

Elliptic Curves and the Special Values of L-functions
ICTS, 2021

**Introduction to Elliptic Curves:
Lecture 1**

Anupam Saikia
*Department of Mathematics,
Indian Institute of Technology Guwahati*

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Elliptic curves are ubiquitous in mathematics. Study of elliptic curves brings together number theory, algebra, analysis and algebraic geometry.

- Elliptic curves have been used to prove **Fermat's Last Theorem**.
- Elliptic curves have provided breakthrough toward resolving the **Congruent Number Problem**.
- Elliptic curves have been very useful in **cryptography**, i.e., in coding messages for secure transmission.
- Elliptic curves are also used in **factorization** algorithm for integers.
- The **Birch and Swinnerton-Dyer Conjecture**, one of the seven Millennium Problems, is a prediction about relation between the algebraic and the analytic properties of an elliptic curve.

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Weierstrass Equation for an Elliptic Curve

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- An elliptic curve over a field K can be defined as a *non-singular projective curve* of *genus 1* with a specified point $\mathcal{O} \in E(K)$.

- Using the Riemann-Roch Theorem, one has an equivalent description of elliptic curve as a plane cubic curve:

An elliptic curve over a field K is a '*non-singular curve*' defined by an equation of the form

$$E : y^2 + a_1xy + a_3y = x^3 + a_2x^2 + a_4x + a_6, \quad a_i \in K,$$

together with '*a point at infinity*' \mathcal{O} .

- When the *characteristic* of the underlying field K is not 2 or 3, the Weierstrass equation above can be simplified to

$$y^2 = x^3 + ax + b, \quad a, b \in K.$$

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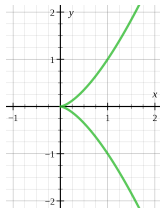
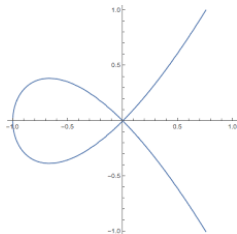
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Non-singularity

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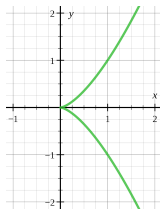
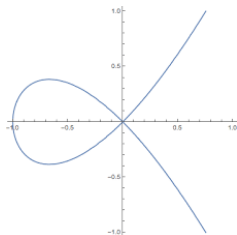
- A curve in \mathbb{R}^2 is called **non-singular** if it has a well-defined **tangent** at each of its points.
- For example, $y^2 = x^2(x + 1)$ and $y^2 = x^3$ are **singular** at $(0, 0)$ in the diagram above.

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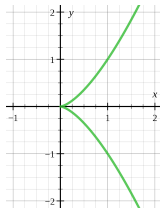
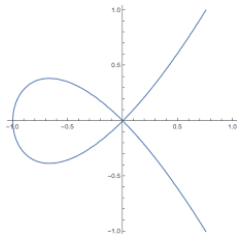
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Singular Points

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- For a curve $f(x, y) = 0$ in \mathbb{R}^2 , the slope of the **tangent** at a point $P = (x_0, y_0)$ is given by

$$\frac{dy}{dx}(P) = -\frac{\partial f / \partial x(P)}{\partial f / \partial y(P)}.$$

- The tangent is not well-defined at (x_0, y_0) on $f(x, y) = 0$ if

$$\frac{\partial f}{\partial x}(x_0, y_0) = 0 = \frac{\partial f}{\partial y}(x_0, y_0).$$

- Thus, (x_0, y_0) is a **singular point** of the cubic curve given by $f(x, y) = y^2 - (x^3 + ax + b)$ if and only if $y_0 = 0$, $3x_0^2 + a = 0$, and $x_0^3 + ax_0 + b = 0$, i.e., x_0 is a **double root** of $x^3 + ax + b$.
- In general, a curve over any field K (not necessarily \mathbb{R}) defined by a polynomial $f(x, y) \in K[x, y]$ is called non-singular at $P = (x_0, y_0)$ if the Jacobian matrix $\left(\frac{\partial f}{\partial x}(P), \frac{\partial f}{\partial y}(P)\right)$ has rank 1.

