



# Games, Networks and Self-Organization

Explaining the collective transition to social cooperation

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in collaboration with

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Shakti N Menon

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Interacting  
Epidemics &  
Games

Games on Graphs:  
Coevolution of  
cooperation &  
communities

Games  
@ Complex Systems  
Group in IMSc

Minority Games &  
Information

Solution concepts  
Co-action vs Nash

V Sasidevan, A Kushal

V Sasidevan

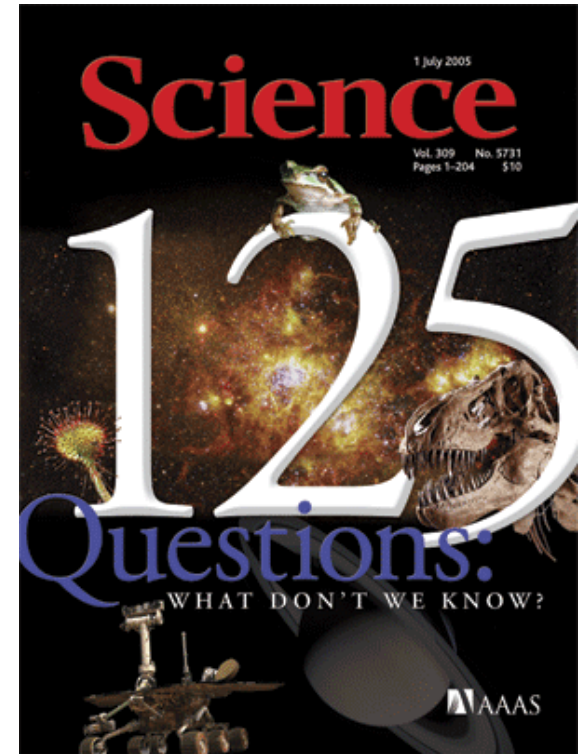
# Why cooperate ?

Elizabeth Pennisi (2005):

“When Charles Darwin was working out his grand theory on the origin of species, he was perplexed by the fact that animals from ants to people form social groups in which most individuals work for the common good. This seemed to run counter to his proposal that individual fitness was key to surviving over the long term”

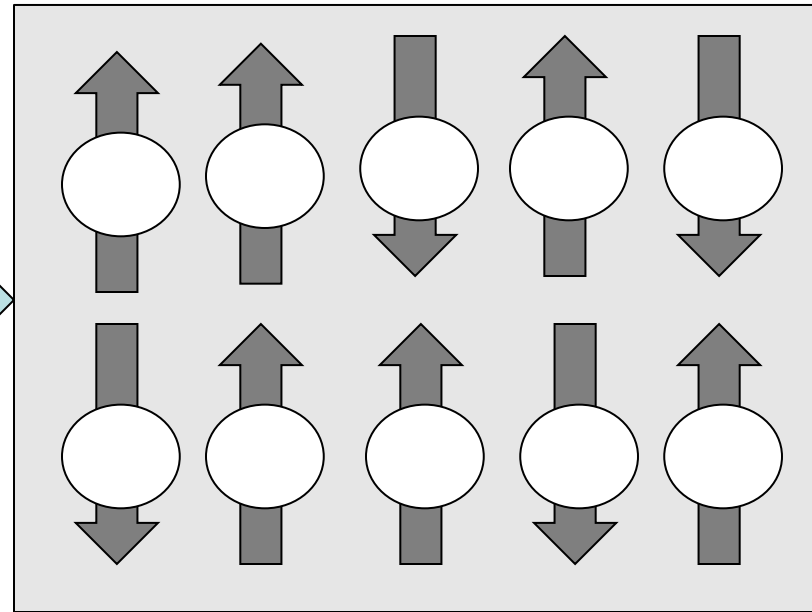
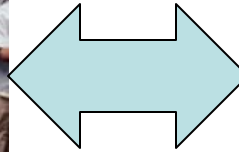
J B S Haldane: “I will jump into the river to save two brothers or eight cousins” (precursor to Hamilton’s Rule)

Natural selection may encourage altruistic behavior among kin as it improves the reproductive potential of the genetically related group as a whole, but unclear why unrelated individuals should help each other.



July 2005

# From the perspective of physicists...



# Emergence

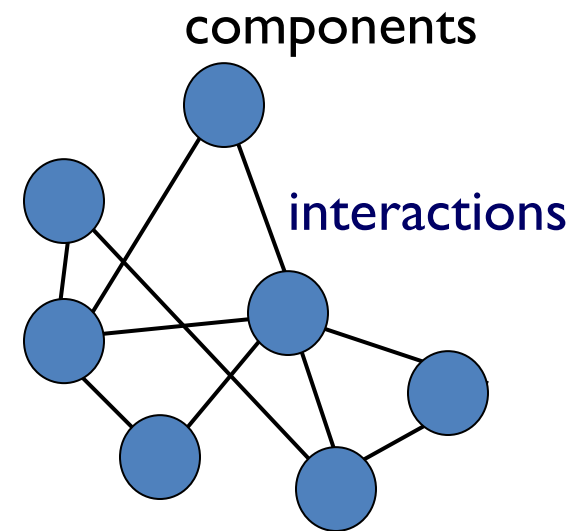
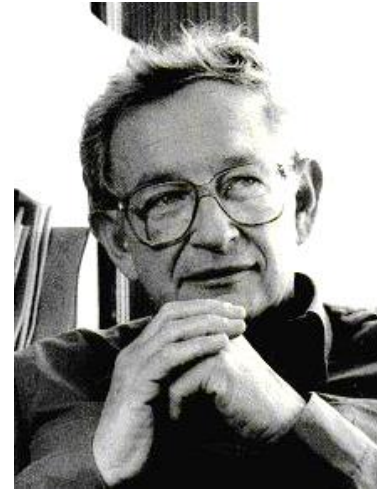
## “More is different”

A complex system comprising

- **many interacting components**, and
- connected with each other in a **network**

→ results in **emergence** at the level of the system,  
of collective behavior **qualitatively different**  
from that of the **individual components**.

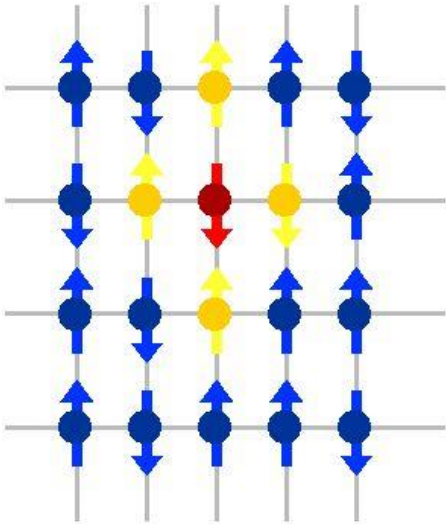
E.g., component = sensible individuals  
system = mob  
emergent behavior = riot



### The Question:

how interactions between ‘selfish’ (rational) agents →  
unexpected systems-level coordination (‘cooperation’)

# Spin models as a paradigm for Complex Systems



- **Spin orientation**: mutually exclusive choices
- **Choice dynamics**: decision based on information about choice of majority in local neighborhood

Simplest case: 2 possible choices

Ising model with Ferromagnetic interactions: each agent can be in one of 2 states (Yes/No , +/-)

