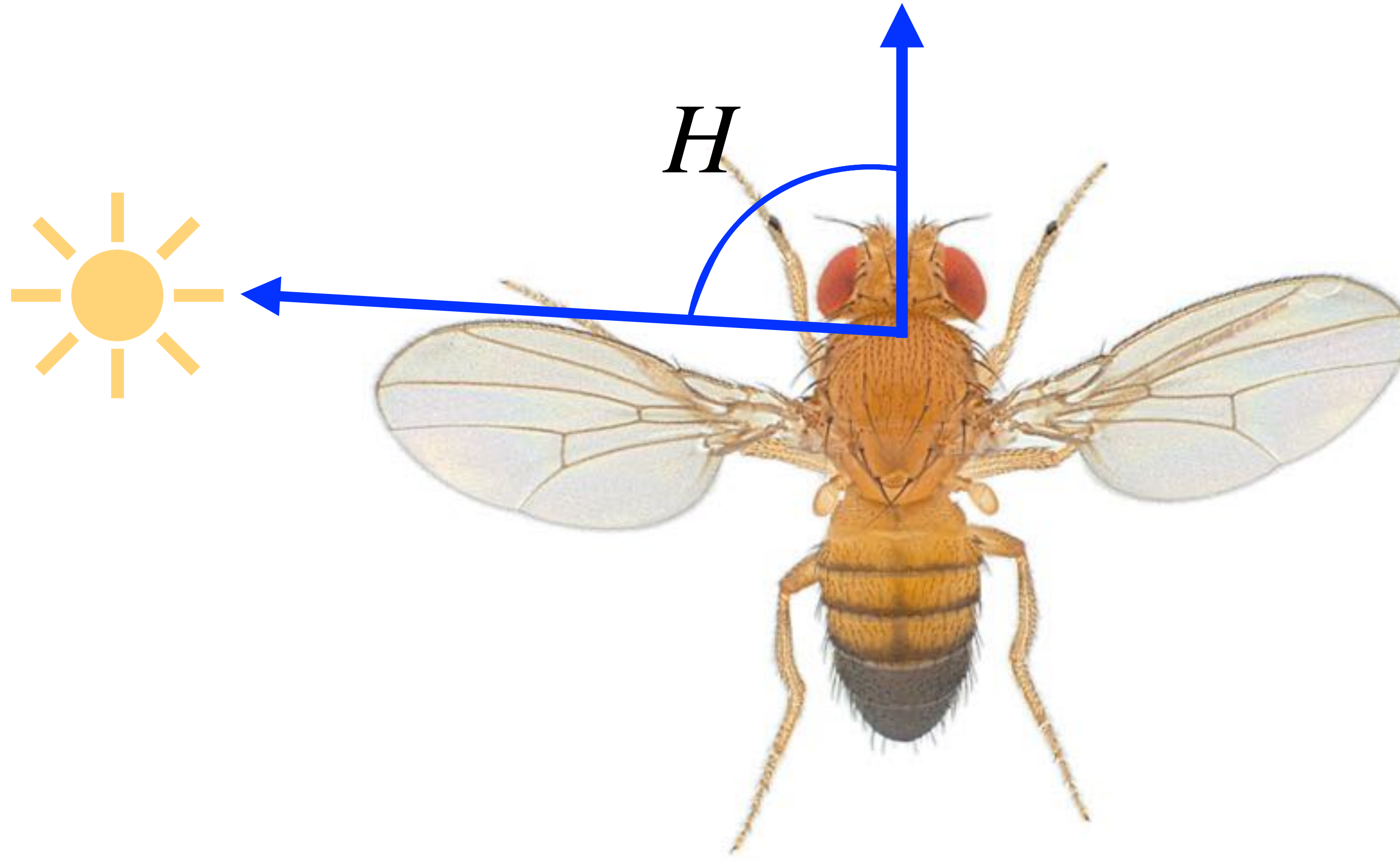


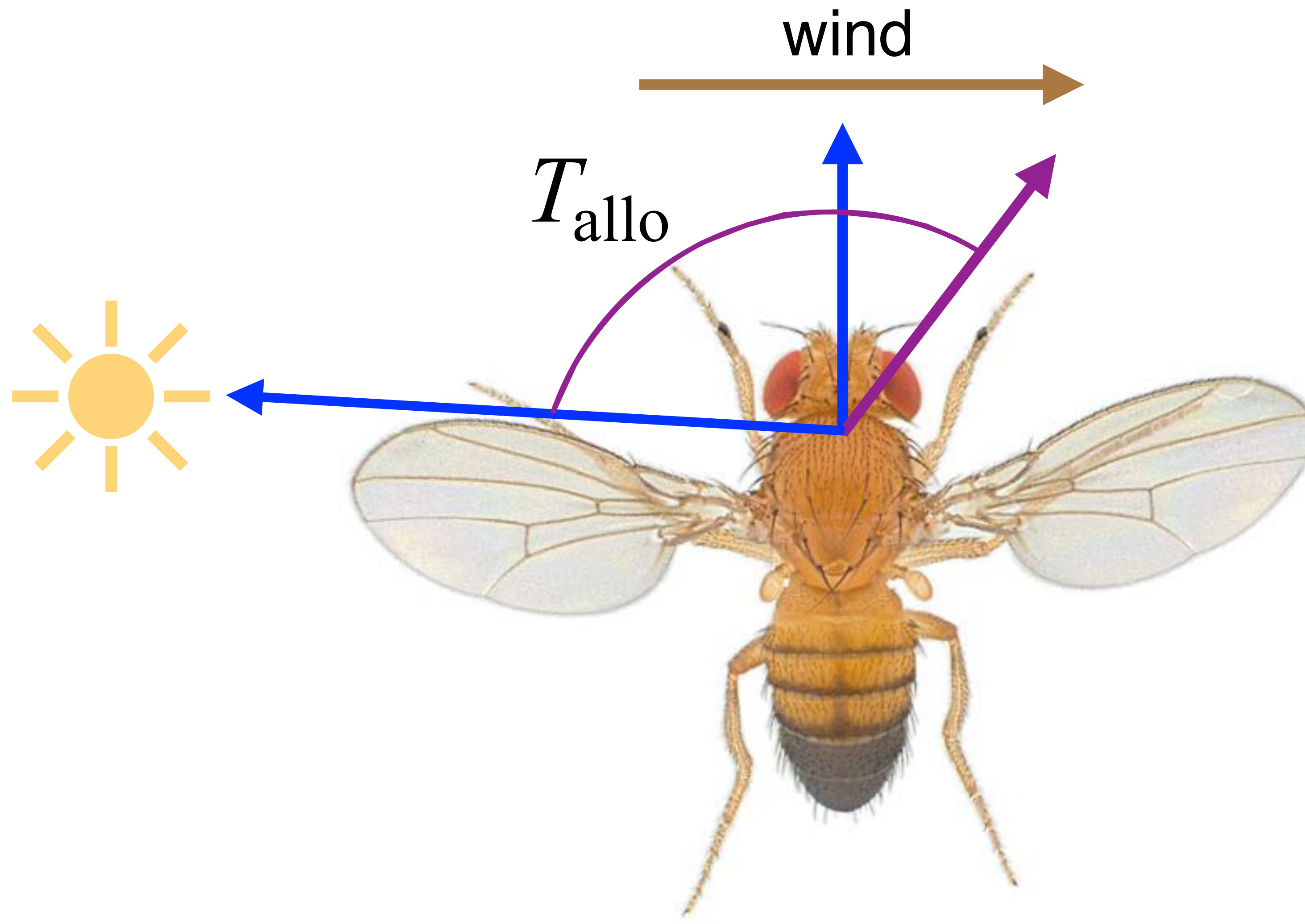
How Do Flies Navigate



How does a fly know which way it is heading?

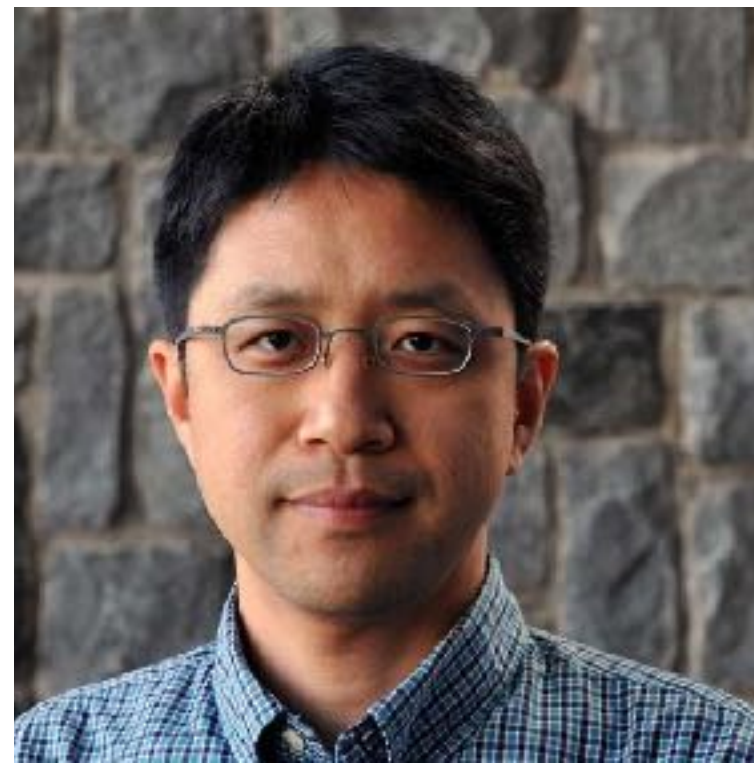


How does a fly know which way it is traveling?





Vivek Jayaraman



Sung-Soo Kim



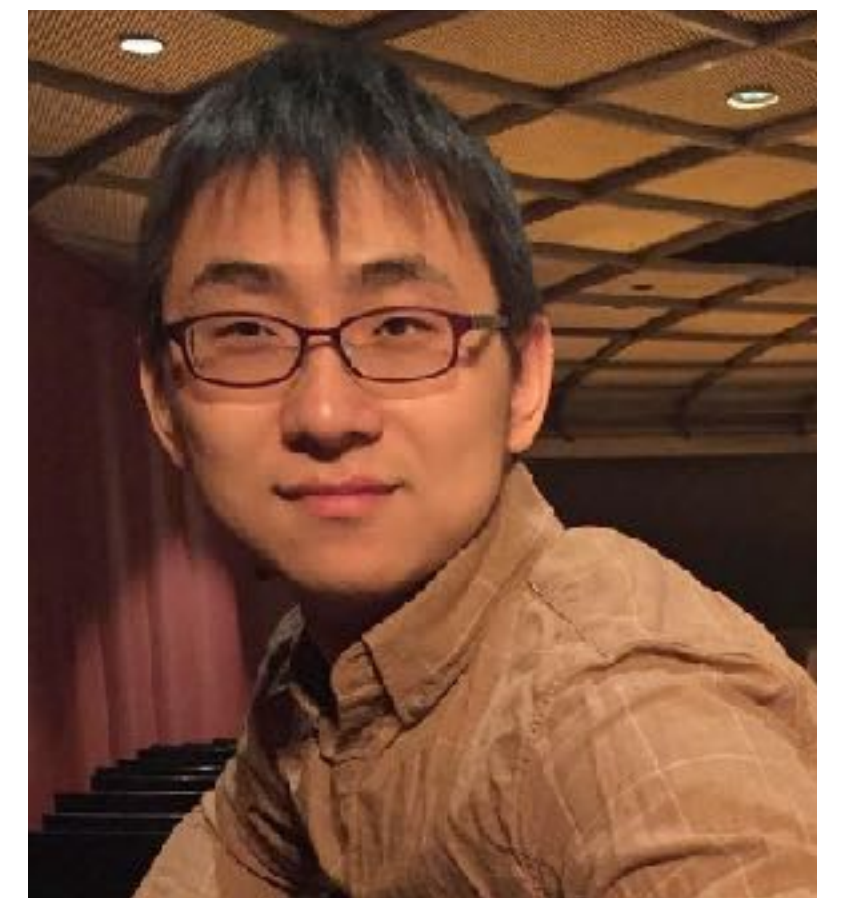
Gaby Maimon



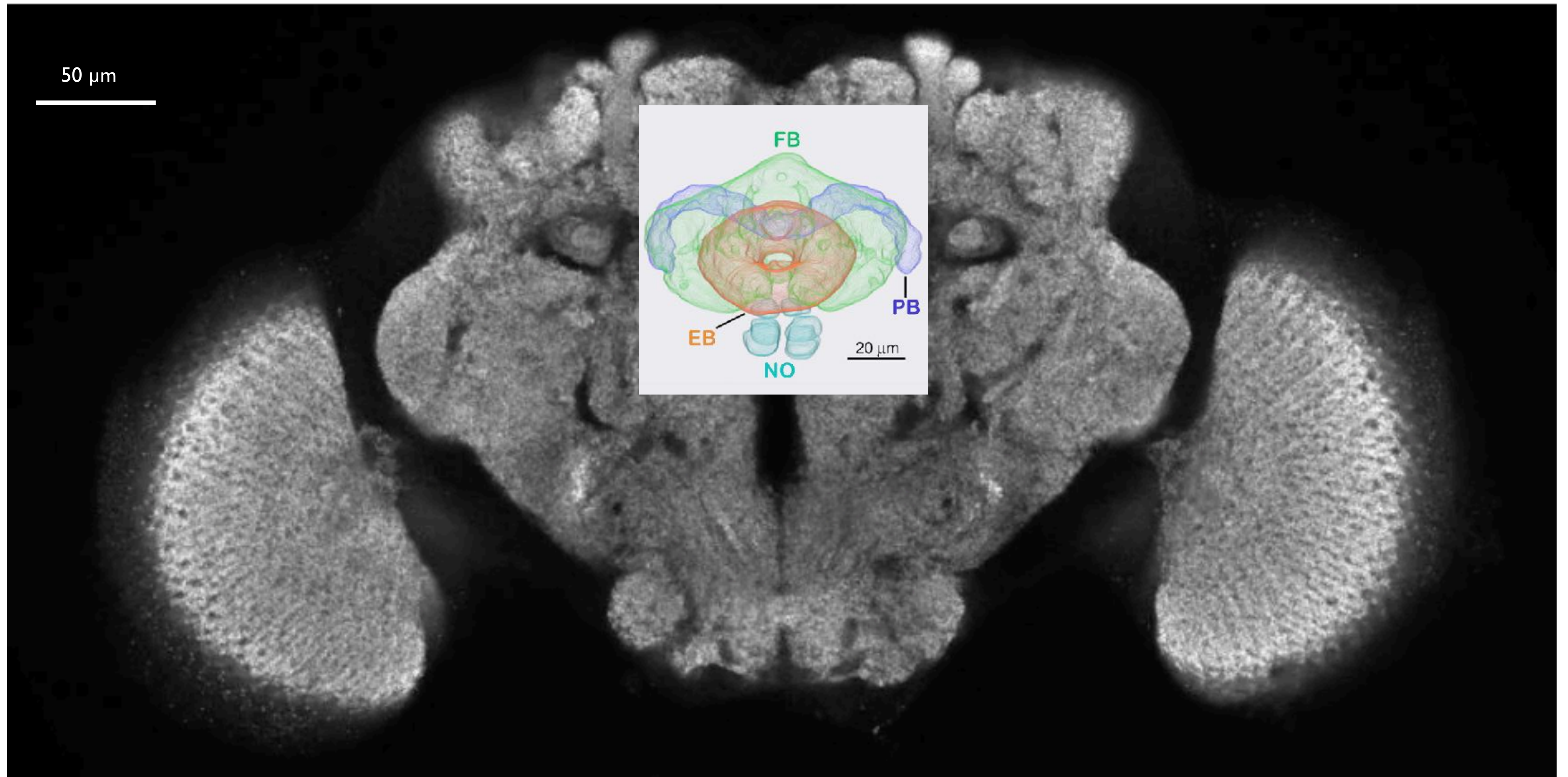
Ann Hermundstad

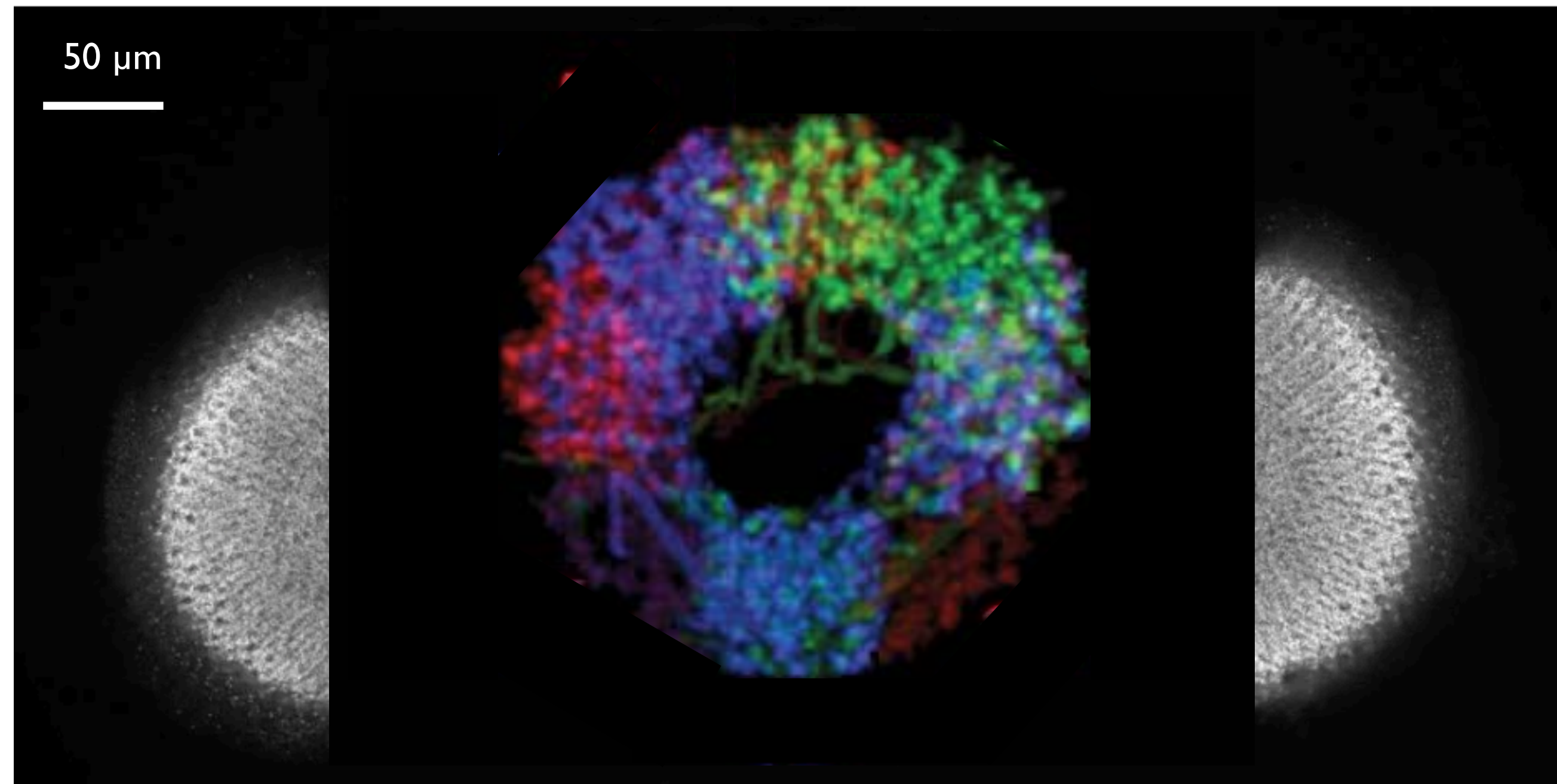


Sandro Romani

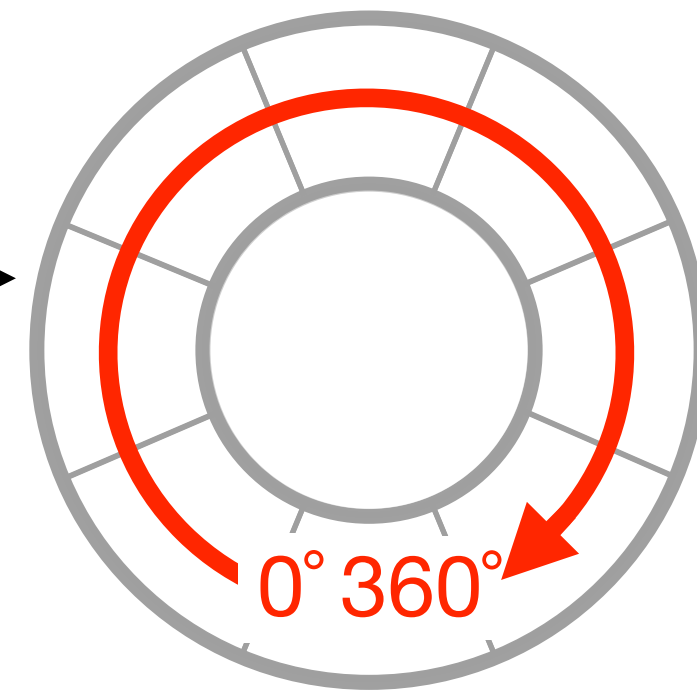


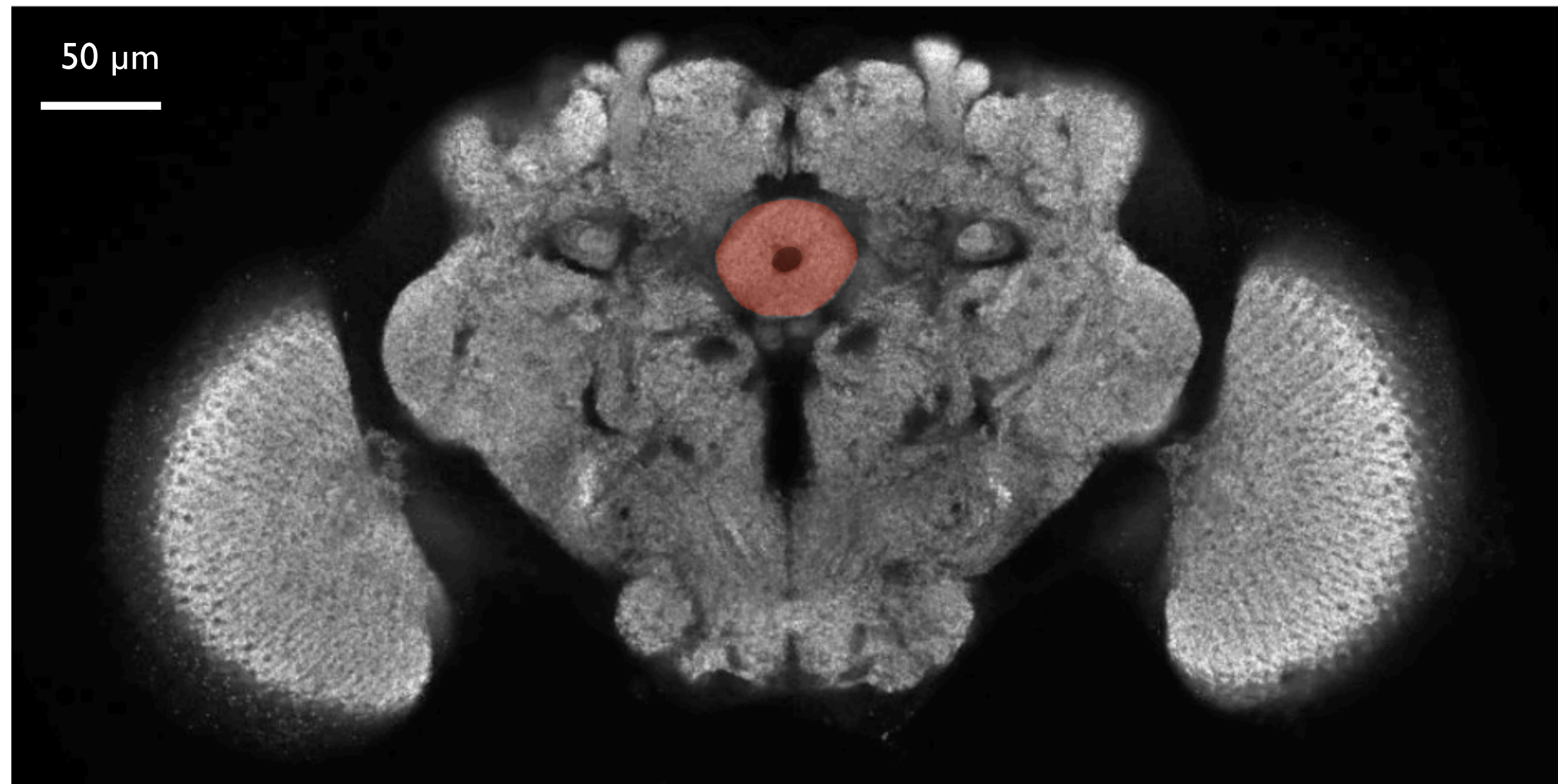
Cheng Lyu





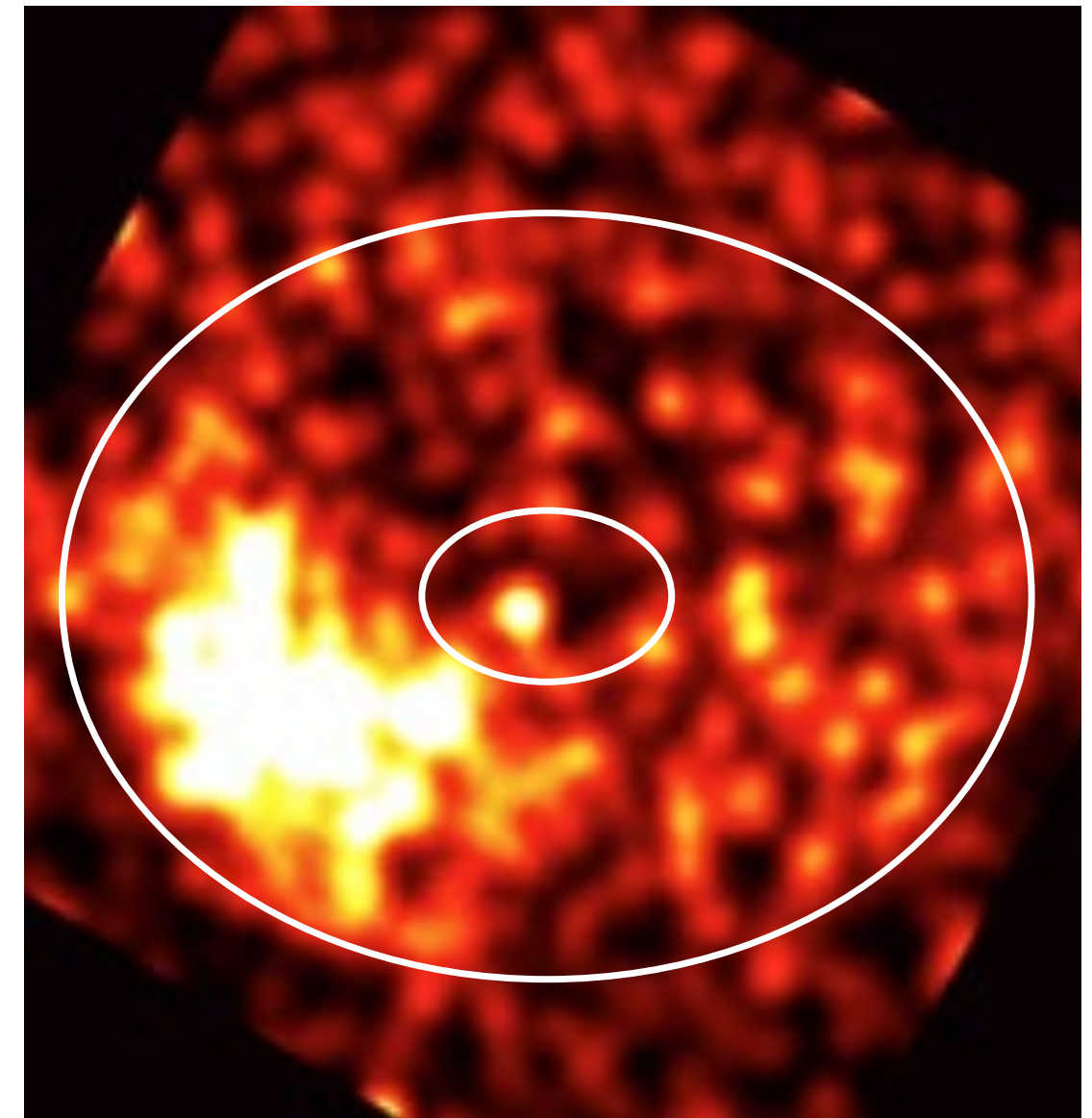
**ellipsoid
body**

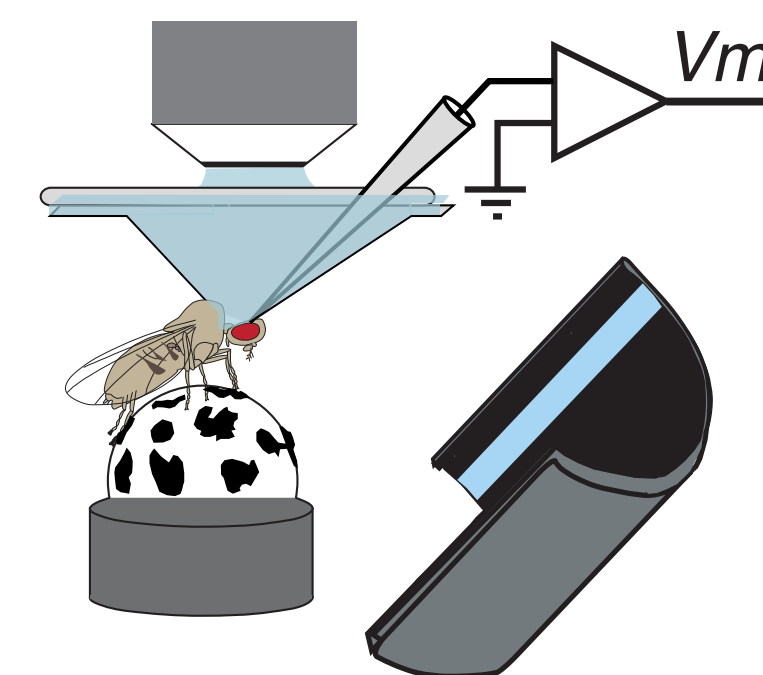
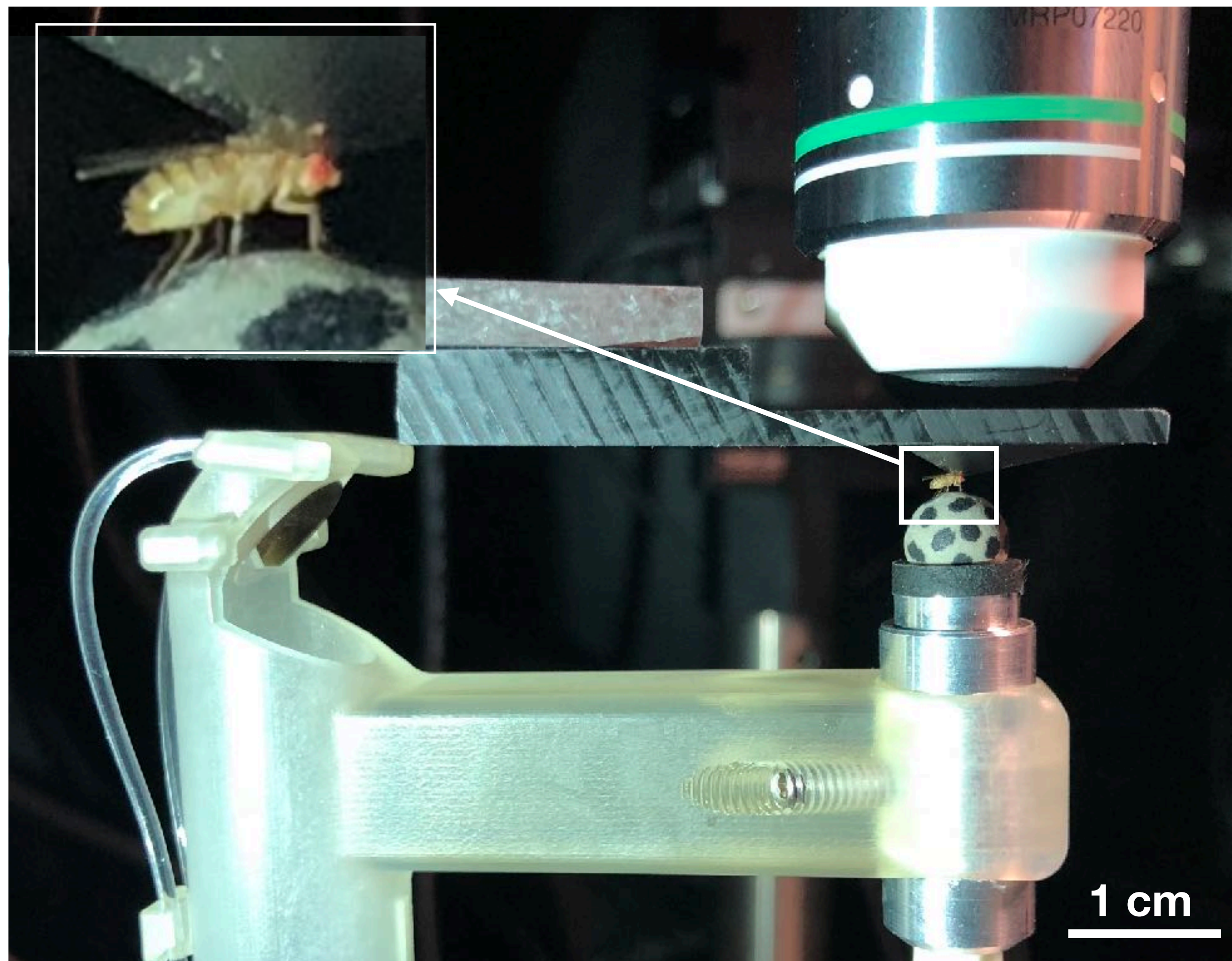