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The Discriminant

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- The **discriminant** of a cubic polynomial $g(x) \in K[x]$ is given by

$$\Delta(g) = \prod_{i>j} (\alpha_i - \alpha_j)^2 = (\alpha_1 - \alpha_2)^2 (\alpha_2 - \alpha_3)^2 (\alpha_1 - \alpha_3)^2,$$

where α_i 's are the roots of $g(x)$.

- So $g(x)$ has repeated roots if and only if $\Delta(g) = 0$.
- It can be easily computed that the discriminant of $g(x) = x^3 + ax + b$ is $\Delta(g) = -(4a^3 + 27b^2) \in K$.
- Hence the curve $y^2 = x^3 + ax + b$ is **non-singular** if

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Intersection with a Straight Line: a diagram

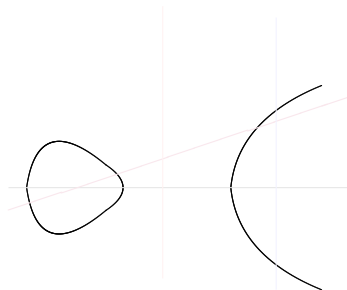
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The points with **real coordinates** on $E : y^2 = x^3 - 25x$ and
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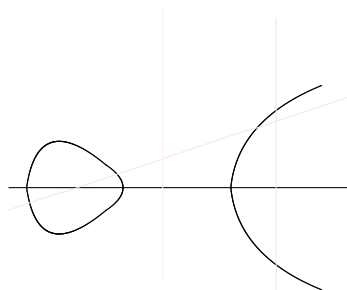
$$(mx + c)^2 = x^3 - 25x$$



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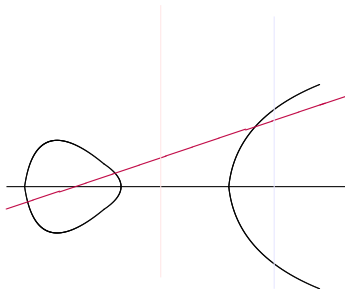
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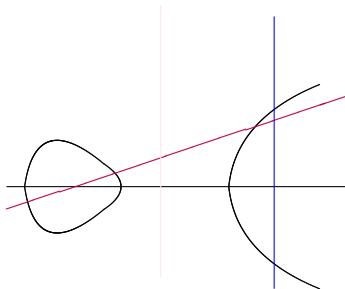
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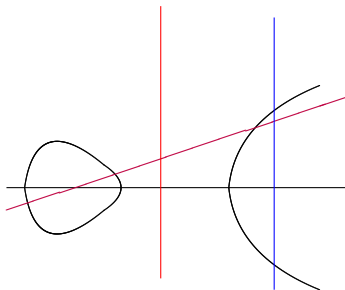
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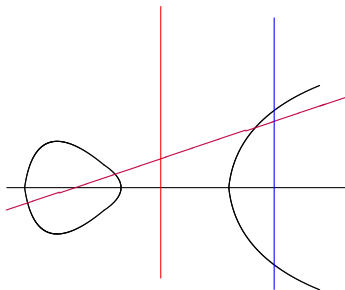
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The Point at Infinity on an Elliptic Curve

- Any non-vertical straight line intersects the curve at three points.
- A non-vertical line $y = mx + c$ ($m, c \in \mathbb{R}$) will have three real points of intersection or one real and two complex points of intersection, as seen by substitution $y = mx + c$ in $y^2 = x^3 + ax + b$.
- However, the vertical lines $x = x_0$ will have either two real or two complex points of intersection. For a consistent theory, we need a third point of intersection. We adjoin an additional 'point at infinity' to the curve.
- This point can be visualized as lying on the top (and the bottom) of the xy -plane at infinity.
- Any two vertical lines intersect at the point at infinity, say \mathcal{O} .
- The point at infinity is best understood in terms of projective coordinates.

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- However, the vertical lines $x = x_0$ will have either two real or two complex points of intersection. For a consistent theory, we need a third point of intersection. We adjoin an additional 'point at infinity' to the curve.
- This point can be visualized as lying on the top (and the bottom) of the xy -plane at infinity.
- Any two vertical lines intersect at the point at infinity, say \mathcal{O} .
- The point at infinity is best understood in terms of projective coordinates.

