?

Question

Can we discretize a $\mathbb{W}$ -gradient flow in space replacing $\rho \in \mathcal{P}_2(\mathbb{R}^d)$ by

$$\rho^{(h)} = \sum_{x \in \Gamma} \rho_x^{(h)} \delta_x \quad \text{with parameters } \rho_x^{(h)} \in \mathbb{R}_{\geq 0},$$

with a discrete point set $\Gamma \subset \mathbb{R}^d$?

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Answer: Yes. But it's much more complicated than one might think.

One difficulty is how to make sense of $\int h(\rho^{(h)}) \, dx$ etc.
But there is an even more fundamental one.

Here's a no-go example by Filippo.

No-go example (1/3)

Consider the following **linear transport** equation in 1D:

$$\partial_t \rho = \partial_x (x \rho) \quad \text{is the } \mathbb{W}\text{-gradient flow for } \mathbf{E}(\rho) = \int_{\mathbb{R}} \frac{x^2}{2} \rho \, dx.$$

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The initial value problem with $\rho_0 = \delta_{\bar{x}}$ has the **explicit solution**

$$\rho_t = \delta_{x_t} \quad \text{with} \quad x_t = e^{-t} \bar{x}.$$

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The **JKO approximation**

$$\rho_{\tau}^n = \operatorname{argmin}_{\rho} \left(\frac{1}{2\tau} \mathbb{W}(\rho, \rho_{\tau}^{n-1})^2 + \mathbf{E}(\rho) \right)$$

produces the iterates $\rho_{\tau}^n = \delta_{x_{\tau}^n}$ with

$$x_{\tau}^n = \operatorname{argmin}_{x \in \mathbb{R}} \left(\frac{(x - x_{\tau}^{n-1})^2}{2\tau} + \frac{x^2}{2} \right),$$

that is $x_{\tau}^n = (1 + \tau)^{-n} \bar{x}$ — which yields a **fairly good approximation**.

No-go example (2/3)

Let's try with $\rho^{(h)} = \sum_{x \in \Gamma} \rho_x^{(h)} \delta_x$ with $\Gamma \subset \mathbb{R}$ such that $\bar{x} \in \Gamma$ and

$$h := \inf \{ |x - x'| \mid x, x' \in \Gamma, x \neq x' \} > 0.$$

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The first JKO step functional

$$\frac{1}{2\tau} \mathbb{W}(\rho^{(h)}, \delta_{\bar{x}})^2 + \mathbf{E}(\rho^{(h)}) = \sum_{x \in \Gamma} \left(\frac{(x - \bar{x})^2}{2\tau} + \frac{x^2}{2} \right) \rho_x^{(h)}$$

is minimized by δ_{x^*} where

$$x^* = \operatorname{argmin}_{x \in \Gamma} \left(\frac{(x - \bar{x})^2}{2\tau} + \frac{x^2}{2} \right).$$

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$$x^* = \operatorname{argmin}_{x \in \Gamma} \left(\frac{(x - \bar{x})^2}{2\tau} + \frac{x^2}{2} \right).$$

If $\tau > 0$ is so small that $2\tau\bar{x} < (1 + \tau)h$, then $x^* = \bar{x}$.

The evolution is **frustrated**.

Still, good news:

Theorem ([Hraivoronska&Santambrogio'25])

*Under the **inverse CFL condition** $h/\tau \rightarrow 0$,
this **discretization converges** as $h, \tau \rightarrow 0$.
It even works with (very) nonlinear diffusion.*

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It even works with (very) nonlinear diffusion.*

In any case: The scheme is **no good** for semi-discretization **in space only**.

So that's the end for today? Goodbye!

Fortunately, there is a workaround
by Alex (and several others).

Explained in two-point space (1/3)

Consider the problem on a **two-point space** $\Gamma = \{0, h\}$.