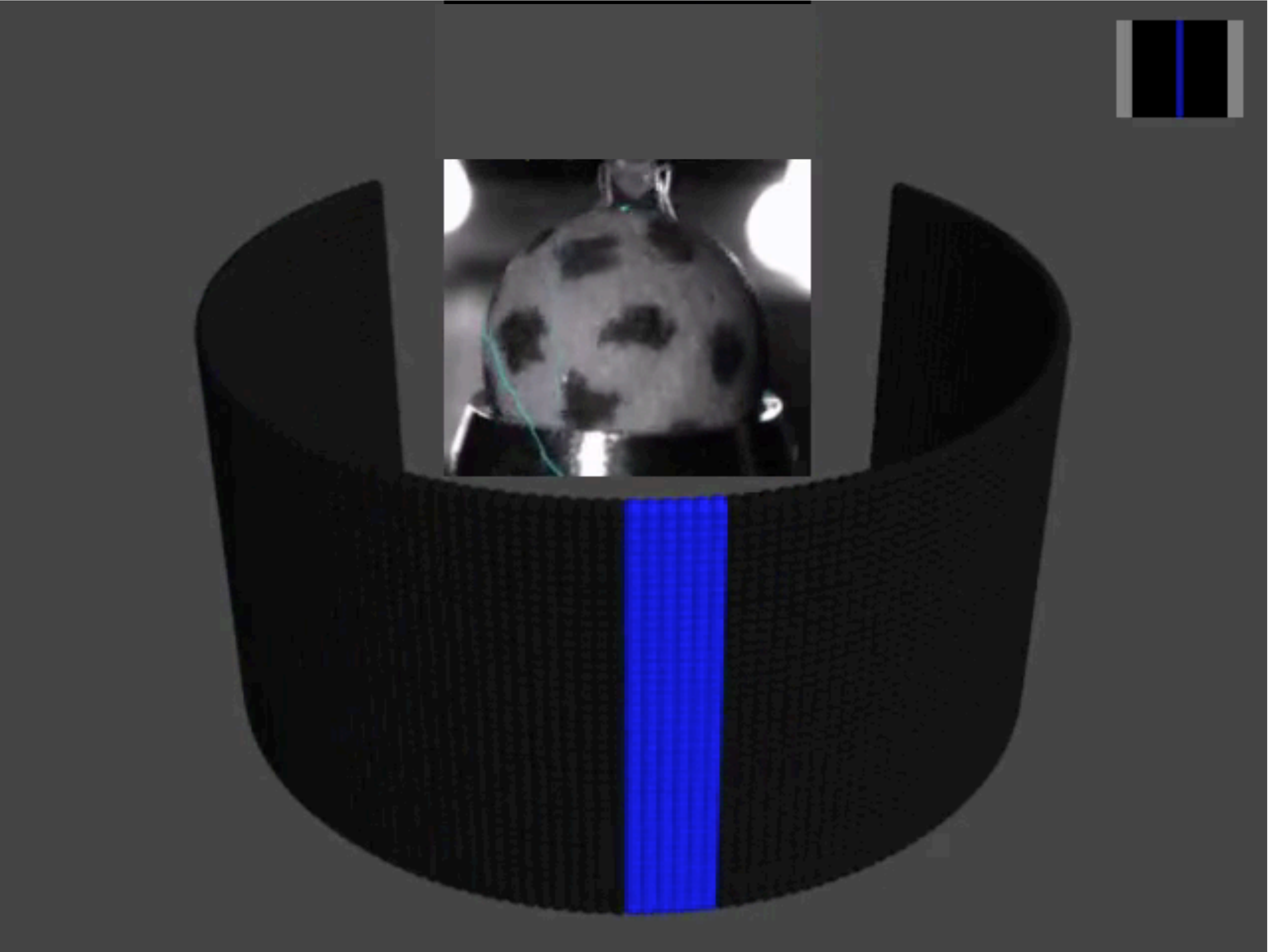


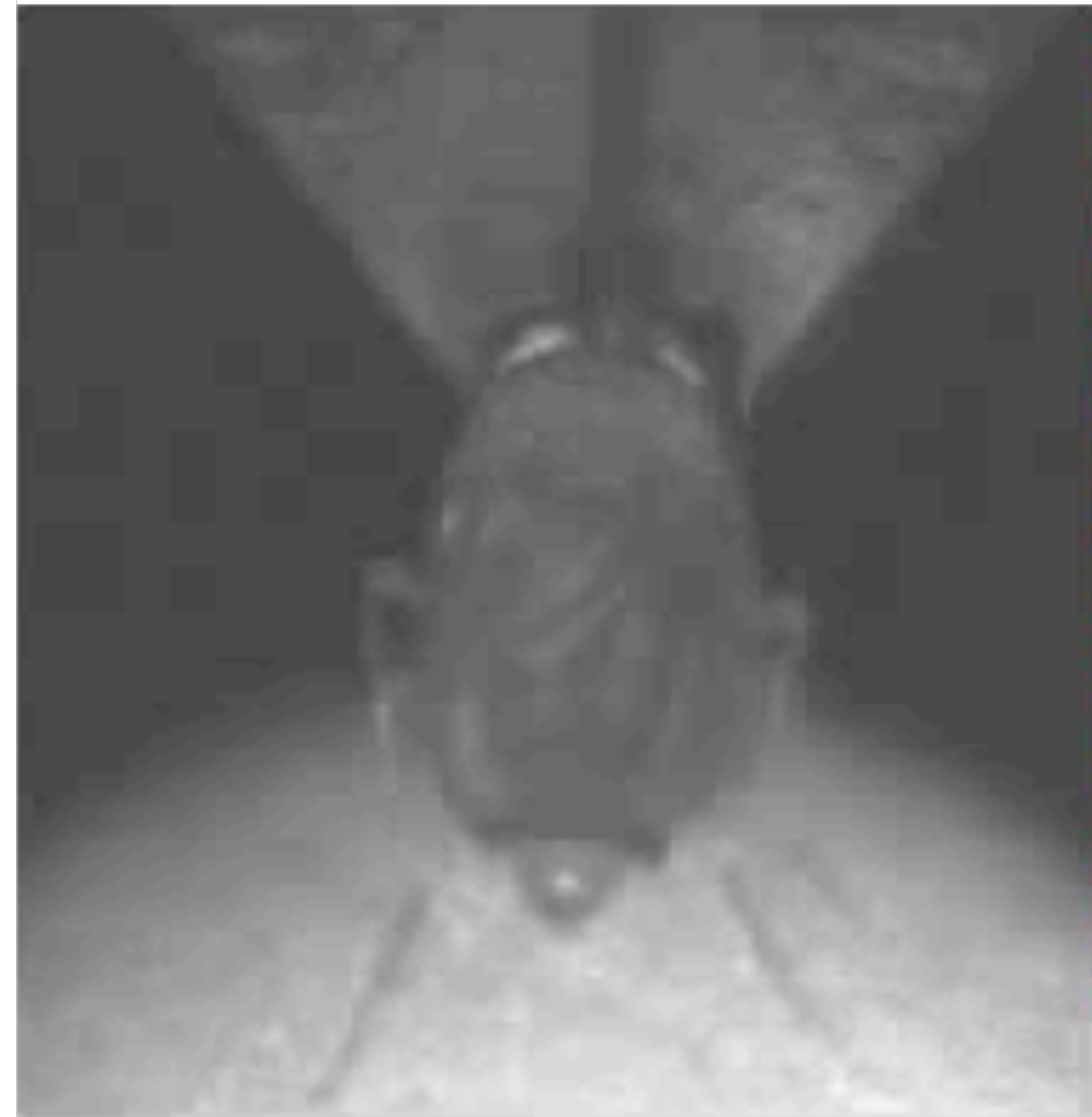
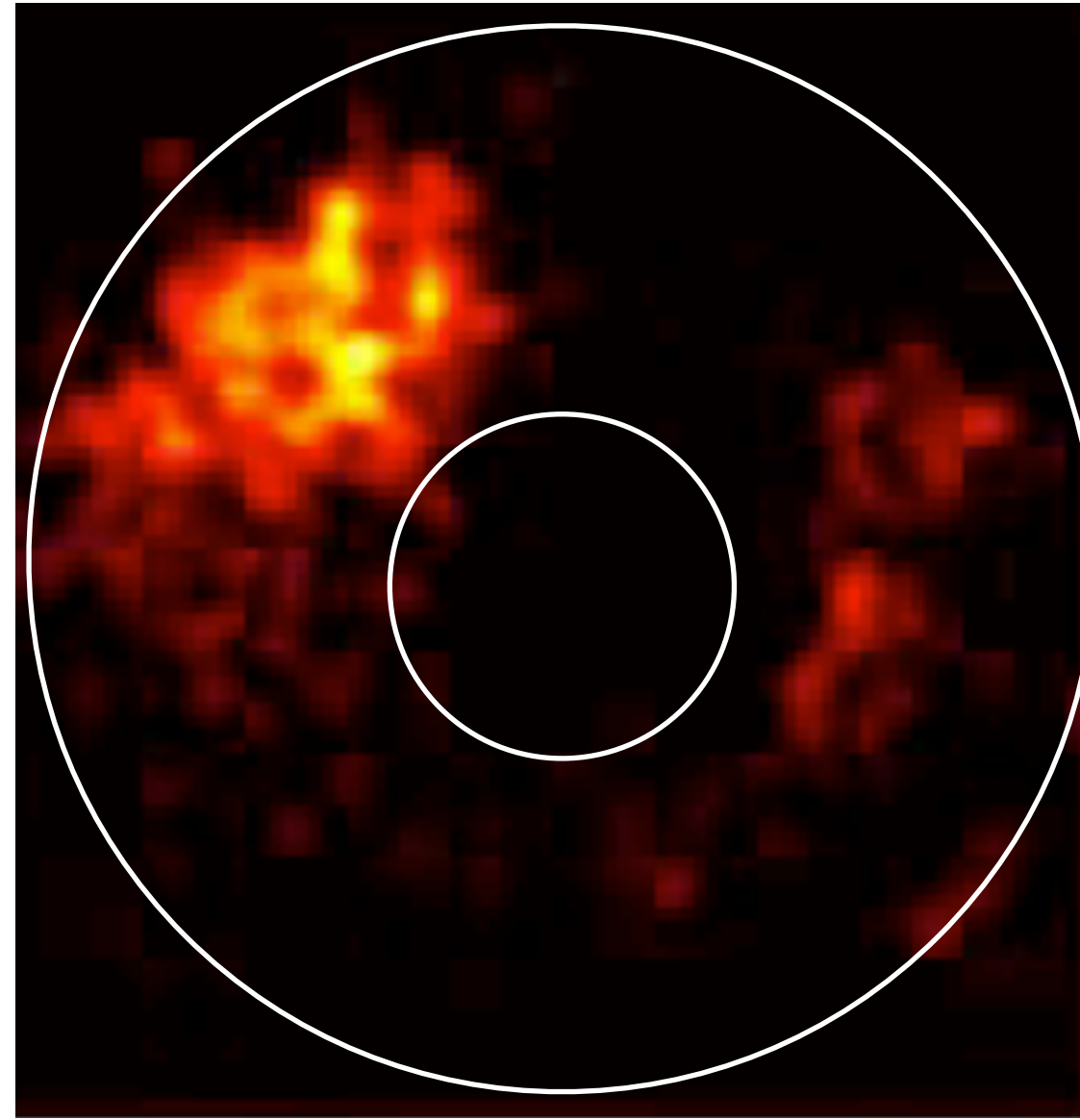
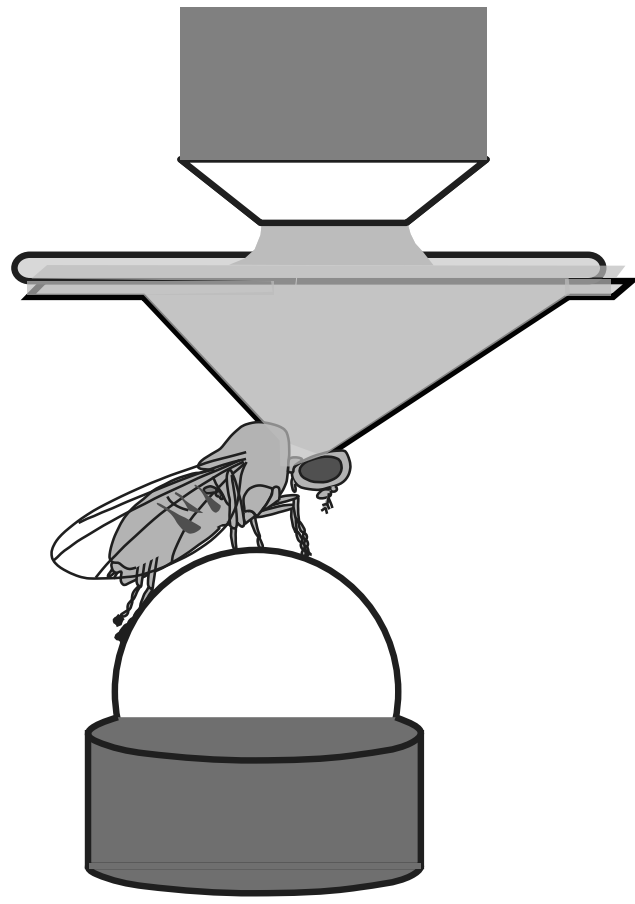
**ellipsoid
body**

H

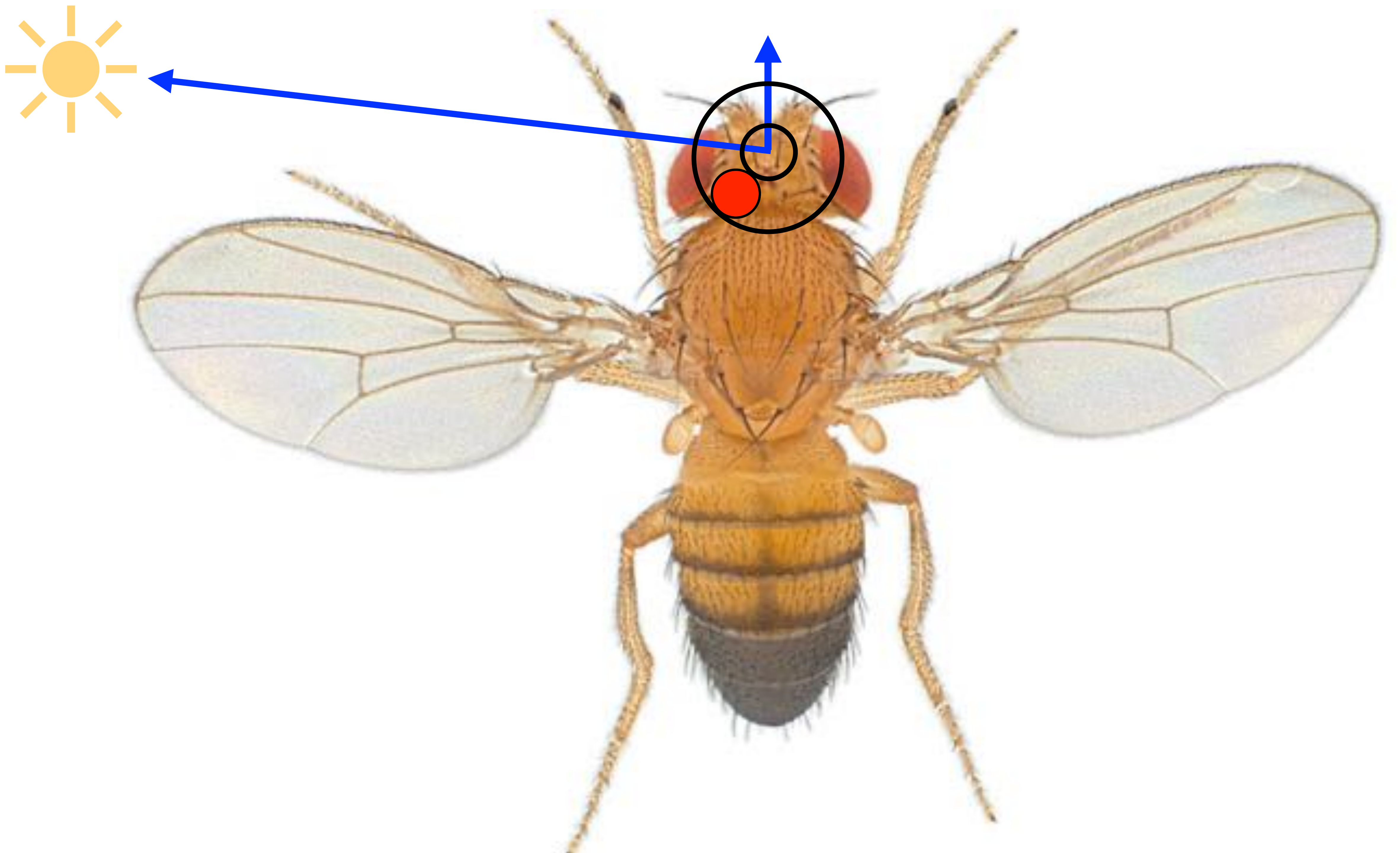


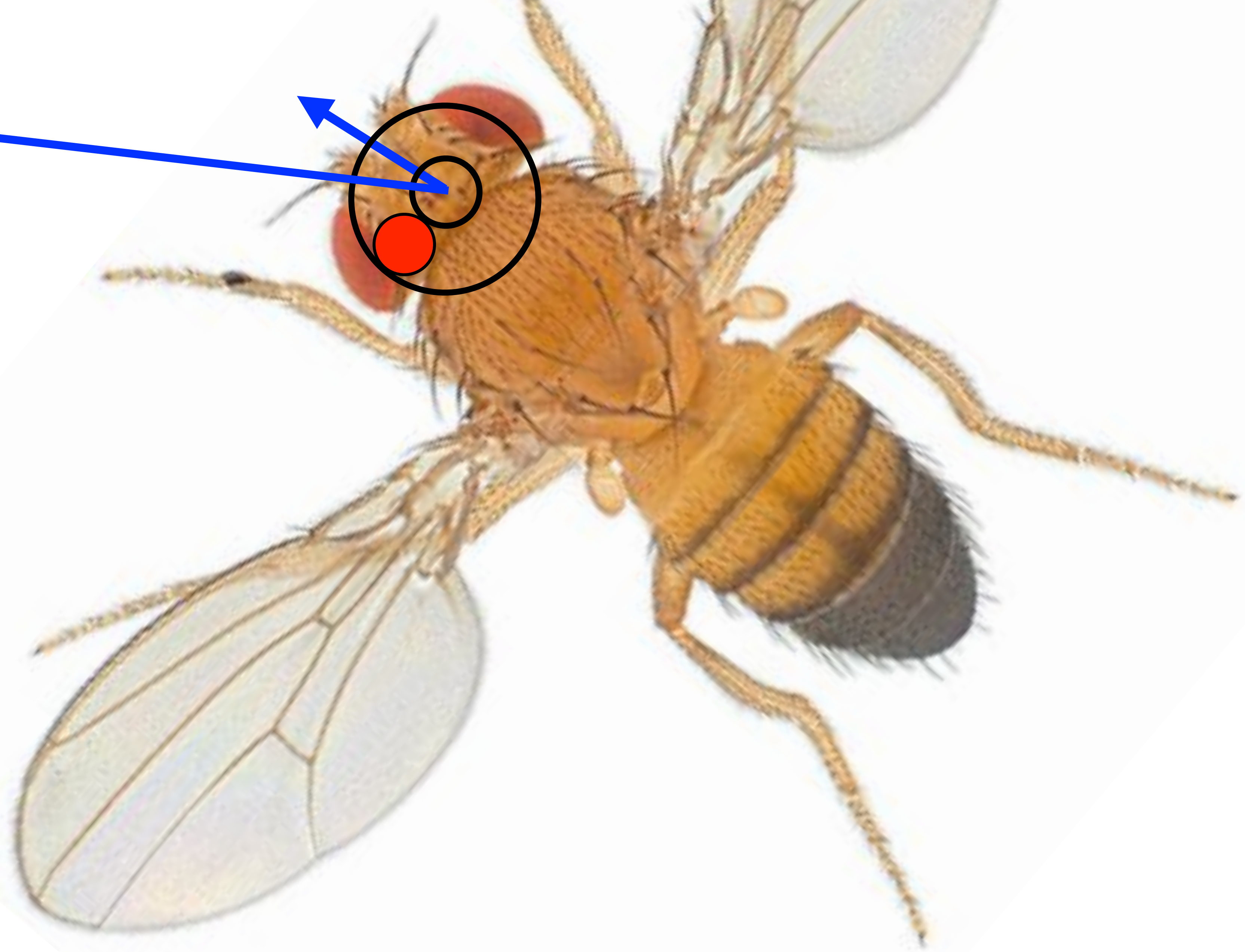
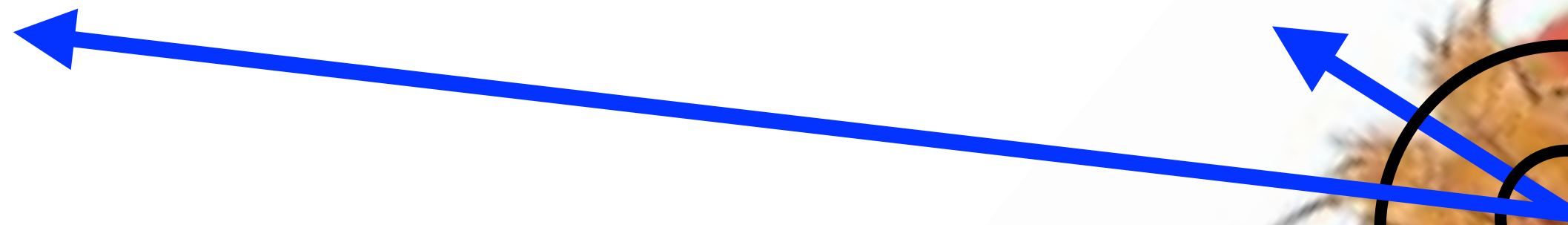
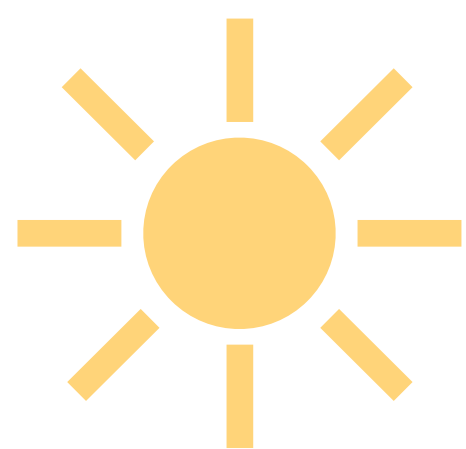


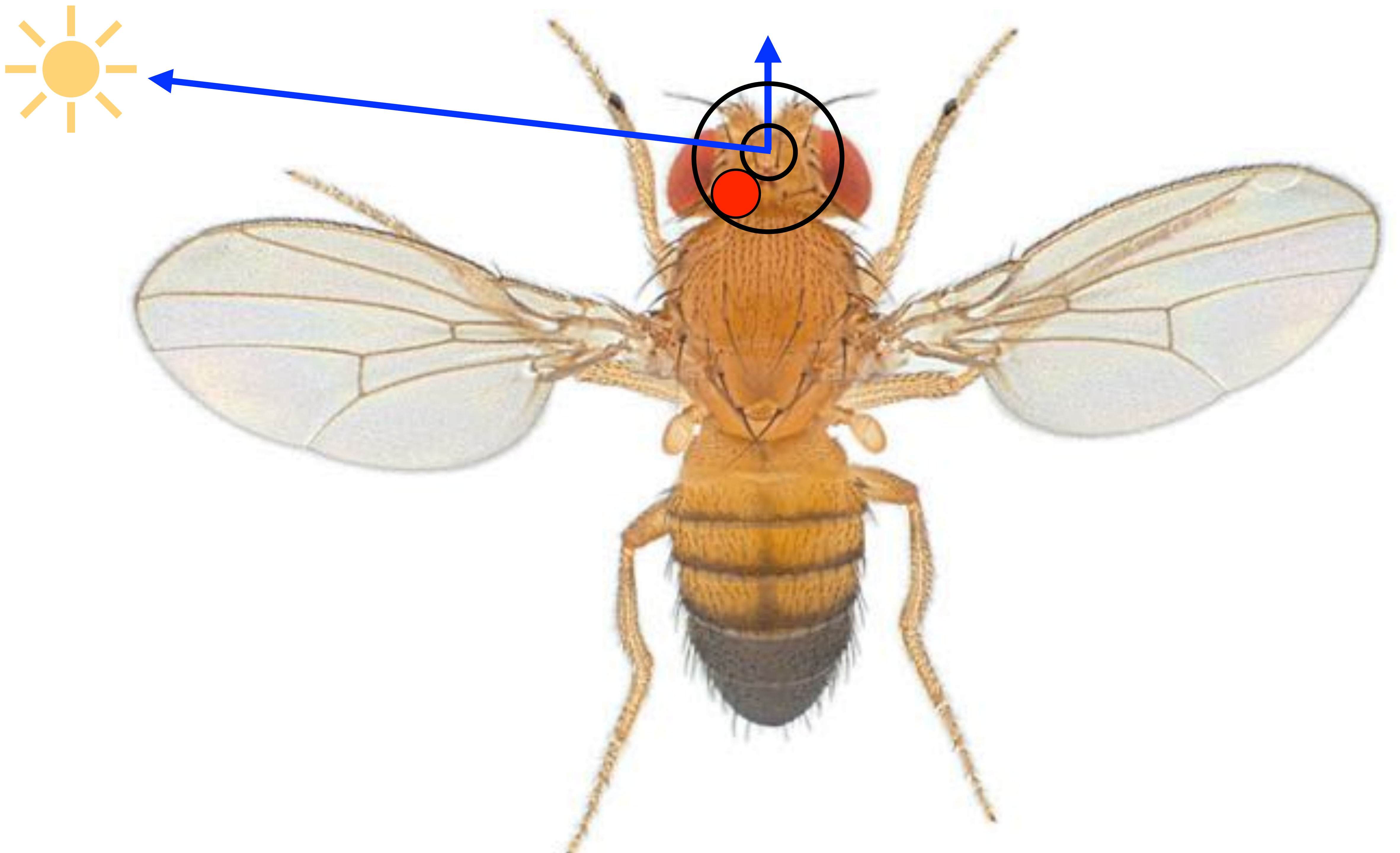




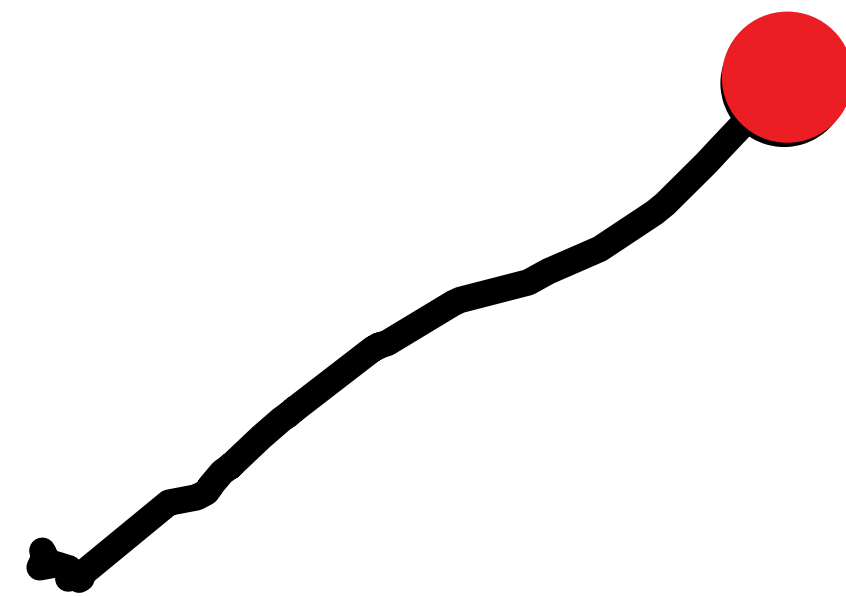
Seelig, Jayaraman (2015)