The Projective Space over a Field K

Introduction

The Point at
Infinity

Group Structure

- Let \overline{K} denote the algebraic closure of a field K . Define a relation \sim on the set of non-zero $(n+1)$ -tuples

$$(a_0, a_1, \dots, a_n) \in \overline{K}^{n+1} \setminus \{(0, 0, \dots, 0)\} \quad \text{by}$$

$$(a_0, a_1, a_2, \dots, a_n) \sim (a'_0, a'_1, a'_2, \dots, a'_n) \text{ if and only if} \\ a'_0 = ta_0, \quad a'_1 = ta_1, \quad \dots, \quad a'_n = ta_n \quad \text{for some } t \in \overline{K}^\times.$$

Clearly, \sim is an equivalence relation.

- The **projective n -space** over K is defined as the set of equivalence classes

$$\mathbb{P}^n = \frac{\{(a_0, a_1, a_2, \dots, a_n) \in \overline{K}^{n+1} \setminus (0, 0, \dots, 0)\}}{\sim}.$$

- We denote the **affine n -space** over K by

$$\mathbb{A}^n = \{(x_1, x_2, \dots, x_n) : x_i \in \overline{K}\}.$$

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The Points in the Projective Plane

- Let $[a : b : c]$ denote a point in \mathbb{P}^2 , i.e.,

$$[a : b : c] = \{t(a, b, c) \in \overline{K}^3 \setminus (0, 0, 0) \mid t \neq 0\}.$$

- Any point (x, y) in the affine plane A^2 corresponds to a unique point $[x : y : 1]$ in \mathbb{P}^2 .
- For a point $[a : b : c]$ in \mathbb{P}^2 with $c \neq 0$, we get a unique point $(\frac{a}{c}, \frac{b}{c})$ in the affine plane A^2 .
- However, \mathbb{P}^2 has additional points with $c = 0$ which cannot be identified with the points in the affine plane in this way. The points $[a : b : 0]$ in \mathbb{P}^2 can be thought of as representation of *directions of straight lines parallel to the line $ay = bx$ in the affine plane A^2* . These additional points are known as the *points at infinity* in \mathbb{P}^2 .

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Lines in the Projective Plane

Introduction

The Point at
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Group Structure

- A line in \mathbb{P}^2 consists of a line in \mathbb{A}^2 together with the point at infinity specified by its direction.
- Any two parallel lines in \mathbb{P}^2 intersect at the point at infinity corresponding to their common direction.
- The set of all points at infinity is itself considered to be a line L_∞ , and the intersection of any other line L with L_∞ is the point at infinity corresponding to the direction of L .
- A vertical line in \mathbb{A}^2 contains the additional point $[0 : 1 : 0]$ in \mathbb{P}^2 (as its direction), therefore we can say that any two vertical lines intersect at the point $[0 : 1 : 0]$ at infinity.

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Affine Variety

- Given an ideal I the polynomial ring $\overline{K}[Y_1, \dots, Y_n]$, we define an affine algebraic set as

$$V_I = \{P \in \mathbb{A}^n \mid f(P) = 0 \quad \forall f \in I\}.$$

- Given an affine algebraic set V , we associate an ideal $I(V)$ in $\overline{K}[Y_1, \dots, Y_n]$ generated by

$$\{f \in \overline{K}[Y_1, \dots, Y_n] \mid f(P) = 0 \quad \forall P \in V\}.$$

- An affine algebraic set is called an affine variety if $I(V)$ is a prime ideal in $\overline{K}[Y_1, \dots, Y_n]$.
- An affine variety V is said to be defined over K if its ideal $I(V)$ can be generated by polynomials in $K[Y_1, \dots, Y_n]$.

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Projective Variety

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- A polynomial $f \in \overline{K}[X_0, \dots, X_n]$ is called **homogenous of degree d** if

$$f(\lambda X_0, \dots, \lambda X_n) = \lambda^d f(X_0, \dots, X_n) \quad \forall \lambda \in \overline{K}^\times.$$

An ideal I in $\overline{K}[X_0, \dots, X_n]$ is called a **homogenous ideal** if it generated by homogenous polynomials.