# The 2-dimensional Ising model (1944)

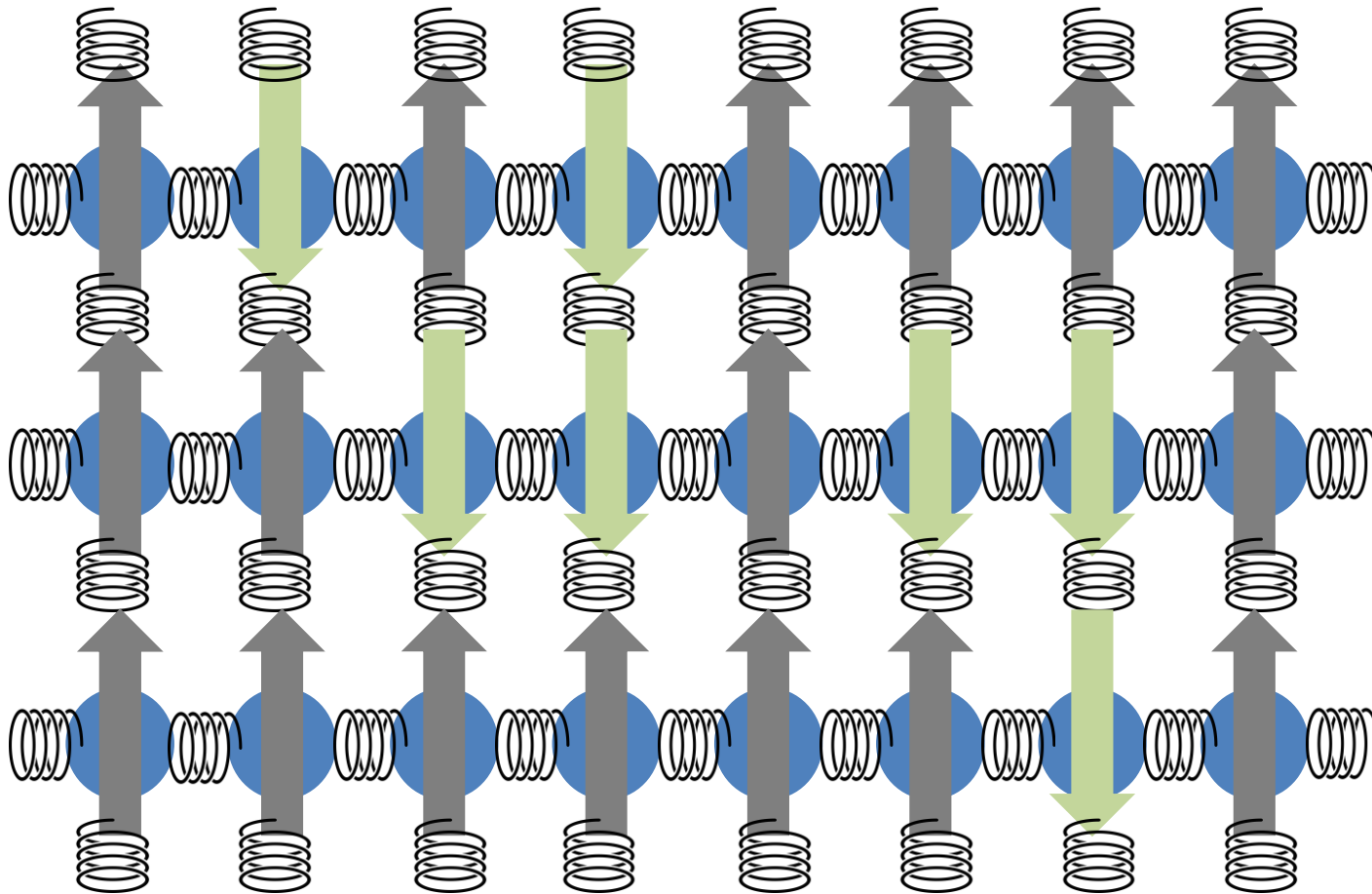
Emergence: transition to self-organized coordination

The system spontaneously orders at  $T < T_c$

Image: wikipedia



Lars Onsager

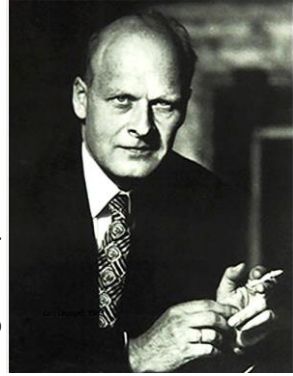


# The 2-dimensional Ising model (1944)

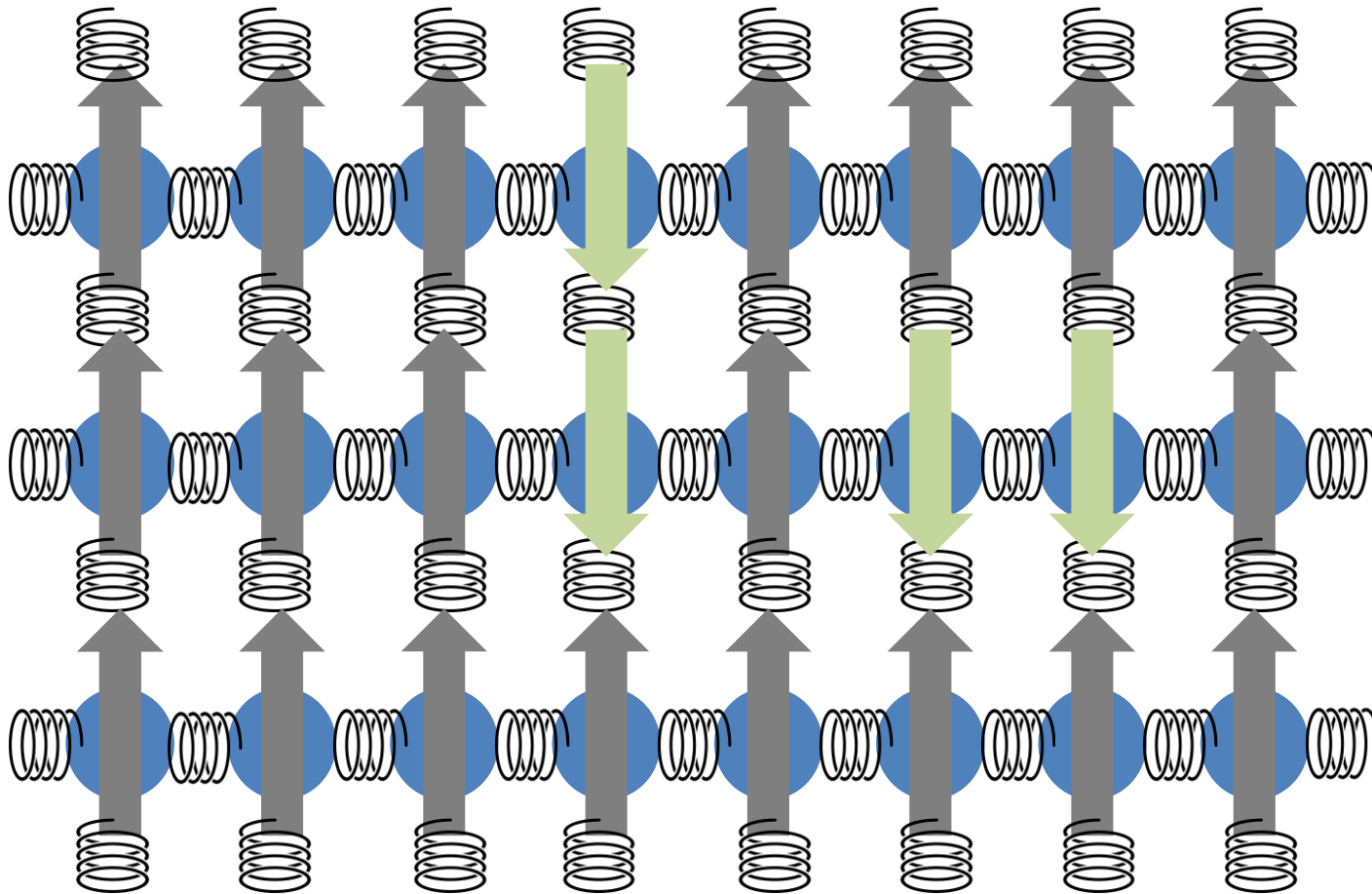
Emergence: transition to self-organized coordination

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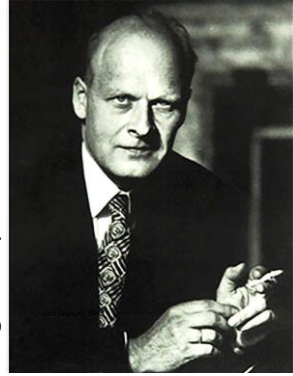