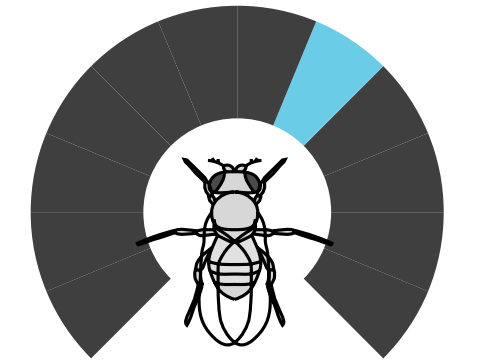
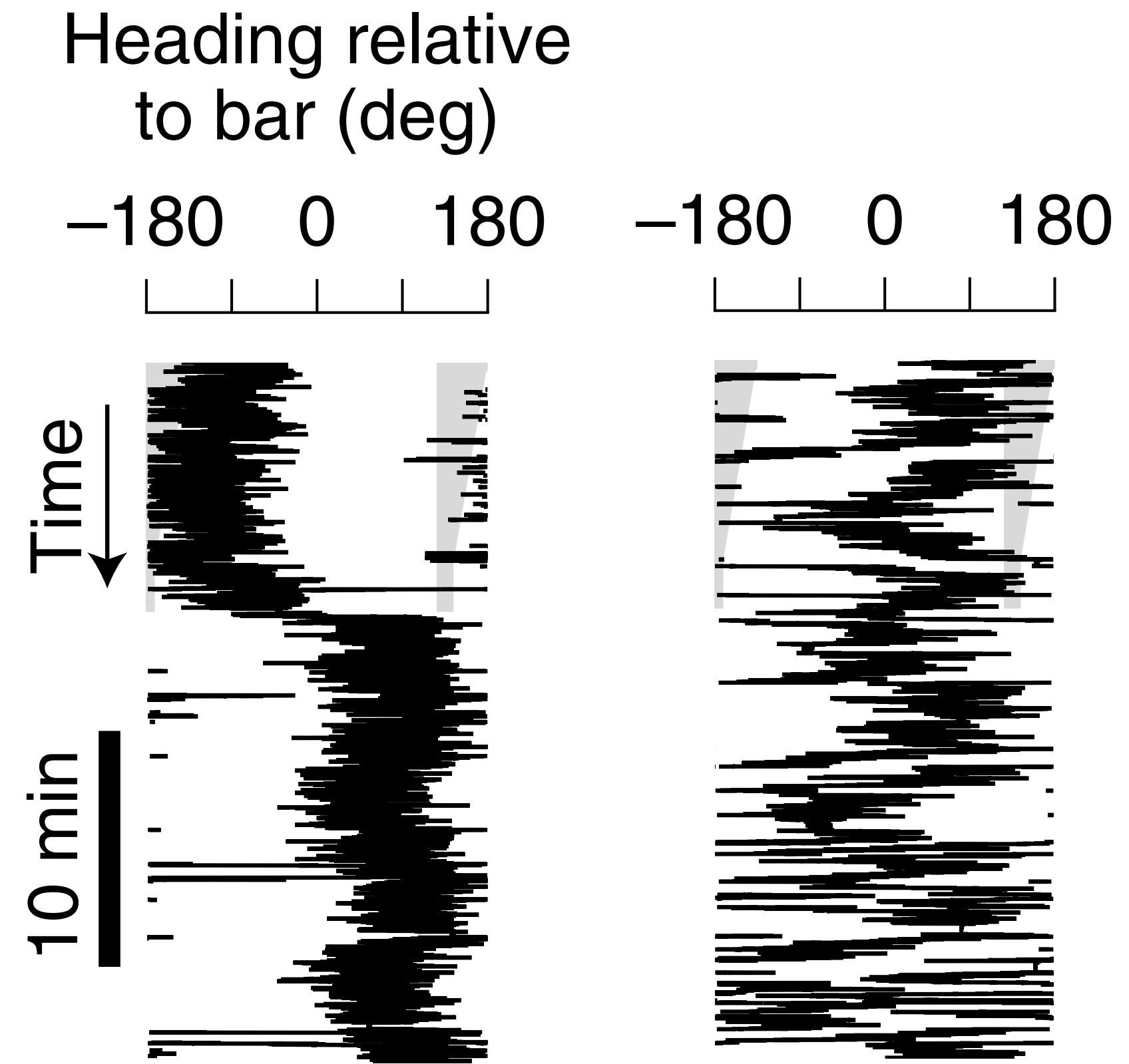




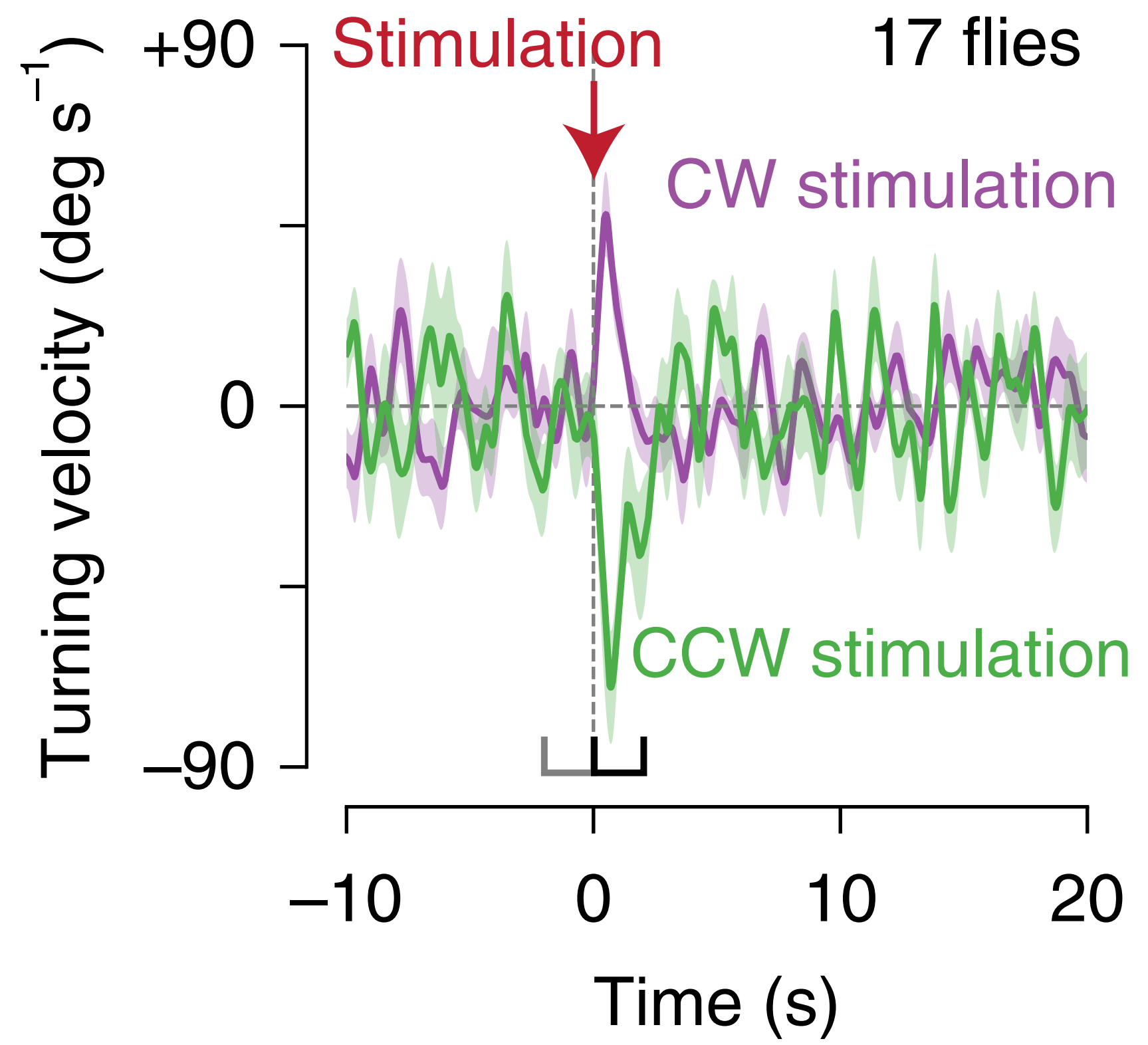
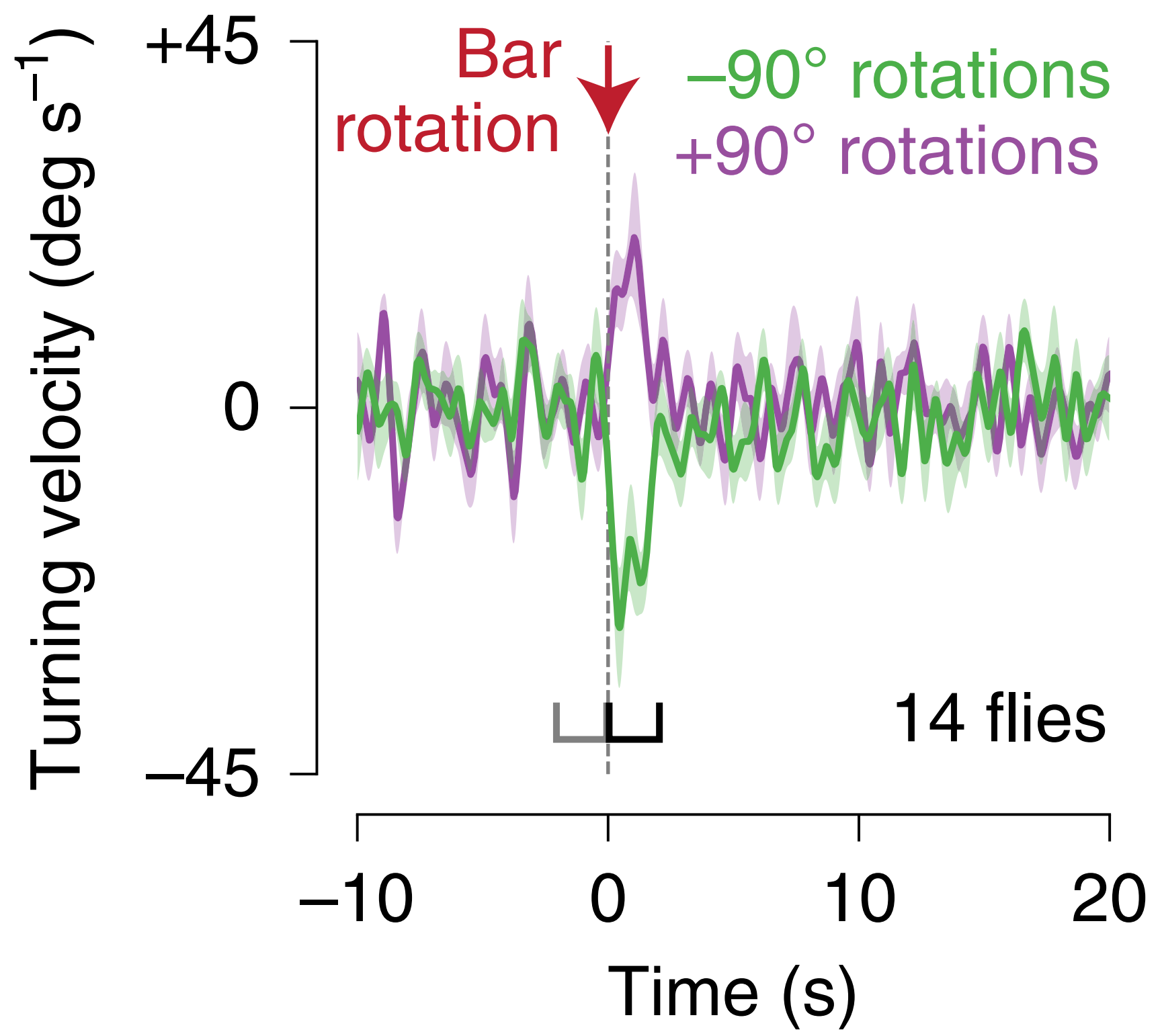
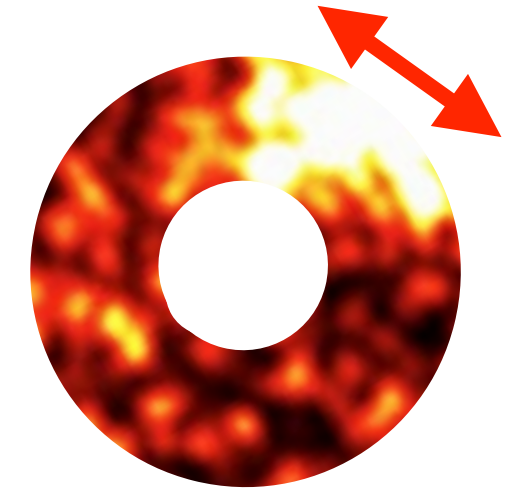
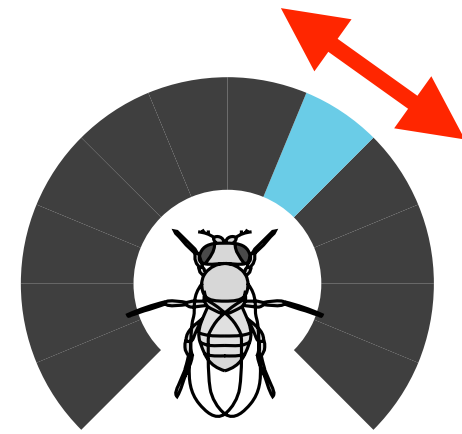
60 minutes

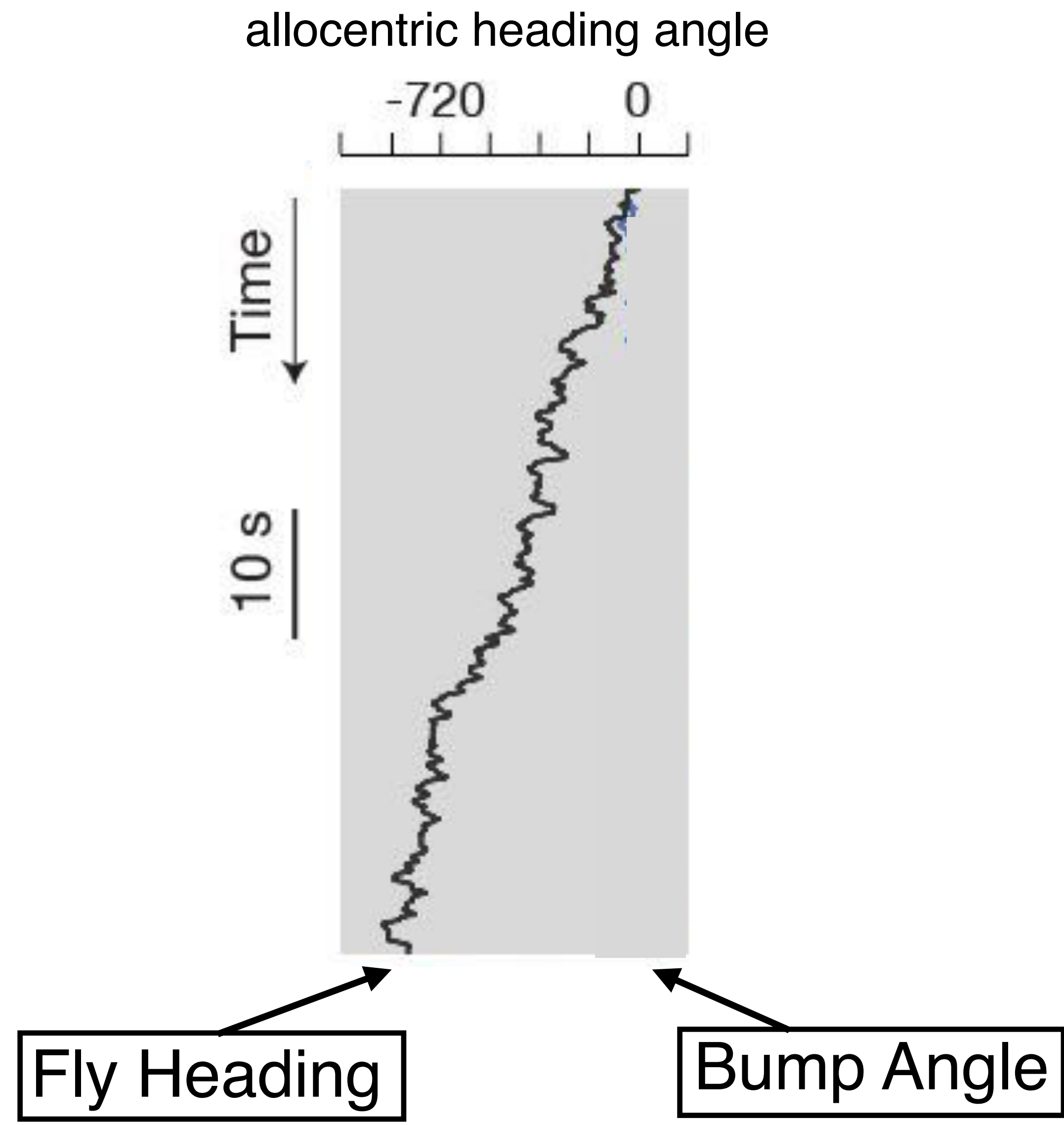


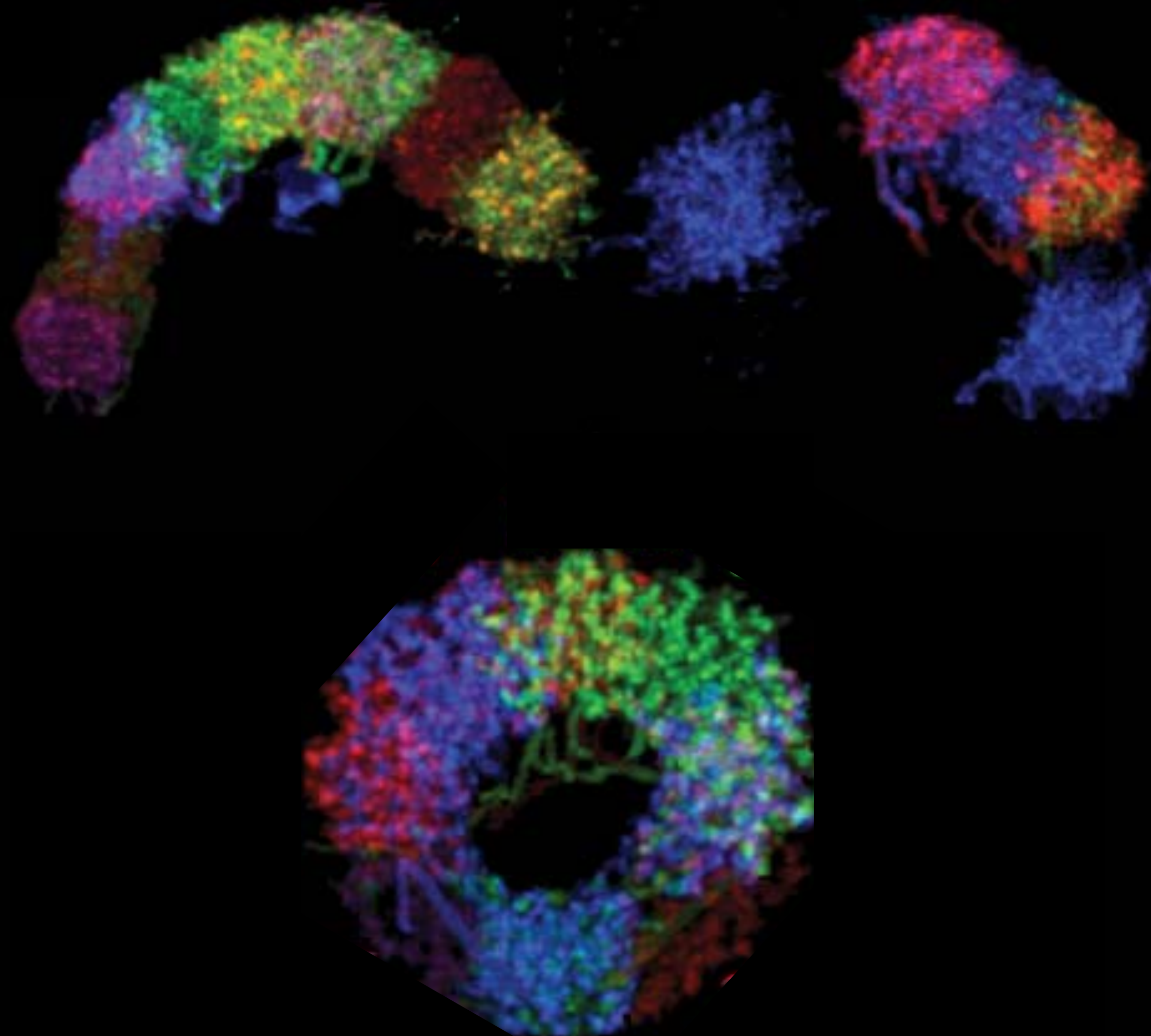
1 m



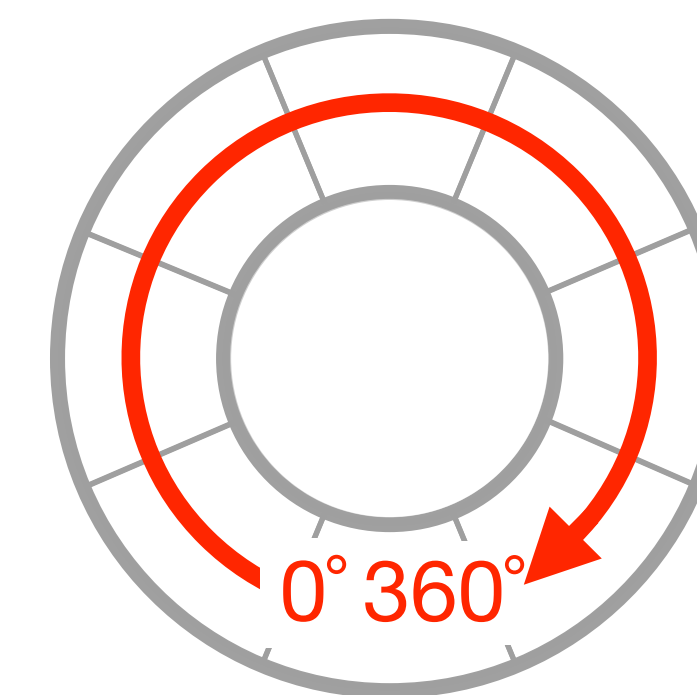
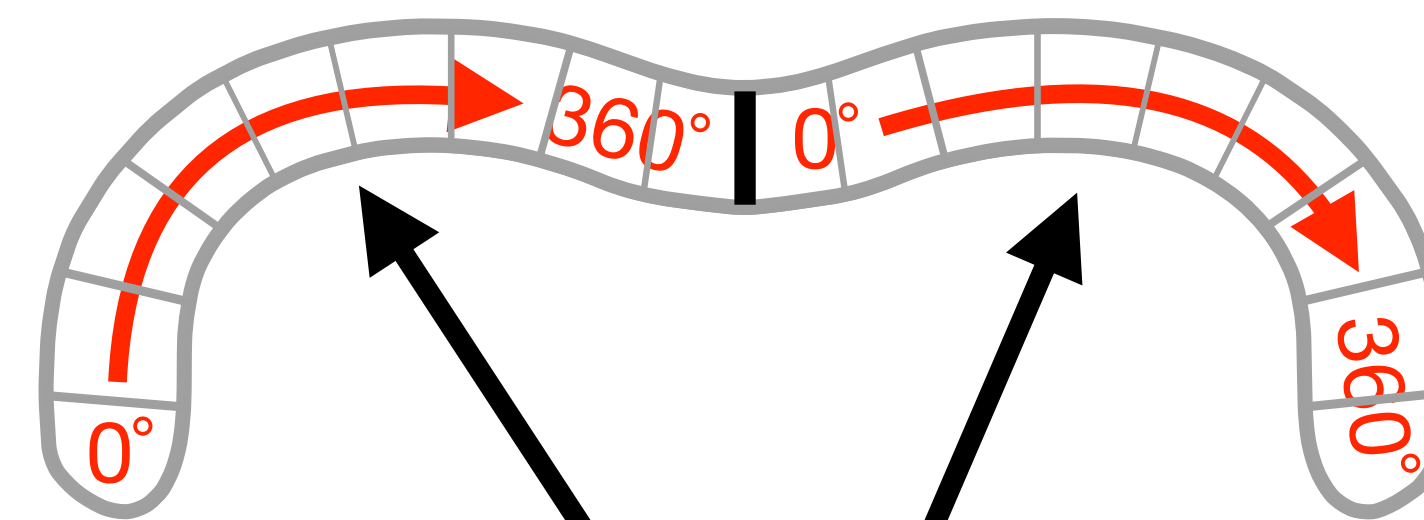
Closed loop bar



