

# A Novel Two Stage Approach for Single Pulse Post-processing

-Shubham Singh and the SKA-PSS team:

(A. Karastergiou, A. Naidu, B. Stappers, B. Shaw, B. Posselt, D. Lumba, G. Berriman, J. Taylor, K. Rajwade, L. Levin, M. Droog, M. Mickaliger, P. Thiagaraja, R. Hombal)

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The SKAO logo features the letters 'SKAO' in a bold, blue, sans-serif font. A stylized star, composed of red and white segments, is positioned between the 'K' and 'A'.The logo for The University of Manchester, featuring the word 'MANCHESTER' in white serif font above the year '1824' in a smaller white serif font, all set against a purple rectangular background.

The University of Manchester

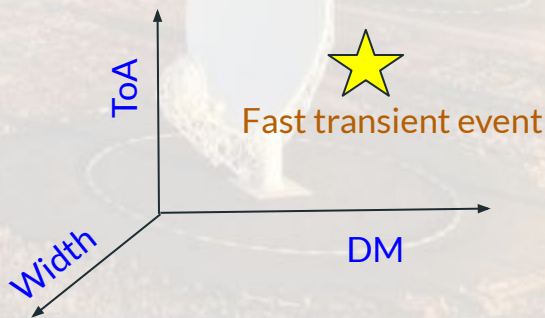


# The Post-processing Parameter Space

# Fast transient search

Fast transients can be described by three parameters in addition to their sky coordinates,

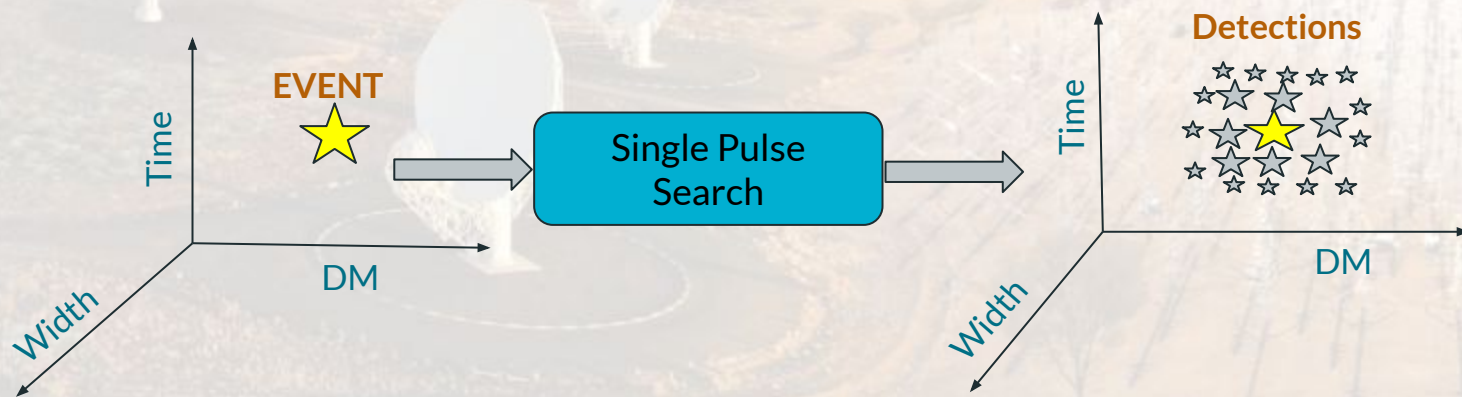
1. Distance from observer ( Indicated by electron column density, **DM**)
2. When did the event happen ( Time of occurrence/arrival, **ToA**)
3. For how long the transient event last (Duration of the event, **Width**)