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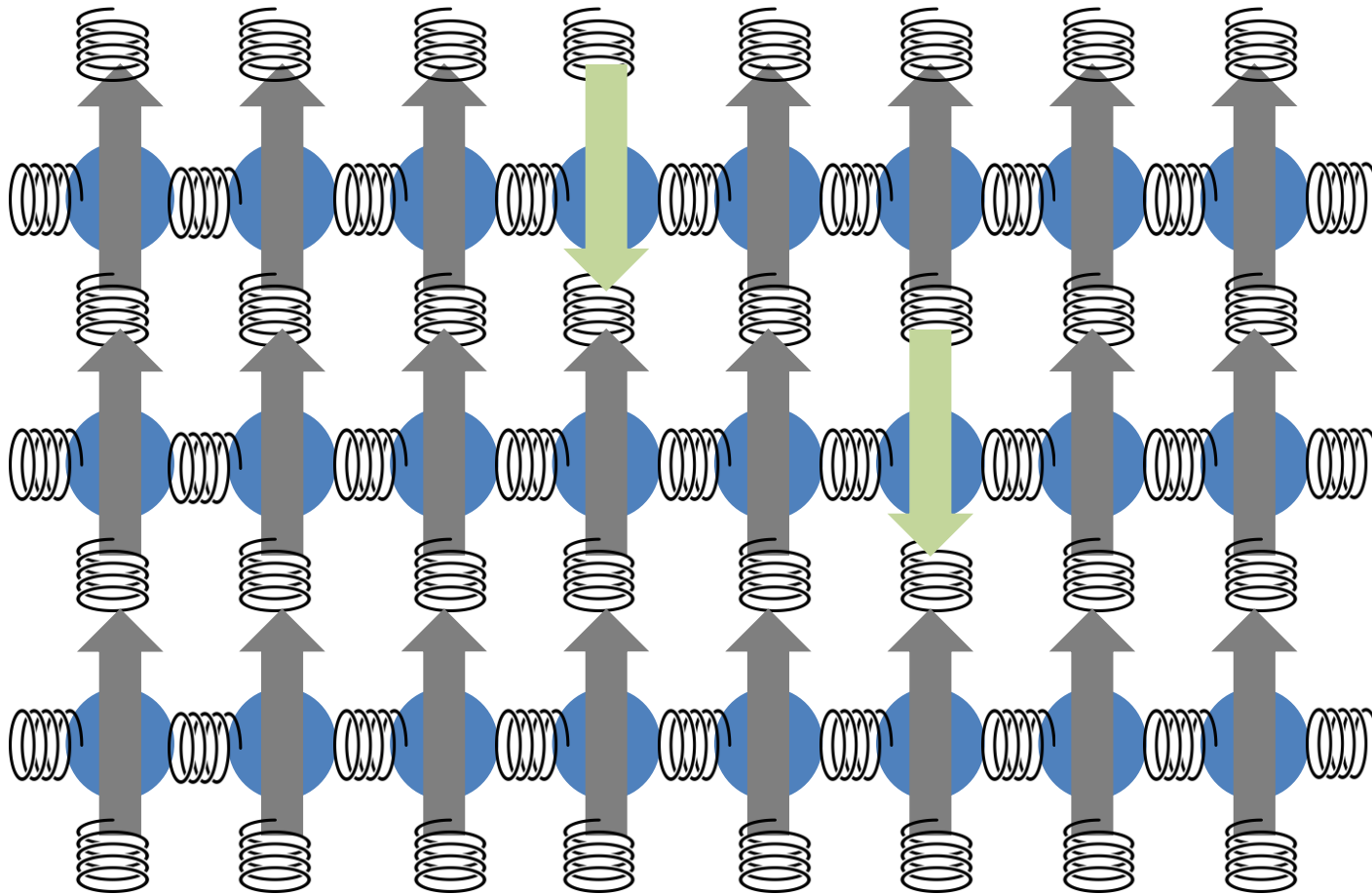
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Image: wikipedia



Lars Onsager



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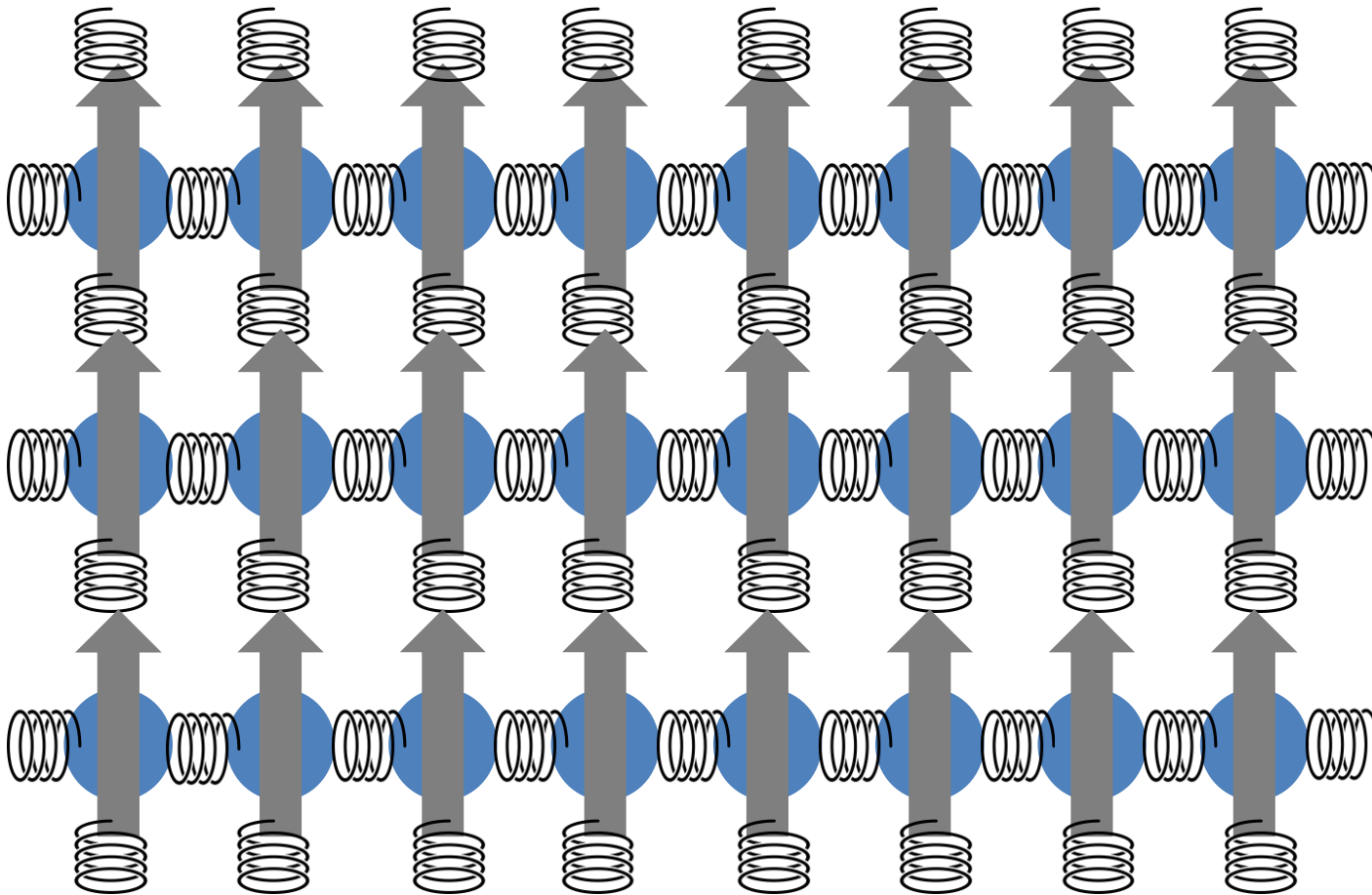
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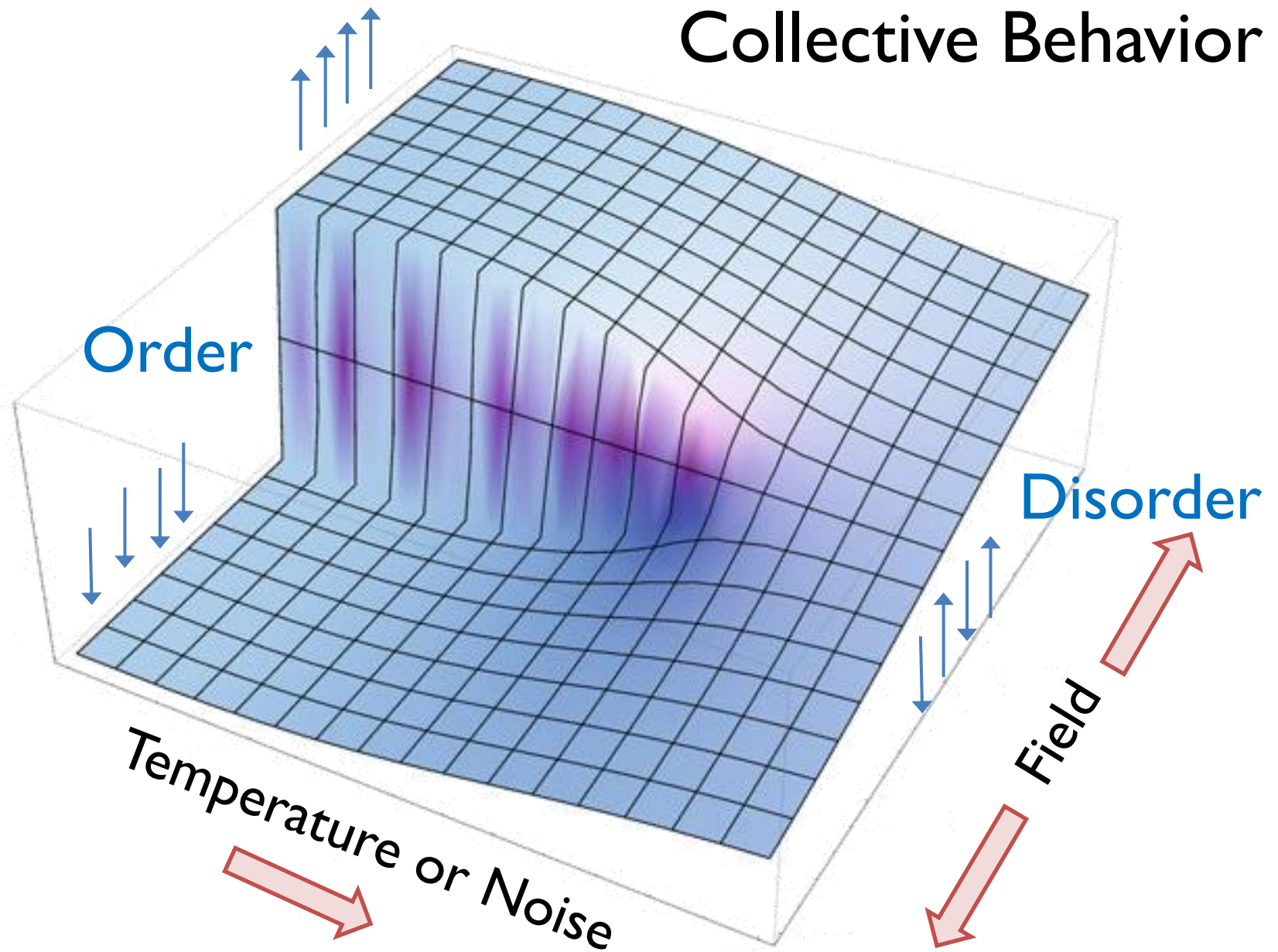
Image: wikipedia



