# COLLABORATIVE PREDICTION VIA TRACTABLE AGREEMENT PROTOCOLS

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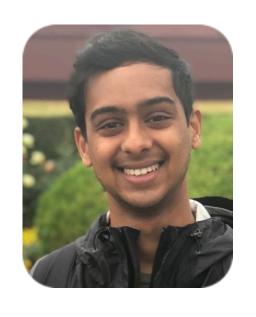
Based on joint works with:



Natalie Collina UPenn



Ira Globus-Harris
UPenn → Cornell



Varun Gupta
UPenn → Vector Institute



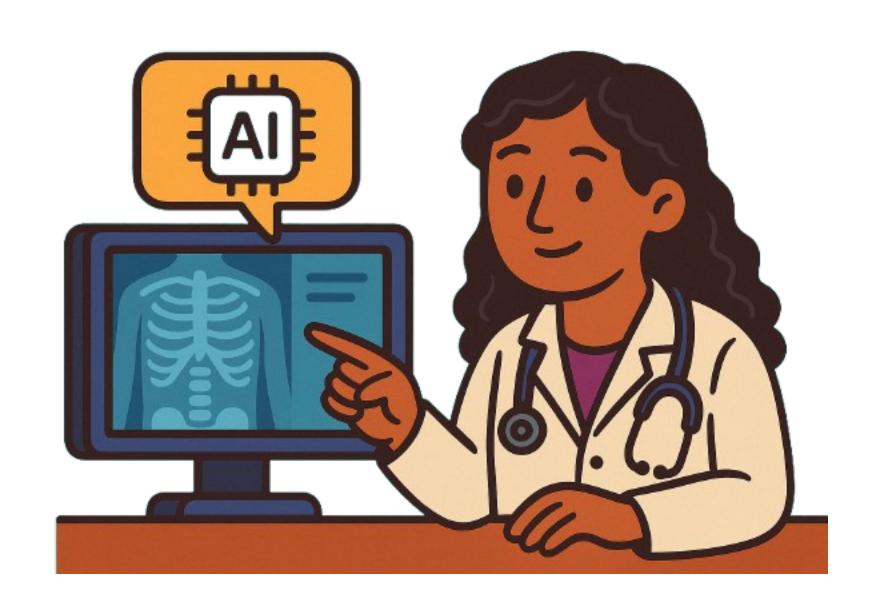
Aaron Roth UPenn



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## HOW DO WE USE AI SYSTEMS TODAY?







Increasingly, we are interacting with Al agents to do tasks and make decisions

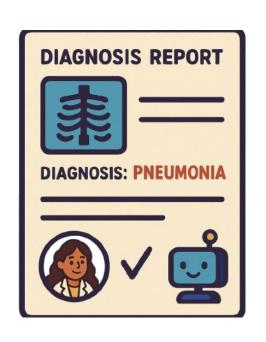
## EXAMPLE: DOCTOR USING AI SYSTEM

Patient disposition

Patient appearance

Relevant context





Medical history

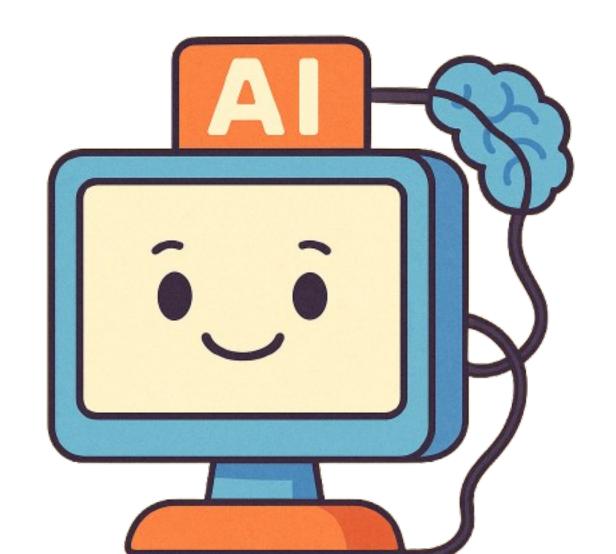


Lab reports





Medical Journals Pretrained information



## GOALS: WHAT DO WE DESIRE FROM THIS INTERACTION?

### Complementarity

• The interaction leverages the complementary skills of the Al and the human

### Agreement

• The doctor and Al model reach consensus on the decision

## Accuracy

The end outcome for the patient is positive

## Information Aggregation

• Outcome is as good as if they both had each other's complete information

We want the team to improve over either human or Al working alone

## REALITY: HUMANS USING AI SYSTEMS

Agree to disagree: the symmetry of burden of proof in human-AI collaboration

Karin Rolanda Jongsma # 1, Martin Sand # 2

#### A.I. Chatbots Defeated Doctors at Diagnosing Illness

A small study found ChatGPT outdid human physicians when assessing medical case histories, even when those doctors were using a chatbot.

By Rishika Sadam

## Humans and Al: Do they work better together or alone?

MIT Sloan Office of Communications 🔀 | Oct 28, 2024

Defining medical liability when artificial intelligence is applied on diagnostic algorithms: a systematic review

Clara Cestonaro <sup>1</sup>, Arianna Delicati <sup>1</sup>, Beatrice Marcante <sup>1</sup>, Luciana Caenazzo <sup>1</sup>, Pamela Tozzo <sup>1,\*</sup>

Al slows down some experienced software developers, study finds

By **Anna Tong** 

July 10, 2025 7:31 PM GMT+5:30 · Updated July 10, 2025

#### **Incorrect AI Advice Influences Diagnostic Decisions**

System developers must consider how AI explanation might impact reliance on Al advice

healthcare Al made up a body part – what happens when doctors don't notice?

Google's

Google dubbed an error from its Med-Gemini model a typo. Experts say it demonstrates the risks of AI in medicine.