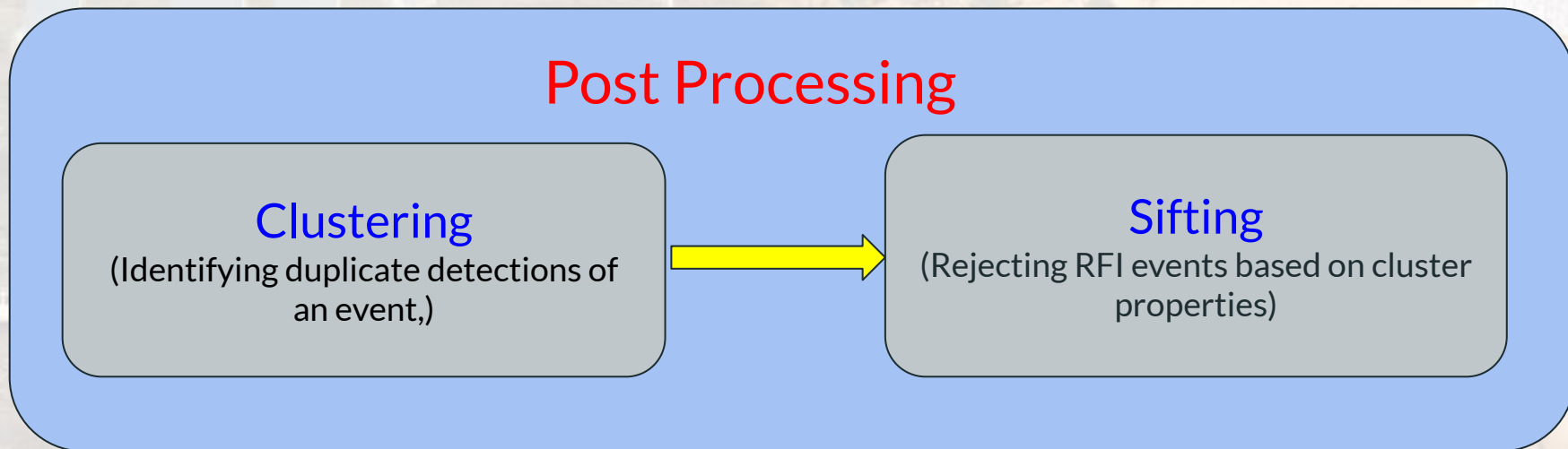
# Final result of single pulse search

- The telescope search mode data is searched over,
  1. All time samples
  2. Set of Trial DMs
  3. Set of trial Width
- The result of the search is a set of detections in the Time-DM-Width space with associated S/N.



# Need for post processing

- A strong and wide event can sometimes produce millions of duplicate detections.
- A big fraction of candidates are RFI generated.



An aerial photograph of a radio telescope array in a desert landscape. In the foreground, several large, white, parabolic radio telescope dishes are visible, some mounted on circular concrete bases. A small white pickup truck is parked on a dirt road near one of the dishes. In the background, a large number of smaller, vertical antenna structures are arranged in a grid-like pattern across the desert floor. The landscape is arid with sparse vegetation and a few small pools of water. The sky is clear and blue, with the sun visible in the upper right corner, creating a bright glow and long shadows.

# Clustering methods

# Friends of friends clustering

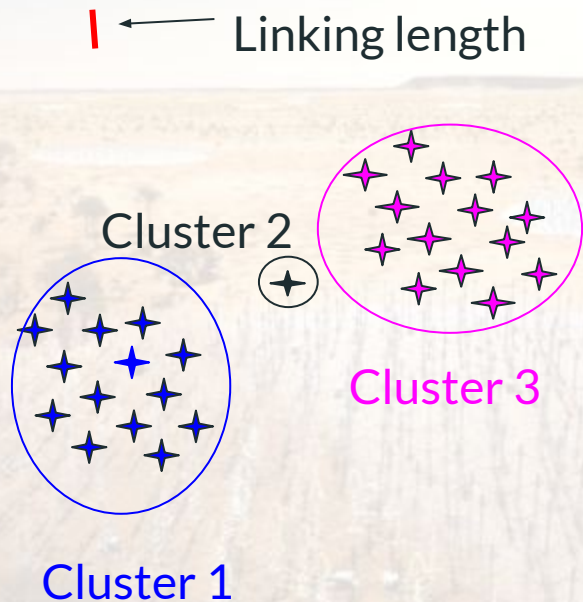
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- Fast
- Can handle large number of detections
- User defined linking lengths
- The linking lengths need to be tuned according to the target pulse
- Can not handle variable density (caused by the DM plans)



