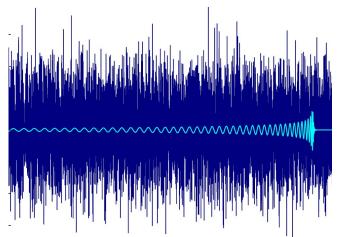




Machine Learning in Gravitational-wave





Prayush Kumar ICTS-TIFR

25 May 2022 LABORATORY FOR INTERDISCIPLINARY BREAKTHROUGH SCIENCE, ICTS-TIFR

# **Gravitational-wave Astronomy**



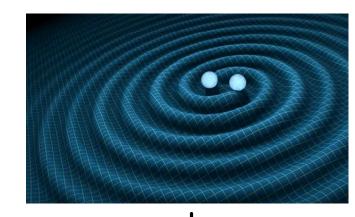




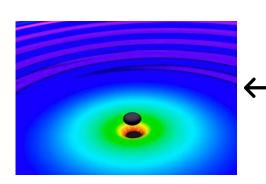
# **Gravitational-wave Astronomy**











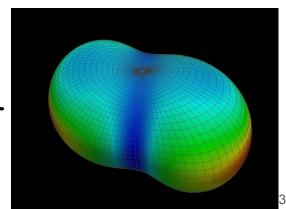
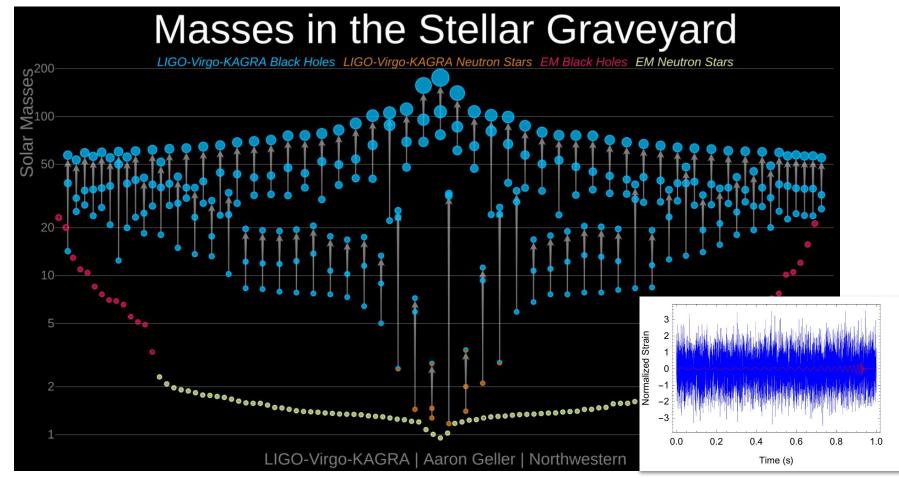
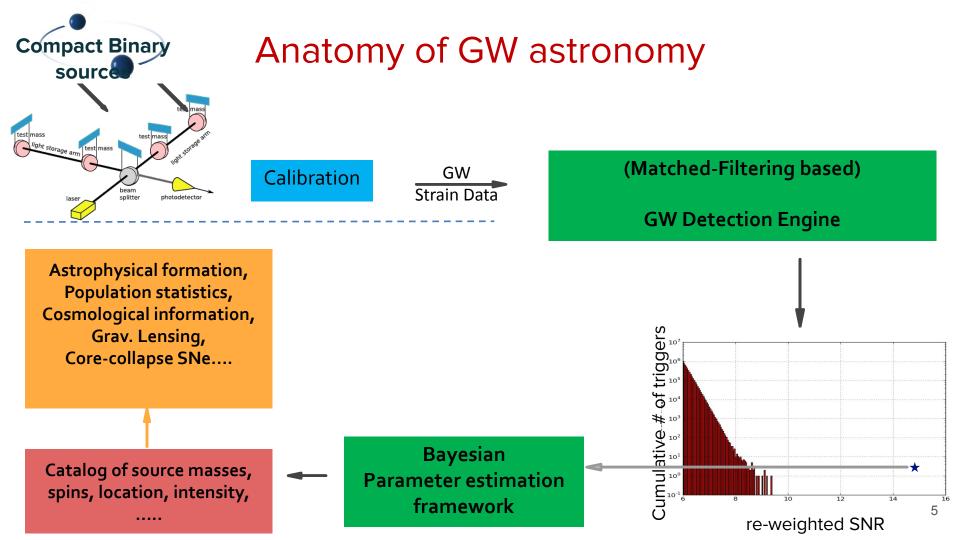