Parametrize $\rho^{(h)} \in \mathcal{P}_2(\Gamma)$ by $r \in [0, 1]$ via

$$\rho^{(h)} = \mu[r] = r\delta_h + (1-r)\delta_0, \quad \text{thus} \quad \mathbf{E}(\mu[r]) = \frac{h^2}{2}r.$$

Then

$$\mathbb{W}(\mu[\hat{r}], \mu[\check{r}])^2 = h^2|\hat{r} - \check{r}|,$$

which is

- **quadratic** in the **fixed** distance h ,
- **one-homogeneous** in the parameters $\hat{r}$ and $\check{r}$.

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- **quadratic** in the **fixed** distance h ,
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The respective JKO step looks strange:

$$\frac{\mathbb{W}(\mu[r], \mu[r_\tau^{n-1}])^2}{2\tau} + \mathbf{E}(\mu[r]) = \frac{h^2}{2\tau}|r_\tau^{n-1} - r| + \frac{h^2}{2}r \rightarrow \min.$$

Its minimizer is either $r = 0$ (for $\tau > 1$) or $r = r_\tau^{n-1}$ (for $\tau < 1$).

Explained in two-point space (2/3)

Replace $\mathbb{W}^2$ by another “inertia” $\mathbf{d}^2$ that is **nonlinear** w.r.t. $\hat{r}$, $\check{r}$.

Example: Try with **relative entropy**

$$\mathbf{d}(\mu[\hat{r}], \mu[\check{r}])^2 = h^2 \hat{r} \psi\left(\frac{\check{r}}{\hat{r}}\right), \quad \psi(z) = z \log z - z + 1.$$

The respective JKO step reads

$$\frac{\mathbf{d}(\mu[r], \mu[r_\tau^{n-1}])^2}{2\tau} + \mathbf{E}(\mu[r]) \cong \frac{h^2}{2\tau} (r - r_\tau^{n-1} \log r) + \frac{h^2}{2} r \rightarrow \min,$$

which leads to the iteration

$$\frac{r_\tau^n - r_\tau^{n-1}}{\tau} = -r_\tau^n$$

and thus $r_\tau^n = (1 + \tau)^{-n} r_\tau^0$,

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which leads to the iteration

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and thus $r_\tau^n = (1 + \tau)^{-n} r_\tau^0$, which yields a **fairly good approximation**, and has limit $r(t) = e^{-t} r(0)$ for $\tau \rightarrow 0$.

Lemma

The JKO iterates (ρ_τ^n) satisfy

$$\begin{aligned} E(\rho_\tau^n) &\leq (1 + \tau)^{-1} E(\rho_\tau^{n-1}), \\ \mathbf{d}(\rho_\tau^n, \rho_\infty)^2 &\leq (1 + \tau)^{-1} \mathbf{d}(\rho_\tau^{n-1}, \rho_\infty)^2. \end{aligned}$$

Moreover, the semi-discrete evolution is **contractive** in the sense that for two JKO approximations $(\hat{r}_\tau^n)$ and $(\check{r}_\tau^n)$:

$$\mathbf{d}(\hat{r}_\tau^n, \check{r}_\tau^n)^2 \leq (1 + \tau)^{-1} \mathbf{d}(\hat{r}_\tau^{n-1}, \check{r}_\tau^{n-1})^2.$$

Proof: Homogeneity $\mathbf{d}(ca, cb)^2 = c \mathbf{d}(a, b)^2$ for all $a, b \in [0, 1]$ and $c > 0$.

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Proof: Homogeneity $\mathbf{d}(ca, cb)^2 = c \mathbf{d}(a, b)^2$ for all $a, b \in [0, 1]$ and $c > 0$.

New angle of attack:

discrete energy + discrete metric $\implies$ contractive discrete PDE,

is replaced by

discrete energy + discrete PDE $\implies$ discrete metric with contractivity.