# Friends of friends clustering

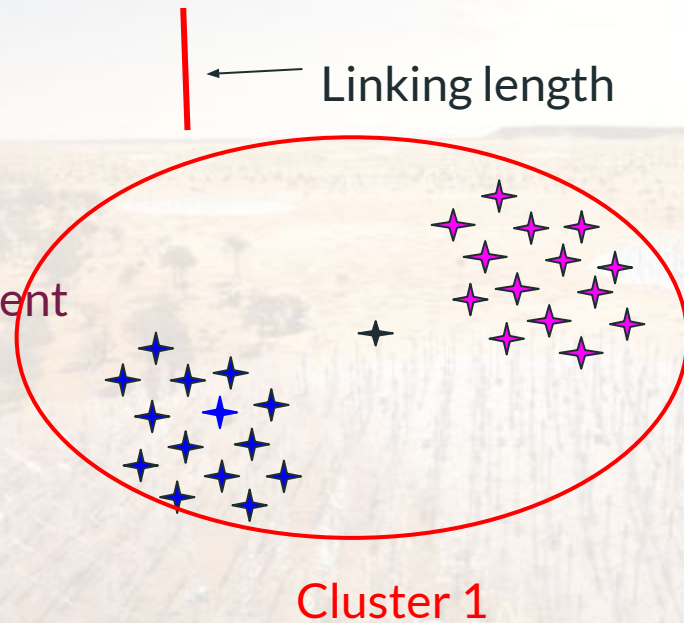
Smaller Linking length can make too many cluster. It can also split a single cluster into multiple clusters.





# Friends of friends clustering

Large linking length might merge multiple independent clusters along with noise.



# DBSCAN Clustering

- Fast
- Can handle large number of detections
- Uses density instead of linking lengths
- Can handle noise
- Still needs a length scale ( $\epsilon$ ) and a number ( $n$ ) to decide density cut-off.
- Can not handle variable density

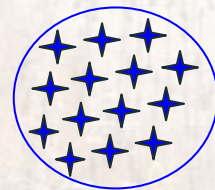


# DBSCAN Clustering

A predefined  $n$  and  $\epsilon$  may work for one density but not for other.

The DM plan used in search creates different detection density for different DM range.

$n=5, \epsilon =$  —



Cluster 1

# HDBSCAN Clustering

- Needs only one user defined parameter (minimum size of the cluster), **can create bias against faint pulsars**
- Tolerant to density variations, hence can handle density variations due to DM-plan
- Robust against noise, can identifies noise points
- **Computationally expensive**





# HDBSCAN Clustering

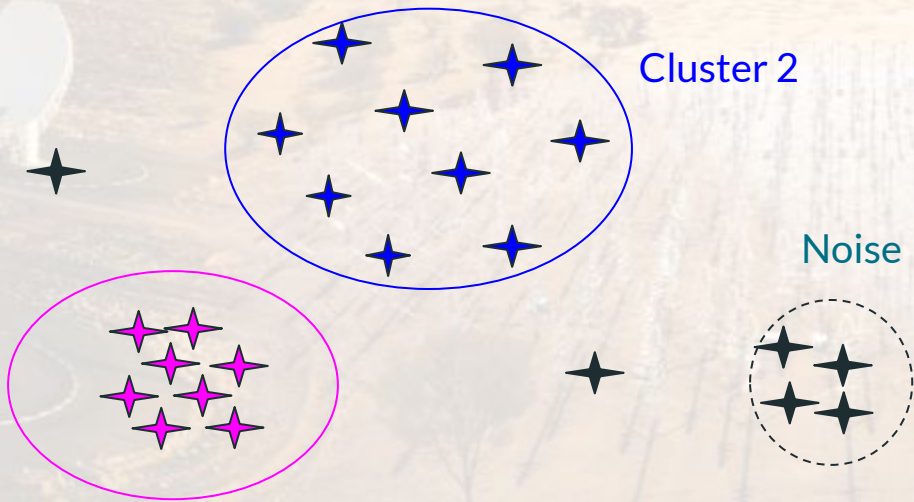
- Uses only one user defined parameter (minimum size of the cluster), **can create bias against faint pulsars**
- Tolerant to density variations, hence can handle density variations due to DM-plan
- Robust against noise, can identifies noise points
- Computationally expensive