Lars Onsager



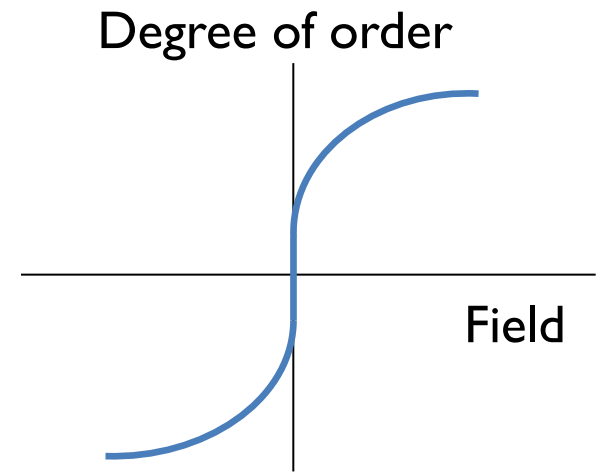
# Collective Behavior



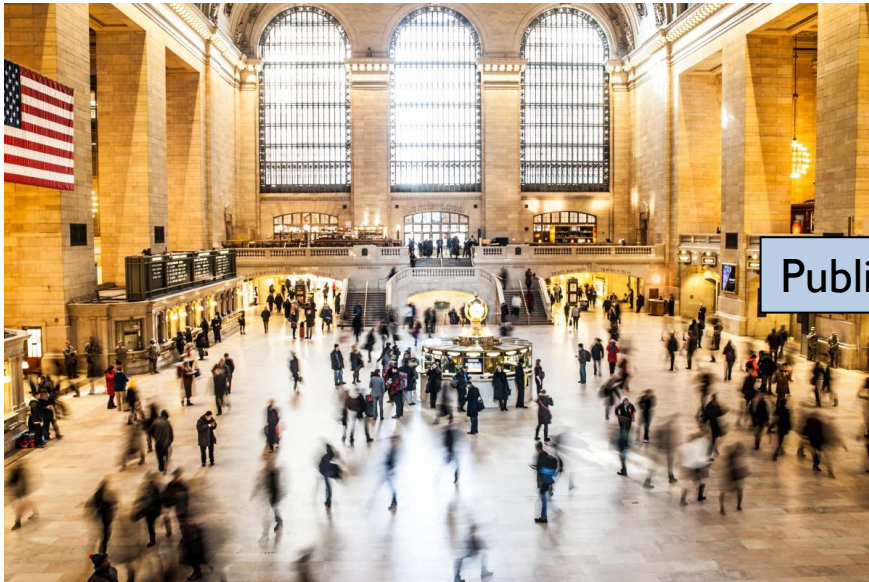
# Emergence of Order-disorder transition

“Field” induced transition from

“Disorder”



“Order”



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Public announcement



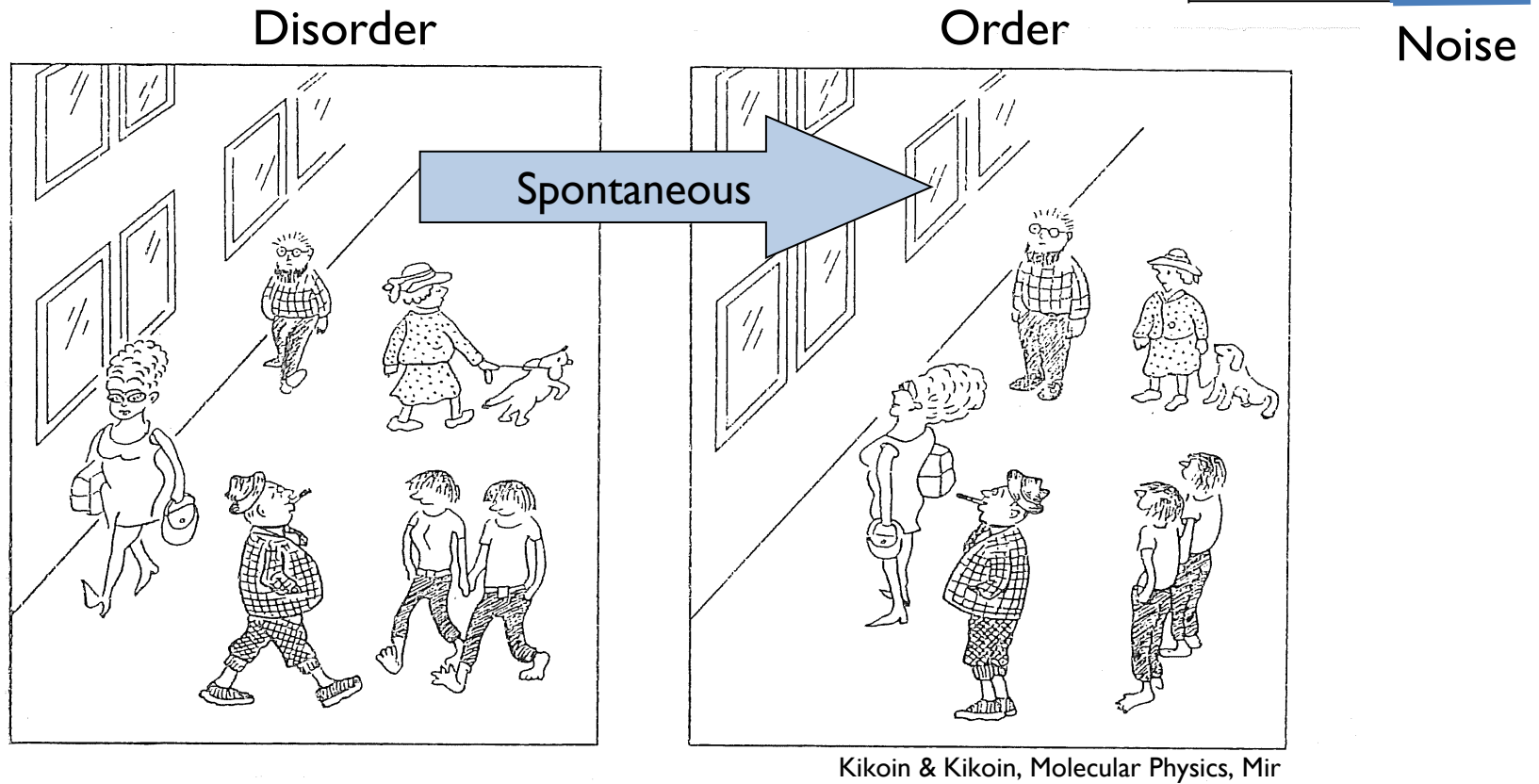
Jake Wyman/Corbis

## Discontinuous or First-order phase transition



# Emergence of Cooperative phenomenon

Self-organized transition from

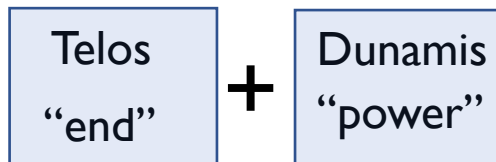


Continuous phase transition

**But...** Agents are not particles!  
Not simply responding inertly to external forces!

Future goals are the driving force for behavior

## Teleodynamics



Agents are necessarily “forward-looking”,  
⇒ current actions are influenced by  
perception of future events.

perception may of course be influenced by  
what has happened in the past ...  
but also by biases and prejudices of the  
individual actors



# From spins to games

“I think that I will pick A”

But “she thinks that I think that I will pick A”

But “she thinks that I think that she thinks that I think that I will pick A”

And so on...



An infinite regress of *theories of mind* two opponents  
use to guess the action that the other will choose

How to choose course of action ?