India's Apollo Hospitals bets on AI to tackle staff workload

These systems are already being used,



# Can we design systems that guarantee that humans make better decisions when using Al?

## Roadmap:

- Collaboration via Bayesian Agreement Protocols
- Show how to relax 'Bayesian' assumptions to make these protocols tractable using calibration
- Show when such agreement protocols provably lead to information aggregation

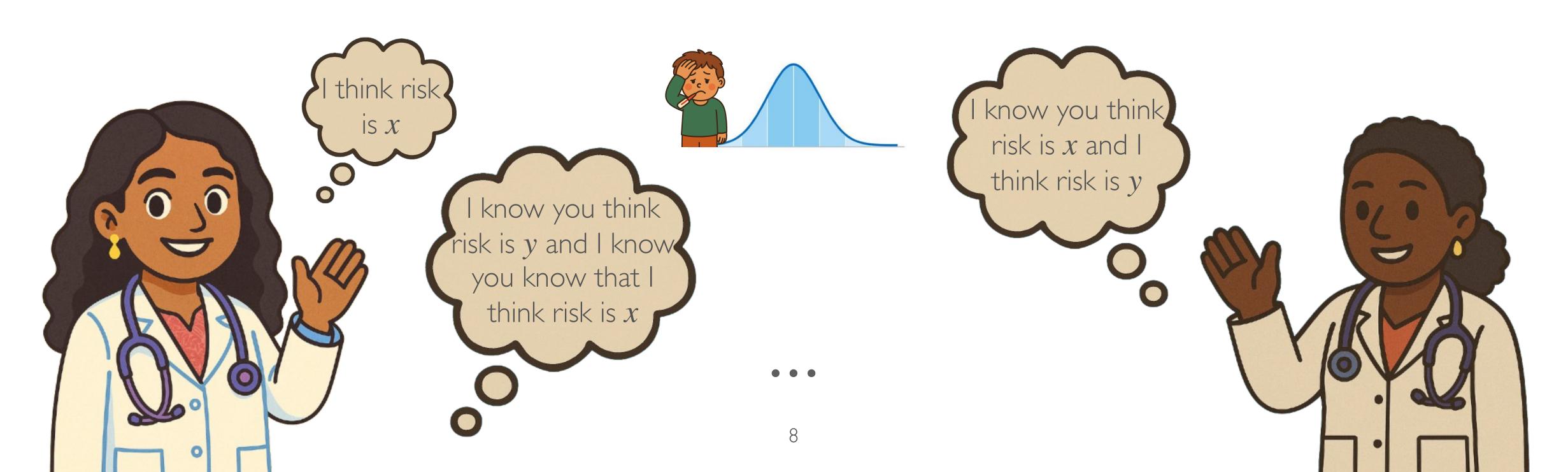
# Part I: Bayesian Agreement Protocols

## AGREEMENT

### Theorem [Aumann'76]

If two Bayesian agents have a shared prior and *common* knowledge of each other's posterior expectation, the posterior expectation will be the same.

Bayesian agents with common knowledge cannot agree to disagree

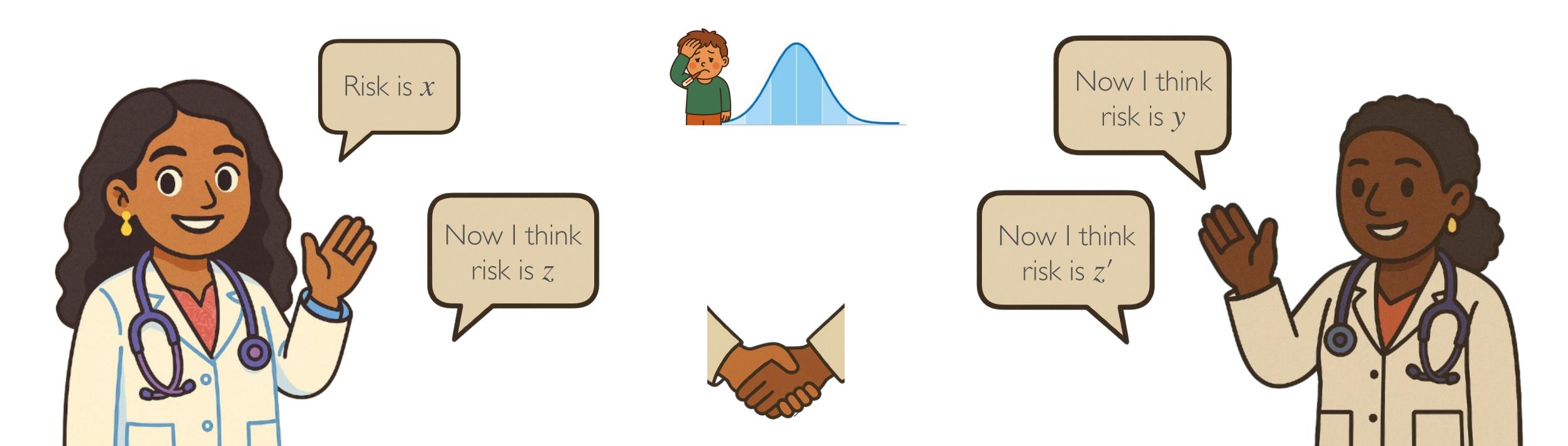


## AGREEMENT

## Theorem [Geanakoplos-Polemarchakis'82]

If the underlying state space is *finite*, agreement happens in a finite number of rounds, if each agent shares the expectation in each round.

## Bayesian agents agree in finite time



## AGREEMENT

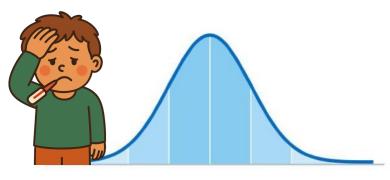
## Theorem [Aaronson'05]

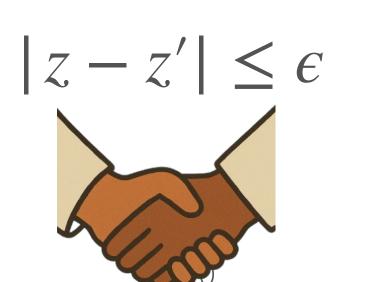
If each agent shares their posteriors at each round, for scalar predictions, with

probability  $1-\delta$ , they reach  $\epsilon$ -agreement in at most  $\frac{1}{\epsilon^2\delta}$  rounds.

Bayesian agents agree in #rounds independent of state size!