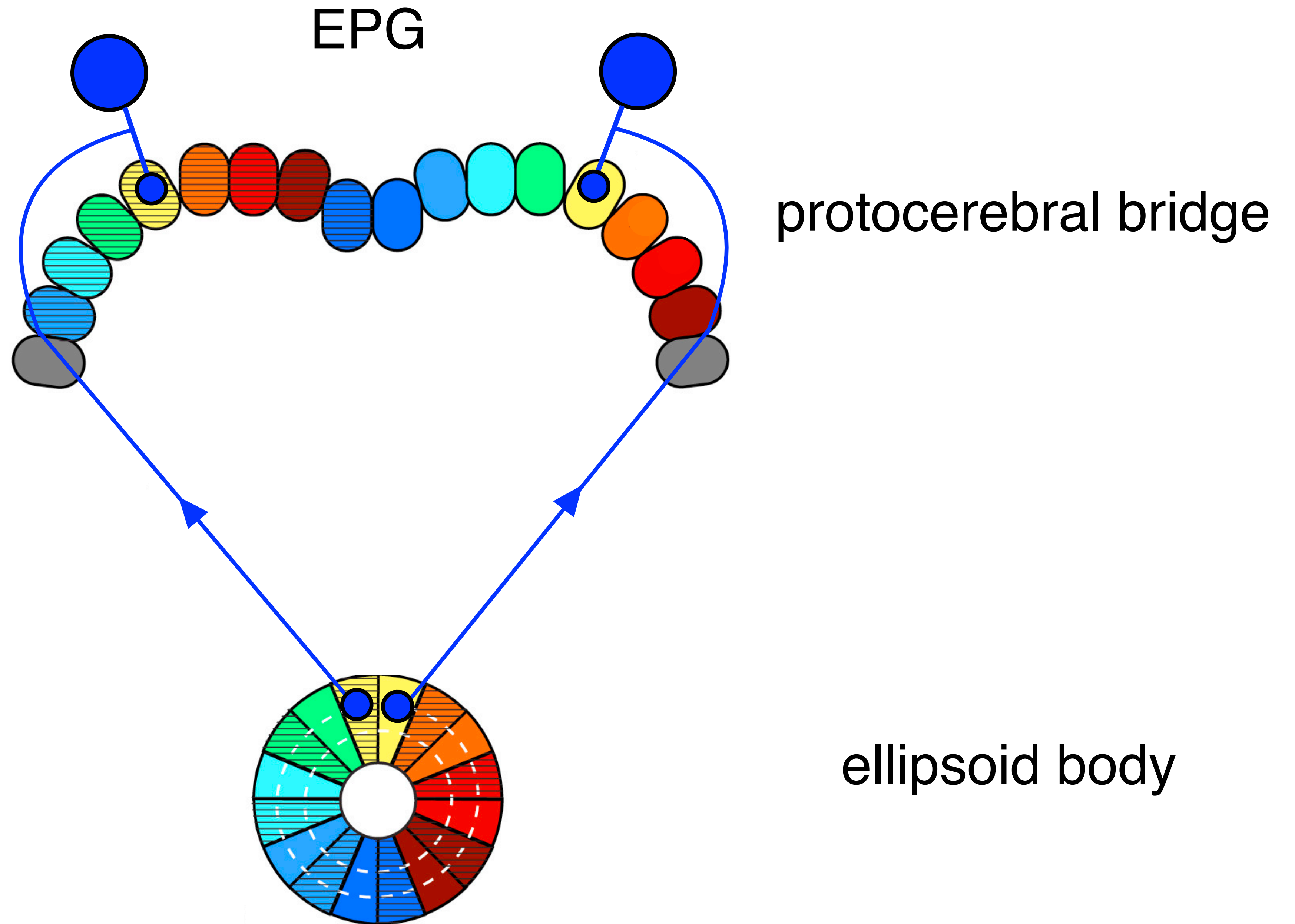




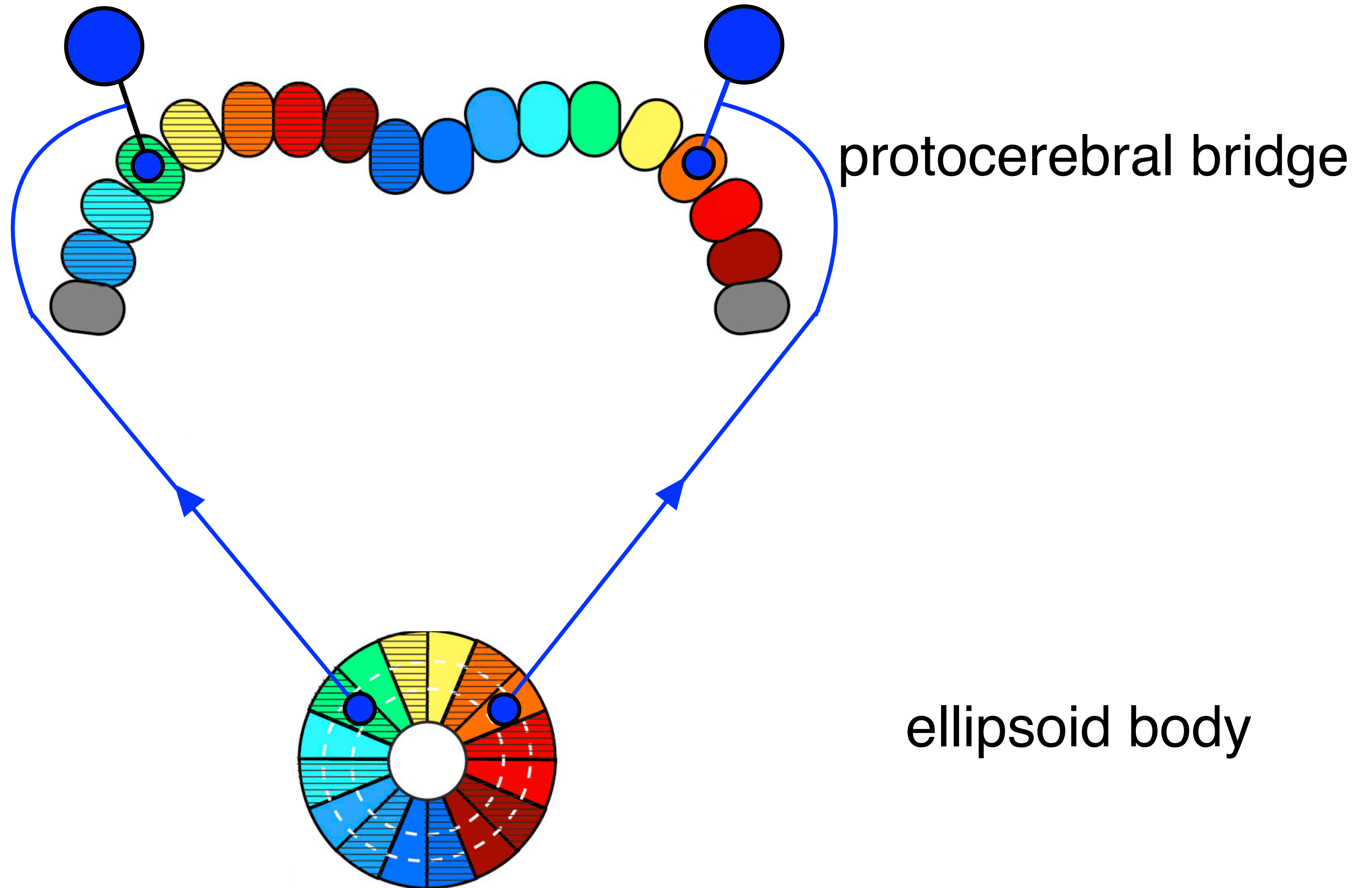
protocerebral bridge



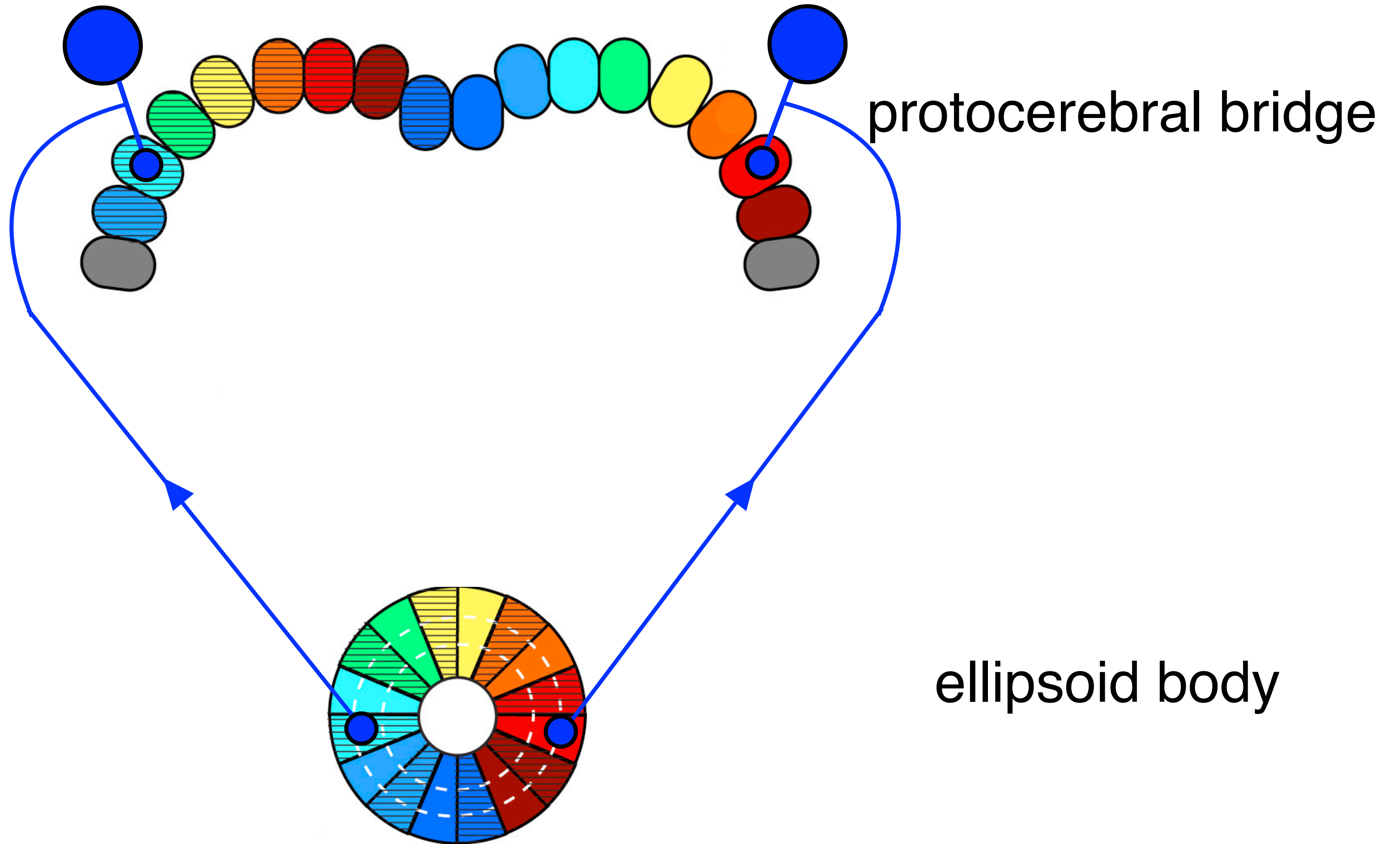
**ellipsoid
body**

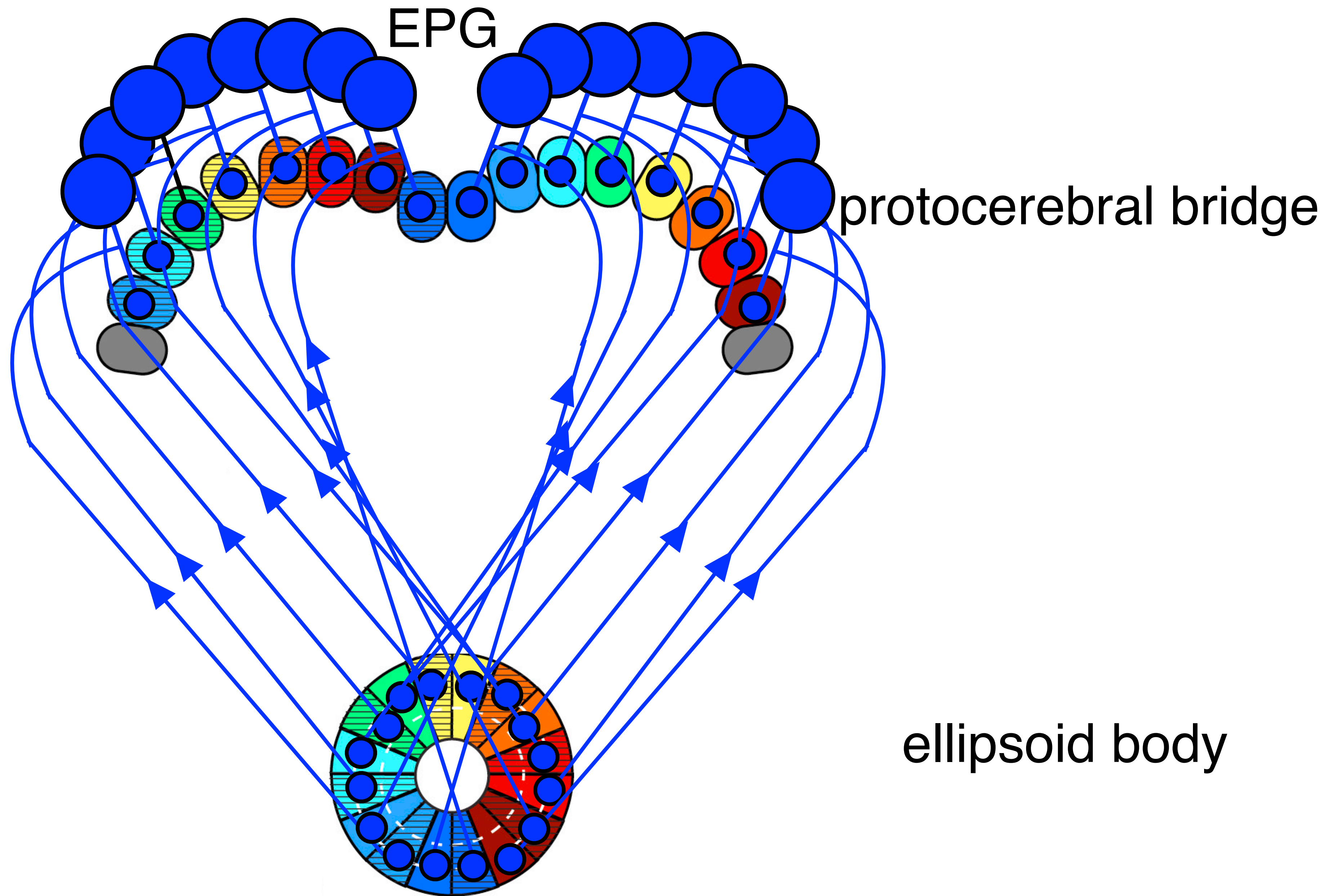


EPG

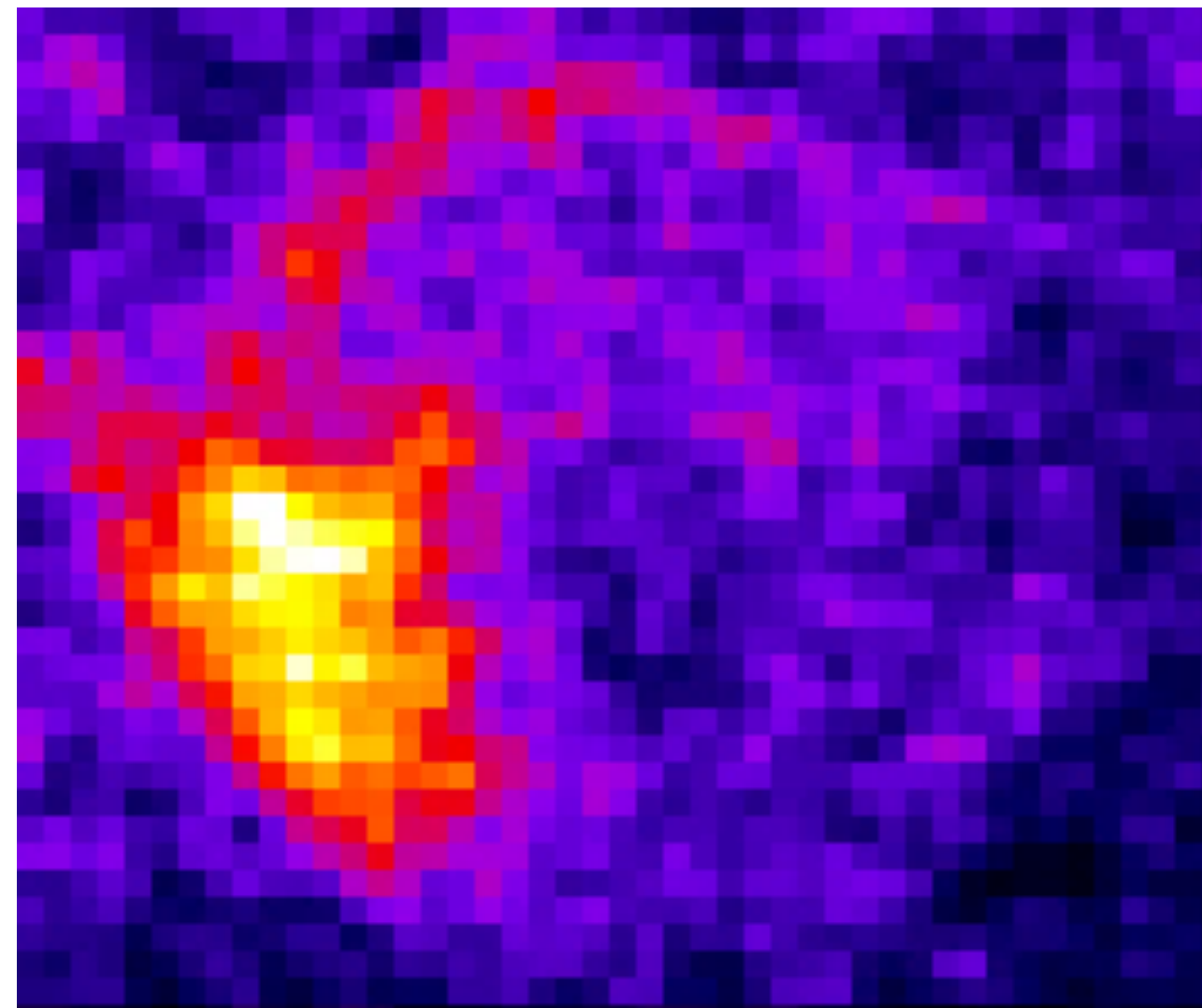
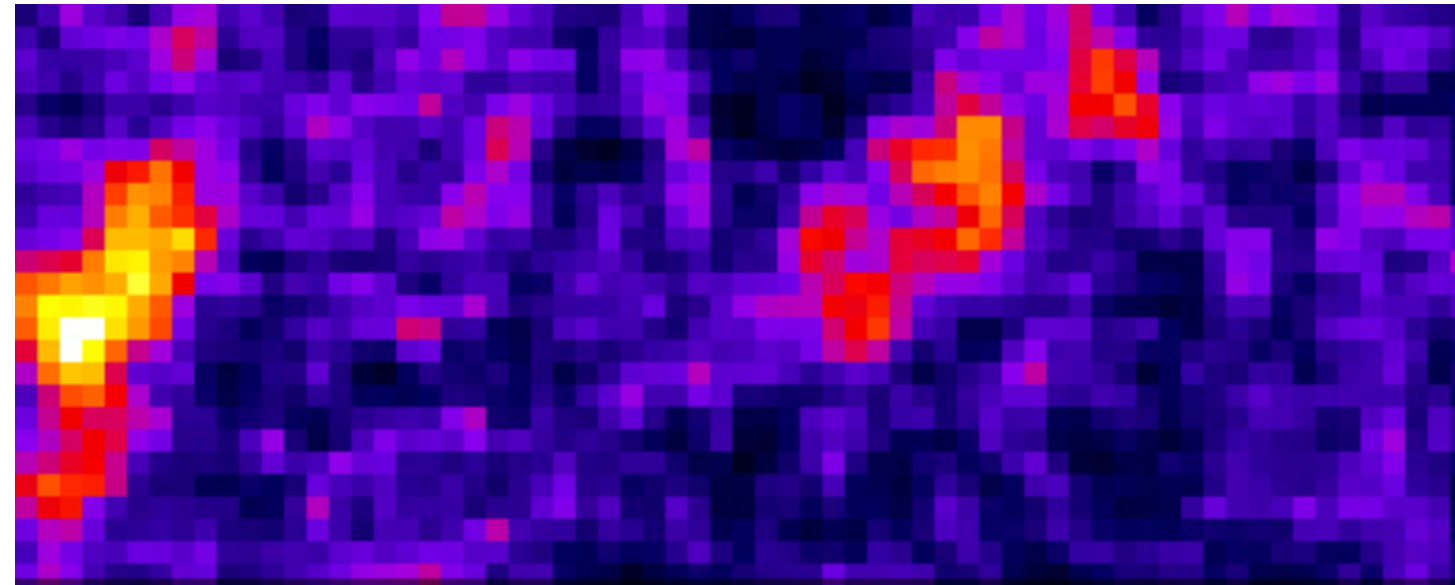


EPG

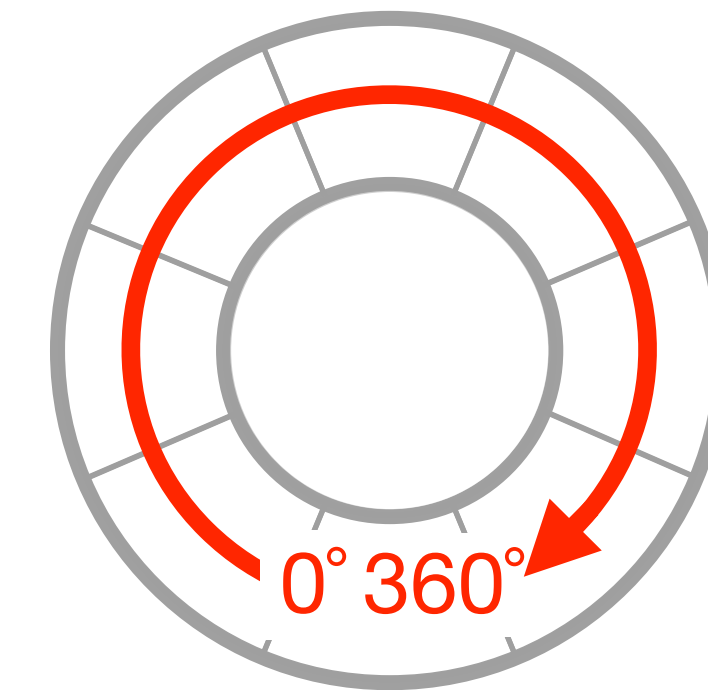
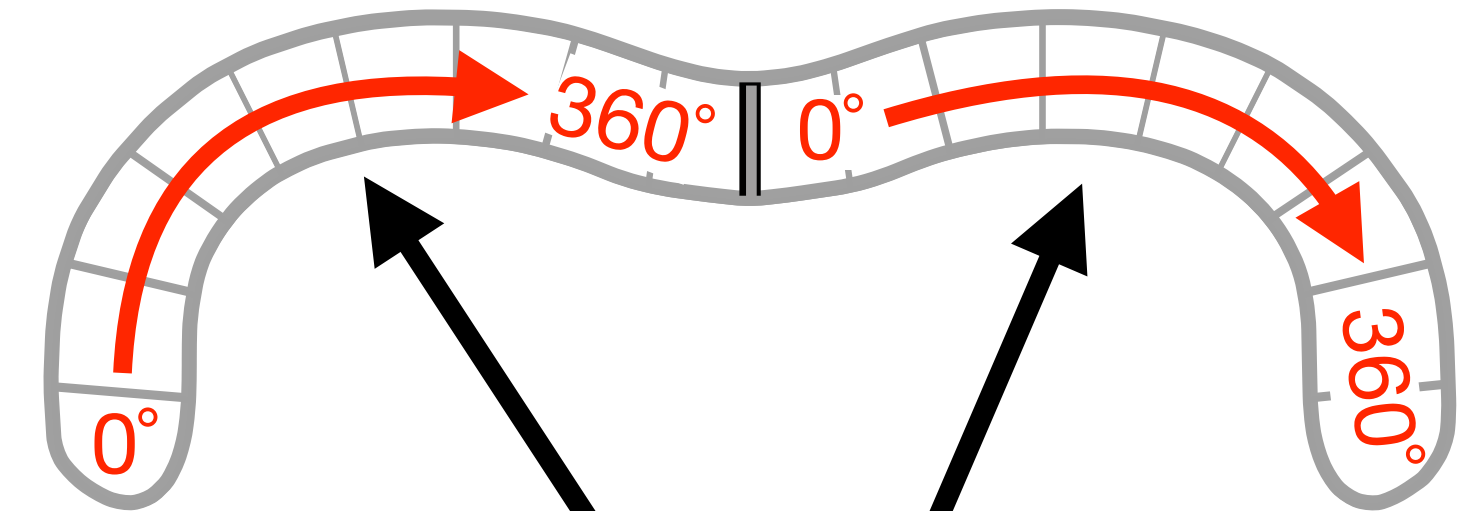




EPG



protocerebral bridge

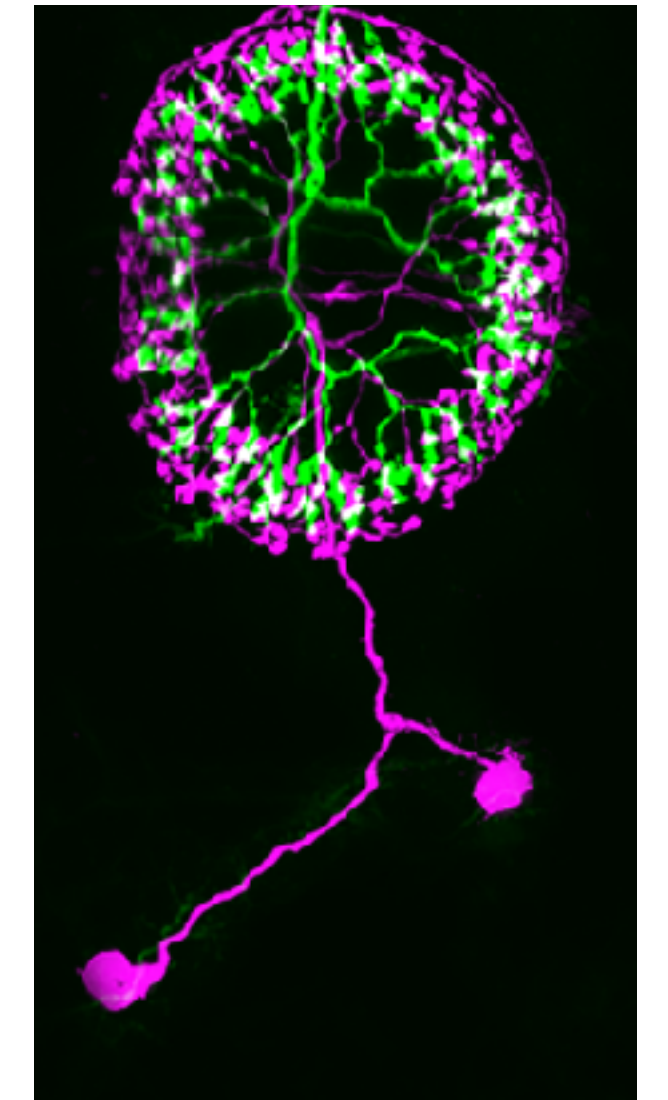
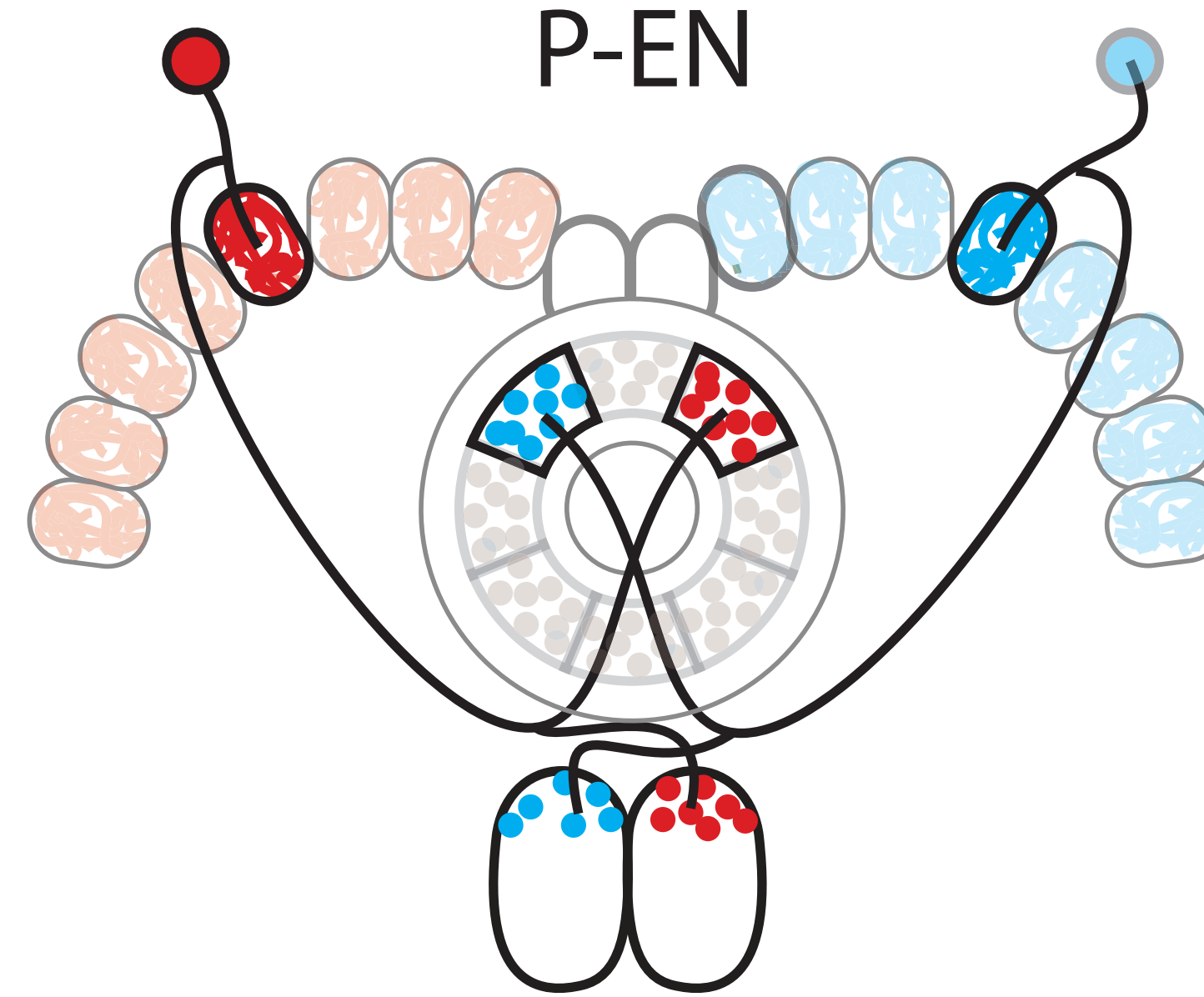
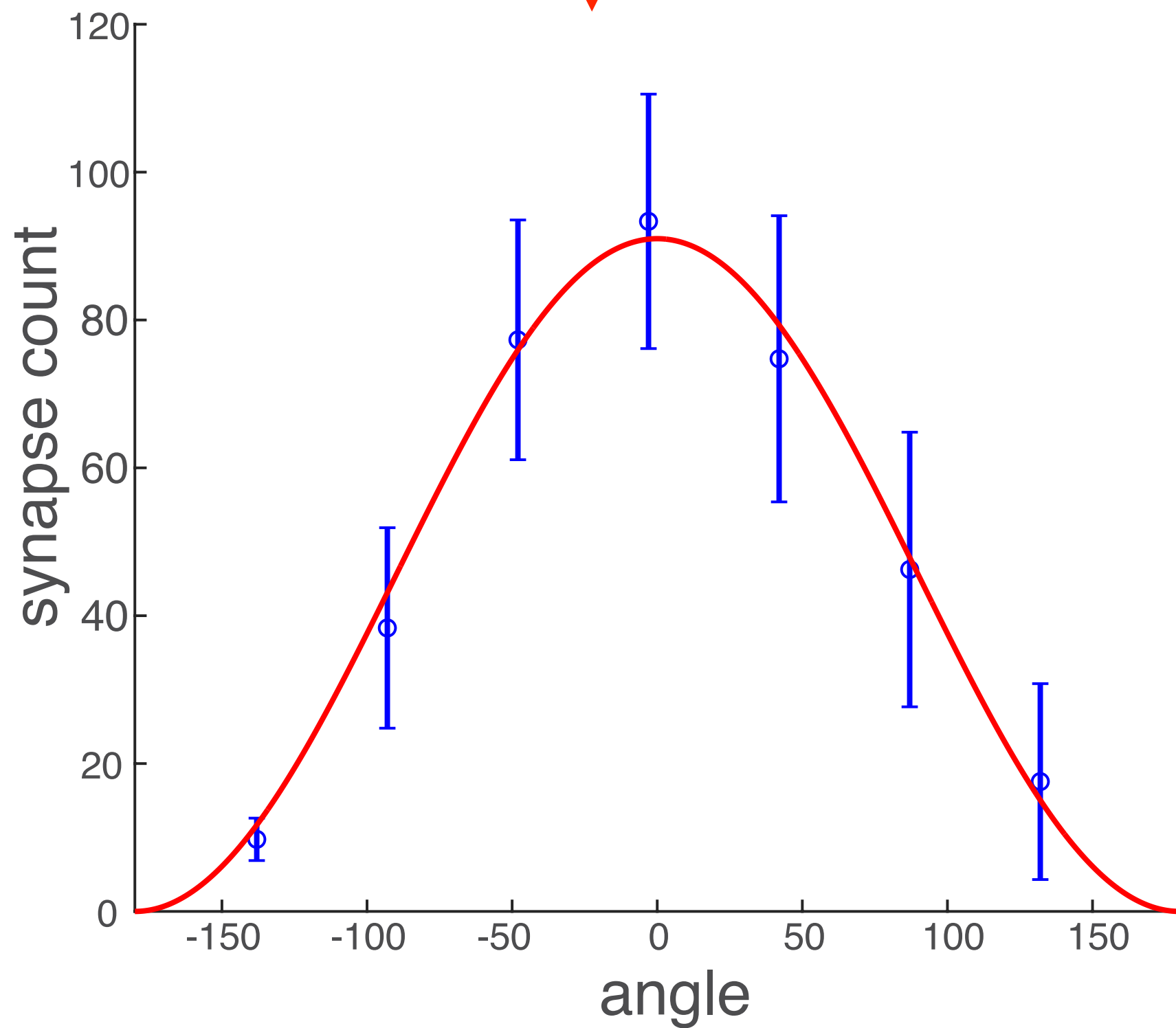


**ellipsoid
body**

Cheng Lyu

Green, Adachi, Shah, Hirokawa,
Magani, Maimon (2017)

$$\tau \frac{dr_i}{dt} = -r_i + F\left(\sum_{j=1}^N \left(\boxed{J_0 + J_i \cos(\theta_i - \theta_j)} + \boxed{L \cos(\theta_i - \theta_j + \pi/4) + R \cos(\theta_i - \theta_j - \pi/4)} \right) r_j + \boxed{I \cos(V - \theta_i)}\right)$$



Turner-Evans, Wegener, Rouault, Franconville,
Wolff, Seelig, Druckmann, Jayaraman (2017)

Green, Adachi, Shah, Hirokawa, Magani, Maimon (2017)

Kim, Hermundstad, Romani,
Abbott, Jayaraman (2019)

Ben-Yishai, Bar-Or, Sompolinsky (1995); Skaggs, Knierim, Kudrimoti, McNaughton (1995); Zhang (1996);

Kim, Rouault, Druckmann, Jayaraman (2017); Kakaria, de Bivort (2017); Cope, Sabo, Vasilaki, Barron, Marshall (2017)

$$\tau \frac{dr_i}{dt} = -r_i + F\left(\sum_{j=1}^N \left(J_0 + J_1 \cos(\theta_i - \theta_j)\right) r_j\right)$$

$$\tau \frac{dr_i}{dt} = -r_i + F\left(\sum_{j=1}^N \left(J_0 + J_1 \cos(\theta_i - \theta_j) + L \cos(\theta_i - \theta_j + \pi/4) + R \cos(\theta_i - \theta_j - \pi/4)\right) r_j\right)$$