# Should rational<sup>(\*)</sup> agents cooperate ?

<sup>(\*)</sup> agents are non-altruistic, only interested in maximizing their own benefit



# Should rational<sup>(\*)</sup> agents cooperate ?

## Enter.... Game Theory

- ❑ **Games**: Strategic interactions between agents
- ❑ **Agents**: Variety of entities, ranging from human beings/ animals/ cells to organizations and nations, or even, computer programs.
- ❑ Each agent receives a **payoff** depending upon the strategy choice made by all agents including herself
- ❑ Agents aim to **maximize their payoff** by choosing optimal **strategies**, taking into account that other agents will also be doing the same

<sup>(\*)</sup> agents are non-altruistic, only interested in maximizing their own benefit

# 2-person symmetric single-stage games

Each agent (A and B) has two possible strategies (Actions 1 and 2)

Each agent receives a payoff corresponding to the pair of choices made by them:

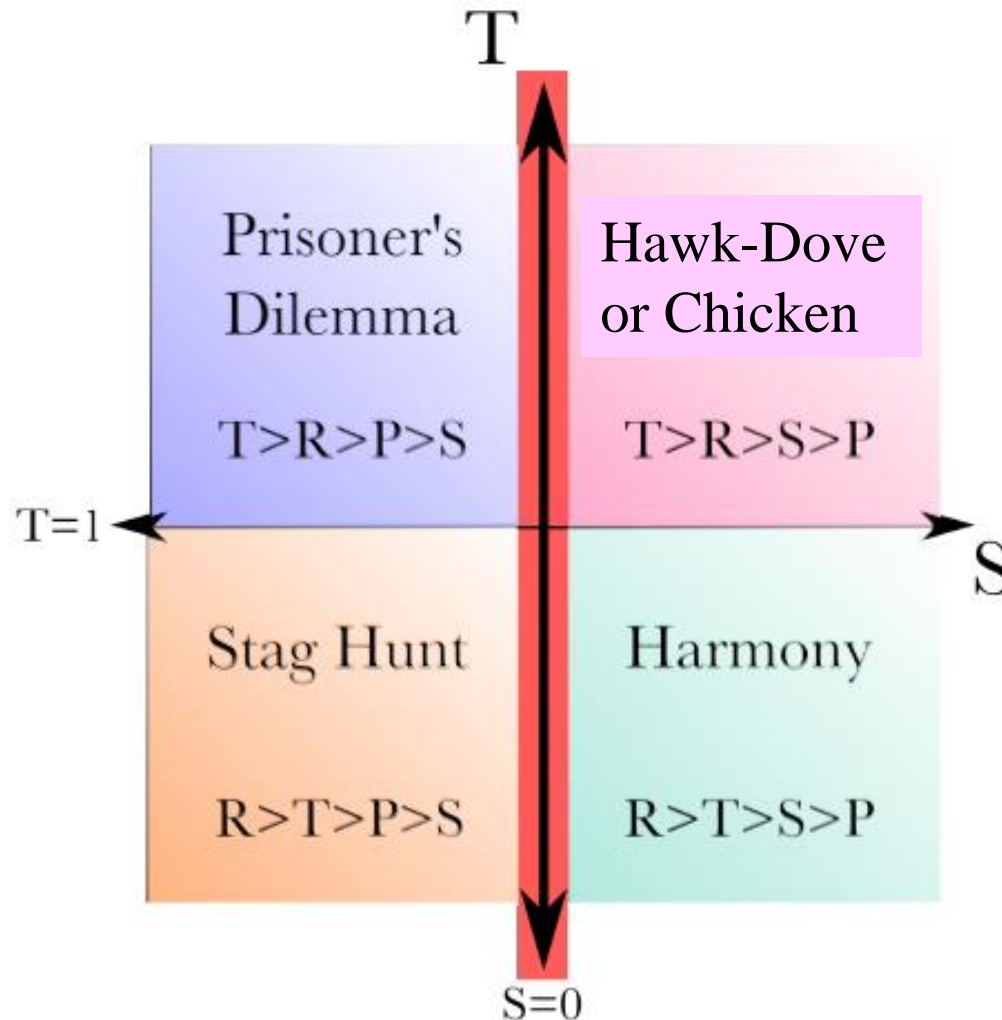
		Agent B	
		Action 1	Action 2
Agent A	Action 1	(R,R)	(S,T)
	Action 2	(T,S)	(P,P)

An agent may employ a **mixed strategy**, in which she **randomly** selects her options, choosing **Action 1** with some **probability  $p$**  and **Action 2** with **probability  $(1 - p)$** .

A **pure strategy** corresponds to  $p=0$  or  $p=1$

# Varying the relative ordering of the payoffs yields different 2-person symmetric games

Two of the payoffs  $P$  and  $R$  can be fixed w/o loss of generality to set origin and scale of the payoff values

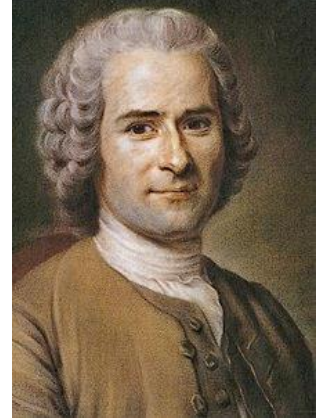








# Example: Stag-Hunt

$$R > T \geq P > S$$

Jean-Jacques Rousseau (1755)

Describes social situations where cooperation required to achieve best possible outcome



$S_i$			
		COOPERATE	DEFECT
	COOPERATE		
	DEFECT		

Evolutionary Games Infographics Project

Strategy defined by probability  $p$  of Action 1 [probability of Action 2 is  $(1-p)$ ]

Strategic interaction between 2 agents choosing

- ❑ Action 1: a high-risk strategy having potentially large reward, viz., hunting for stag
- ❑ Action 2: a relatively low-risk, but poor-yield, strategy, viz., hunting for hare.

Three Nash equilibria:

- $p^*=1$  a pure strategy (also ESS)
- $p^*=0$  a pure strategy (also ESS)
- $p^* = P/(P - R + T)$  a mixed strategy [assuming  $S=0$ ]

The Nash equilibrium of a game may sometimes be **inferior** to an **alternate choice of actions by the agents in which all the parties get higher payoff** ... gives rise to “social dilemmas” such as

# Prisoners Dilemma

$$T > R > P \geq S$$







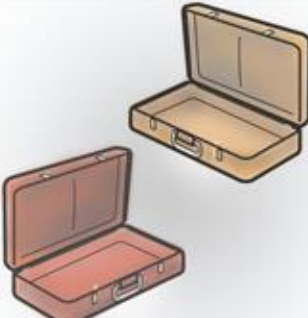
Nash equilibrium for PD : **both defect**

But **mutual cooperation** will result in **higher payoffs R (> P)** for both.

Results of **experimental realizations** of PD and other non-cooperative games incorporating such dilemmas do show **deviation from Nash** solutions...

Humans tend to be much “nicer” than what rational game-theoretic models would tend to suggest

originally framed by Merrill Flood and Melvin Dresher at RAND (1950)

 <b>SELLER</b> 		<b>COOPERATE</b> <b>DEFECT</b>	
<b>BUYER</b> 	<b>COOPERATE</b>		
	<b>DEFECT</b>		

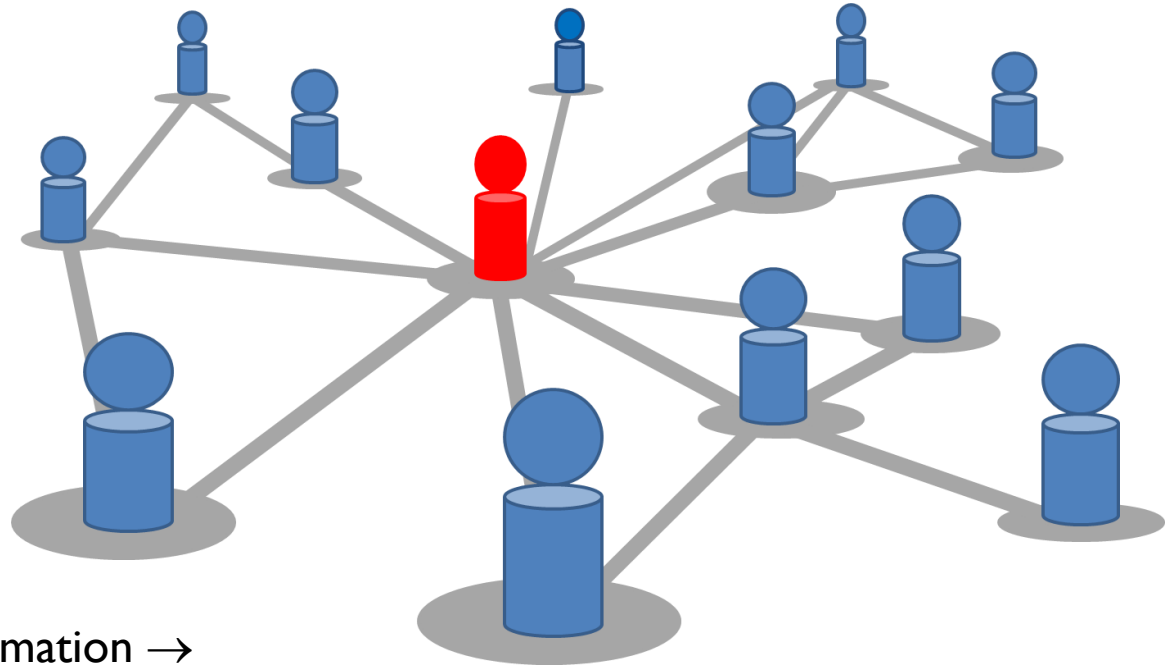
# Games on Graphs

2-player games between rational players well-understood

But games between players connected on a social network – with agents interacting only with their nearest neighbors – Spatial constraints on information communication →

## Bounded Rationality

Each agent has incomplete information → only aware of actions of their neighbors



In iterated games, where players choose a new action at subsequent time steps complex collective behavior arises depending on

- ❑ the type of game (payoff matrix),
- ❑ uncertainty about information of other's actions (noise), and,
- ❑ the nature of the connection topology (network).