## AGREEMENT: WHY IS THIS A GOOD FRAMEWORK?

### Guaranteed Agreement

• Shows that interacting over rounds will lead to consensus quickly, independent of size of features each agent has

## Sharing only Predictions

• The protocol requires only sharing predictions bypassing the need to directly share or translate potentially incompatible raw features or explanations

## Accuracy improving

• Since the protocol is only information revealing, the final predictions will be better than either agents starting predictions

## OTHER APPROACHES TO COLLABORATION

## Vertically Federated Learning

- Use techniques like homomorphic encryption [Hardy et al.'17] to jointly train one model on combined features without revealing the raw data
- Requires cryptographic overhead, and compatible features

### Explanations

- Al provides an "explanation" for its reasoning to help the human
- Explanations can often be complex and even misleading [Bansal et al.'21, Goh et al.'24]

## • Multi-modal Learning [Hardy et al.' 17]

- Combine different data types either by merging features at the start ("early fusion") or by averaging final predictions ("late fusion")
- Requires either feature alignment or provides simple averaging which is insufficient

## AGREEMENT: WHAT ARE THE LIMITATIONS?

## Bayesian Rationality

- Humans/Al models do not behave like bayesian rational agents
- It is intractable to implement posterior calculations over complex state spaces and long interaction histories

#### Common Priors

• Unclear where a common prior would come from for a human and Al model given their different training data and experience

## Can we relax these assumptions while still guaranteeing fast agreement?

# Part 2: Tractable Agreement Protocols



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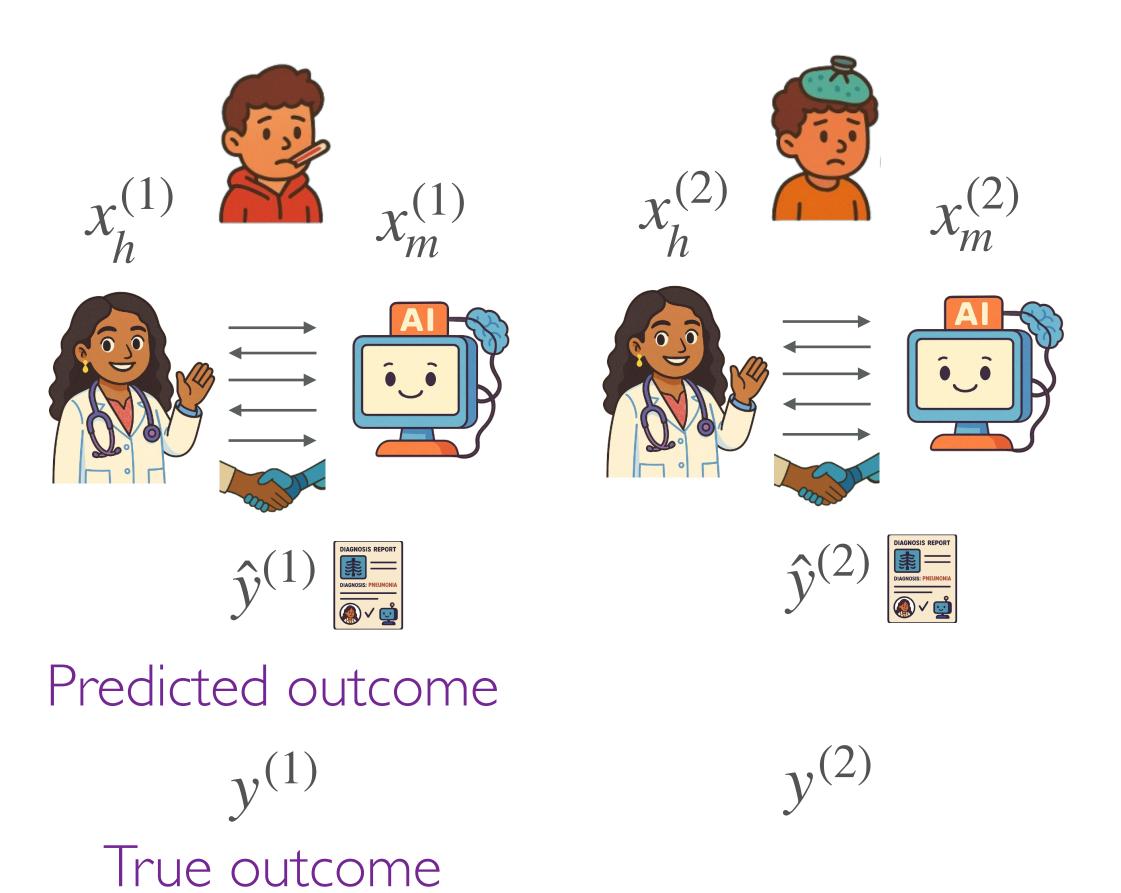
Aaron Roth UPenn

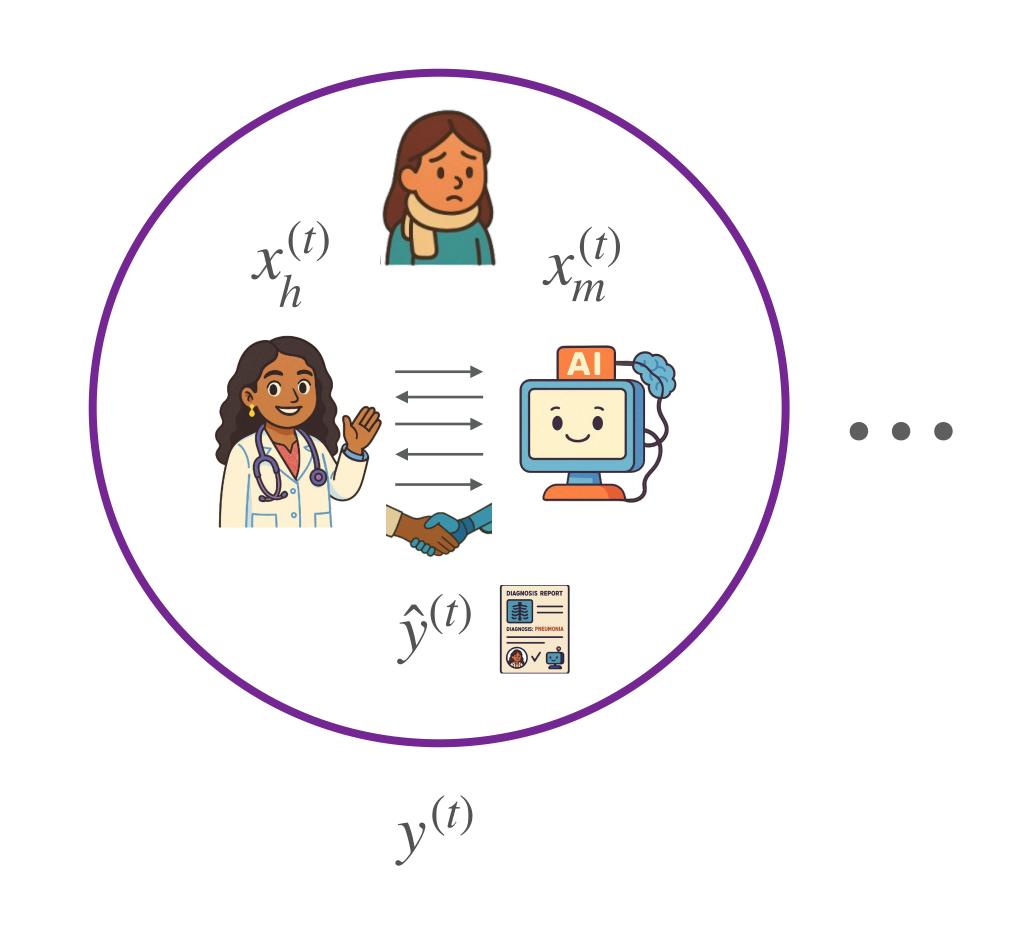
## TRACTABLE AGREEMENT PROTOCOLS: MAIN RESULTS