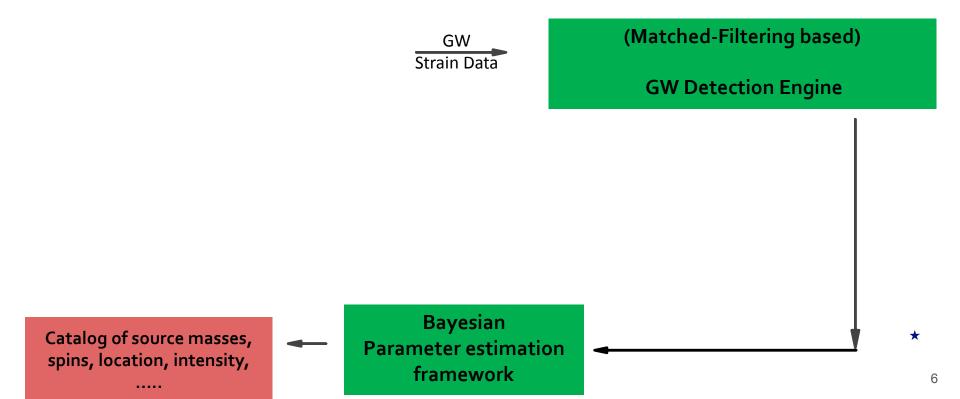
Image credit: Kavli Foundation, LSC; <a href="https://cggplus.files.wordpress.com">https://cggplus.files.wordpress.com</a>;

# GW observations: nearly 100 and counting!

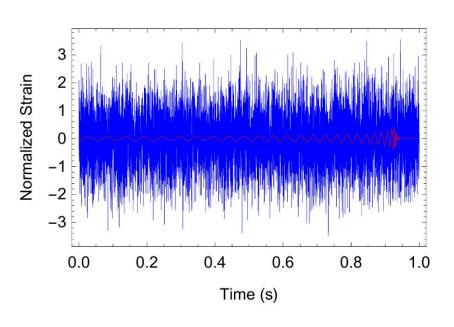


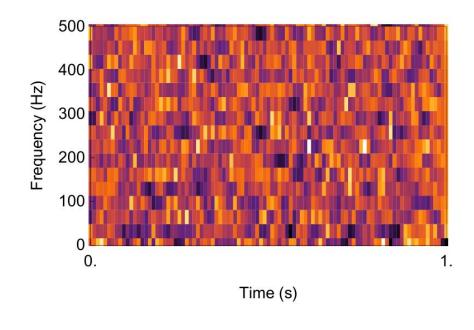


## Anatomy of GW astronomy

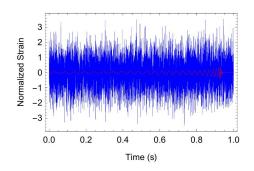


# 1. Detection of GW signals

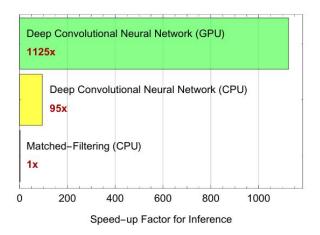


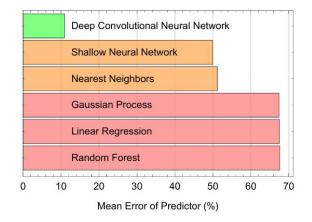


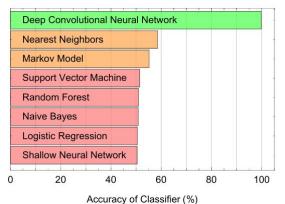
# Detection of GW signals: George & Huerta (2016)