Min cluster size = 5

Cluster 1

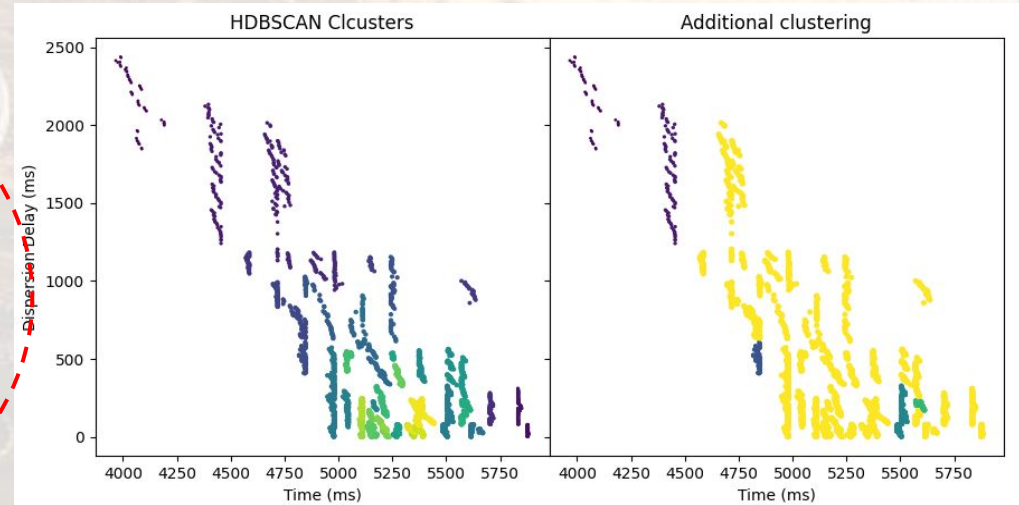
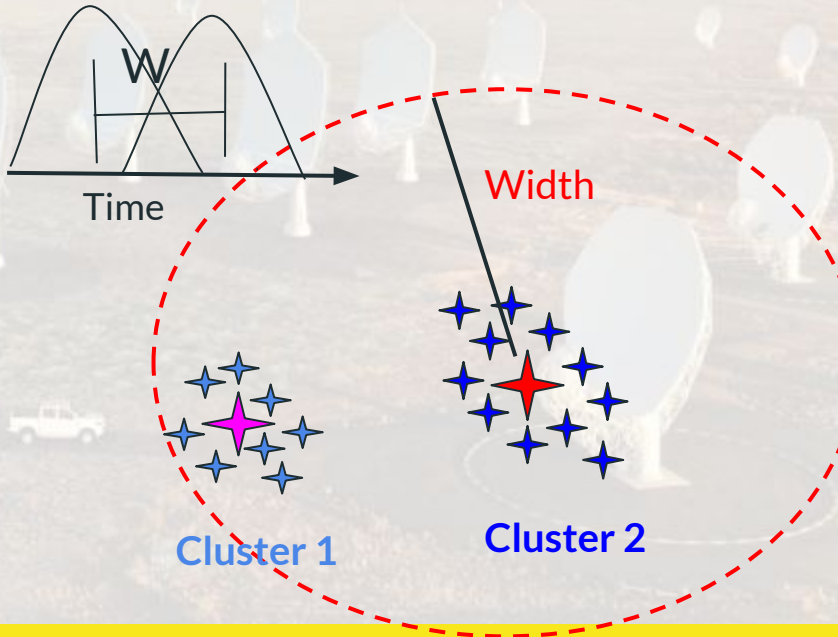
Cluster 2

Noise



# Need for additional clustering step

- In case of wide pulses, multiple clusters are formed for a single event.
- We propose an additional step of clustering that unifies the clusters within the detection width.



# Optimal approach for clustering

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## HDBSCAN Clustering

(With one clustering parameter:  
Minimum cluster size)



## Additional Width Based Clustering

(Uses detection width of brightest  
detection as clustering radius)

An aerial photograph of a radio telescope array in a desert landscape. Several large, white, parabolic dish antennas are visible, some mounted on circular concrete bases. In the foreground, a white pickup truck is parked on a dirt road. To the right, a large, dense array of smaller, vertical antenna structures is visible. The landscape is arid with sparse vegetation and a few small pools of water. The sky is clear and blue, with the sun visible in the upper right corner.