ODE analogy on contractivity (1/3)

General: on manifold $\mathcal{M}$ with metric tensor $\langle \cdot, \cdot \rangle_x$ at each $x \in \mathcal{M}$, define the **cotangent-to-tangent map** $\mathbb{K}_x : T_x^* \mathcal{M} \rightarrow T_x \mathcal{M}$ by

$$\langle v, \mathbb{K}_x \xi \rangle_x = \xi[v] \quad \text{for all } v \in T_x \mathcal{M}, \xi \in T_x^* \mathcal{M}.$$

The **gradient flow** of $e : \mathcal{M} \rightarrow \mathbb{R}$ is

$$\dot{x} \cong -\mathbb{K}_x D_x e.$$

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Specifically: on $\mathcal{M} = \mathbb{R}^n$, define **metric tensor** by

$$\langle v, w \rangle_x = v^T \mathbb{G}_x w$$

with an x -dependent symmetric positive definite matrix $x \mapsto \mathbb{G}_x \in \mathbb{R}^{n \times n}$. Then

$$\mathbb{K}_x \cong \mathbb{G}_x^{-1}.$$

ODE analogy on contractivity (2/3)

Consider a family $(\gamma^t)_{t \geq 0}$ of **curves** $(\gamma_s^t)_{s \in [0,1]}$ that “follow a **vector field**” $F : \mathcal{M} \rightarrow T\mathcal{M}$ e.g. $F = -\mathbb{K}De$,

$$\partial_t \gamma_s^t = F(\gamma_s^t).$$

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The **kinetic energy** of $(\gamma_s^t)_{s \in [0,1]}$

$$a(\gamma^t) = \int_0^1 (\partial_s \gamma)^T \mathbb{G}_\gamma (\partial_s \gamma) \, \mathrm{d}s$$

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The **kinetic energy** of $(\gamma_s^t)_{s \in [0,1]}$ evolves as follows:

$$\begin{aligned} \frac{\mathrm{d}}{\mathrm{d}t} a(\gamma^t) &= \frac{\mathrm{d}}{\mathrm{d}t} \int_0^1 (\partial_s \gamma)^T \mathbb{G}_\gamma (\partial_s \gamma) \, \mathrm{d}s \\ &= -2 \int_0^1 (\partial_s \gamma)^T \mathbb{G}_\gamma M_\gamma \mathbb{G}_\gamma (\partial_s \gamma) \, \mathrm{d}s, \end{aligned}$$

with

$$M_x = -\mathrm{D}_x F[\mathbb{K}_x(\cdot)] + \frac{1}{2} \mathrm{D}_x \mathbb{K}[F].$$

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Consider a family $(\gamma^t)_{t \geq 0}$ of **curves** $(\gamma_s^t)_{s \in [0,1]}$ that “follow a **vector field**” $F : \mathcal{M} \rightarrow \mathbf{TM}$ e.g. $F = -\mathbb{K}De$,

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with

$$M_x = -D_x F[\mathbb{K}_x(\cdot)] + \frac{1}{2} D_x \mathbb{K}[F].$$

Lemma

If $M_x \geq \lambda \mathbb{K}_x$ with some λ for all $x \in \mathcal{M}$, then F is **λ -contractive**:

$$a(\gamma^t) \leq e^{-2\lambda t} a(\gamma^0).$$

ODE analogy on contractivity (3/3)

$$M_x = -D_x F[\mathbb{K}_x(\cdot)] + \frac{1}{2} D_x \mathbb{K}[F] \geq \lambda \mathbb{K}_x$$

looks ugly, but is **just an inequality between matrices**.

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Fundamental idea behind Eulerian calculus

If $F = -\mathbb{K}De$ is a **gradient vector field**,
then $M \geq \lambda \mathbb{K}$ implies that e is **λ -geodesically convex**
(and subsequently exponential control of energy, dissipation, speed, ...).

Proof: With some painful algebra,

$$-\frac{d}{dt}(D_x e^T \mathbb{K}_x D_x e) = 2D_x e^T M_x D_x e \geq 2\lambda(D_x e^T \mathbb{K}_x D_x e).$$

From here, everything else follows by Taylor expansion and integration along trajectories.

Are we still doing anything discrete today?

This is applicable to Fokker-Planck.