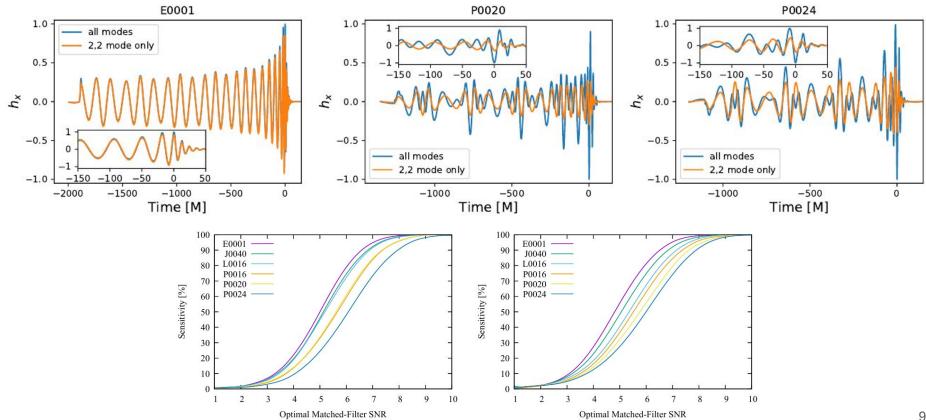
	Input	vector (size: 8192)
1	Reshape Layer	tensor (size: 1 × 1 × 8192)
2	Convolution Layer	tensor (size: 16 × 1 × 8177)
3	Pooling Layer	tensor (size: 16 × 1 × 2045)
4	Ramp	tensor (size: 16 × 1 × 2045)
5	Convolution Layer	tensor (size: 32 x 1 x 2017)
6	Pooling Layer	tensor (size: 32 × 1 × 505)
7	Ramp	tensor (size: 32 × 1 × 505)
В	Convolution Layer	tensor (size: 64 × 1 × 477)
9	Pooling Layer	tensor (size: 64 × 1 × 120)
10	Ramp	tensor (size: 64 × 1 × 120)
11	Flatten Layer	vector (size: 7680)
12	Linear Layer	vector (size: 64)
13	Ramp	vector (size: 64)
14	Linear Layer	vector (size: 2)
15	Softmax Layer	vector (size: 2)
	Output	vector (size: 2)



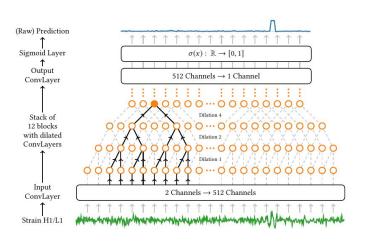


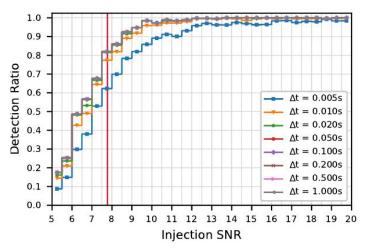


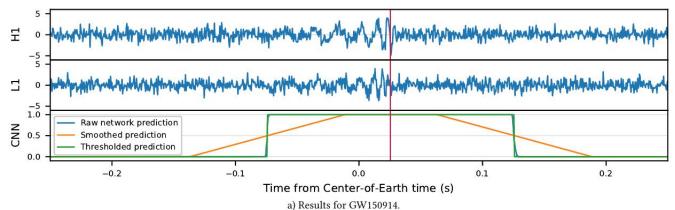
## Detection of GW signals: Rebei et al (2019)



#### Detection of GW signals: Gebhard et al (2019)







## Forecasting (detection) of GW signals: Wei et al (2021)

e = 0.1

e = 0.3

e = 0.5

e = 0.1

e = 0.3

e = 0.5

e = 0.7

--- e=0.7

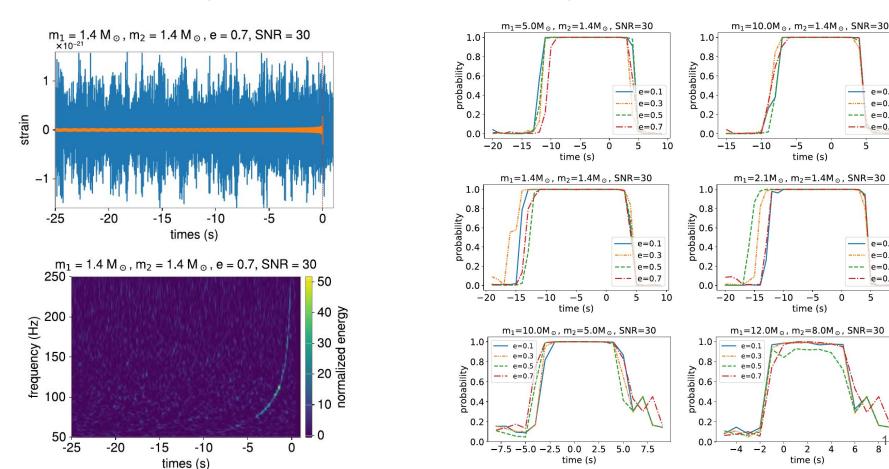
-5

time (s)