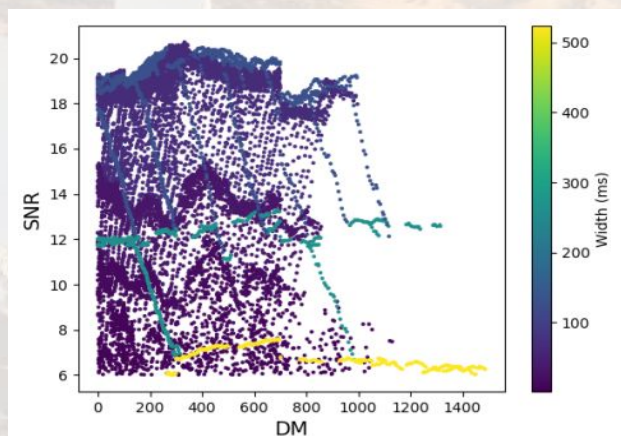
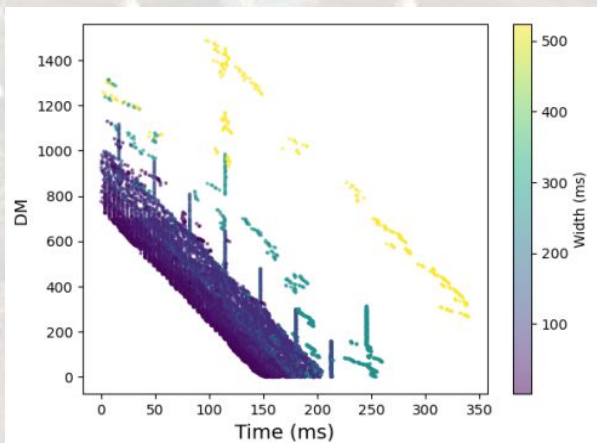
# Sifting methods



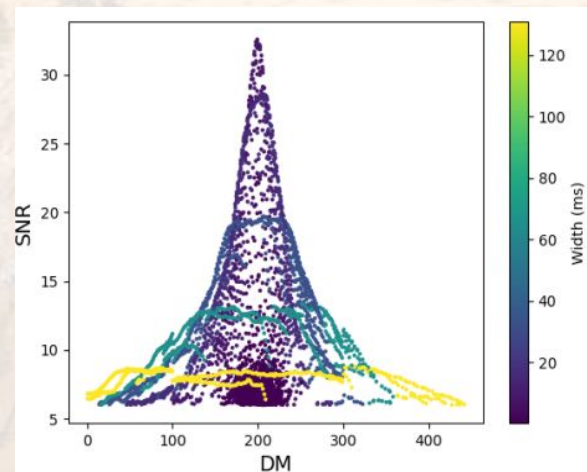
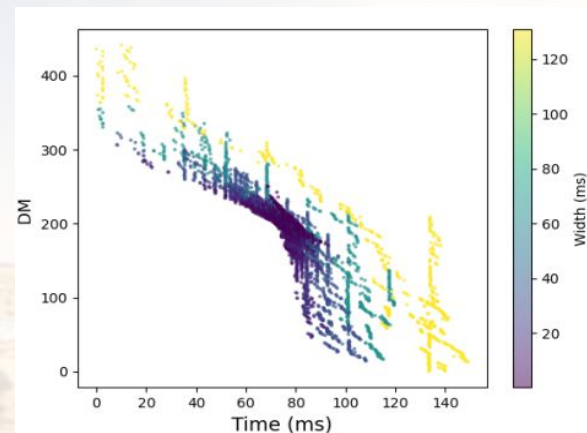
# Selecting cluster features for sifting

- Limited number of intuitive features
- No complex fitting on the data: expensive for large clusters and noisy for small clusters
- Select carefully: feature can introduce bias

## RFI Event



## Astrophysical Event



# Manual thresholding

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- A lower cut-off on the size of cluster can get rid of noise detections.
- A simple lower cut-off on the DM of best detection can remove most of the wideband RFI.
- But excluding narrowband RFI clusters is non-trivial.

# Machine learning sifting methods

We tried three supervised machine learning methods:

1. **Decision tree:** Simple and interpretable, but prone to overfitting and imprecise (accuracy: 70-80%)
2. **Random Forest:** Collection of decision trees, interpretable and accurate (accuracy: 90-100%)
3. **Neural Network:** Performance similar to Random Forest, but hard to interpret results

We decided to use Random Forest for its accuracy, flexibility, and interpretability. We easily achieve **96%** accuracy with our selected features and Random Forest sifting.

# Reducing false negative rate in random Forest

We can use the flexibility of the Random forest classifier to reduce the loss of astrophysical candidates.

Regular Majority Voting:  
An object belongs to class A, if more than 50% trees say so.

Majority Voting to reduce the loss of astrophysical class:  
A cluster is astrophysical if 40% or more trees say so.