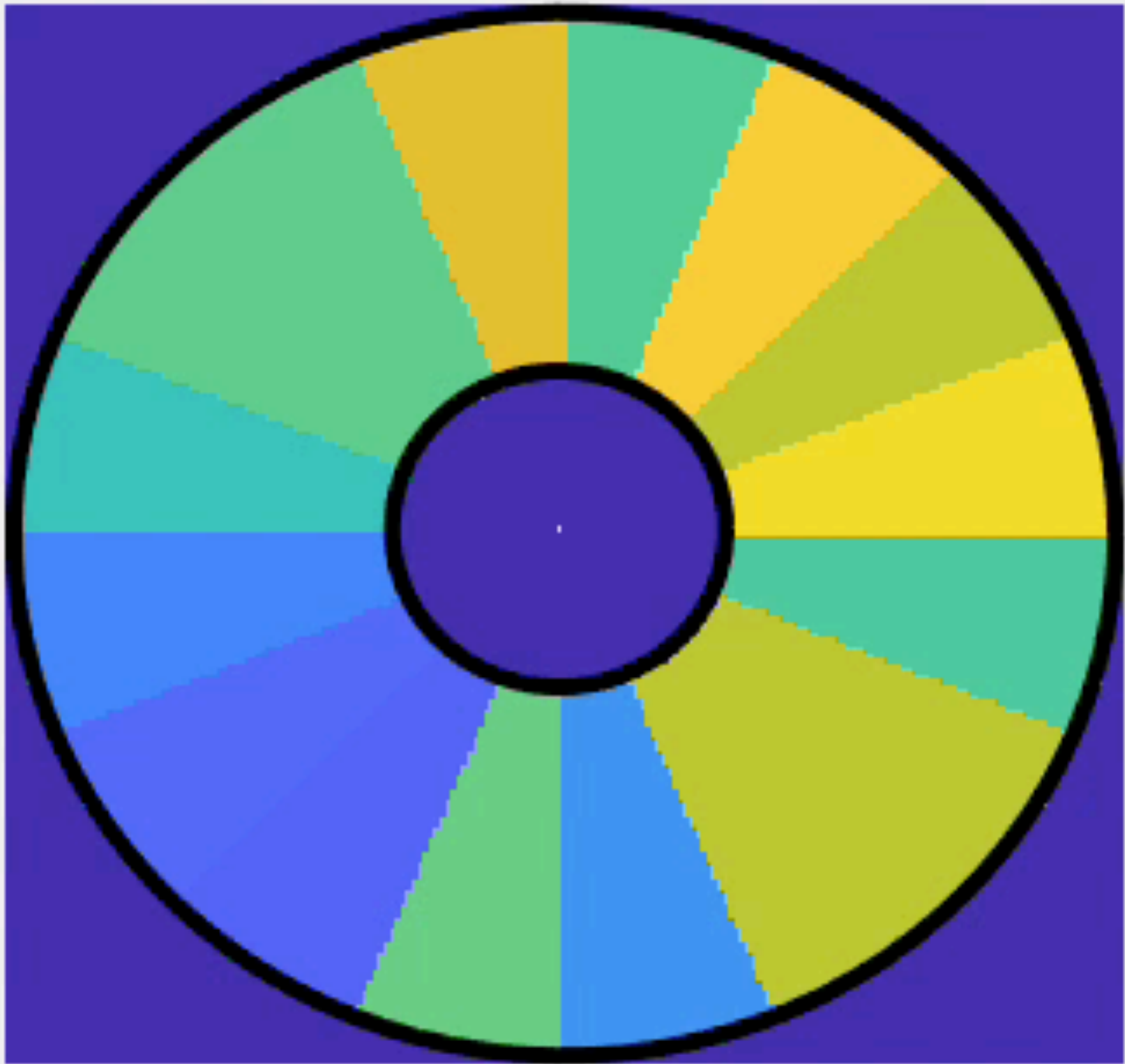
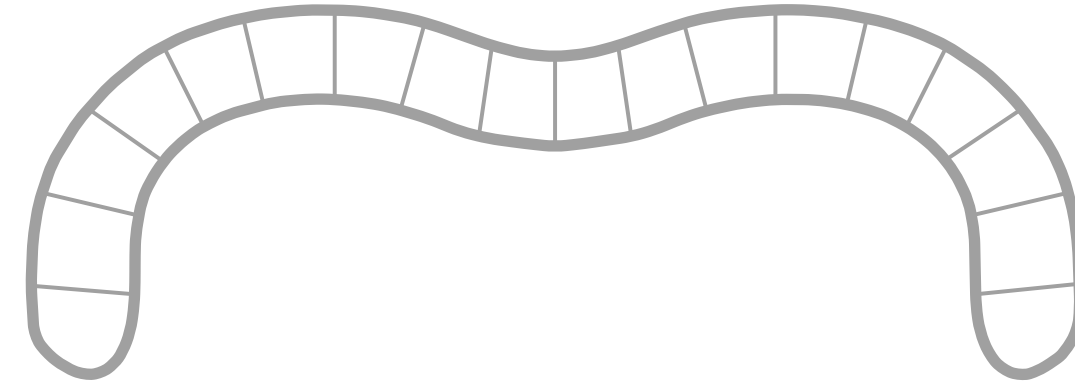
~~$$\tau \frac{dr_i}{dt} = -r_i + F\left(\sum_{j=1}^N \left(J_0 + J_1 \cos(\theta_i - \theta_j) + L \cos(\theta_i - \theta_j + \pi/4) + R \cos(\theta_i - \theta_j - \pi/4)\right) r_j + I \cos(V - \theta_i)\right)$$~~

$$\tau \frac{dr_i}{dt} = -r_i + F\left(\sum_{j=1}^N \left(J_0 + J_1 \cos(\theta_i - \theta_j)\right) r_j + I \cos(V - \theta_i)\right)$$

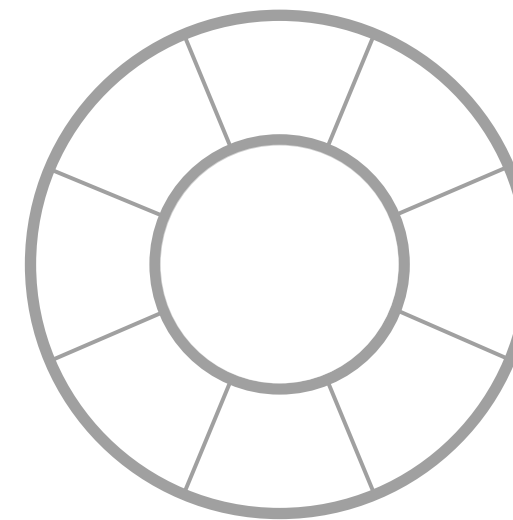
$$\tau \frac{dr_i}{dt} = -r_i + F\left(\sum_{j=1}^N \left(J_0 + J_1 \cos(\theta_i - \theta_j)\right) r_j\right)$$



**protocerebral
bridge**



ellipsoid body



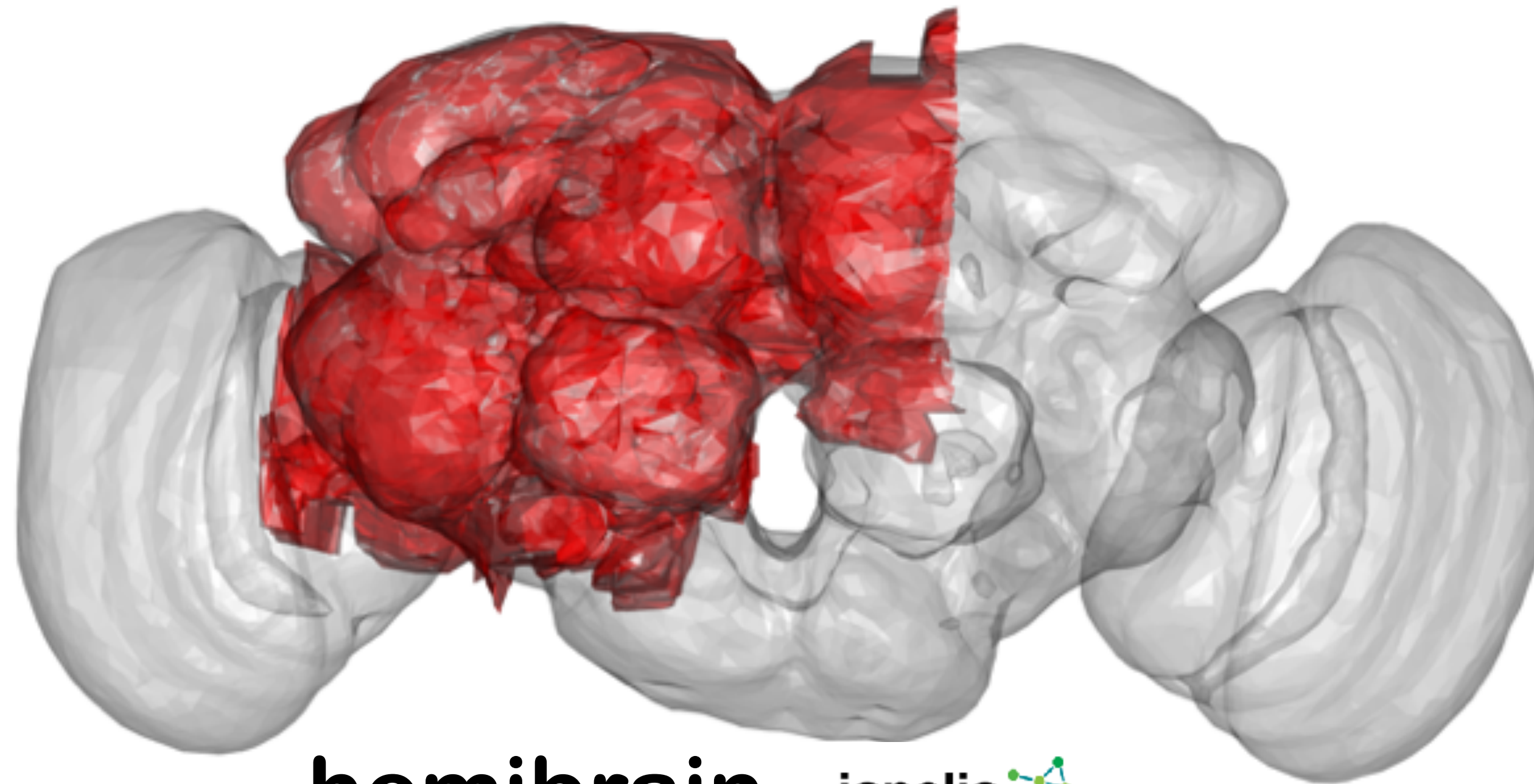
Supporting the Bump

$$J_0 + J_1 \cos(\theta_i - \theta_j)$$



$$\cos(\theta_i - \theta_j) = -\cos(\theta_i - \theta_j - \pi)$$

Complete Fly Brain EM Connectome



hemibrain

janelia
flyEM

Google

<https://neuprint.janelia.org/>

Turner-Evans, Jensen, Ali, Paterson, Sheridan, Ray, Lauritzen, Bock, Jayaraman (2019)

A Connectome of the Adult *Drosophila* Central Brain

C. Shan Xu, Michal Januszewski, Zhiyuan Lu, Shin-ya Takemura, Kenneth J. Hayworth, Gary Huang, Kazunori Shinomiya, Jeremy Maitin-Shepard, David Ackerman, Stuart Berg, Tim Blakely, John Bogovic, Jody Clements, Tom Dolafi, Philip Hubbard, Dagmar Kainmueller, William Katz, Takashi Kawase, Khaled A. Khairy, Laramie Leavitt, Peter H. Li, Larry Lindsey, Nicole Neubarth, Donald J. Olbris, Hideo Otsuna, Eric T. Troutman, Lowell Umayam, Ting Zhao, Masayoshi Ito, Jens Goldammer, Tanya Wolff, Robert Svirskas, Philipp Schlegel, Erika R. Neace, Christopher J. Knecht Jr., Chelsea X. Alvarado, Dennis A. Bailey, Samantha Ballinger, Jolanta A Borycz, Brandon S. Canino, Natasha Cheatham, Michael Cook, Marisa Dreher, Octave Duclos, Bryon Eubanks, Kelli Fairbanks, Samantha Finley, Nora Forknall, Audrey Francis, Gary Patrick Hopkins, Emily M. Joyce, SungJin Kim, Nicole A. Kirk, Julie Kovalyak, Shirley A. Lauchie, Alanna Lohff, Charli Maldonado, Emily A. Manley, Sari McLin, Caroline Mooney, Miatta Ndama, Omotara Ogundeyi, Nneoma Okeoma, Christopher Ordish, Nicholas Padilla, Christopher Patrick, Tyler Paterson, Elliott E. Phillips, Emily M. Phillips, Neha Rampally, Caitlin Ribeiro, Madelaine K Robertson, Jon Thomson Rymer, Sean M. Ryan, Megan Sammons, Anne K. Scott, Ashley L. Scott, Aya Shinomiya, Claire Smith, Kelsey Smith, Natalie L. Smith, Margaret A. Sobeski, Alia Suleiman, Jackie Swift, Satoko Takemura, Iris Talebi, Dorota Tarnogorska, Emily Tenshaw, Temour Tokhi, John J. Walsh, Tansy Yang, Jane Anne Horne, Feng Li, Ruchi Parekh, Patricia K. Rivlin, Vivek Jayaraman, Kei Ito, Stephan Saalfeld, Reed George, Ian Meinertzhagen, Gerald M. Rubin, Harald F. Hess, Louis K. Scheffer, Viren Jain, Stephen M. Plaza

Hulse* , B.K. , Haberkern* , H., Franconville* , R., Turner-Evans* , D.B., Takemura, S., Wolff, T., Noorman, M., Dreher, M., Dan, C., Parekh, R., Hermundstad, A.M., Rubin, G.M. & Jayaraman, V.

A connectome of the *Drosophila* central complex reveals network motifs suitable for flexible navigation and context-dependent action selection.

$$\cos(\theta_i - \theta_j) = -\cos(\theta_i - \theta_j - \pi)$$

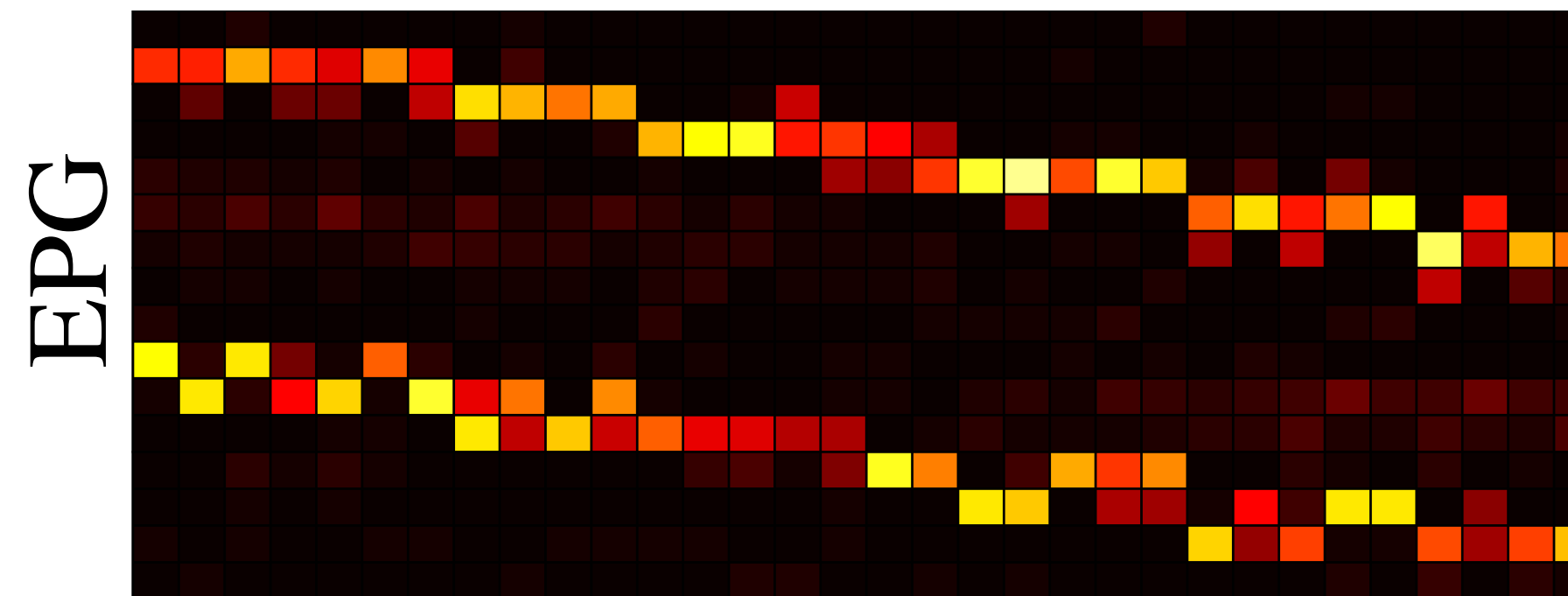


Delta 7

Wolff et al. (2015)

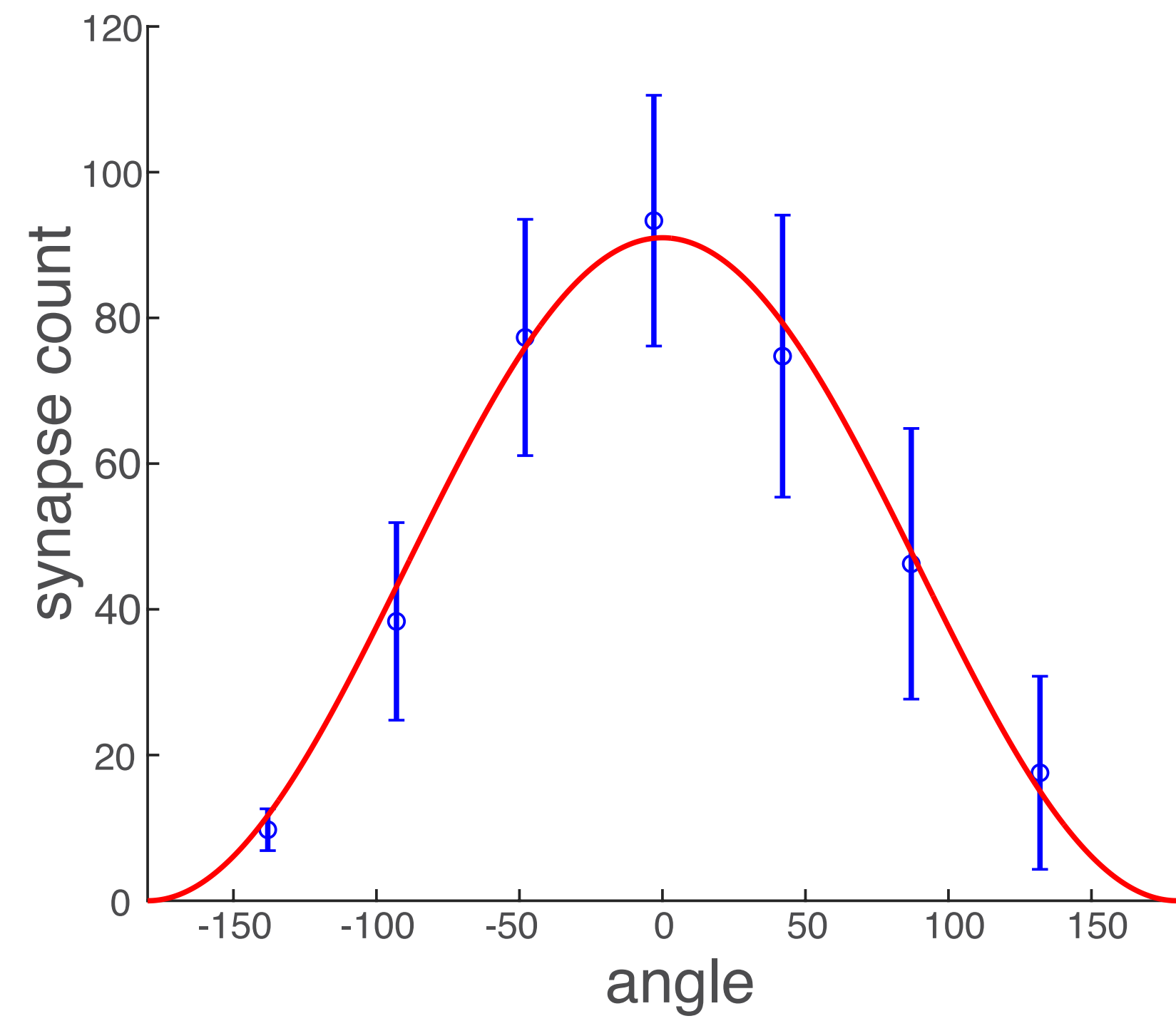
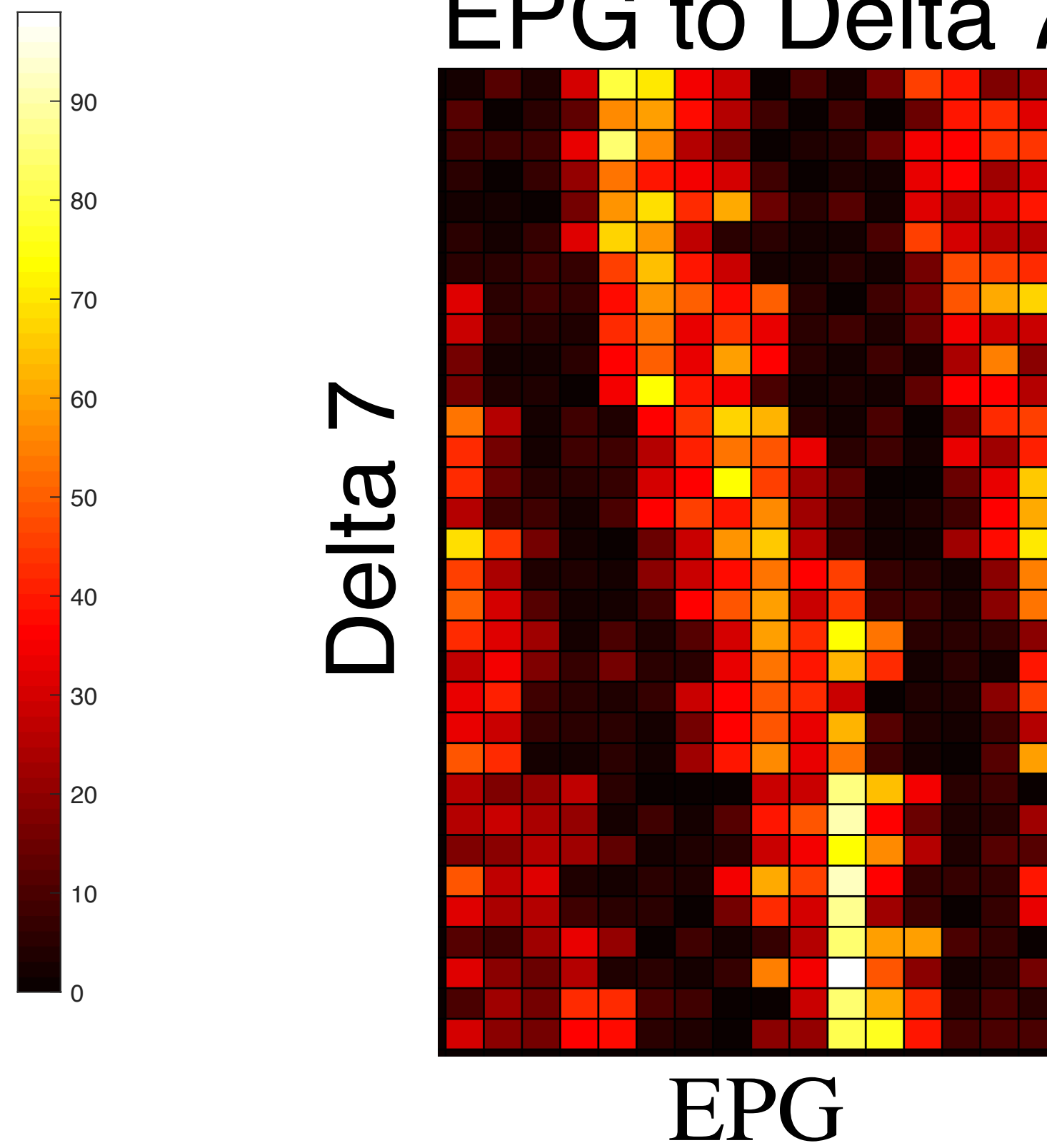
Turner-Evans, Jensen, Ali, Paterson, Sheridan, Ray, Lauritzen, Bock, Jayaraman (2019)

Delta 7 to EPG



Delta 7

EPG to Delta 7



Supporting the Bump

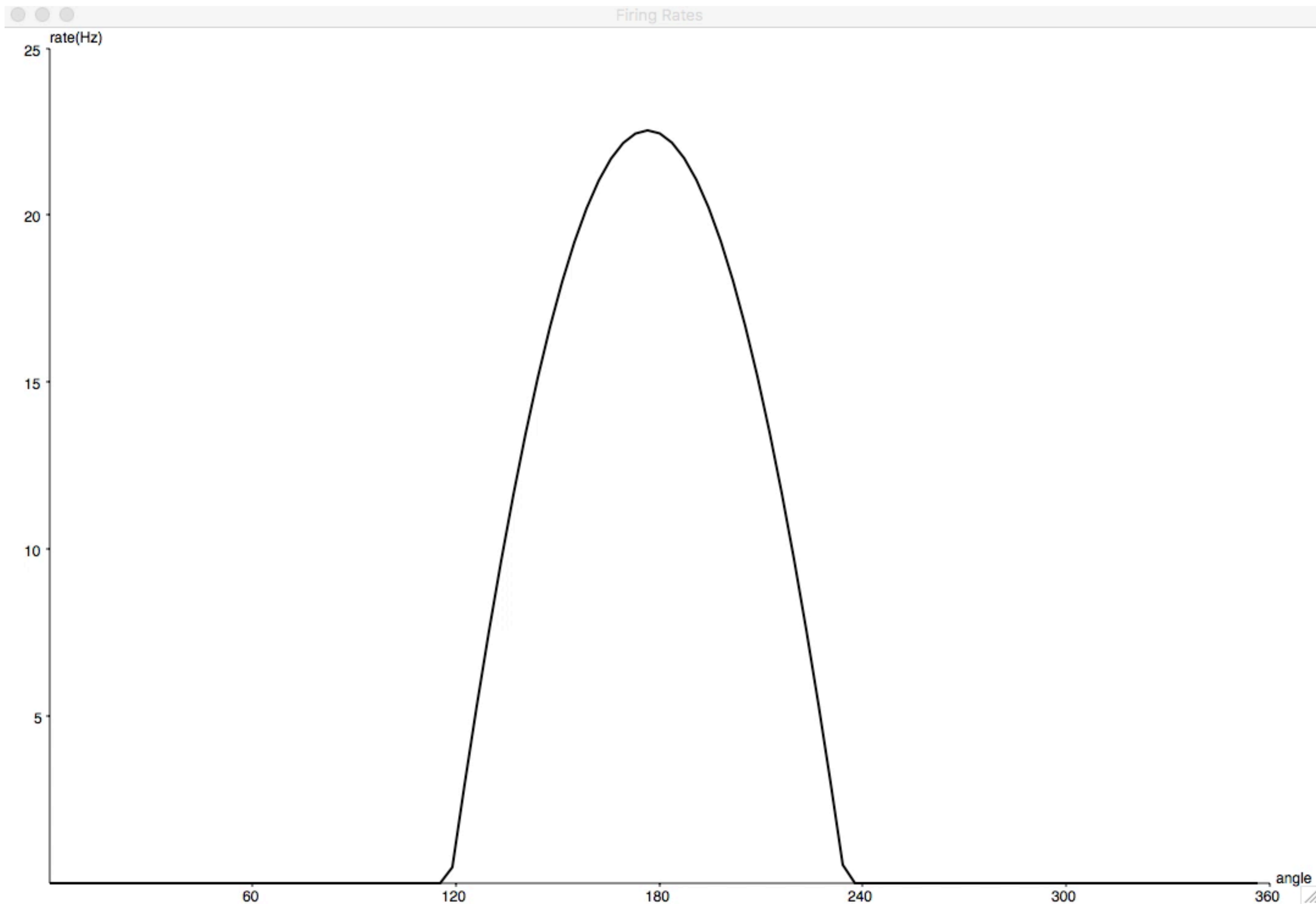
$$J_0 + J_1 \cos(\theta_i - \theta_j)$$

Moving the Bump

$$J_0 + J_1 \cos(\theta_i - \theta_j) + \alpha \sin(\theta_i - \theta_j)$$

Turner-Evans, Wegener, Rouault, Franconville, Wolff, Seelig, Druckmann, Jayaraman (2017)

Green, Adachi, Shah, Hirokawa, Magani, Maimon (2017)



Supporting the Bump

$$J_0 + J_1 \cos(\theta_i - \theta_j)$$

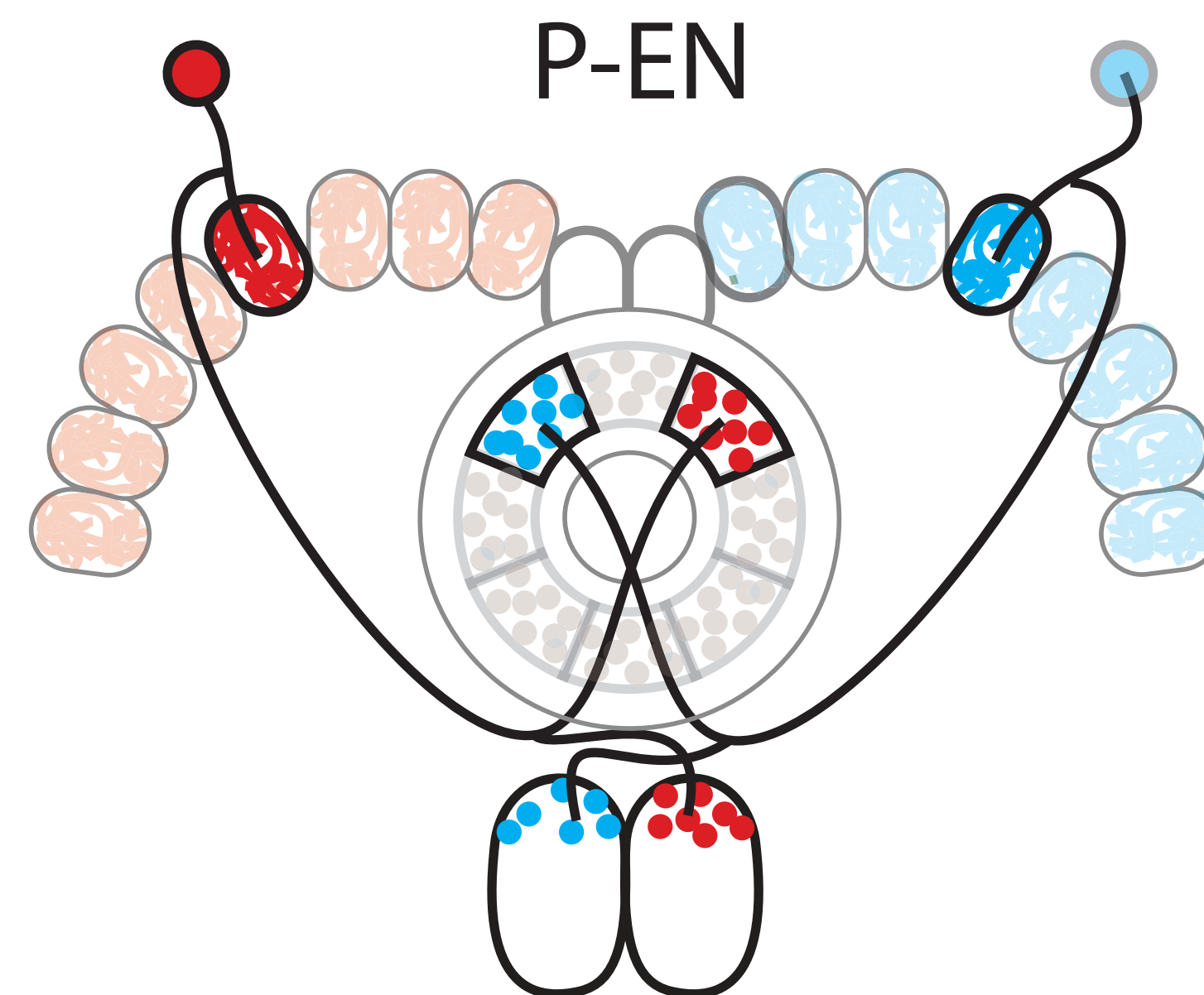
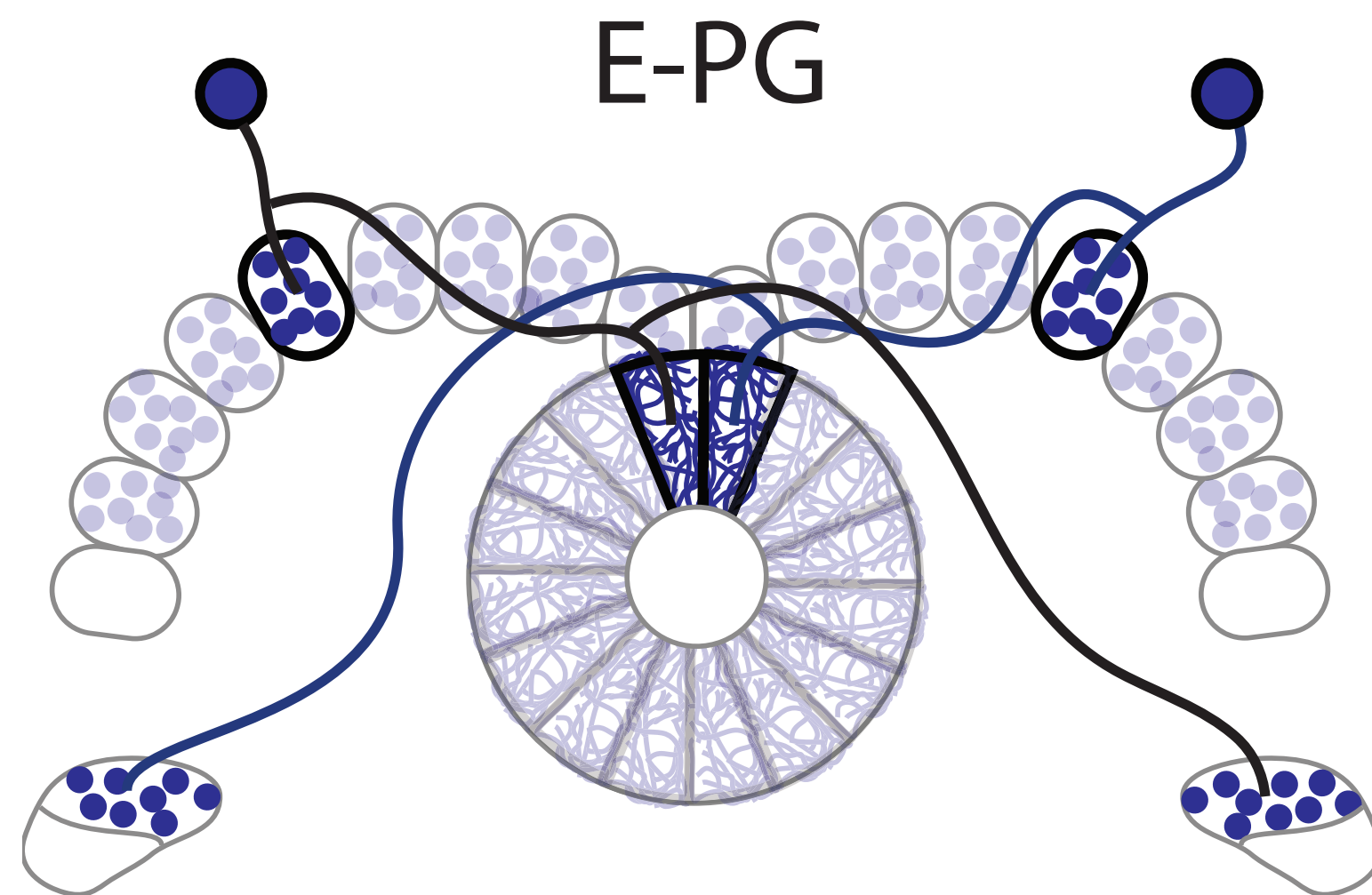
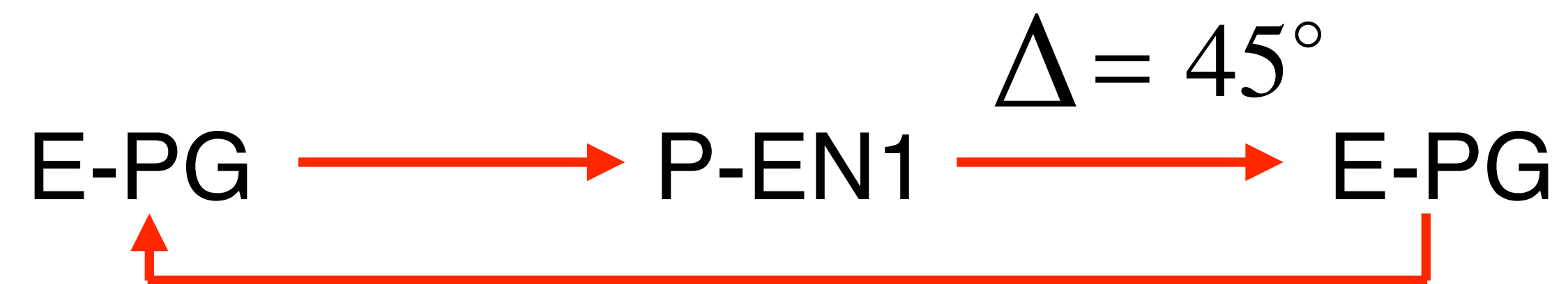
Moving the Bump