- We move to a repeated setting to remove the assumption of priors
- We introduce a new notion of calibration we call conversation calibration
  - Satisfied by Bayesians, but strictly weaker
  - Enforceable computationally efficiently on base model without loss of accuracy
- If agents satisfy conversation calibration then they reach fast agreement
  - The longer the conversation goes, the more accurate the prediction
- Can recover the same rates as [Aaronson'04] in one-shot Bayesian setting
- $\bullet$  Extends beyond 1-dimensional setting to multi-dimensional and action feedback

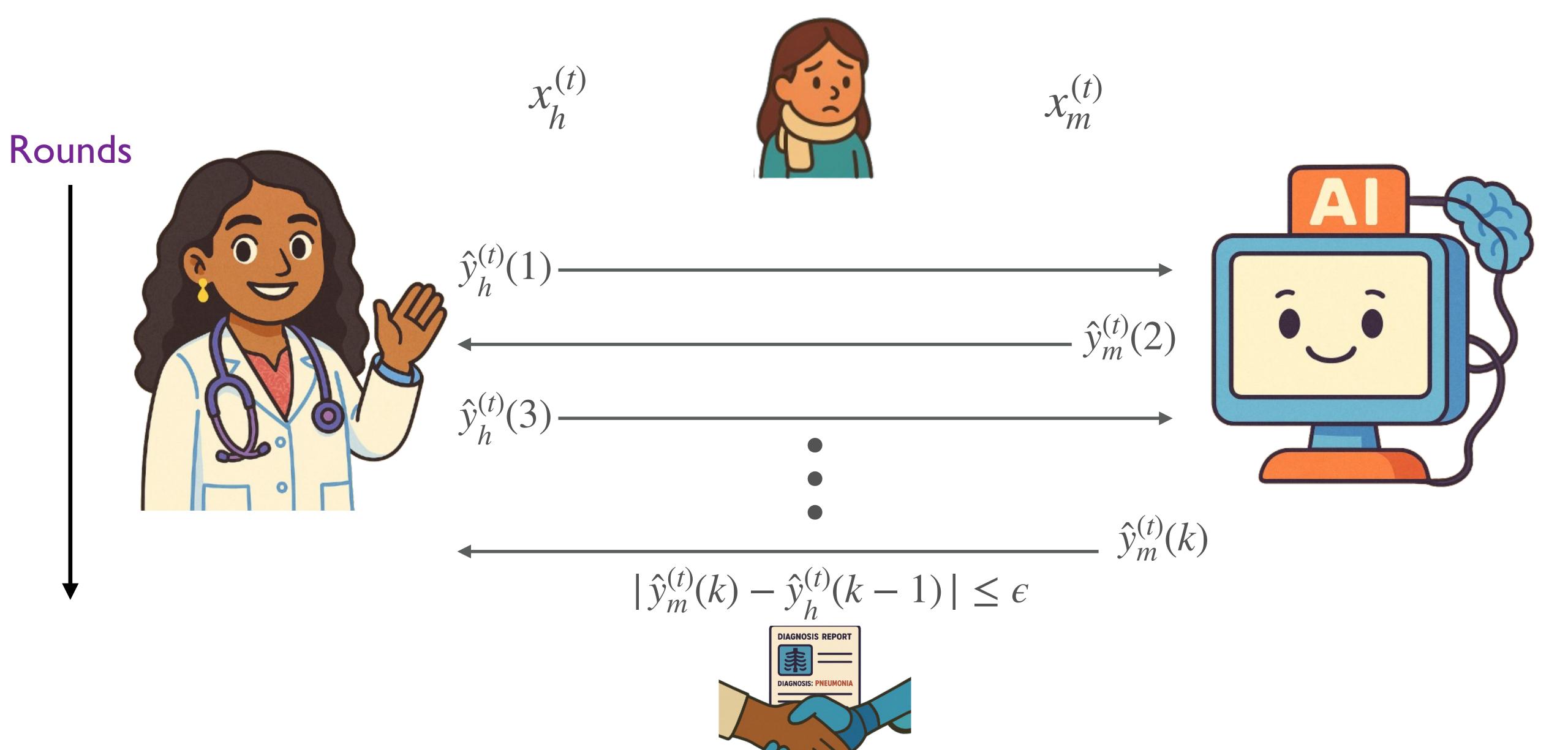
## SETUP

### Input features



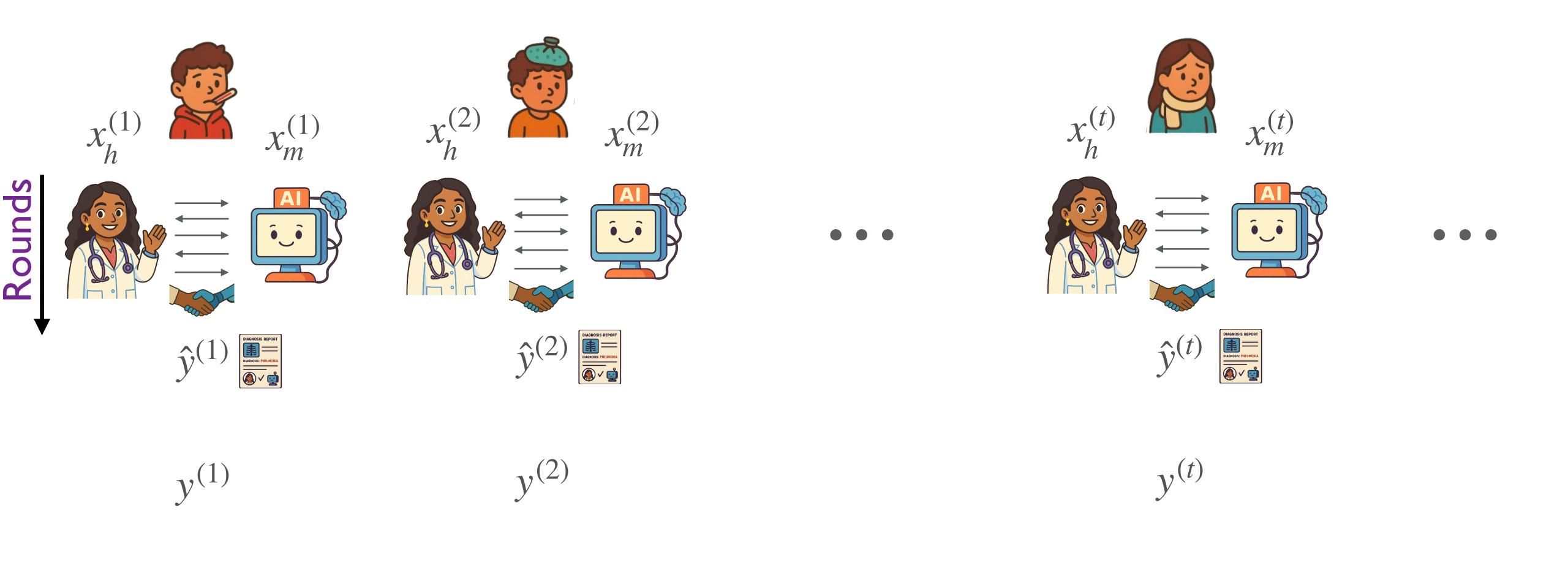


## SETUP



## SETUP

Goal: We want  $1-\delta$  fraction of the days achieve  $\epsilon$  agreement in few rounds













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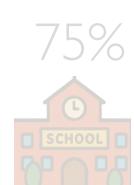