# Example:

## Voluntary vaccination during epidemic

$U_{vv} > U_{vn} > U_{nv} > U_{nn}$  : Harmony

$U_{nv} > U_{vv} > U_{vn} > U_{nn}$  : Hawk-Dove

$U_{nv} > U_{vv} > U_{nn} > U_{vn}$  : Prisoner's Dilemma

$U_{nv} > U_{nn} > U_{vv} > U_{vn}$  : Deadlock

$$f_i = \alpha(I/N) + (1 - \alpha)(k_{inf}/k).$$

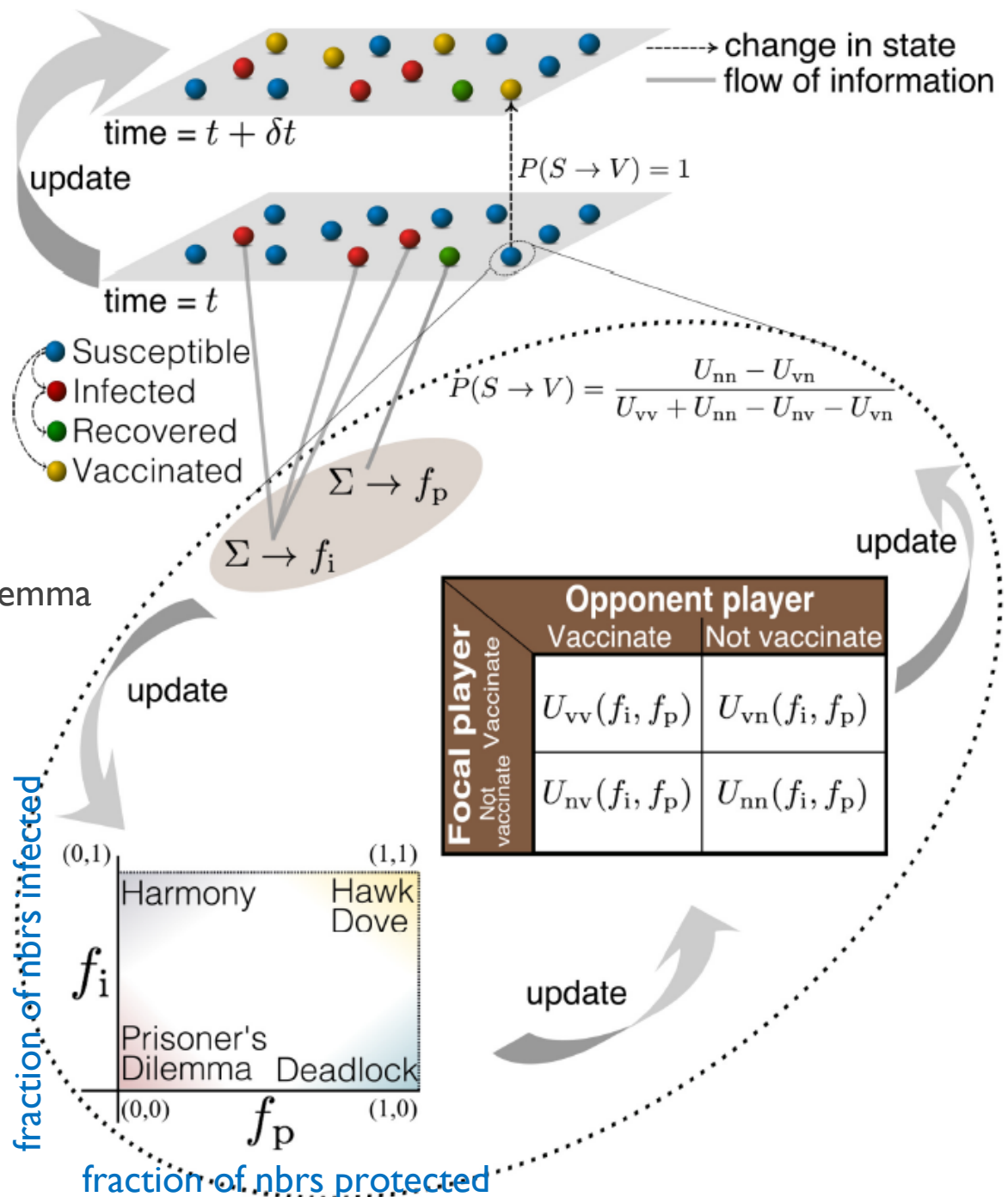
By using parameter  $\alpha$ , we tune the nature of information being used in making decision about vaccination.

$$\alpha = 0$$

Entirely local information

$$\alpha = 1$$

Entirely global information

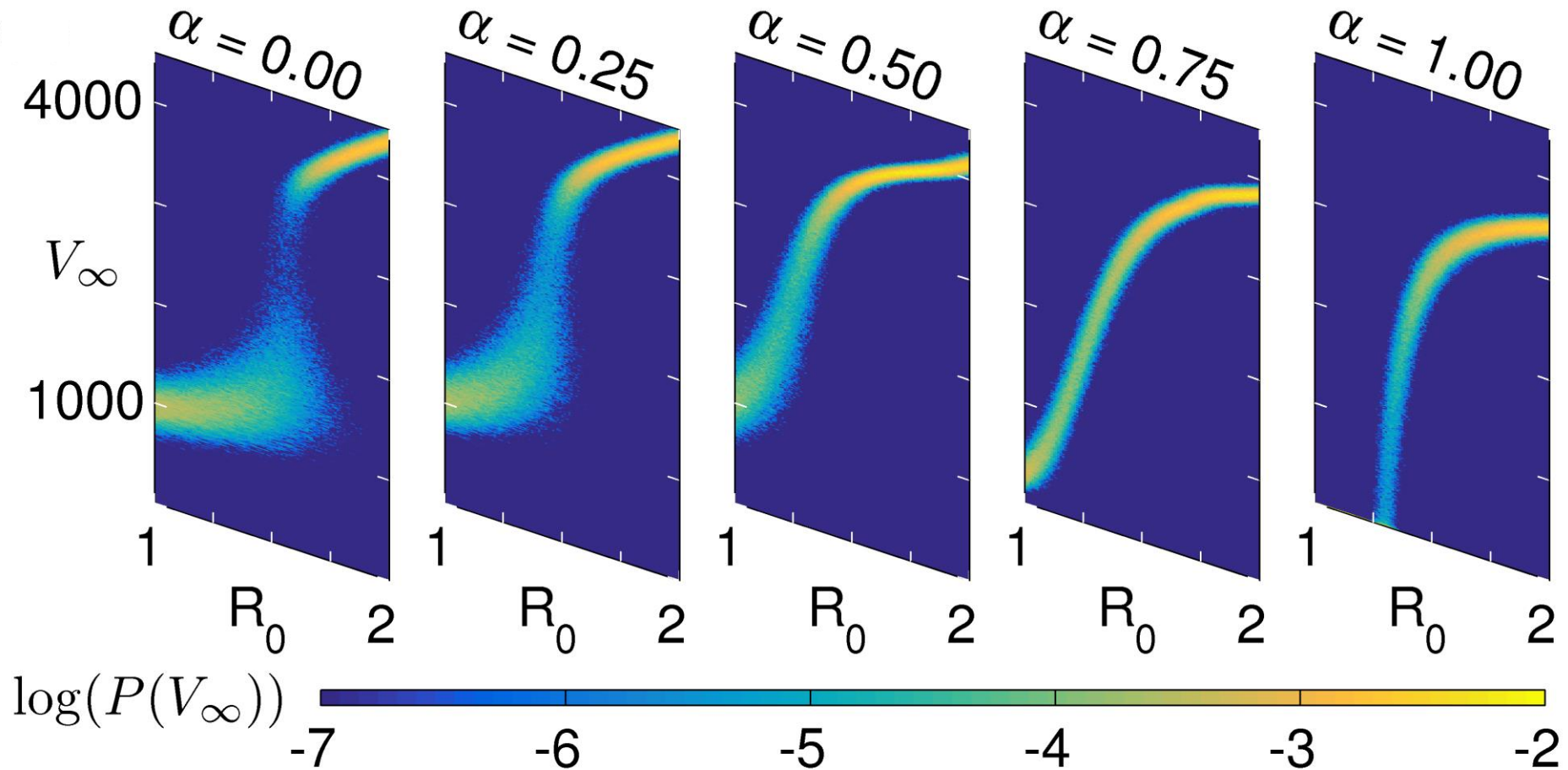




# Phase transition

from low vaccination coverage to high coverage as  $R_0$  is increased

Discontinuous transition for low  $\alpha$ , Continuous transition for high  $\alpha$