Factoring the heat equation (1/2)

Our plan:

- ① You're good at dualities? Pretend for the moment you're not!
- ② Forget how $\mathbb{W}$ -gradient flows had been defined.
- ③ Try to guess $\mathbb{K}$ from the linear Fokker-Planck equation.
- ④ Show that the flow is 1-contractive.
- ⑤ Then repeat, but discretely.

Factoring the heat equation (2/2)

To write the **heat equation** on $\mathbb{R}$,

$$\partial_t \rho = \partial_{xx} \rho$$

in the form $\partial_t \rho = -\mathbb{K}_\rho \mathbf{D}_\rho \mathbf{H}$ with the **entropy**

$$\mathbf{H}(\rho) = \int \rho \log \rho \, dx \quad .$$

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we choose the (symmetric, positive, ...) **cotangent-to-tangent map**

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we choose the (symmetric, positive, ...) **cotangent-to-tangent map**

$$\mathbb{K}_\rho \xi = -\partial_x (\rho \partial_x \xi).$$

Lemma

The flow is **0-contractive**, i.e.,

$$0 \leq \int_{\mathbb{R}} \xi M_\rho \xi \, dx = \int_{\mathbb{R}} \xi \left(-\partial_{xx} (\mathbb{K}_\rho \xi) + \frac{1}{2} \mathbf{D}_\rho \mathbb{K}[\partial_{xx} \rho] \xi \right) dx.$$

Some discretion, please!

- $h\mathbb{Z} = \{\dots, -h, 0, h, 2h, \dots\}$ is the one-dimensional **uniform grid** with mesh width $h > 0$
- $h\mathbb{Z}^* = \{\dots, -\frac{1}{2}h, \frac{1}{2}h, \frac{3}{2}h, \dots\}$ is the **dual grid**
- for a function $u : h\mathbb{Z} \rightarrow \mathbb{R}$, define its **gradient** $\nabla^{(h)}u : h\mathbb{Z}^* \rightarrow \mathbb{R}$ by

$$\nabla_y^{(h)}u = \frac{u_{y+h/2} - u_{y-h/2}}{h}.$$

- for a flux $J : h\mathbb{Z}^* \rightarrow \mathbb{R}$, define its **divergence** $\nabla^{(h)*}\omega : h\mathbb{Z} \rightarrow \mathbb{R}$ by

$$\nabla_x^{(h)*}\omega = \frac{\omega_{x+h/2} - \omega_{x-h/2}}{h}.$$

- the Laplace operator $\Delta^{(h)}$ is

$$\Delta_x^{(h)}u = \nabla_x^{(h)*}(\nabla_u^{(h)}) = \frac{u_{x+h} - 2u_x + u_{x-h}}{h^2}.$$

A complicated writing of the discrete heat equation (1/2)

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$$\dot{\rho}^{(h)} = \Delta^{(h)} \rho^{(h)}.$$

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We want to write $\dot{\rho}^{(h)} = -\mathbb{K}_{\rho}^{(h)} \mathbf{D}_{\rho} \mathbf{H}^{(h)}$ with the discretized entropy

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Write

$$\Delta^{(h)} \rho^{(h)} = \nabla^{(h)*} \nabla^{(h)} \rho^{(h)} = \nabla^{(h)*} \left(\frac{\nabla^{(h)} \rho}{\nabla^{(h)} \log \rho^{(h)}} \nabla^{(h)} \log \rho^{(h)} \right).$$

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Thus we have the desired form for the (symmetric, positive, ...) operator

$$\mathbb{K}_\rho^{(h)} \xi = -\nabla^{(h)*} (\Lambda(\rho^{(h)}) \nabla^{(h)} \xi) \quad \text{w/} \quad \Lambda_y(\rho^{(h)}) = \frac{\rho_{y+h/2}^{(h)} - \rho_{y-h/2}^{(h)}}{\log \rho_{y+h/2}^{(h)} - \log \rho_{y-h/2}^{(h)}}.$$

A complicated writing of the discrete heat equation (2/2)

Remarkably, this weird choice is a good one.