# Optimal approach for sifting

Simple set of cluster features

(Small number of intuitive, easy to compute features)



Random Forest Classifier

(Classifier with higher weightage to astrophysical class to reduce the loss of astrophysical signal)

No Optimal Approach, but this does the job !!

# Single pulse search post-processing in PSS-Cheetah

## Available methods for Clustering

1. FoF (fast approach)
2. HDBSCAN + Width based clustering (robust approach)

## Available methods for Sifting

1. Simple thresholding on features
2. Random Forest classification (RfSift)

**Recommended Combination:** HDBSCAN clustering followed by Random Forest Sifting

# Summary

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- The single pulse post-processing has two parts: clustering and sifting
- The clustering step aims to identify clusters belonging to a specific event.
- HDBSCAN followed by a width based clustering is the optimal way to cluster single pulse detection.
- The sifting step aims to identify RFI clusters and remove them.
- The Random Forest classification of clusters with simple set of features is an effective and flexible method for sifting.
- The Random Forest Classifier can be tuned to reduce false negative rates, reducing the loss of astrophysical signal.



— Thanks !



# Difference between RFI and Astrophysical clusters

## Astrophysical Signal vs Narrowband RFI

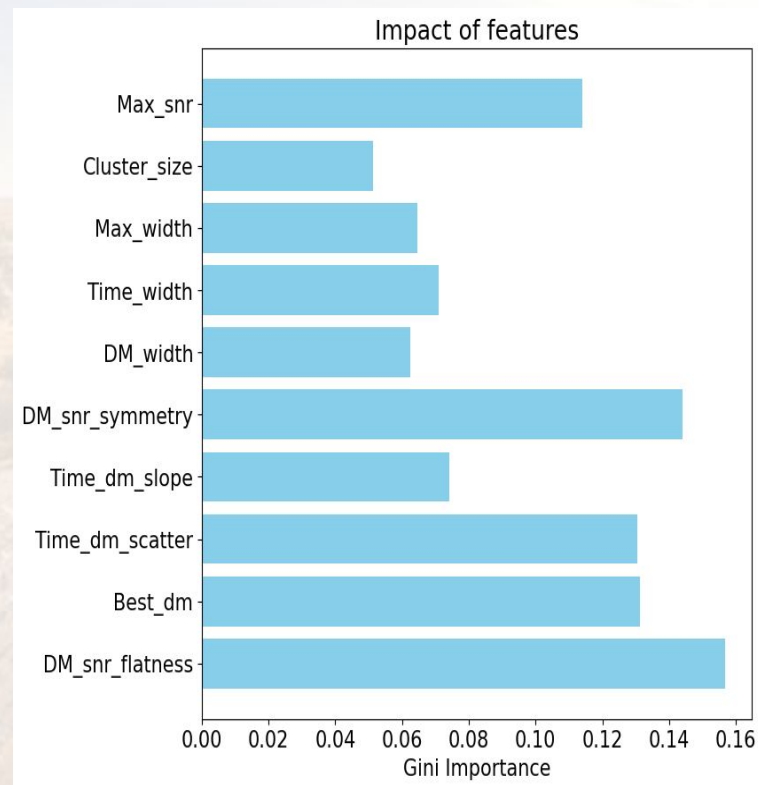
A few fundamental differences how narrowband and wideband signals appear in DM-Time plane and DM-S/N plot

## Astrophysical Signal vs wideband RFI

Very similar, only difference is the DM corresponding to best S/N detection, which is very small in case of wideband RFI

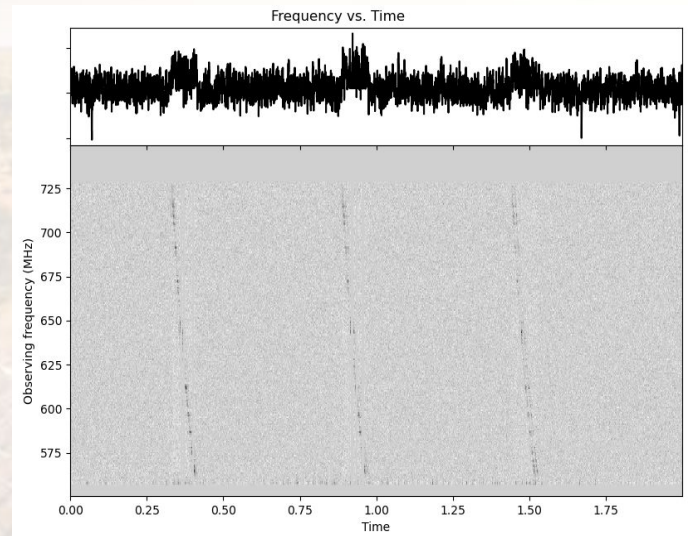
# Performance of cluster features with random forest