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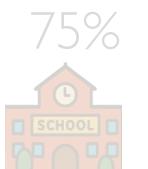




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SCHOOL











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## CONVERSATION CALIBRATION

• Calibration: Predictions should be unbiased conditional on the prediction itself.

For all 
$$p \in [0,1]$$
,  $\sum_{t=1}^{I} \mathbb{I}[\hat{y}_{m}^{t} = p](p-y^{t}) = 0$ .

Over predicts  $p$  correct on average many days

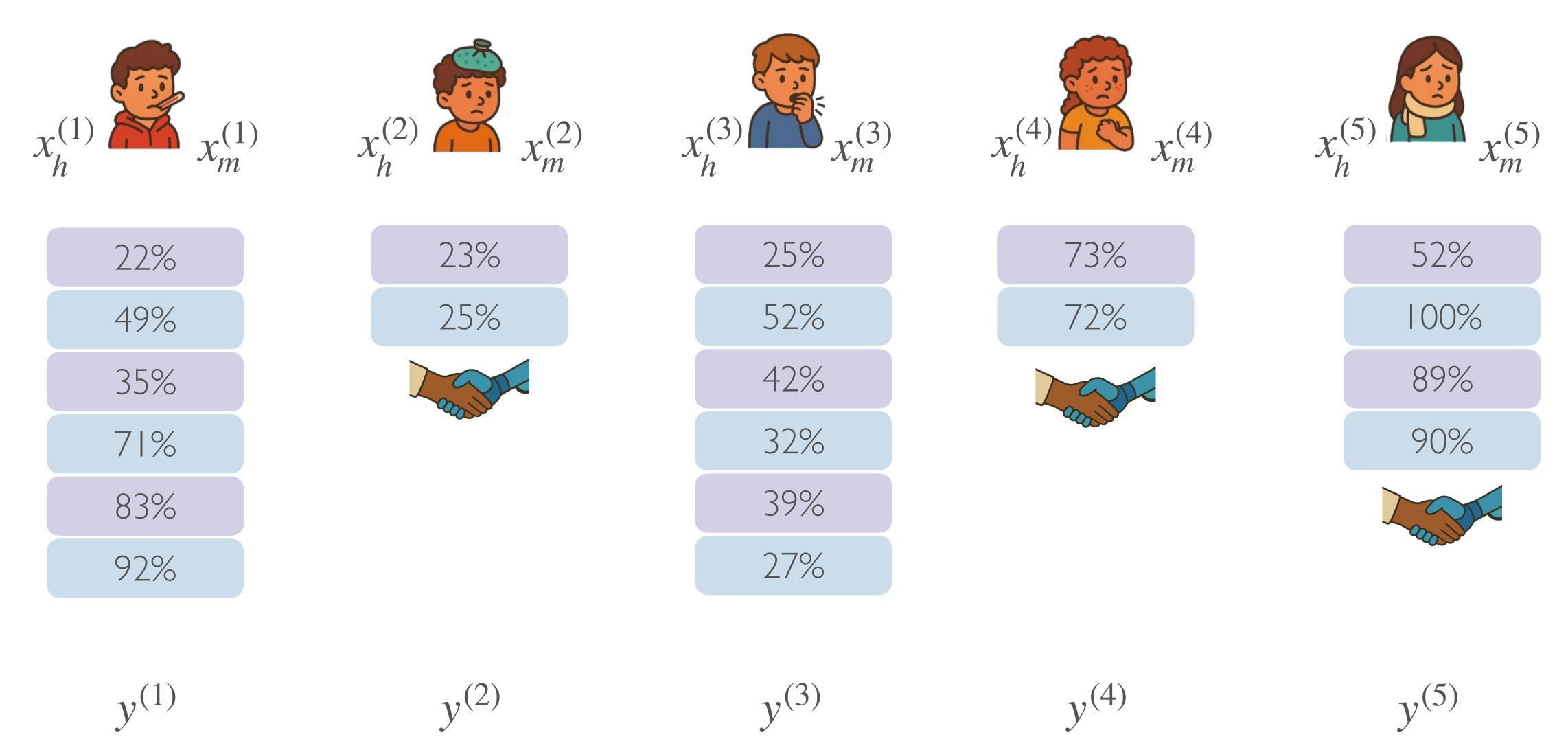
• Conversation Calibration: Predictions should be unbiased conditional on the predictions of the other agent in the previous round. For AI, for all even rounds k, and  $p, p' \in [0,1]$ ,

$$\sum_{t=1}^{T} \mathbb{I}[\hat{y}_m^{(t)}(k) = p] \mathbb{I}[\hat{y}_h^{(t)}(k-1) = p'](p-y^{(t)}) = 0.$$
 when Al after human Al's predictions are predicts  $p$  predicts  $p'$  correct on average many days