Theorem ([Maas'11, Mielke'13])

The discrete heat equation is 0-contractive, i.e., $M \geq 0$.

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Theorem ([Maas'11, Mielke'13])

The discrete heat equation is 0-contractive, i.e., $M \geq 0$.

Proof: mainly uses two ingredients:

- M_ρ is a tridiagonal matrix with nice algebraic properties, and
- Λ has a lot of nice algebraic properties.

Now what for linear Fokker-Planck? (1/3)

Return to continuous. For V such that $V'' \geq \lambda > 0$ and $\rho_\infty := e^{-V} \in \mathcal{P}_2(\mathbb{R})$, consider the relative entropy

$$H_V(\rho) = \int \rho \log \rho \, dx + \int \rho V \, dx \quad .$$

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Return to continuous. For V such that $V'' \geq \lambda > 0$ and $\rho_\infty := e^{-V} \in \mathcal{P}_2(\mathbb{R})$, consider the relative entropy

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Lemma

The flow is λ -contractive.

Now what for linear Fokker-Planck? (2/3)

Choose a discrete steady state $\rho_{\infty}^{(h)} \in \mathcal{P}_2(h\mathbb{Z})$ by

$$\rho_{\infty,x}^{(h)} = \int_{x-h/2}^{x+h/2} \rho_{\infty}(x') \, dx'$$

and accordingly

$$\mathbf{H}_V^{(h)}(\rho^{(h)}) = h \sum_x \rho^{(h)} \log \frac{\rho^{(h)}}{\rho_{\infty}^{(h)}} \quad \text{with} \quad D_{\rho} \mathbf{H}_V^{(h)} \cong 1 + \log \frac{\rho^{(h)}}{\rho_{\infty}^{(h)}}.$$

Further, introduce a balanced inhomogeneity:

$$\mathbb{K}_{\rho}^{(h)} \xi = \nabla^{(h)*} \left[\omega \Lambda \left(\frac{\rho^{(h)}}{\rho_{\infty}^{(h)}} \right) \nabla^{(h)} \xi \right] \quad \text{w/} \quad \omega_y = \sqrt{\rho_{\infty,y+h/2}^{(h)} \rho_{\infty,y-h/2}^{(h)}}.$$

Then the gradient flow is:

$$\dot{\rho}_x^{(h)} = \nabla_x^{(h)*} \left(\omega \nabla^{(h)} \left[\frac{\rho}{\rho_{\infty}} \right] \right).$$

Now what for linear Fokker-Planck? (3/3)

Theorem ([Mielke'13])

If $V'' \geq \lambda > 0$, then there is some $\lambda_h \xrightarrow{h \searrow 0} \lambda$ s.t.

- $\rho_\infty^{(h)}$ is the *unique minimizer* of $\mathbf{H}_V^{(h)}$
- the entropy *decays exponentially*:

$$\mathbf{H}_V^{(h)}(\rho_t^{(h)}) - \mathbf{H}_V^{(h)}(\rho_\infty^{(h)}) \leq e^{-2\lambda_h t} (\mathbf{H}_V^{(h)}(\rho_0^{(h)}) - \mathbf{H}_V^{(h)}(\rho_\infty^{(h)})),$$

and so do velocity, dissipation, and distance to equilibrium.

- the flow is *λ_h -contractive*:

$$\mathbb{W}_V^{(h)}(\rho_{\hat{h}t}, \rho_{\check{h}t})^2 \leq e^{-2\lambda_h t} \mathbb{W}_V^{(h)}(\rho_{\hat{h}0}, \rho_{\check{h}0})^2.$$

What next? Same for NONlinear Fokker-Planck?