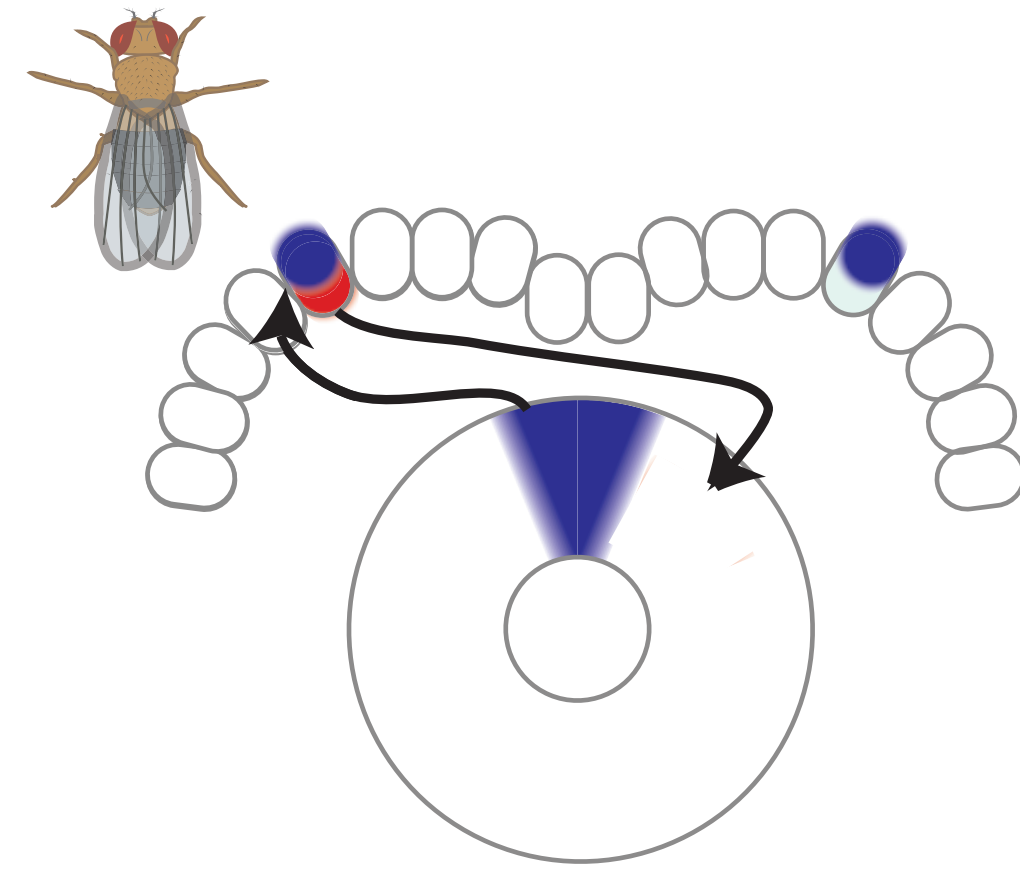
$$J_0 + J_1 \cos(\theta_i - \theta_j) + \alpha \sin(\theta_i - \theta_j)$$

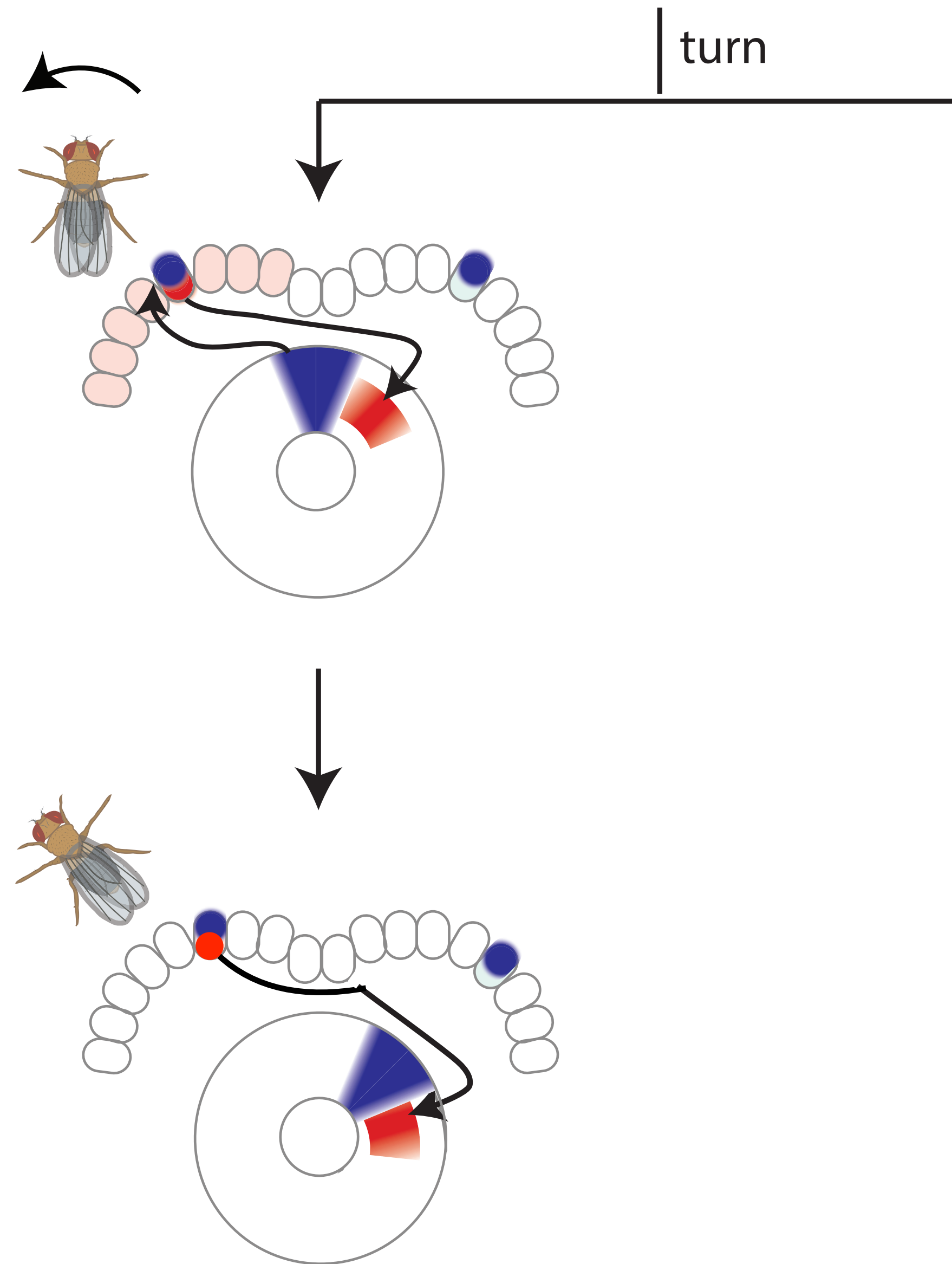
$$J_0 + J_1 \cos(\theta_i - \theta_j) + \alpha' \cos(\theta_i - \theta_j - \Delta)$$

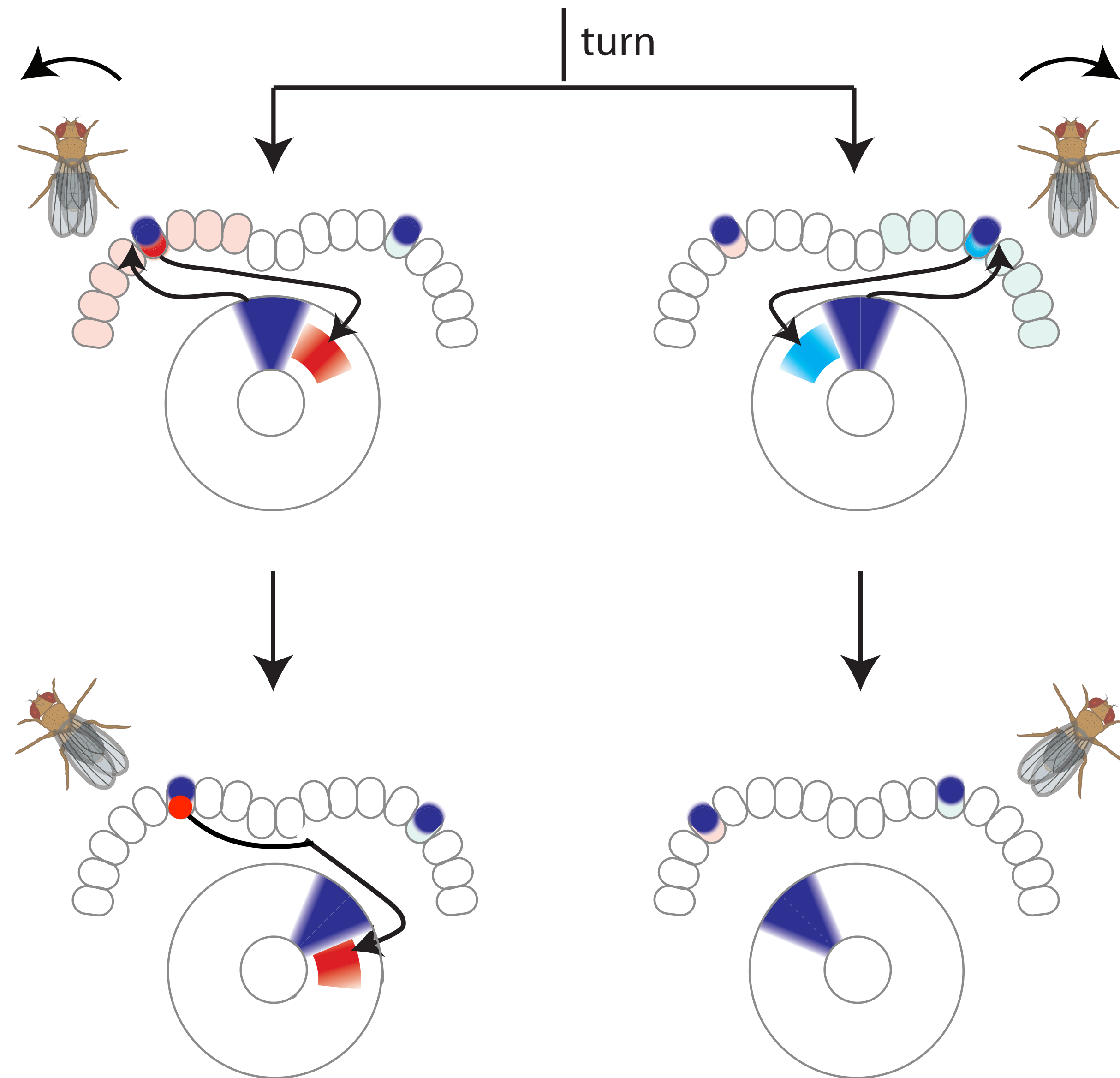
$$= J_0 + J_1(1 + \alpha' \cos(\Delta)) \cos(\theta_i - \theta_j) + \alpha' \sin(\Delta) \sin(\theta_i - \theta_j)$$

$$\tau \frac{dr_i}{dt} = -r_i + F\left(\sum_{j=1}^N \left(J_0 + J_1 \cos(\theta_i - \theta_j) + \boxed{L \cos(\theta_i - \theta_j + \pi/4) + R \cos(\theta_i - \theta_j - \pi/4)}\right) r_j\right)$$



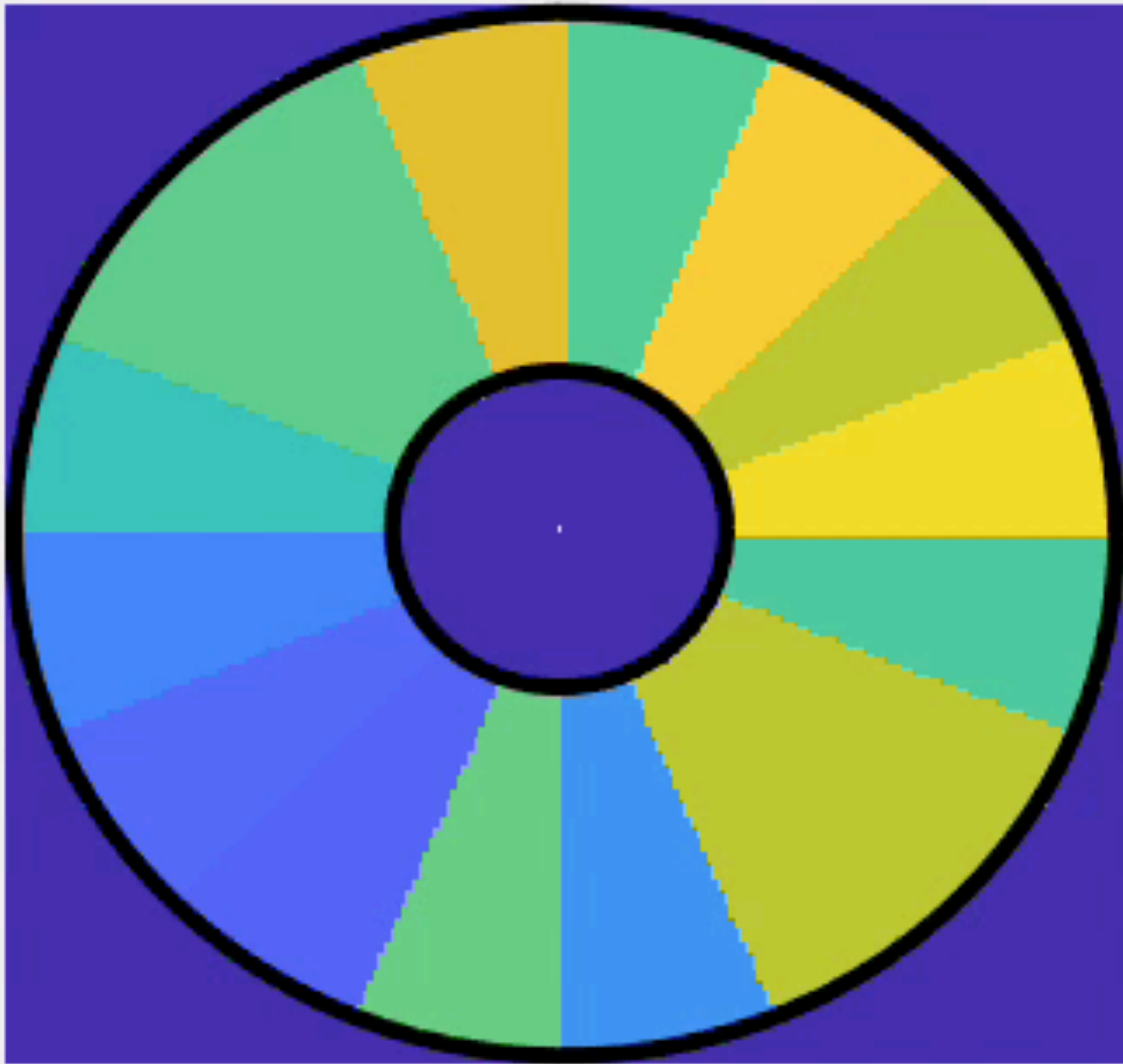
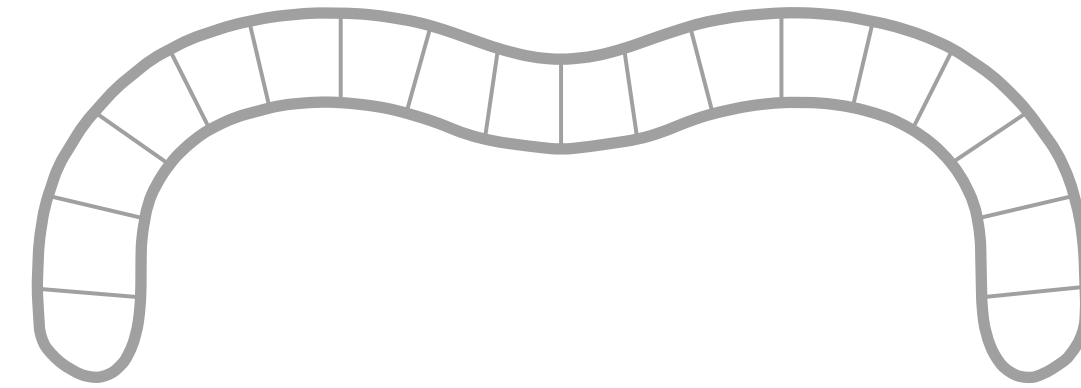




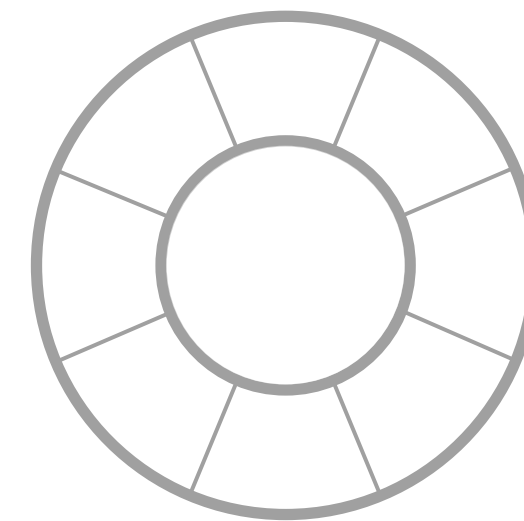




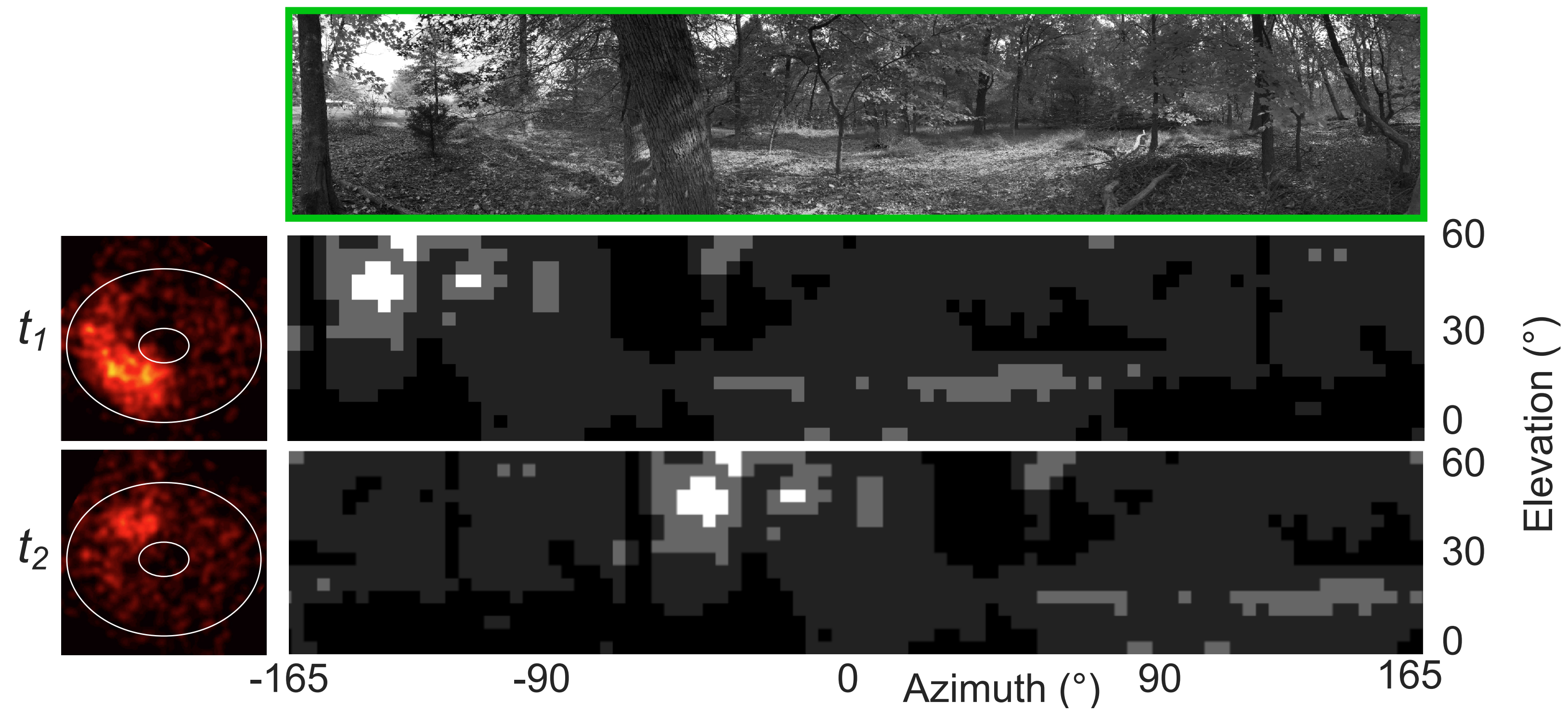
**protocerebral
bridge**



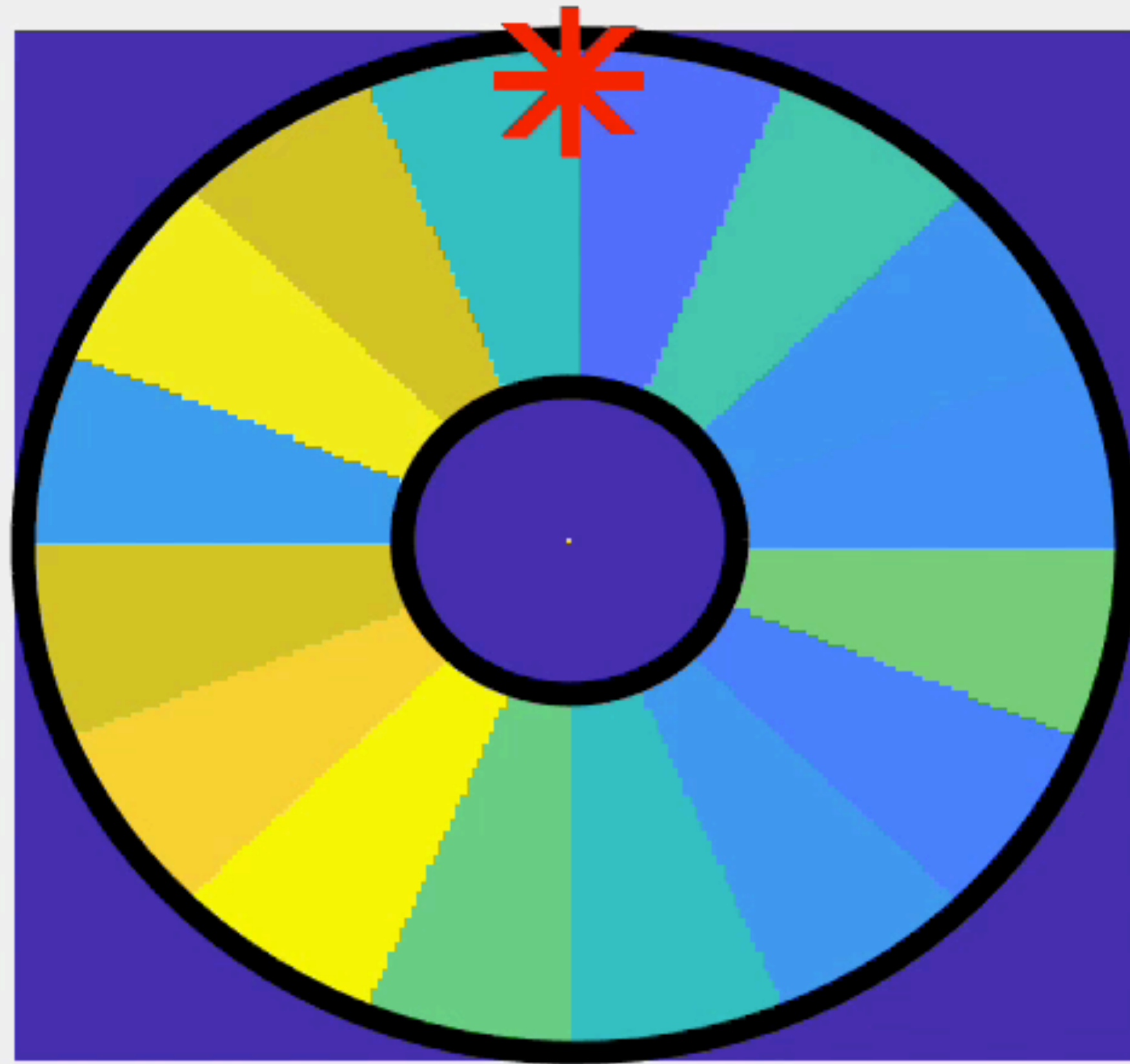
ellipsoid body



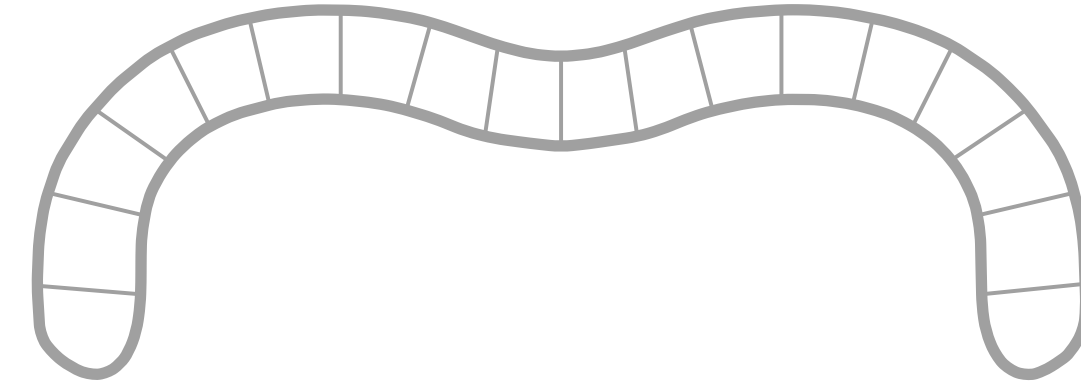




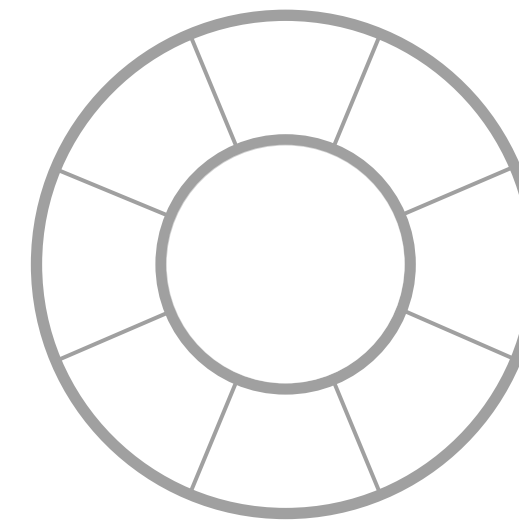
$$\tau \frac{dr_i}{dt} = -r_i + F \left(\sum_{j=1}^N \left(J_0 + J_1 \cos(\theta_i - \theta_j) \right) r_j + I \cos(V - \theta_i) \right)$$