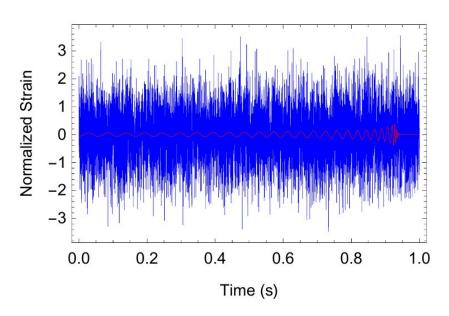
-5

time (s)

time (s)

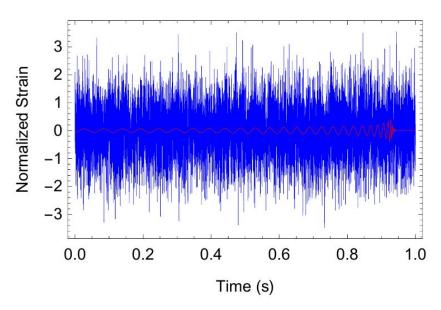


# 2. Measuring source parameters



Difficulties are the same as for the detection problem: Signal is weaker than instrument noise, we therefore need clever techniques for precisely characterizing the source of GW signals

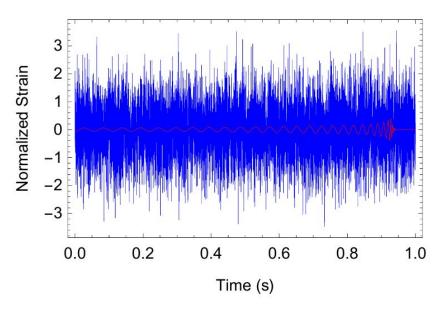
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Here also we **need low-latency**results since follow-up of GW
events for EM counterparts needs
prompt alerts to be sent to
telescope partners!

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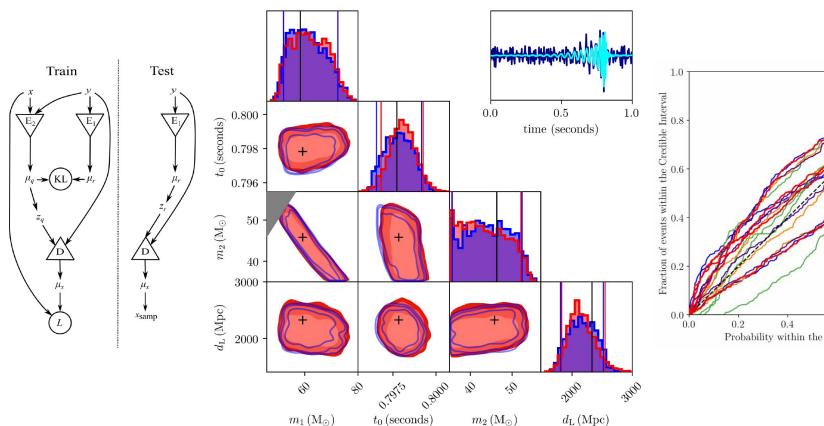


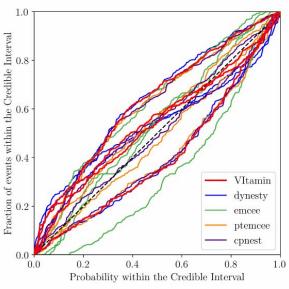
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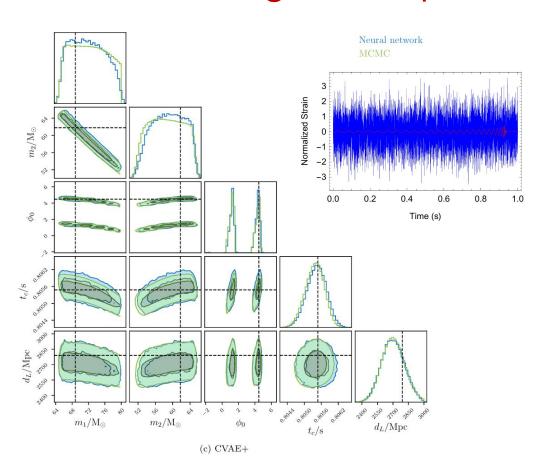
Matched-filtering based Bayesian parameter estimation takes between **5 hours to 5 days per event**!