Try same idea for quadratic porous medium equation

$$\partial_t \rho = \Delta \rho^2,$$

which is the $\mathbb{W}$ -gradient flow of

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Discretizing this as

$$\dot{\rho}^{(h)} = \Delta(\rho^{(h)})^2 \quad \text{and} \quad \mathbf{H}^{(h)}(\rho^{(h)}) = h \sum_x (\rho^{(h)})^2$$

and consequently

$$\mathbb{K}_x^{(h)}[\xi] = \nabla^{(h)*} \left(A(\rho^{(h)}) \nabla^{(h)} \xi \right) \quad \text{w/} \quad A_y(\rho^{(h)}) = \frac{\rho_{y+h/2}^{(h)} + \rho_{y-h/2}^{(h)}}{2}.$$

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Theorem ([Erbar&Maas'12])

*This discretization has **no convexity at all**.*

And ... what about DLSS?

Residual convexity survives!

Yes, you have seen this before

Recall: the rescaled DLSS equation

$$\partial_t \rho = -2\partial_x \left(\rho \partial_x \frac{\partial_{xx} \sqrt{\rho}}{\sqrt{\rho}} \right) + \partial_x (x \rho)$$

is the $\mathbb{W}$ -gradient flow of the relative Fisher information

$$\mathbf{F}'(\rho) = 2 \int_{\mathbb{R}} (\partial_x \sqrt{\rho})^2 dx + \int_{\mathbb{R}} \frac{x^2}{2} \rho dx,$$

which is **totally not** displacement convex, but still,

Theorem

$$\begin{aligned} \mathbf{H}'(\rho_t) - \mathbf{H}'(\rho_\infty) &\leq e^{-2t} (\mathbf{H}'(\rho_0) - \mathbf{H}'(\rho_\infty)), \\ \mathbf{F}'(\rho_t) - \mathbf{F}'(\rho_\infty) &\leq e^{-2t} (\mathbf{F}'(\rho_0) - \mathbf{F}'(\rho_\infty)). \end{aligned}$$

Key: $\mathbf{F}'(\rho) + 1 = \frac{1}{2} |\partial \mathbf{H}'(\rho)|^2$ with 1-displacement convex entropy

$$\mathbf{H}'(\rho) = \int_{\mathbb{R}} \rho \log \rho dx + \int_{\mathbb{R}} \frac{x^2}{2} \rho dx.$$

Recycling is a great thing

With the Alex-style discretizations

$$\dot{\rho}^{(h)} = \nabla^{(h)*} \left(\omega \nabla^{(h)} \left[\frac{\rho^{(h)}}{\rho_{\infty}^{(h)}} \right] \right) \quad \& \quad \mathbf{H}^{(h)'} = h \sum_{x \in \delta\mathbb{Z}} \rho_x^{(h)} \log \left(\frac{\rho_x^{(h)}}{\rho_{\infty, x}^{(h)}} \right),$$

introduce a discretized relative Fisher information by

$$\mathbf{F}^{(h)'} = -\frac{1}{2} \frac{d}{dt} \mathbf{H}^{(h)'} = h \sum_{y \in (h\mathbb{Z})^*} \omega_y \nabla_y^{(h)} \log \left(\frac{\rho^{(h)}}{\rho_{\infty}^{(h)}} \right) \nabla_y^{(h)} \left(\frac{\rho^{(h)}}{\rho_{\infty}^{(h)}} \right).$$

The gradient flow of $\mathbf{F}^{(h)'}$ with respect to $\mathbb{K}$ looks horrible, but:

Theorem ([Maas+M'16])

There is some $\lambda_h \xrightarrow{h \searrow 0} 1$ s.t.

$$\mathbf{H}^{(h)'}(\rho_t^{(h)}) - \mathbf{H}^{(h)'}(\rho_{\infty}^{(h)}) \leq e^{-2\lambda_h t} (\mathbf{H}^{(h)'}(\rho_0) - \mathbf{H}^{(h)'}(\rho_{\infty}^{(h)})),$$

$$\mathbf{F}^{(h)'}(\rho_t^{(h)}) - \mathbf{F}^{(h)'}(\rho_{\infty}^{(h)}) \leq e^{-2\lambda_h t} (\mathbf{F}^{(h)'}(\rho_0) - \mathbf{F}^{(h)'}(\rho_{\infty}^{(h)})).$$

That's all for this course

Thank you for following!