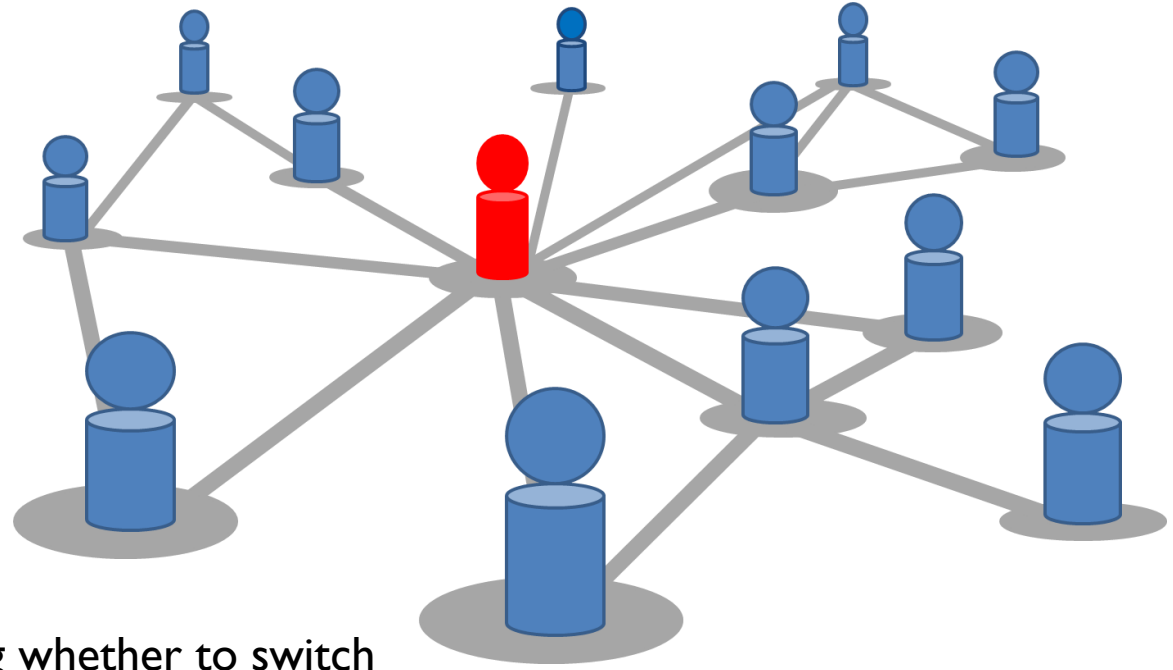
Probability distribution of  $V_\infty$  as a function of  $R_0$  for different values of  $\alpha$



# Can connection topology alone drive transition to cooperation ?

Each agent on a node plays a 2-person game with each of its neighbors

Each agent  $i$  plays a 2-person game – decided by a payoff matrix with  $P=S=0$ ,  $R=1$  and  $T$ , a free parameter – with each of its neighbors, and collects a net payoff  $\pi_i$  at the end of one iteration of the game



Noise or uncertainty in deciding whether to switch between actions arising from incomplete information results in the stochastic action update rule

each agent  $i$  randomly picks a neighbor  $j$  and copies its action with a probability

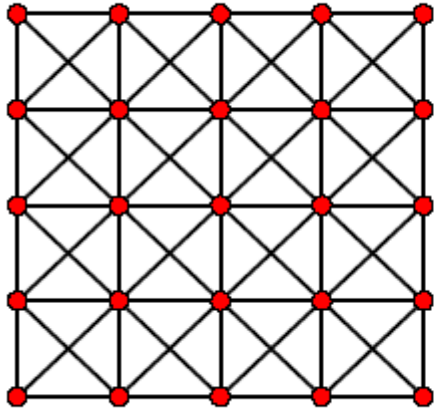
Fermi distribution function

$$\Pi_{i \rightarrow j} = \frac{1}{1 + \exp(-(\pi_j - \pi_i)/K)}$$

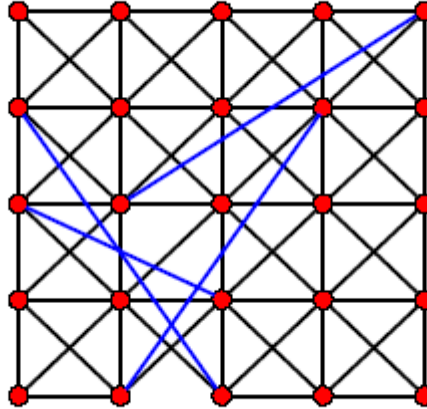
$K$  is a temperature, a measure of the “noise” in the decision-making process

The connection topology of interactions is systematically altered using the paradigm of

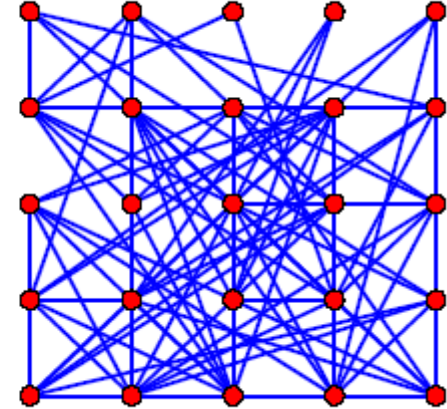
## “Small world” networks



Regular Network  
 $p = 0$



“Small-world” Network  
 $0 < p < 1$



Random Network  
 $p = 1$



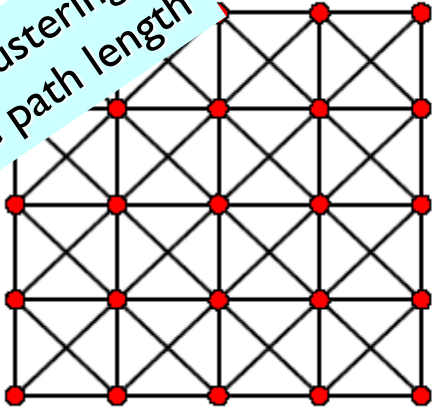
Increasing Randomness

$p$ : fraction of random, long-range connections

The connection topology of interactions is systematically altered using the paradigm of