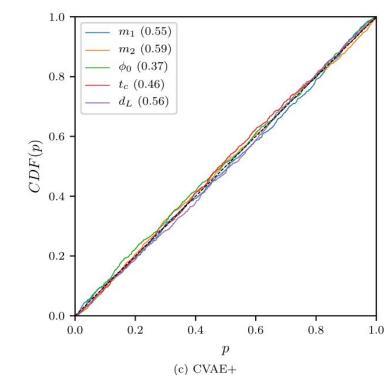
#### Measuring source parameters: Gabbard et al (2020)



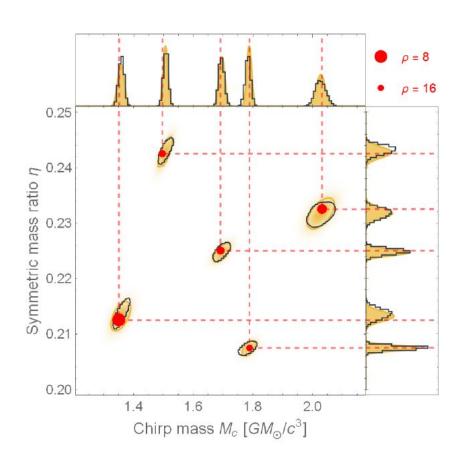


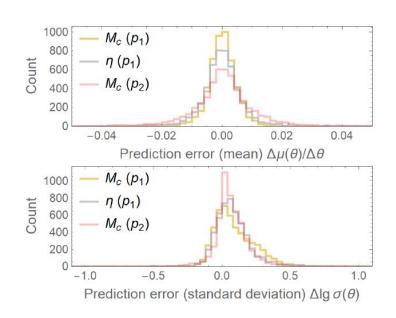
#### Measuring source parameters: Green et al (2020)





#### Measuring source parameters: Chua et al (2020)





# Summary & Future Outlook

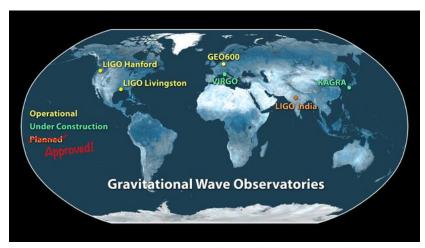
LIGO-India Scientific Collaboration

#### ML / Al can now be applied to:

- Low-latency detection of GW signals
- Measurement of source parameters from GW signals
- Characterization of GW detector noise transients

#### Future:

- Most of these applications are in proof-of-concept stage
- No sufficiently clear understanding yet of the
  - (a) statistical confidences in AI detections, and
  - (b) source parameter measures in Bayesian framework
  - ⇒ More nuanced applications of AI needed
- AI-based methods need to be scalable to future networks of 5 detectors: HLVKI
- Development of AI based algos needs substantial computing expertise & hardware
- Discover yet-undetected signal types
- Develop GW signal models by solving PDEs with neural-network based operators























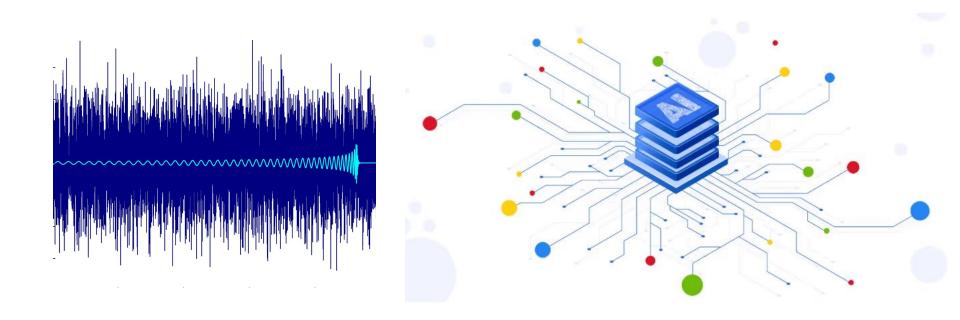




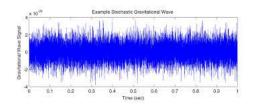


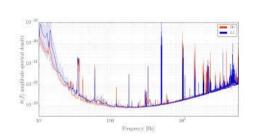


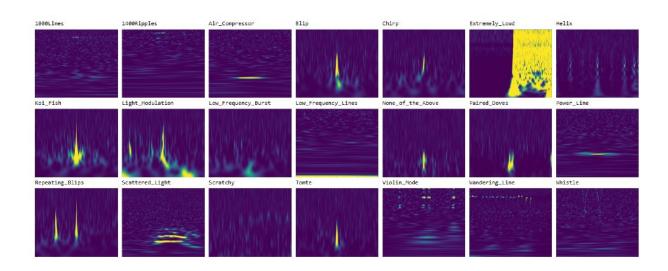
#### Questions?



#### Detector Noise Characterization: George et al (2017)







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