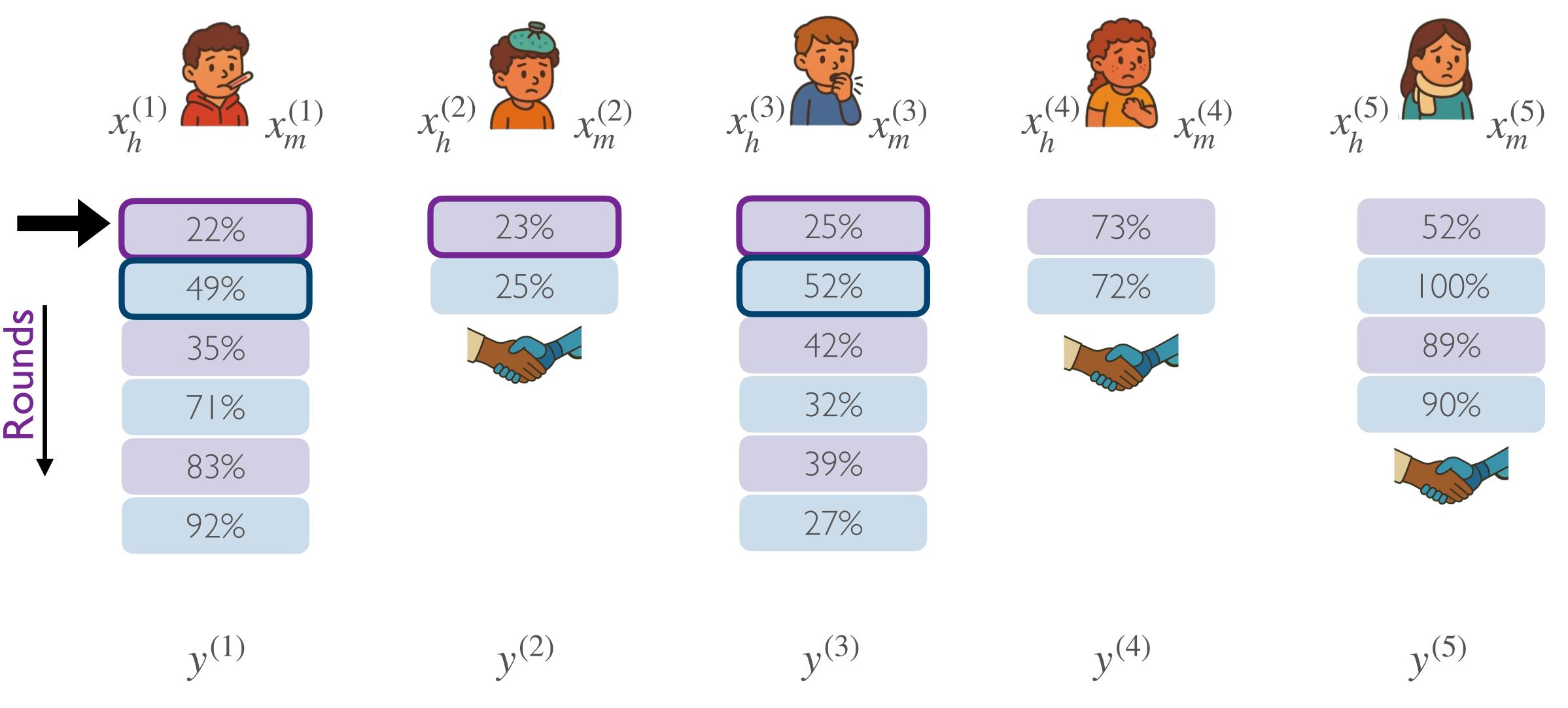
We relax this to approximate calibration and bucketing of the predictions of the other agent

## CONVERSATION CALIBRATION

Rounds



## CONVERSATION CALIBRATION



If the AI is conversation calibrated then the expectation of outcome on days 1 and 3 should be roughly 50%

## CONVERSATION CALIBRATION -> FAST AGREEMENT

## Theorem [Colina-G-Gupta-Roth'24]

If both the human and Al are (approximately) conversation calibrated then on a

 $1-\delta$  fraction of the days, they achieve  $\epsilon$ -agreement after at most K rounds for

$$K \leq \frac{1}{\epsilon^2 \delta - \beta(T)}.$$

eta(T) goes to 0 as  $T o\infty$  for the appropriate choice of bucketing and distance to calibration [Blasiok et al.'23] for both predictors

Using prior work [Qiao-Zheng'24, Arunachaleswaran et al.'25], we can design efficient algorithms with  $\beta(T) \approx T^{-1/3}$ 

## CONVERSATION CALIBRATION ->> FAST AGREEMENT

#### Proof sketch:

Consider the days on which we haven't reached agreement by round k, we know that the predictions at round k are

- at least  $\epsilon$  far from predictions at round k-1, and
- calibrated conditional on the predictions at round k-1

#### Lemma

If a sequence 2 is calibrated conditional on sequence 1 then sequence 2 has lower (or equal) squared error than sequence 1.