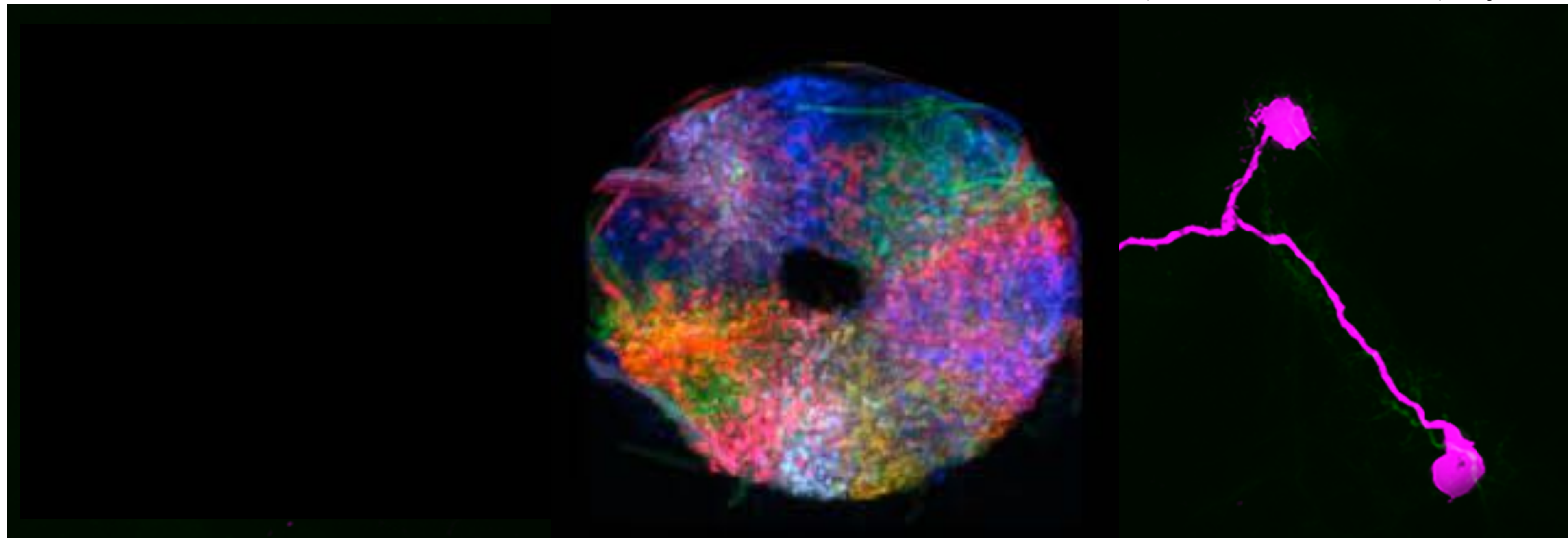
**protocerebral
bridge**



ellipsoid body



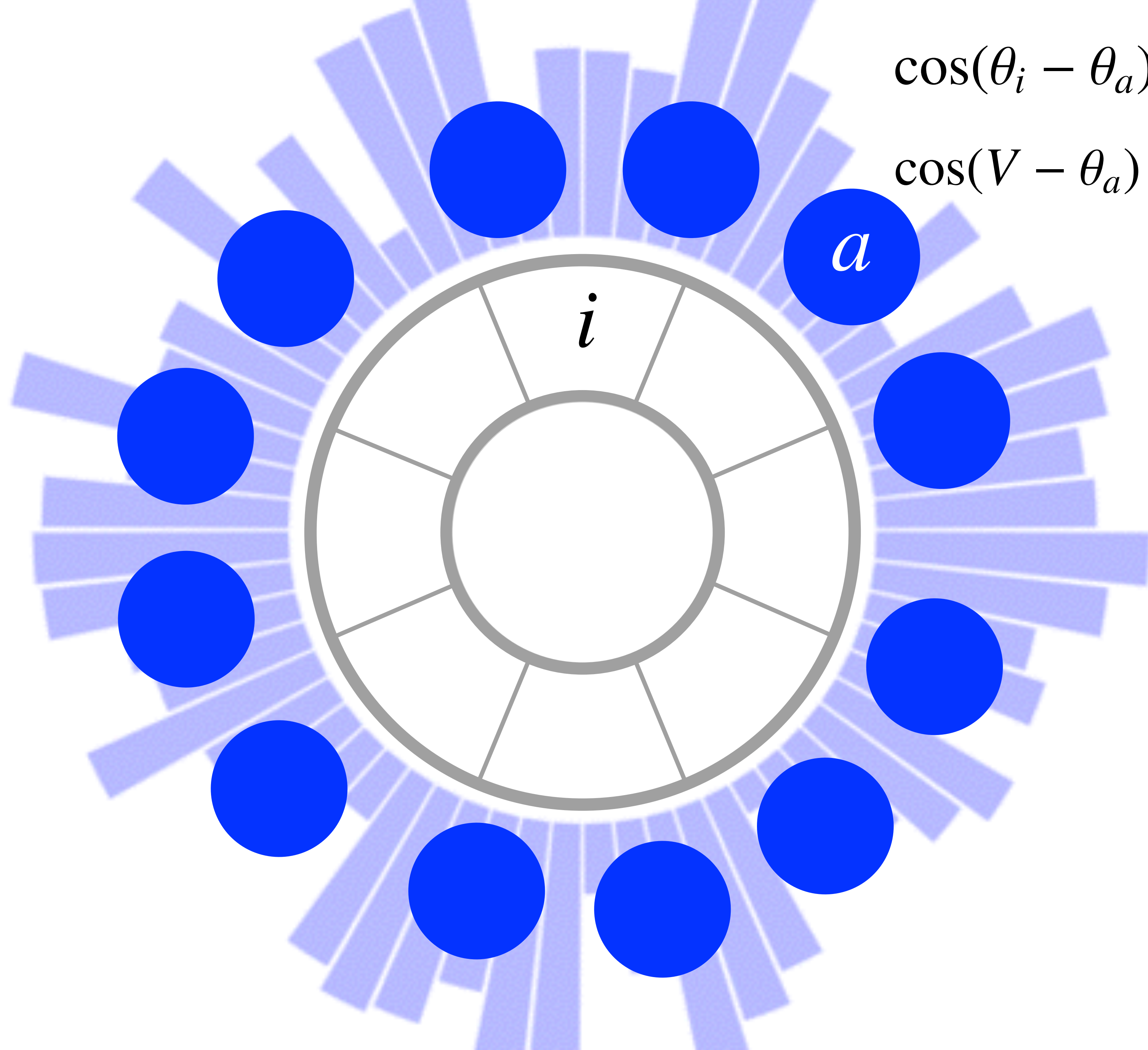
Tanya Wolff, Janelia FlyLight



Fisher, Lu, D'Alessandro, Wilson (2019)

Seelig, Jayaraman (2013)

Kim, Hermundstad, Romani, Abbott, Jayaraman (2019)



$\cos(\theta_i - \theta_a)$ ring-to-compass synaptic strength

$\cos(V - \theta_a)$ ring neuron response

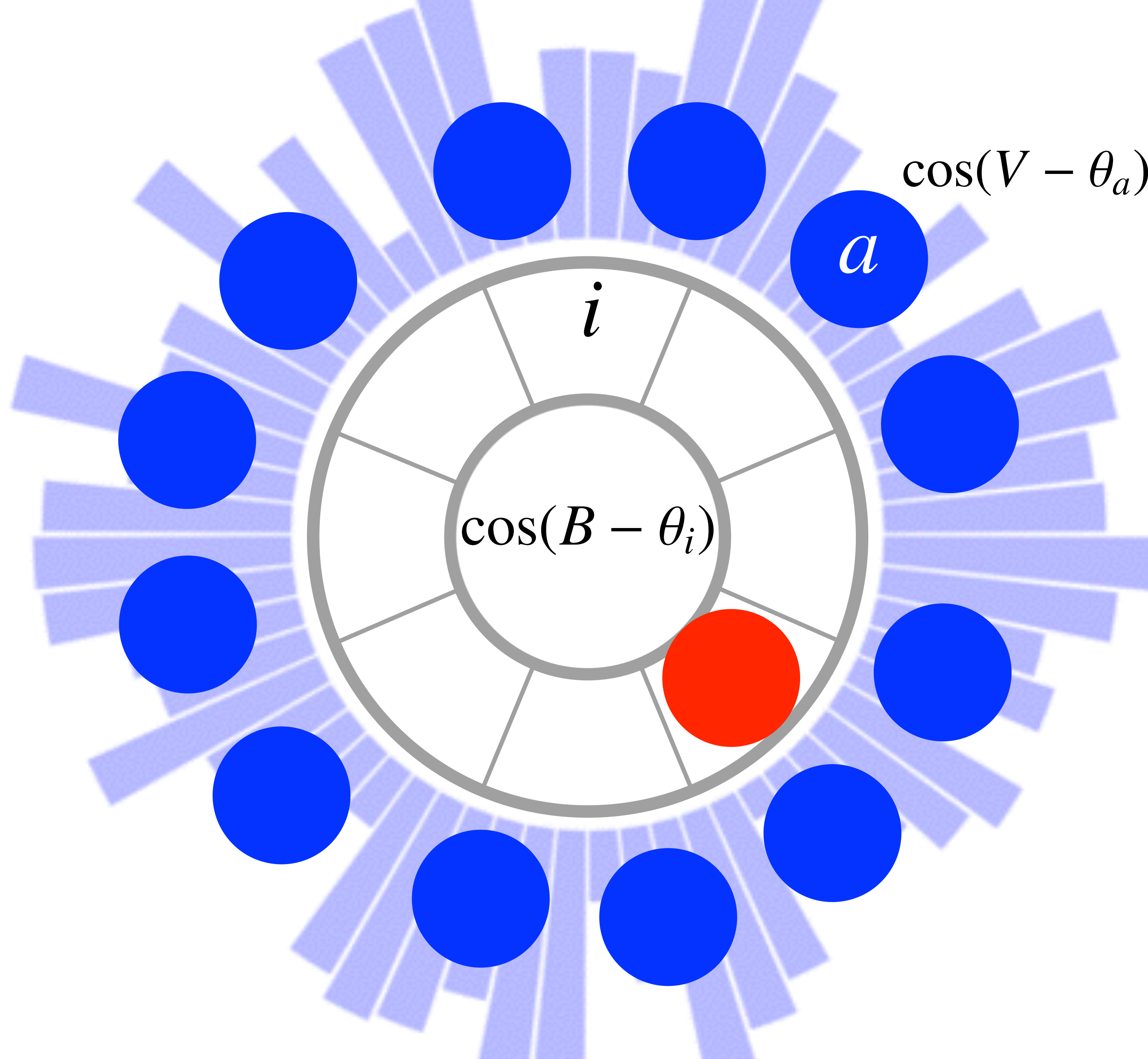
$$I_i =$$

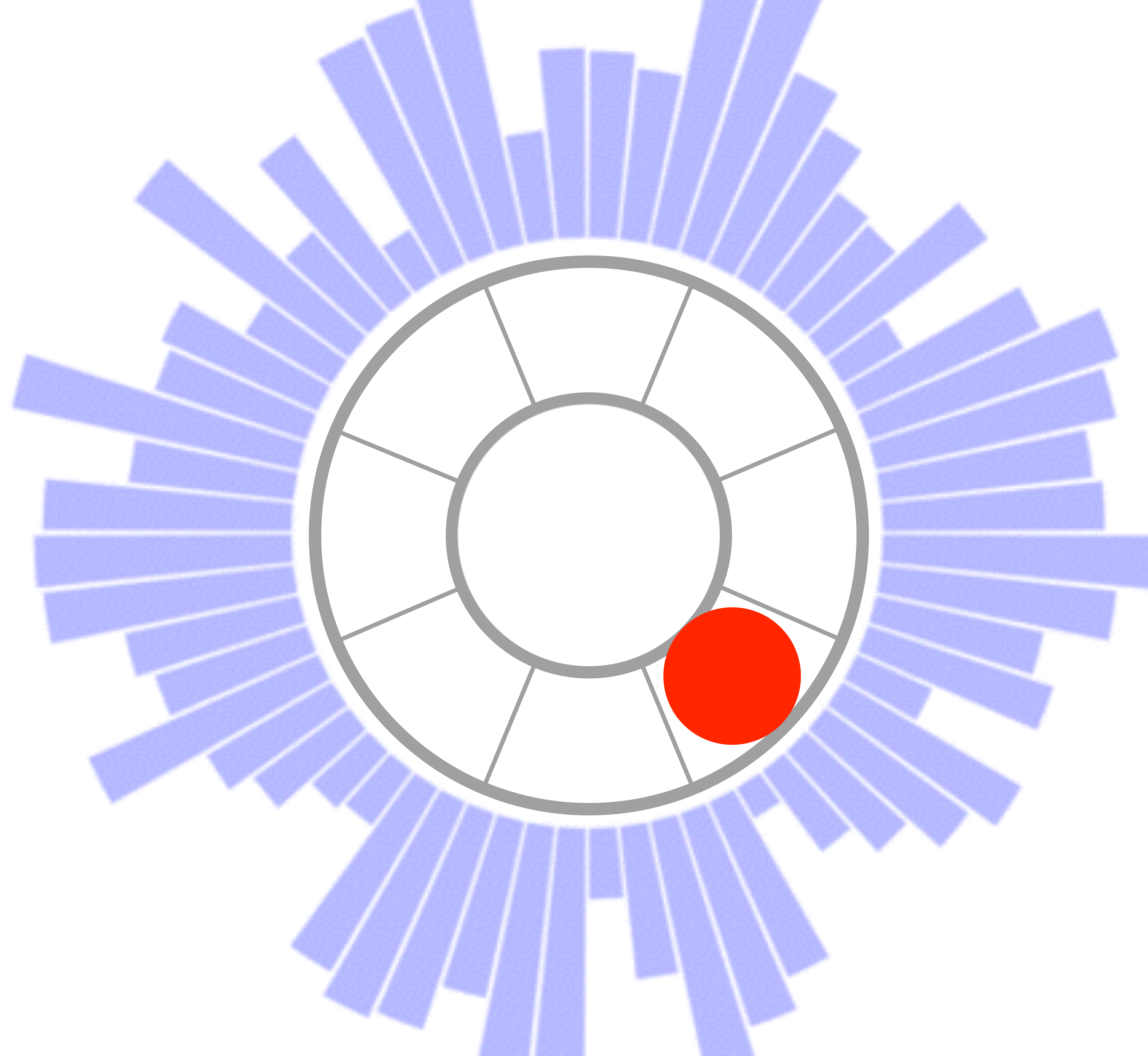
ring-to-compass synaptic strength

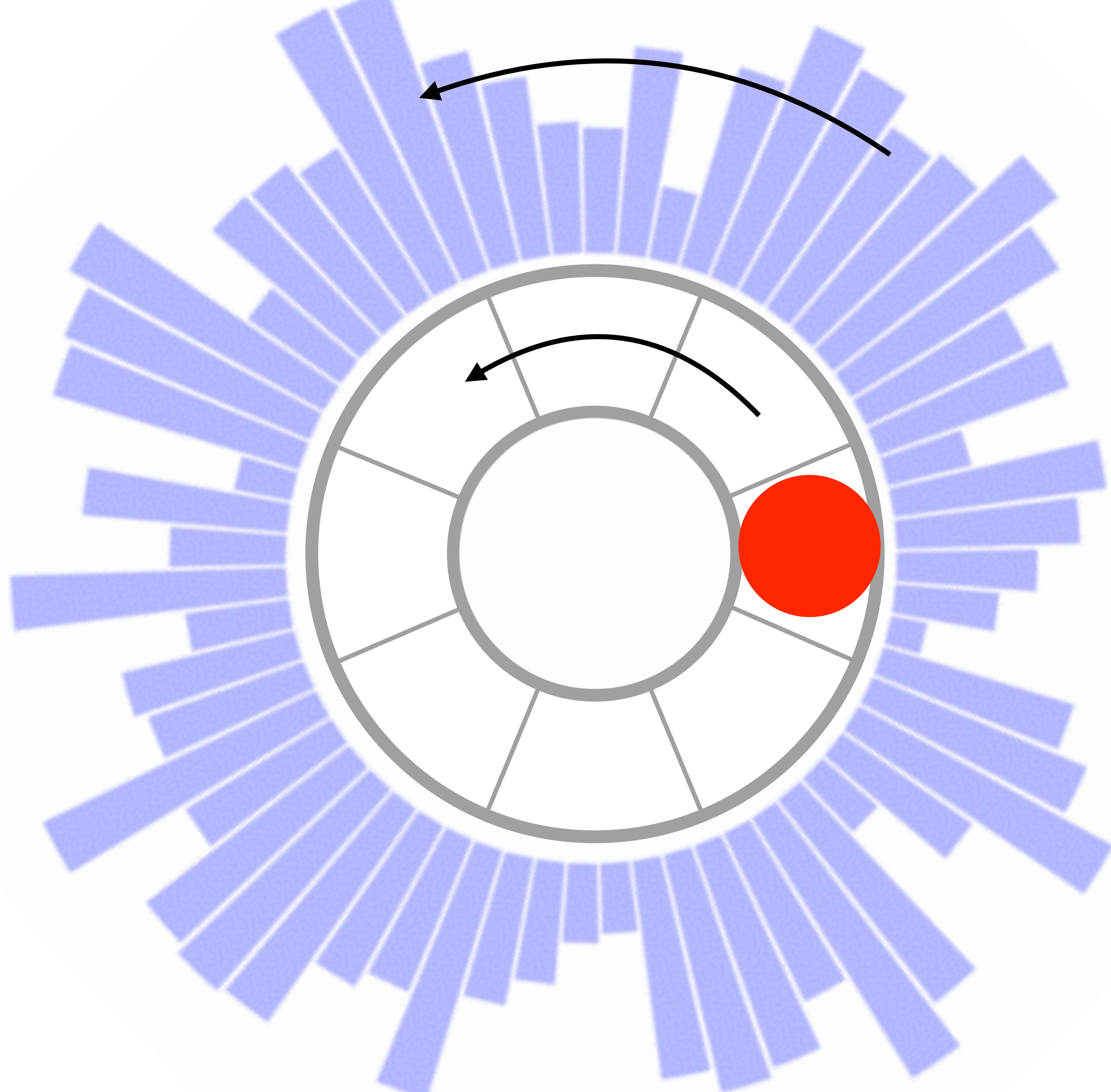
*

ring neuron response

→ $\cos(V - \theta_i)$







bump x ring

change in ring-to-compass
synaptic strength

$$\frac{1}{\pi} \cos(B - \theta_i) \cos(V - \theta_a)$$

$$B = V$$

ring-to-compass
synaptic strength

$$\frac{1}{\pi} \int_0^{2\pi} dV \cos(V - \theta_i) \cos(V - \theta_a)$$

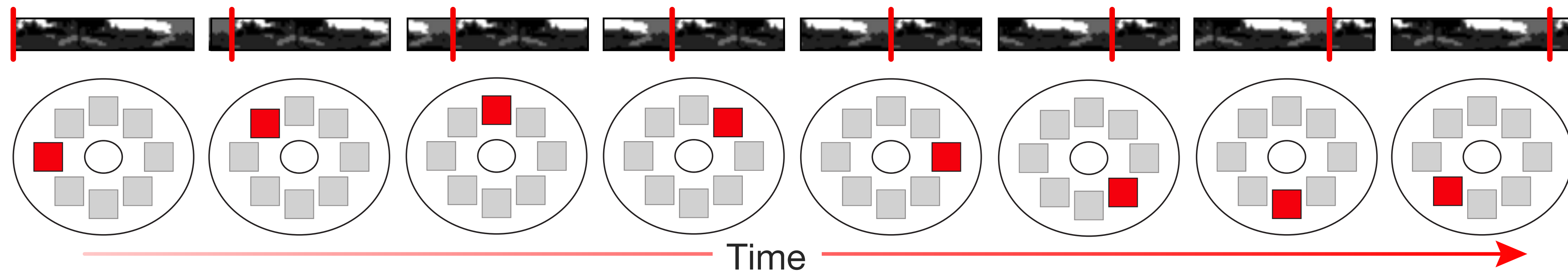
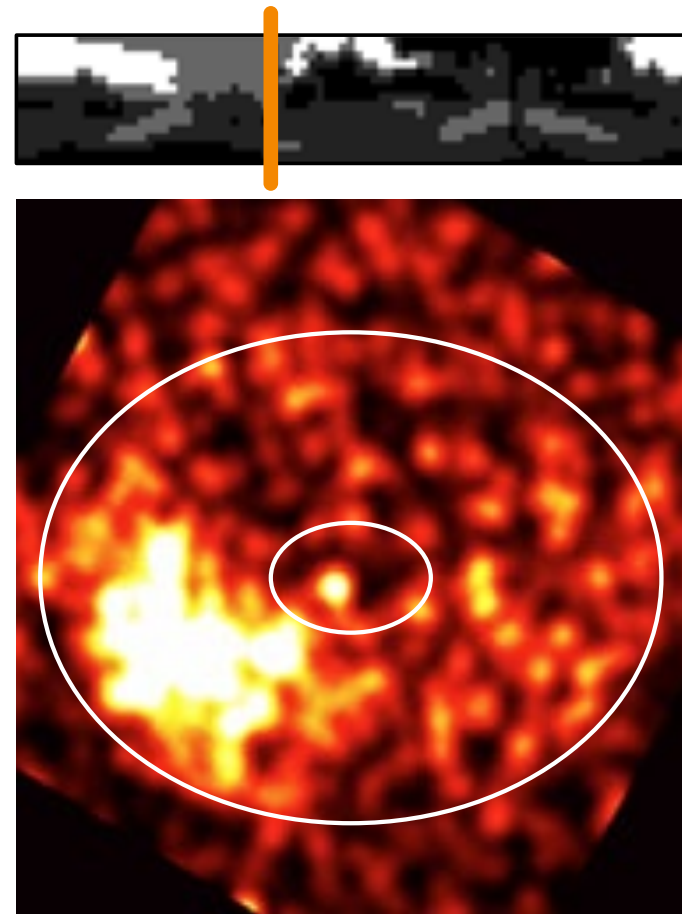
$$= \frac{1}{2\pi} \int_0^{2\pi} dV \left(\cos(\theta_i - \theta_a) + \cos(2V - \theta_i - \theta_a) \right)$$

\parallel

0

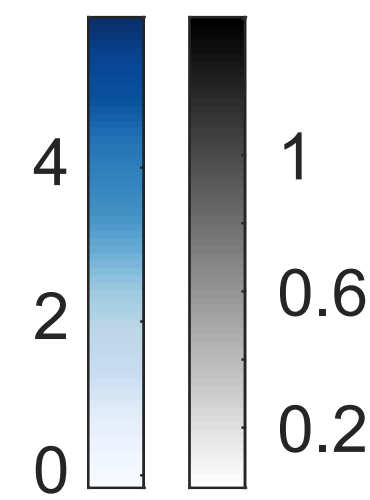
$$= \cos(\theta_i - \theta_a)$$

Before



Kim, Hermundstad, Romani, Abbott, Jayaraman (2019)

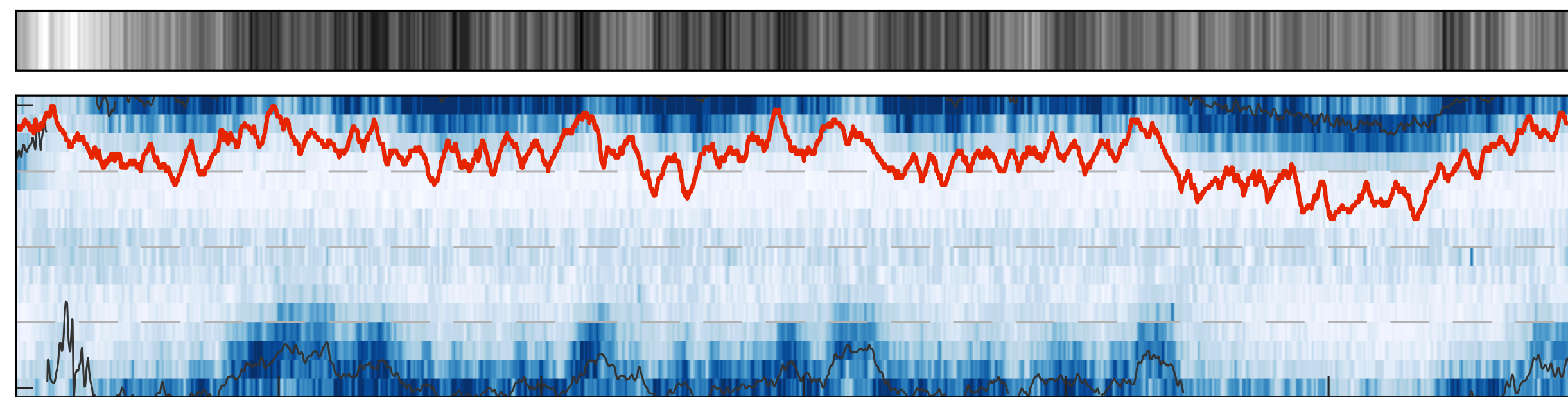
BEFORE



ROIs

16

1



165

0

-165

0

10

20

30

40

50

Time (s)

bump x ring

$$\frac{1}{\pi} \cos(B - \theta_i) \cos(V - \theta_a)$$

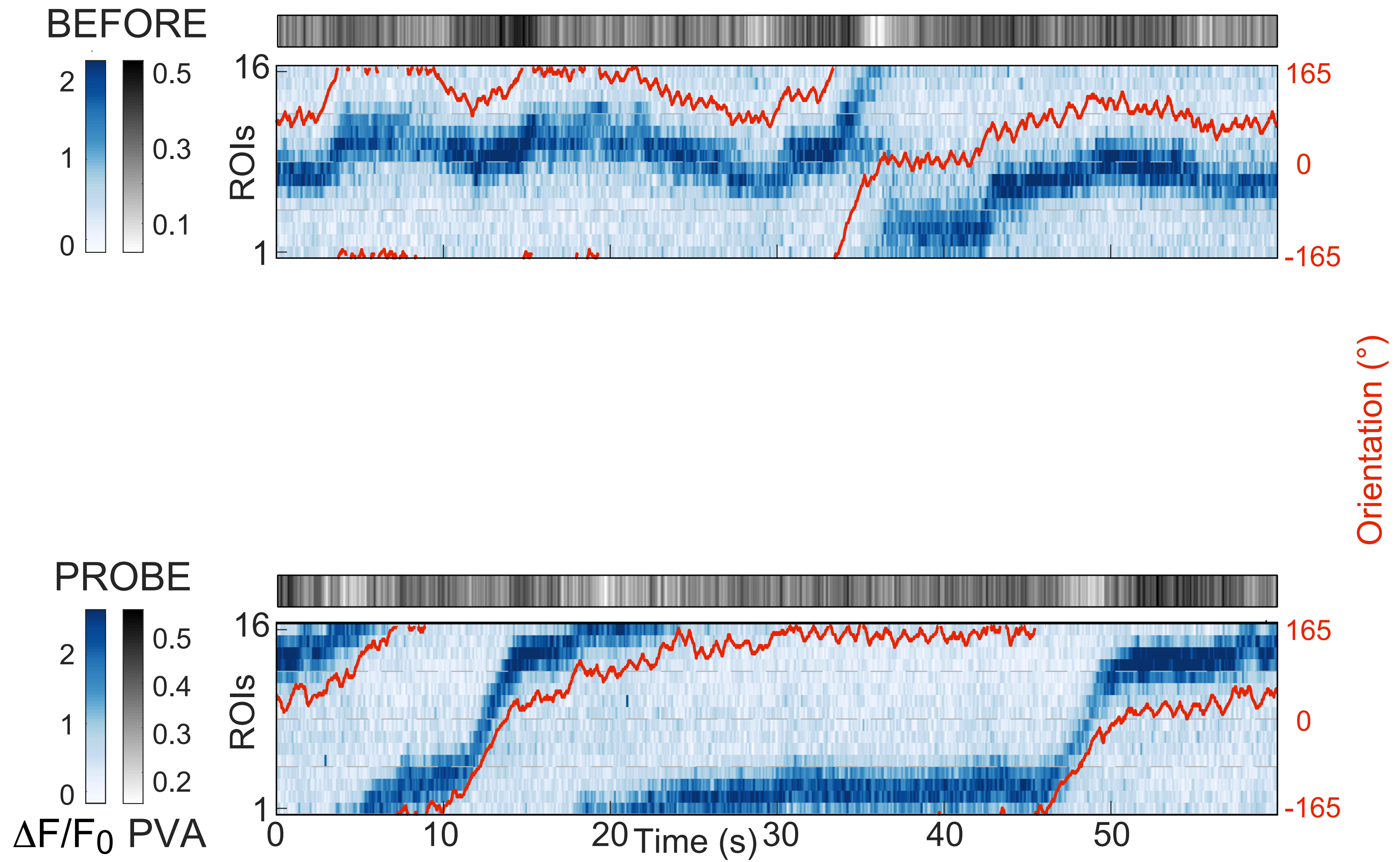
$$B = V$$

$$\frac{1}{\pi} \int_0^{2\pi} dV \cos(V - \theta_i) \cos(V - \theta_a)$$

$$= \frac{1}{2\pi} \int_0^{2\pi} dV \left(\cos(\theta_i - \theta_a) + \cos(2V - \theta_i - \theta_a) \right)$$