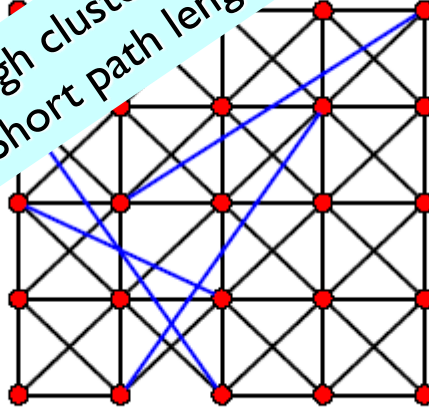
## “Small world” networks

High clustering,  
Large path length



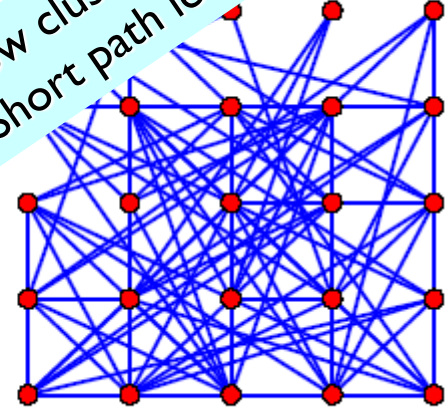
Regular Network  
 $p = 0$

High clustering,  
Short path length



“Small-world” Network  
 $0 < p < 1$

Low clustering,  
Short path length



Random Network  
 $p = 1$

Increasing Randomness

$p$ : fraction of random, long-range connections

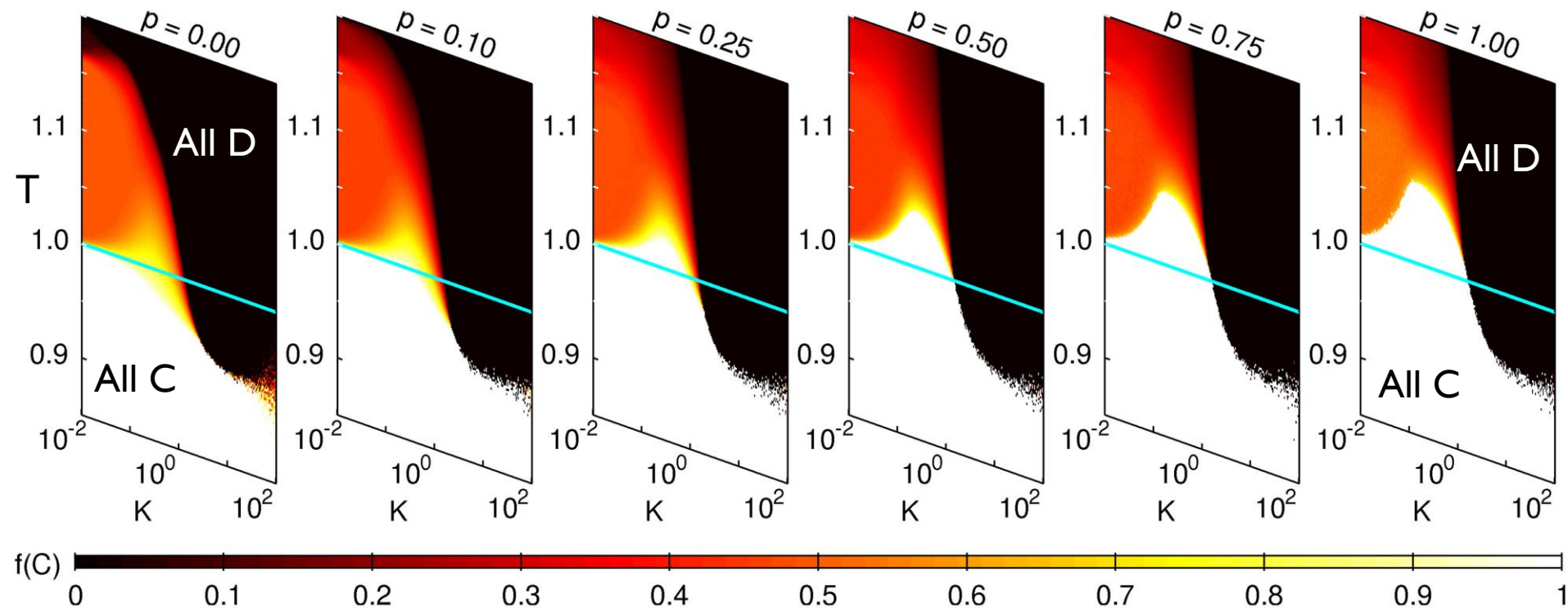
Watts and Strogatz (1998): Many biological, technological and social networks have connection topologies that lie between the two extremes of completely regular and completely random.

# Three collective dynamical states

For each value of game dynamics parameters  $T$  (temptation payoff) and  $K$  (noise), the system converges to one of two possible collective dynamical states: (i) all C (absorbing state), (ii) all D (absorbing state) and (iii) a fluctuating state F where each agent intermittently switches between cooperation and defection

Regular Network

Random Network



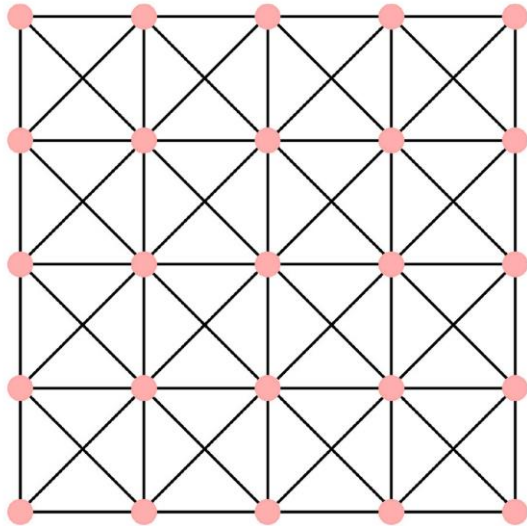
But as the connection topology (governed by  $p$ ) changes, the phase diagram also alters

# Topological transition: Cooperation as a consequence of nature of connections among agents

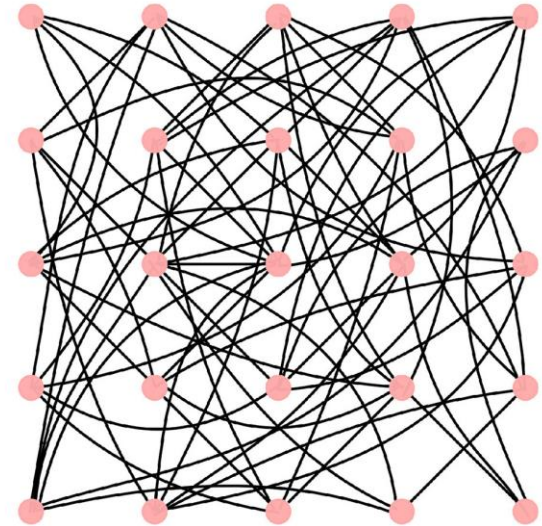
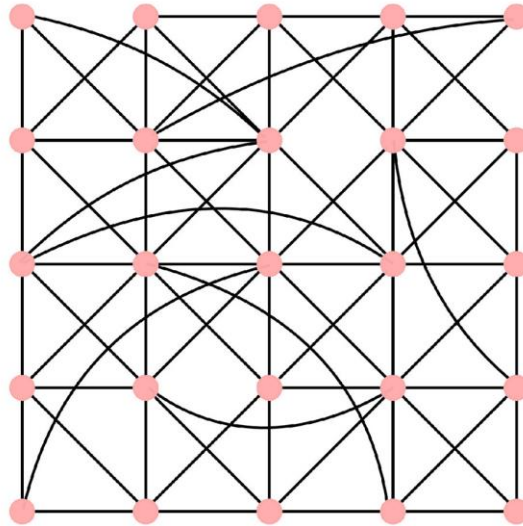
$$p = 0$$

$$0 < p < 1$$

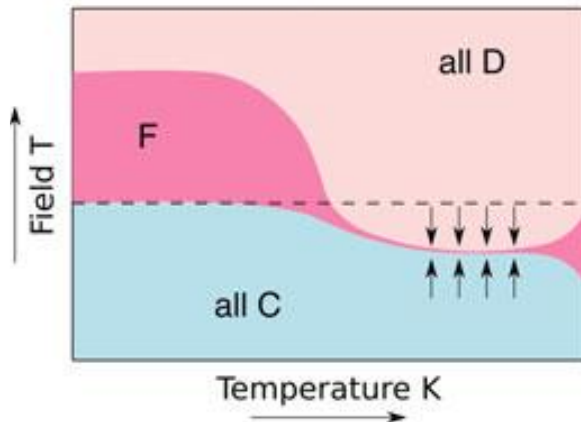
$$p = 1$$



2D lattice

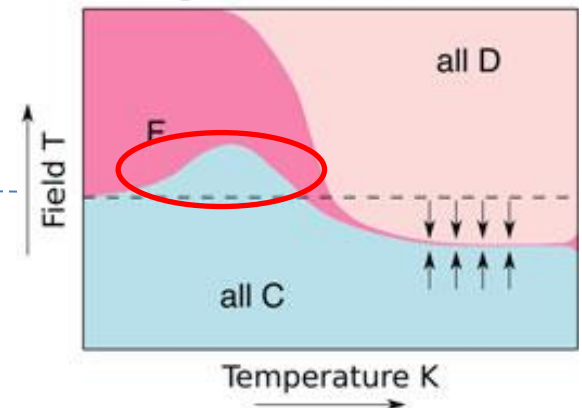


Homogeneous random network



Prisoners Dilemma regime

Stag Hunt regime



The temptation  $T$  can be viewed as a field, in analogy to spin systems, as its value biases an agent's preference for which action to choose. agents update their action at every round by choosing a neighbor at random and copying their action with a probability that is given by a Fermi function, where the level of temperature (noise) is controlled by the parameter  $K$ .

# Conclusions

- ❑ When played in a spatially extended setting, iterated games provide a framework for the investigation of the process of collective decision-making under conditions of bounded rationality (incomplete information)
- ❑ While payoff matrices are known and are identical for all agents, individuals only have knowledge of the choice of actions of that subset of agents with whom they had previously interacted (i.e., their topological neighbors).
- ❑ As  $T$  decreases below  $R = 1$ , the game changes from the Prisoner's Dilemma (characterized by a unique equilibrium that is given by the dominant strategy of mutual defection) to the Stag Hunt (characterized by multiple equilibria).
- ❑ The transition between all D and all C is **discontinuous**, as it involves an abrupt change in the order parameter  $f(C)$  [asymptotic fraction of cooperating agents]. The transition from these absorbing states to the fluctuating regime is a continuous one.
- ❑ The all C regime moves up the  $K - T$  plane as  $p$  is increased explaining the sudden emergence of complete cooperation in the PD regime when moving from a regular lattice to a random network keeping average number of neighbors fixed.



# THANKS



- ❑ V. Sasidevan & S. Sinha, *Scientific Reports* **5**, 13071 (2015)
- ❑ V. Sasidevan & S. Sinha, *Scientific Reports* **6**, 30831 (2016)
- ❑ S. N. Menon, V. Sasidevan & S. Sinha, *Front. Phys.* **6**, 34 (2018)
- ❑ A. Sharma, S. N. Menon, V. Sasidevan & S. Sinha, *PLoS Comput. Biol.* **15**, e1006977 (2019)
- ❑ S. N. Menon, V. Sasidevan & S. Sinha, in *Network Theory and Agent-Based Modeling in Economics and Finance* (Springer, 2019) pp 265-281. (arxiv1906.11683)