Sequence 2 can make better predictions within the level sets of sequence 1

## CONVERSATION CALIBRATION ->> FAST AGREEMENT

#### Two cases:

• Either  $1-\delta$  fraction of the rounds reach agreement, or



• On at least  $\delta$  fraction of the rounds, in round k, we improve upon the squared error by  $\epsilon^2$  (since predictions were  $\epsilon$  different from the predictions in round k-1)

Till we reach case 1, at each round we decrease average squared error by  $\epsilon^2 \delta$ 

Total #rounds we can disagree =

Max possible average squared error

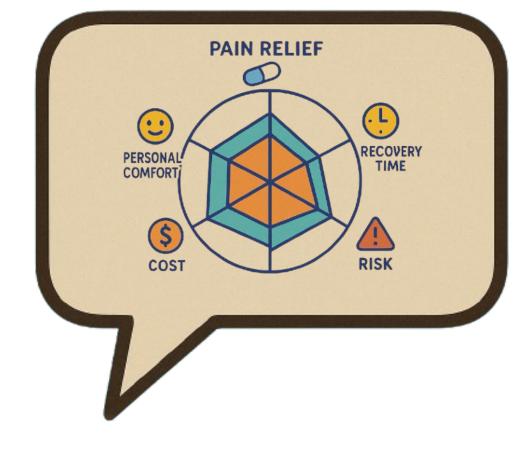
Decrease in average squared error at each round

$$pprox \frac{1}{\epsilon^2 \delta}$$

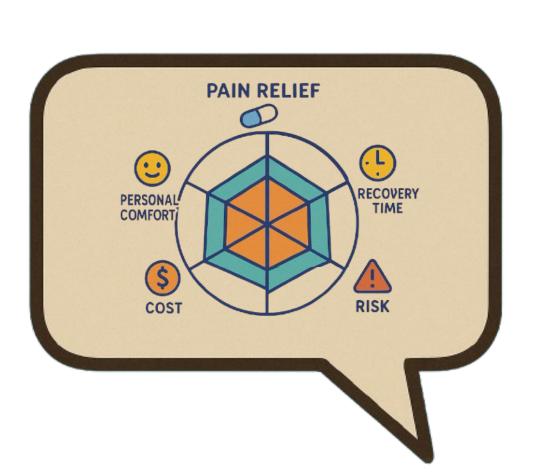
## EXTENSIONS - MULTI-DIMENSIONAL

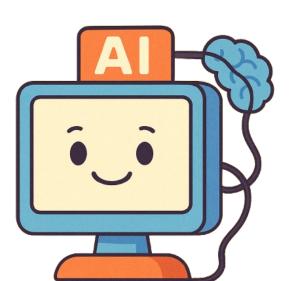
- Marginal conversation-calibration on each coordinate
- Agree when predictions on all dimensions within  $\epsilon$
- Guarantee that error in at least one dimension will go down by  $\epsilon^2 \delta /d$
- . Total squared error is  $d\Longrightarrow$  agreement happens in  $pprox \frac{d^2}{\epsilon^2\delta}$











## EXTENSIONS - ACTION FEEDBACK

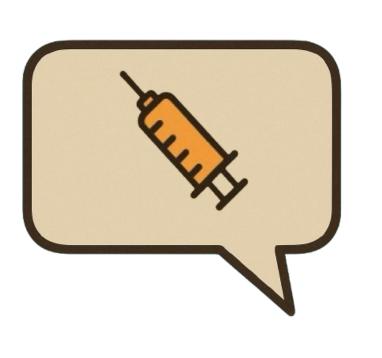
- Extend to best-response action feedback via decision-conversation-calibration (defined based on utilities)
- If no agreement then the other party can improve utility by  $\epsilon\delta$  Utility is linear
- . So we get to agreement happens in  $\approx \frac{1}{\epsilon \delta}$  rounds

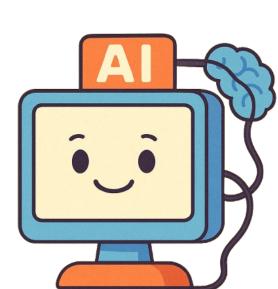
Size of action set shows up in eta(T) so we need T to be large enough before this kicks in









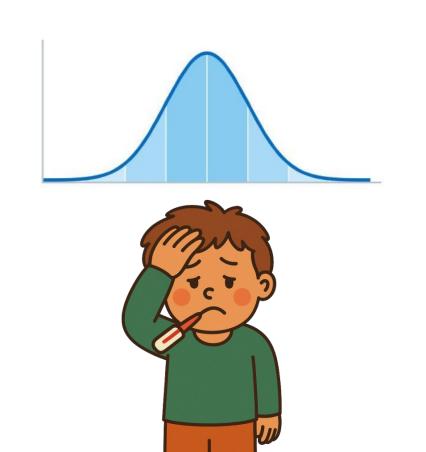


## REDUCTION TO ONE-SHOT

- Assume first day is the observed state and the other days the observation is drawn i.i.d. from the prior
- Bayesians are approximately conversation-calibrated  $T 
  ightarrow \infty$
- By our theorem,  $1-\delta$  fraction rounds will reach agreement in  $1/\epsilon^2\delta$  rounds
- But Bayesians don't need history of other rounds, so we can permute the rounds
- Therefore, probability first round reaches agreement in  $1/\epsilon^2\delta$  rounds is  $1-\delta$







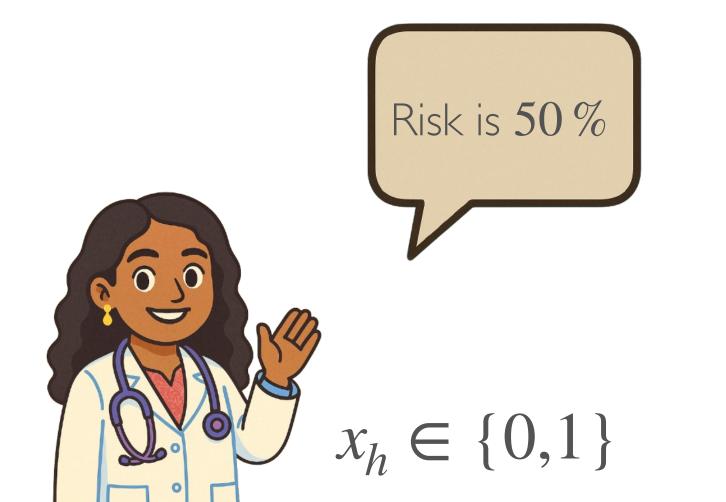




## IS AGREEMENT ENOUGH?

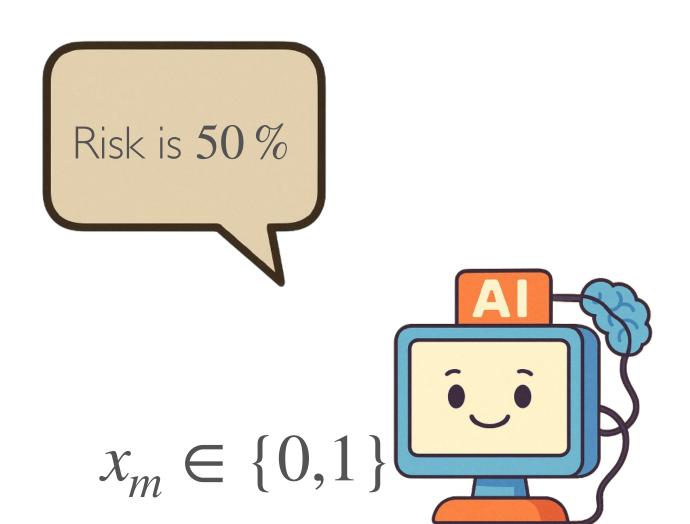
- Agreement guarantees that we improve over either party working alone
- But are we as good as the best we could have done if we saw all features?
  - Well, not always