1. **Max\_snr:** Maximum detection SNR in the cluster
2. **Cluster\_size:** Number of detections in cluster
3. **Max\_width:** Detection width of brightest member
4. **Time\_width:** Extent in time axis
5. **DM\_width:** extent in DM axis
6. **DM\_snr\_symmetry:** measure of how symmetric DM-SNR plot is
7. **Time\_dm\_slope:** Slope of the Time DM plot
8. **Time\_dm\_scatter:** Scatter in Time-DM plane
9. **Best\_dm:** DM of best detection
10. **DM\_snr\_flatness:** The flatness measure of DM-SNR plot



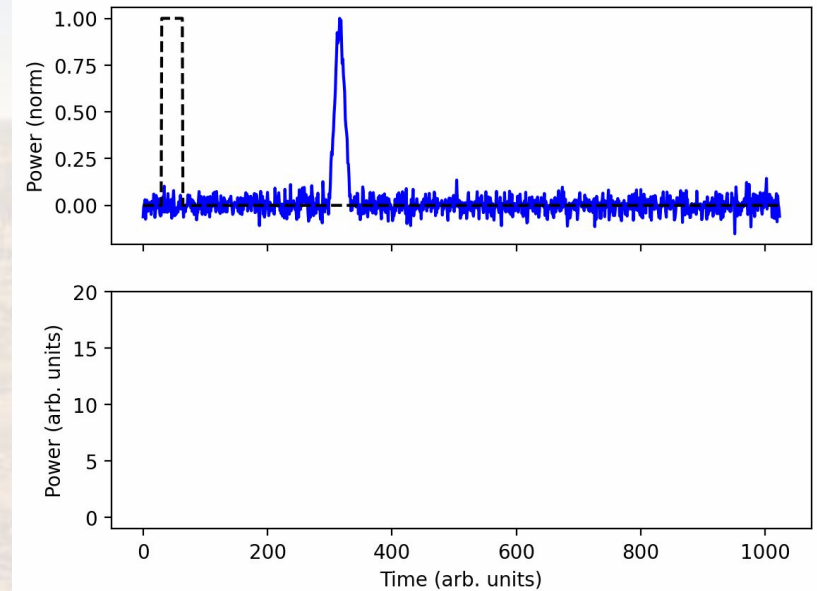
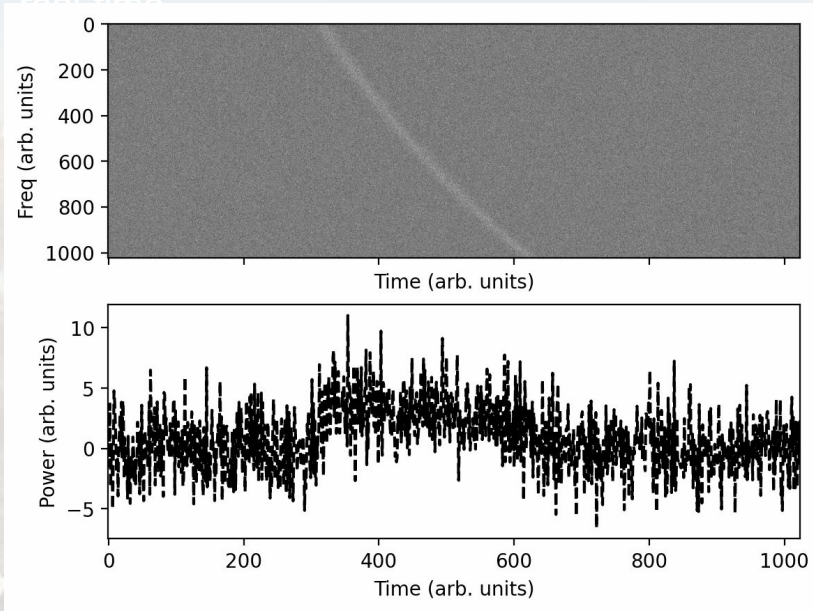
# Radio data from the telescope

- The radio telescope is pointed towards the interesting sky coordinates (RA, Dec)
- High time resolution data with enough frequency channels is recorded
- The final product is Time-frequency data corresponding to a sky coordinates.