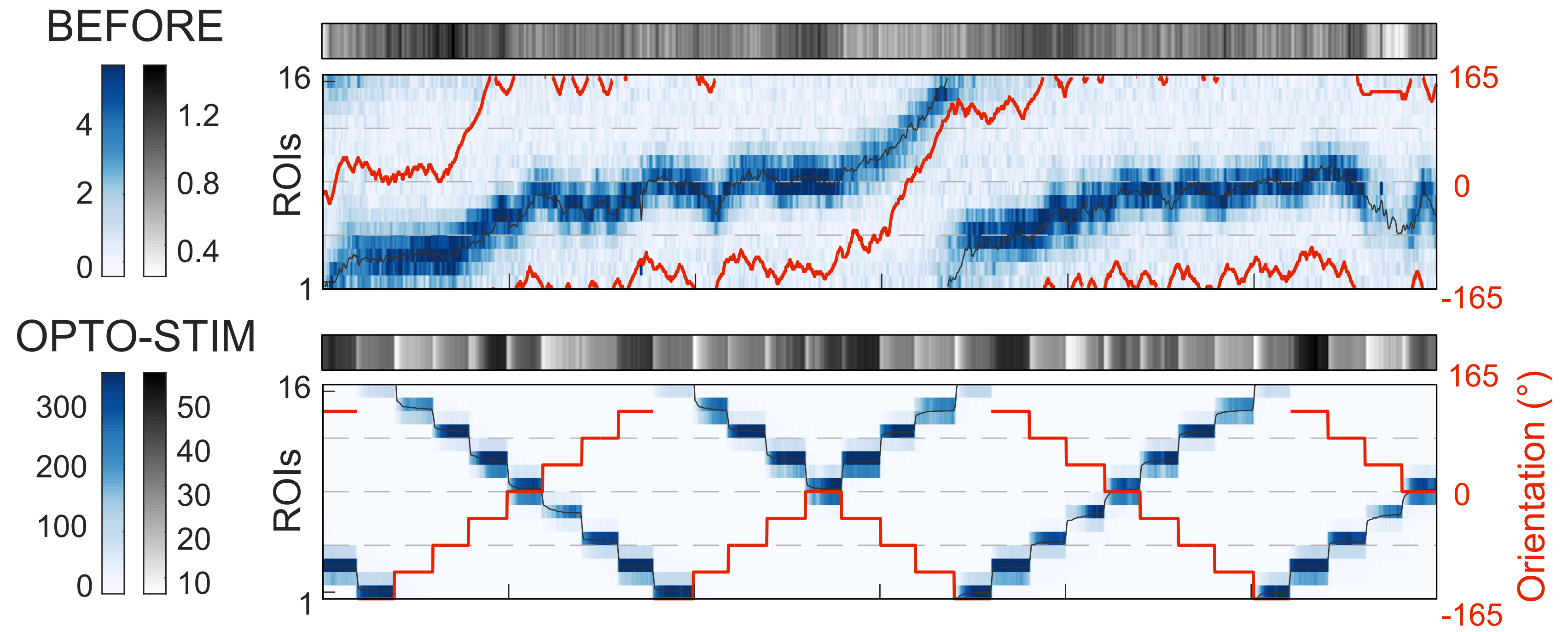
\parallel
 0

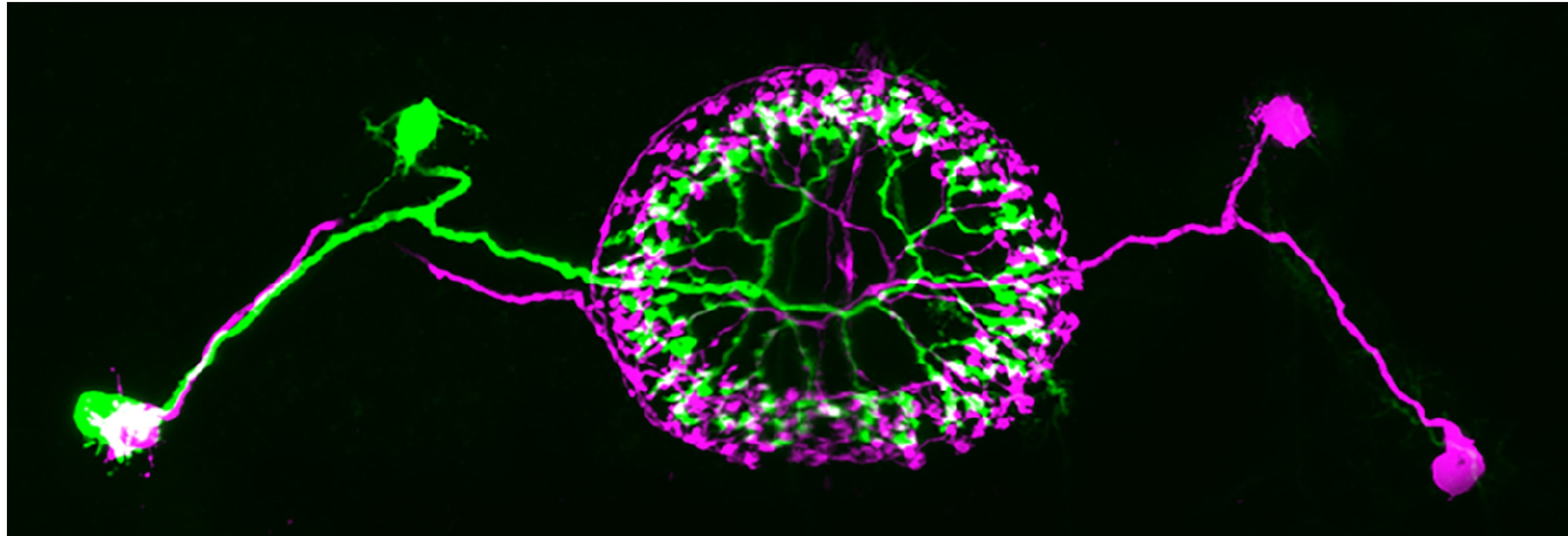
$$= \cos(\theta_i - \theta_a)$$



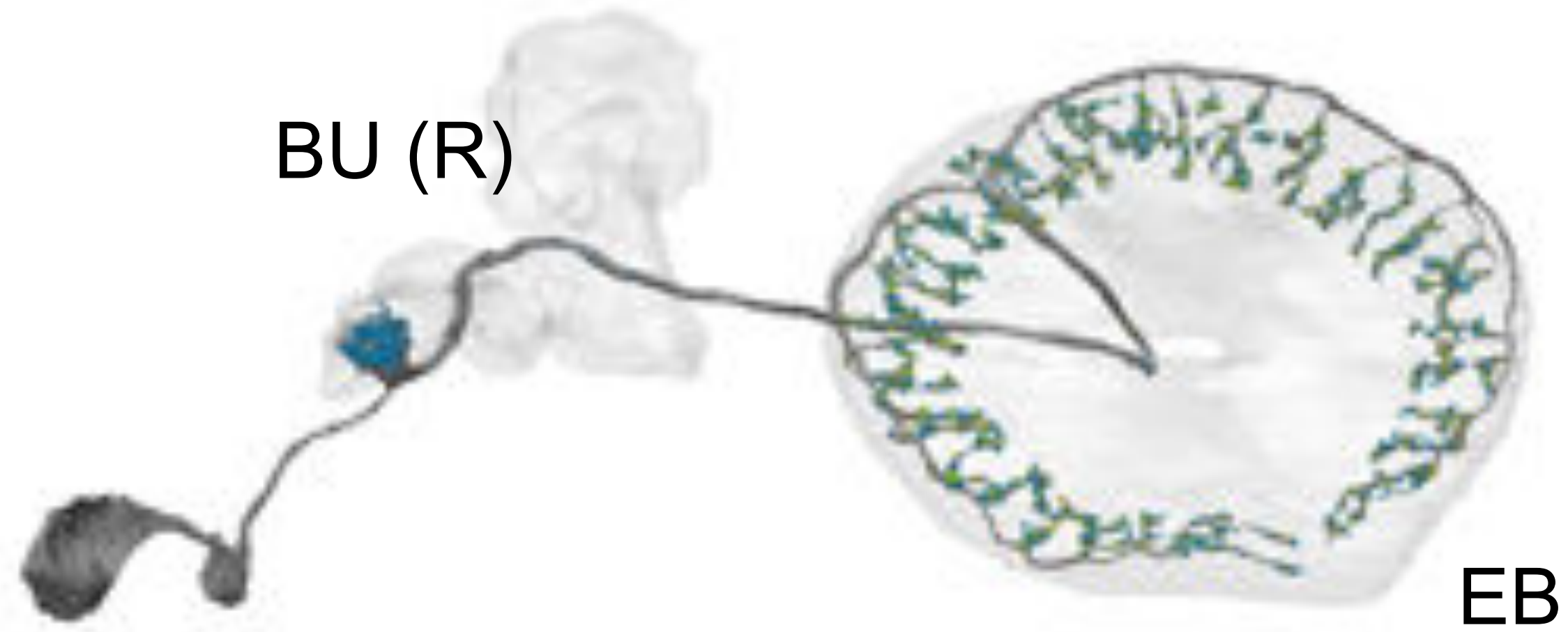
$$B = V \rightarrow \cos(\theta_i - \theta_a) \rightarrow \cos(V - \theta_i)$$

$$B = -V$$

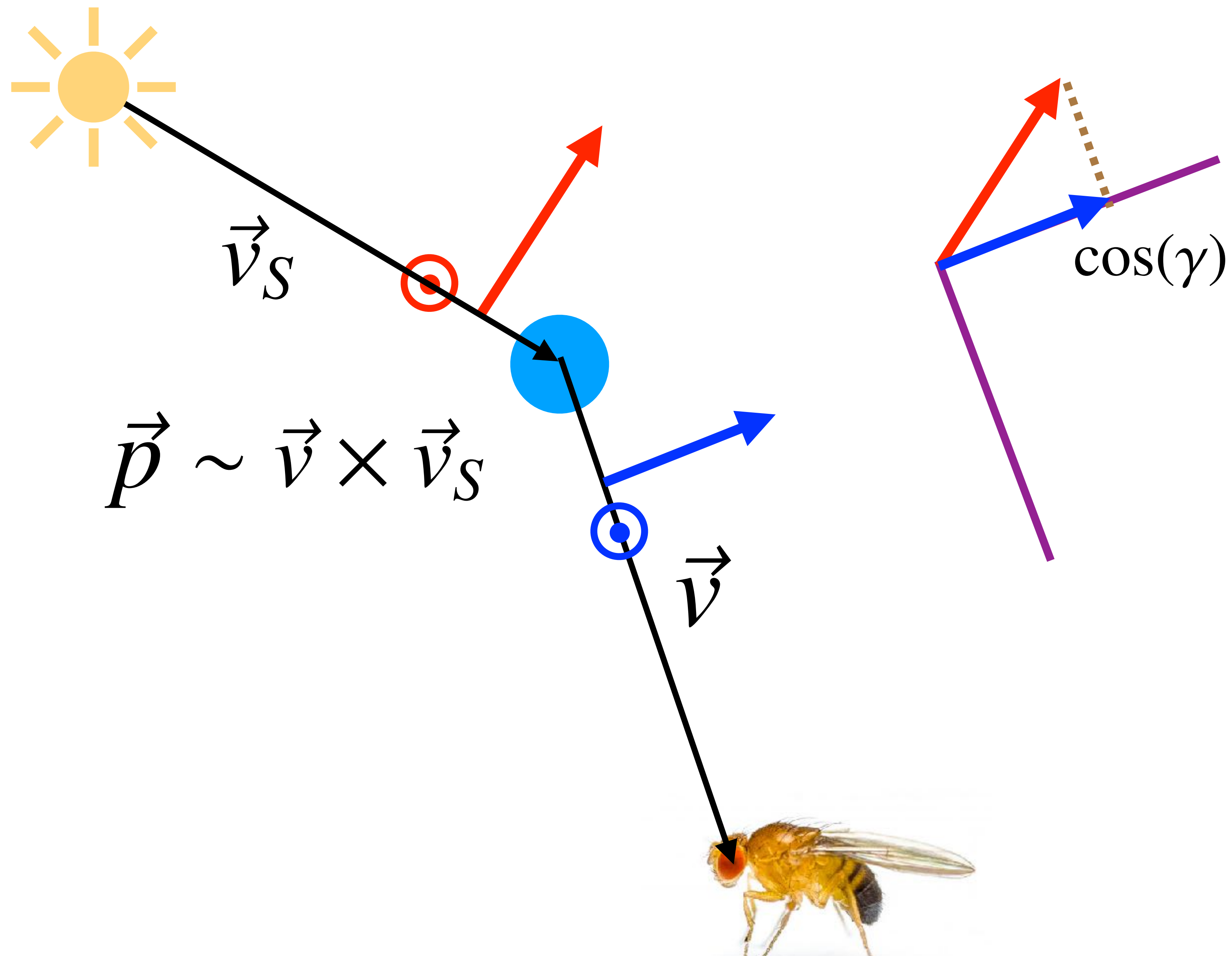


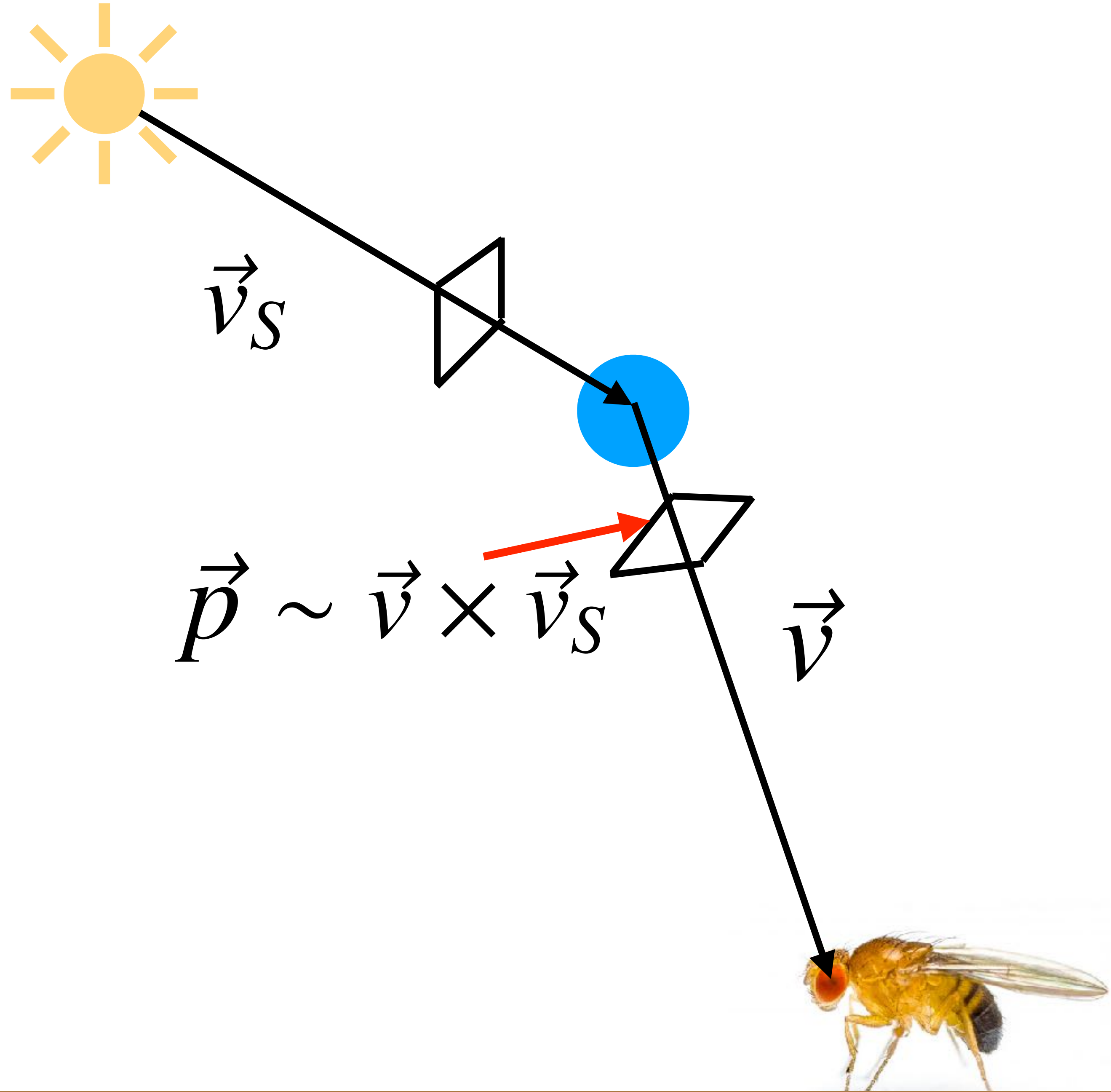


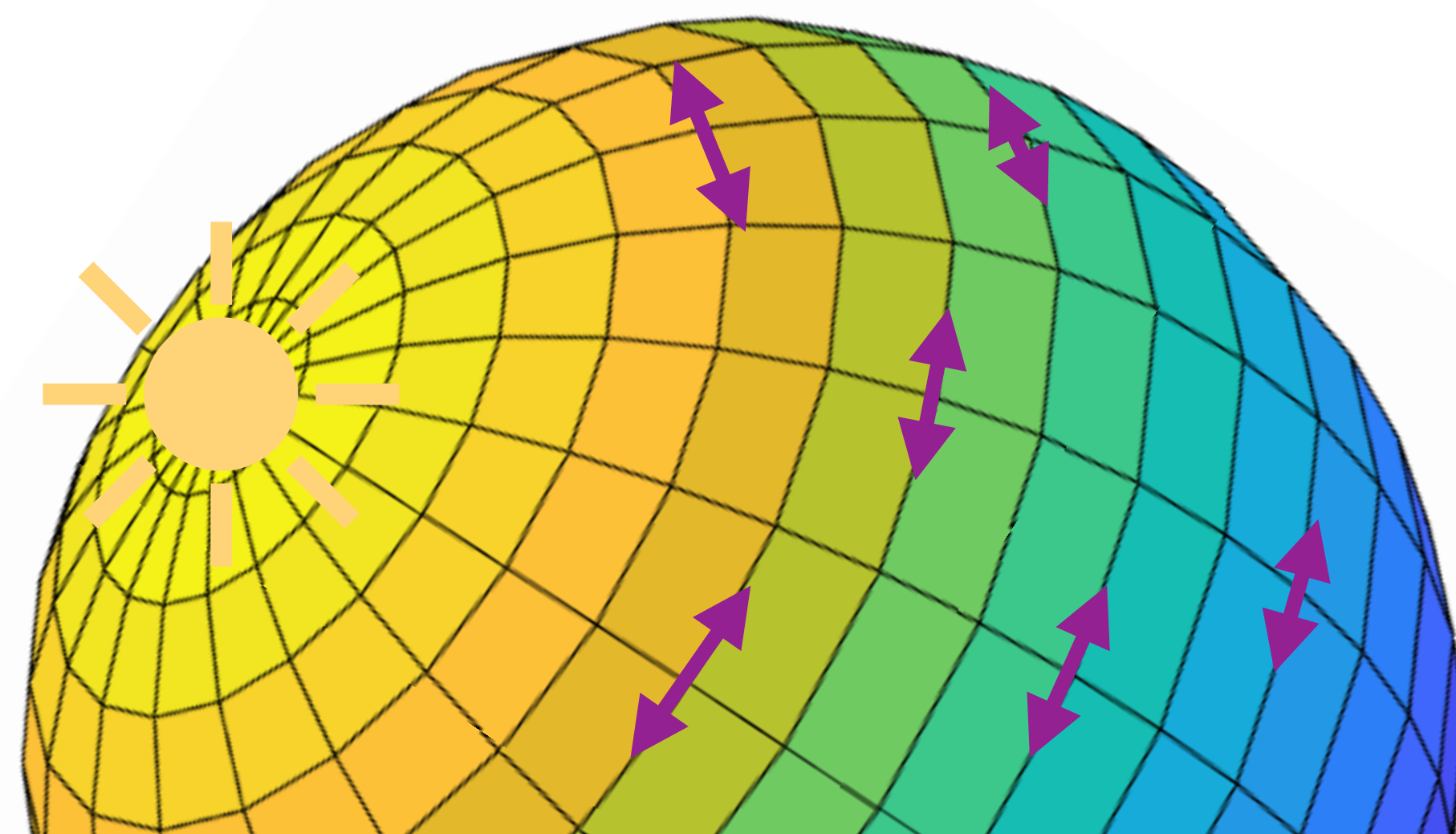
ER4m



Hulse, Haberkern, Franconville, Turner-Evans, Takemura, Wolff, Noorman,
Dreher, Dan, Parekh, Hermundstad, Rubin, Jayaraman (2021)



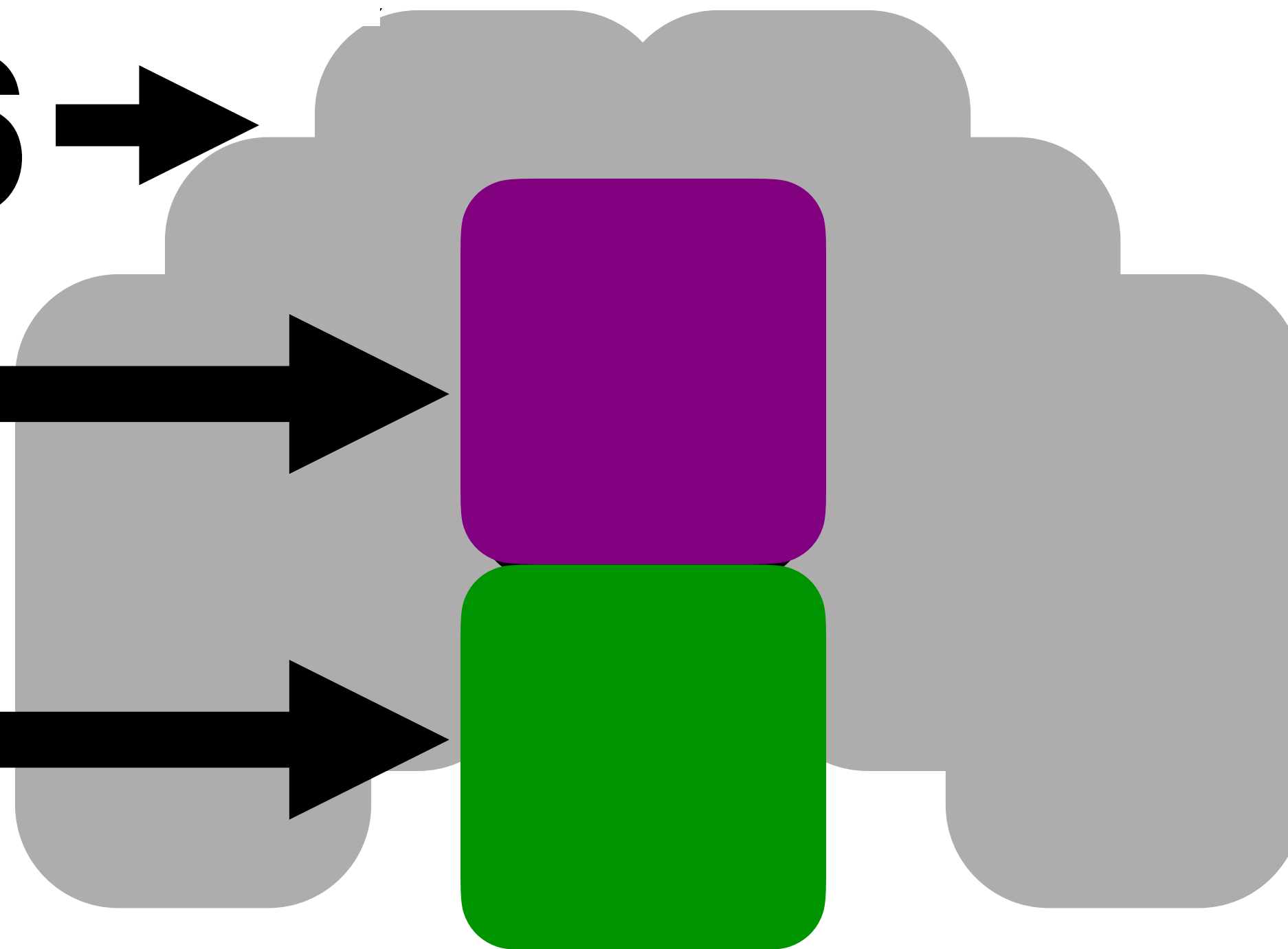


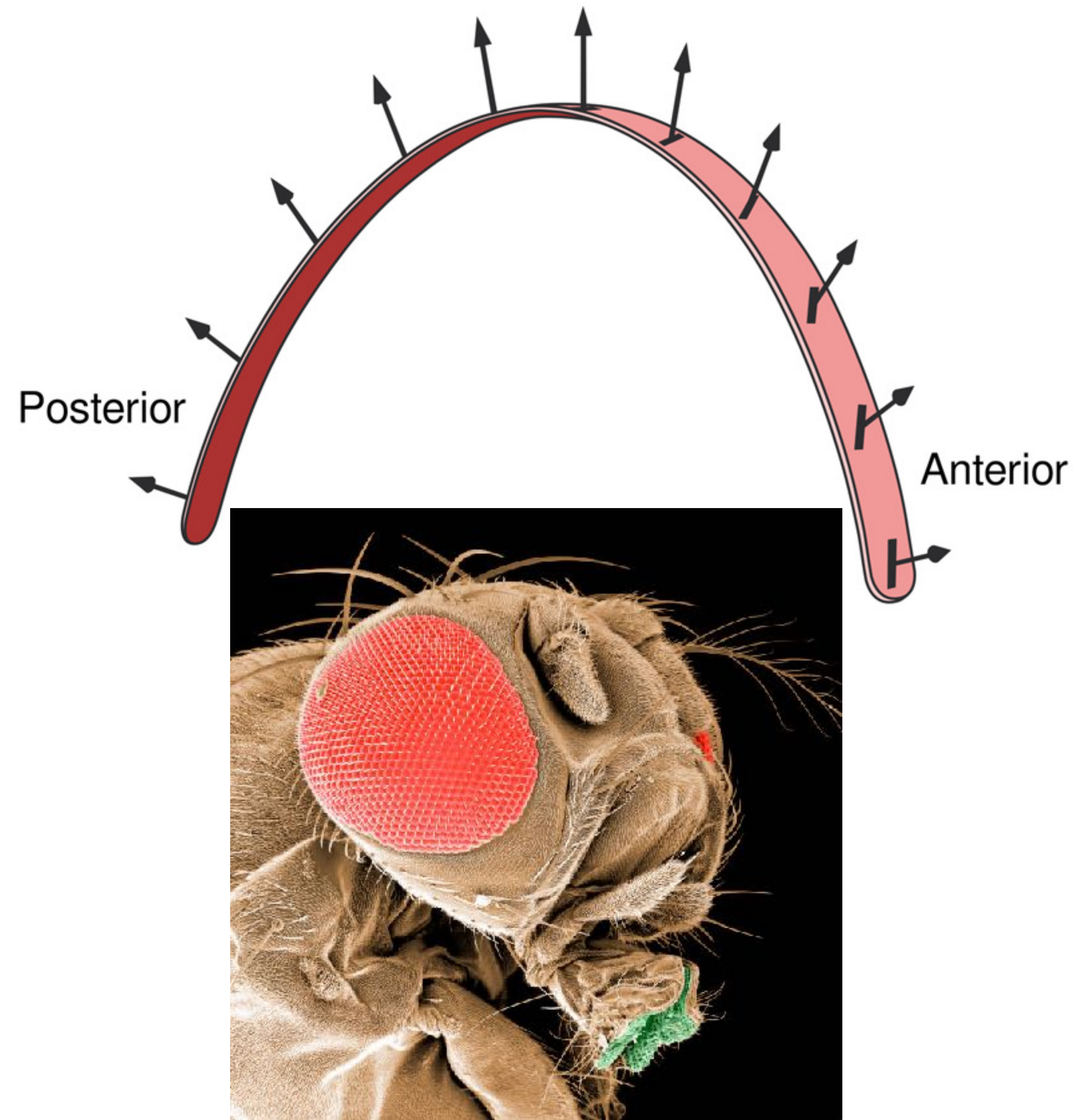


R1-6 →

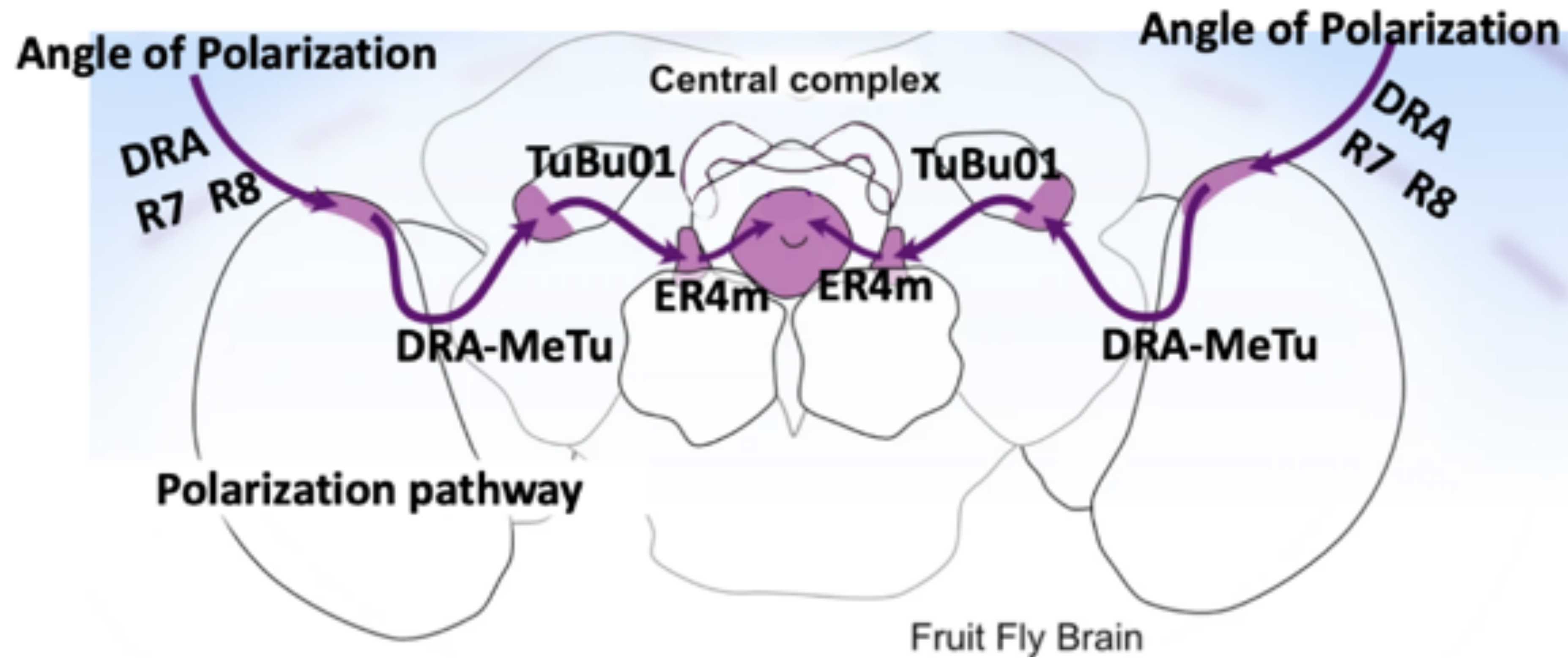
R7 →

R8 →



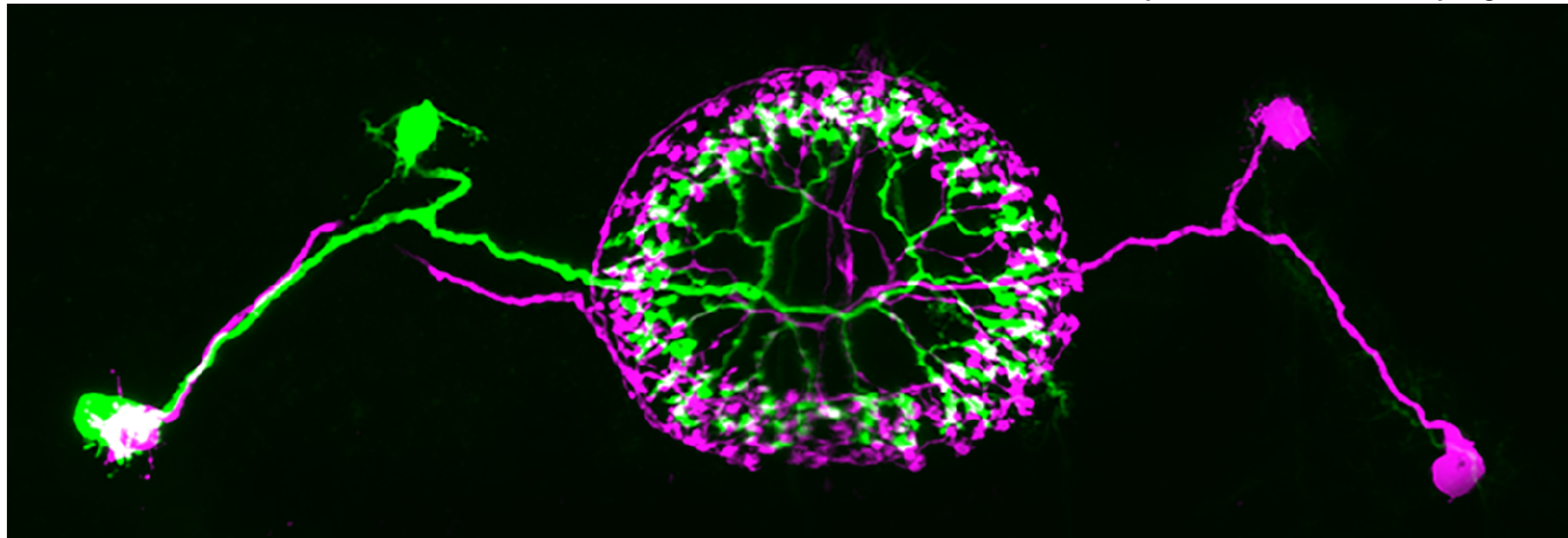


Weir, Henze, Bleul, Baumann-Klausener, Labhart, Dickinson (2016)



Hardcastle, Omoto, Kandimalla, Nguyen, Keles, Boyd, Hartenstein, Frye (2021)

Sharon Su, Rudy Behnia



Alloception