# When can we guarantee 'information aggregation' without sharing features?



$$y = x_h + x_m \mod 2$$





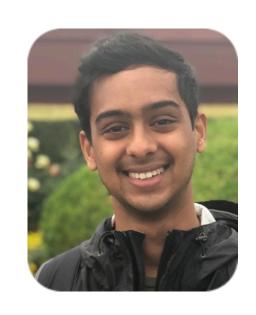
# Part 3: Information Aggregation via Agreement



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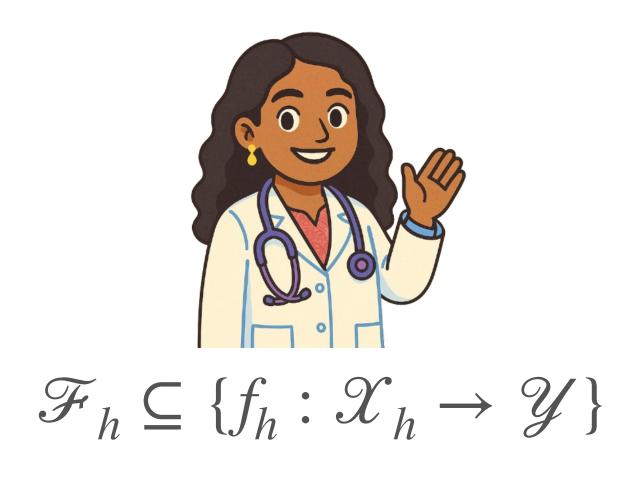


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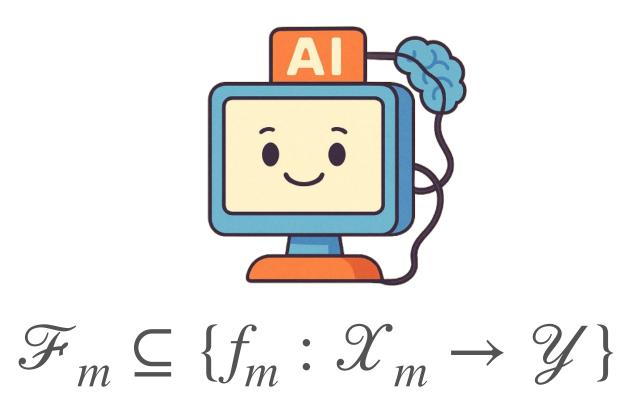
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## COLLABORATIVE PREDICTION: SETUP





$$\mathcal{F}_J \subseteq \{f_J : \mathcal{X}_h \times \mathcal{X}_m \to \mathcal{Y}\}$$



**Goal:** We want the agreed upon predictions to have low regret w.r.t. function class  $\mathcal{F}_J$  defined on the joint features  $x = (x_h, x_m)$ 

Not possible always (recall parity), so when is it true?

## COLLABORATIVE PREDICTION: DEFINITIONS

## Weak-learning (recall boosting):

- For all distributions, Bounded linear predictors satisfy this with  $w(\gamma) = \Theta(\gamma^2)$ 
  - If there is some  $f_I \in \mathcal{F}_I$  that improves over the constant predictor by  $\gamma$
  - Then there exists either  $f_h \in \mathcal{F}_h$  over the human's features or  $f_m \in \mathcal{F}_m$  over the Al's features that also improves over the constant predictor by  $w(\gamma)$

[Kong-Schoenebeck'23, Frongillo et al.'23] studied assumptions that do guarantee agreement implies information aggregation for Bayesians. Ours are strictly weaker!

## COLLABORATIVE PREDICTION: MAIN RESULT

#### Conversation Multi-Calibration

Multi-calibration ← no-swap regret

For AI, for all even rounds k, values  $p, p' \in [0,1]$ , and  $f_m \in \mathcal{F}_m$ 

$$\sum_{t=1}^{T} \mathbb{I}[\hat{y}_m^{(t)}(k) = p] \mathbb{I}[\hat{y}_h^{(t)}(k-1) = p'] f_m(x_m)(p-y^{(t)}) = 0$$
 when AI after human predicts  $p'$  after human predicts  $p'$  when checked against a different rule  $f_m$ 

## Theorem [Colina-GlobusHarris-G-Gupta-Roth-Shi'25]

If both the human and Al are (approximately) conversation multi-calibrated with respect to  $\mathcal{F}_h$  and  $\mathcal{F}_m$  respectively and  $(\mathcal{F}_h, \mathcal{F}_m, \mathcal{F}_J)$  satisfy weaklearnability then agreement\* implies low regret with respect to  $\mathcal{F}_J$ .

## COLLABORATIVE PREDICTION: HIGH-LEVEL PROOF

#### Proof sketch:

- We run the protocol till the end of K rounds
- $\bullet$  We show that there is a round k where the fraction of disagreements are small
- At this round across days, the predictions have low-swap regret with  $\mathcal{F}_h \cup \mathcal{F}_m$
- Using weak-learning guarantee on the level-sets, we get that this should imply low external regret to  $\mathcal{F}_J$
- Running for more rounds breaks the low-swap regret condition, but regret cannot increase by much

# Take-aways:

- Simple interaction works: Exchanging only predictions or actions (no raw features!) can drive effective collaboration
- Tractable conditions suffice: We don't need unrealistic Bayesian assumptions; efficiently checkable conditions like conversation calibration/swap regret suffice
- Agreement ⇒ Aggregation: Under a natural "weak learning" condition, protocols guaranteeing fast agreement also achieve information aggregation
- Provides a practical path: Offers efficient algorithms to build systems where humans and Al provably make better decisions together

Thank you for listening!