# What is PSS (PULSAR SEARCH SUBSYSTEM)

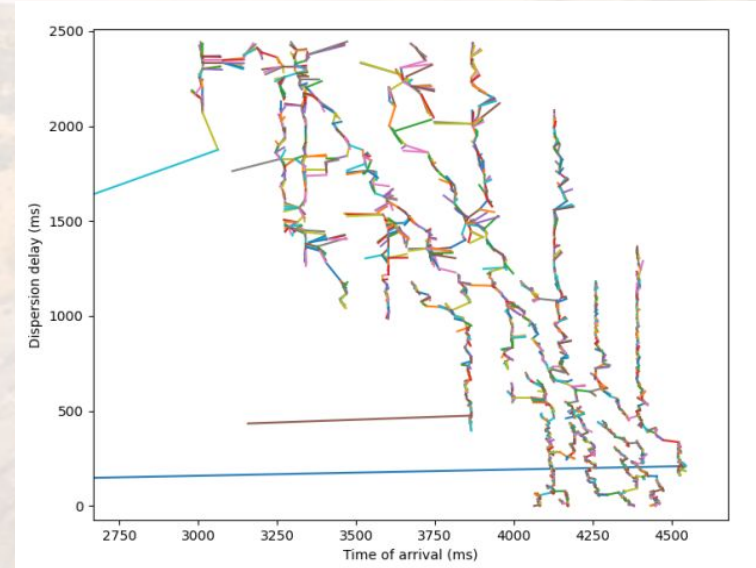
The subsystem aims to find pulsars and **fast transients** in real time



Credits: Kaustubh Rajwade

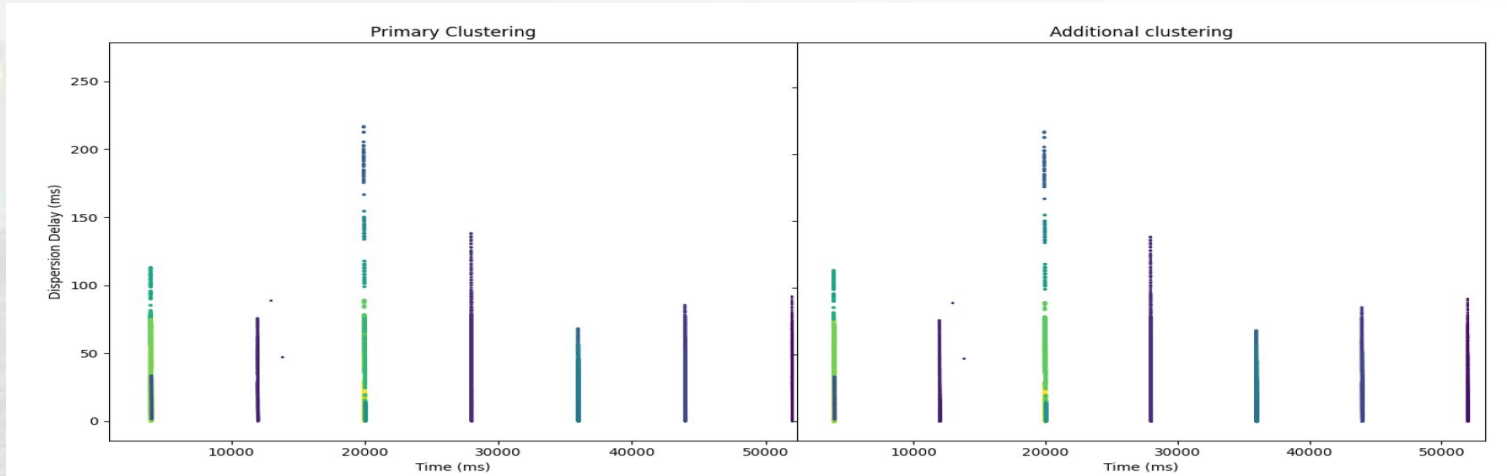
# Constructing MST based on MRD

- 'Spanning\_tree\_MRD' class provides tools to compute MRD and construct MST.
- Method 'Compute\_coredist()' is first used to compute the core distance for all data points.
- Then method 'construct\_tree()' is used to construct the MST based on MRD.





# Examples of additional clustering step based on width



Case of narrow pulses (10 ms wide, 24 clusters are reduced to 20)