- Given a homogenous ideal I , we define a **projective algebraic set** as

$$V_I = \{P \in \mathbb{P}^n \mid f(P) = 0 \text{ for all homogenous } f \in I\}.$$

- Given a projective algebraic set V , we associate a homogenous ideal $I(V)$ in $\overline{K}[X_0, \dots, X_n]$ generated by

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The Projective Closure of an Affine Variety

Introduction

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- Given any $f \in \overline{K}[Y_1, \dots, Y_n]$ of degree d , we can define a homogenous polynomial

$$f^*(X_0, \dots, X_n) = X_n^d f\left(\frac{X_0}{X_n}, \dots, \frac{X_n}{X_n}\right) \in \overline{K}[X_0, \dots, X_n].$$

- Given an affine algebraic set V in \mathbb{A}^n , we can think of it as a subset of \mathbb{P}^n via the embedding

$$\phi_n : \mathbb{A}^n \longrightarrow \mathbb{P}^n, \quad (y_1, \dots, y_n) \mapsto [y_1 : \dots : y_n : 1].$$

- The projective closure of V is the projective algebraic set \overline{V} whose homogenous ideal $I(V)$ is generated by $\{f^*(X_0, \dots, X_n) \mid f \in I(V)\}$.

- If V is an affine variety, the \overline{V} is a projective variety with $\overline{V} \cap \mathbb{A}^n = V$.

- We consider an elliptic curve as the projective closure of the affine curve corresponding to the ideal generated by the polynomial $f(x, y) = y^2 - (x^3 + ax + b) \in K[x, y]$.

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$$f^*(X_0, \dots, X_n) = X_n^d f\left(\frac{X_0}{X_n}, \dots, \frac{X_n}{X_n}\right) \in \overline{K}[X_0, \dots, X_n].$$

- Given an affine algebraic set V in \mathbb{A}^n , we can think of it as a subset of \mathbb{P}^n via the embedding

$$\phi_n : \mathbb{A}^n \longrightarrow \mathbb{P}^n, \quad (y_1, \dots, y_n) \mapsto [y_1 : \dots : y_n : 1].$$

- The projective closure of V is the projective algebraic set \overline{V} whose homogenous ideal $I(V)$ is generated by

$$\{f^*(X_0, \dots, X_n) \mid f \in I(V)\}.$$

- If V is an affine variety, the \overline{V} is a projective variety with $\overline{V} \cap \mathbb{A}^n = V$.

- We consider an elliptic curve as the projective closure of the affine curve corresponding to the ideal generated by the polynomial

$$f(x, y) = y^2 - (x^3 + ax + b) \in K[x, y].$$

The Projective Closure of an Affine Variety

Introduction

The Point at
Infinity

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Elliptic Curve as a Projective Variety

Introduction

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- In the projective plane, the equation of an elliptic curve is the homogenized equation $E_H : Y^2 Z = X^3 + aXZ^2 + bZ^3$ using the substitution $x = \frac{X}{Z}$ and $y = \frac{Y}{Z}$ in the affine equation $E : y^2 = x^3 + ax + b$.
- The affine points on E correspond to the points $[X : Y : 1]$ lying on E_H . But the elliptic curve has additional points $[X : Y : Z]$ in the projective plane given by $Z = 0$.
- Substituting $Z = 0$ in the homogenized equation, we obtain $X^3 = 0$, i.e., $X = 0$, and hence $Y \neq 0$. Therefore, an elliptic curve contains only one additional point in the projective plane, which can be taken as $[0 : 1 : 0]$.
- The point $[0 : 1 : 0]$ is known as the point at infinity on the elliptic curve and denoted by \mathcal{O} . It is a point of inflection for the curve, as it is a point of multiplicity 3.

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Sections

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The Point at
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Group Structure

Sections

Introduction

The Point at
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Group Structure

1 Introduction

2 The Point at Infinity

3 Group Structure

Group Structure

Introduction

The Point at
Infinity

Group Structure

- The points on an elliptic curve have the **structure of a group**.
- Given two points P and Q on E , we can add them in a geometric way to get a third point R on E .
- For this addition of points, we have
 - **identity element**,
 - **inverse for each point**,
 - **associativity** and
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The Chord and Tangent Method

Introduction

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- Let us fix a point O on E . It is convenient to take the point at infinity \mathcal{O} as O .
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- Then we draw a chord joining $P * Q$ and O , and this chord hits E at a third point R , which we declare to be the sum of P and Q , denoted $P \oplus Q = R$.
- One can verify that this operation is commutative, associative (the proof is non-trivial), has O as the identity (ie, $P \oplus O = P$ for all P), and each point P has an inverse (ie, given a point P on E , we can find a point T on E with $P \oplus T = O$).

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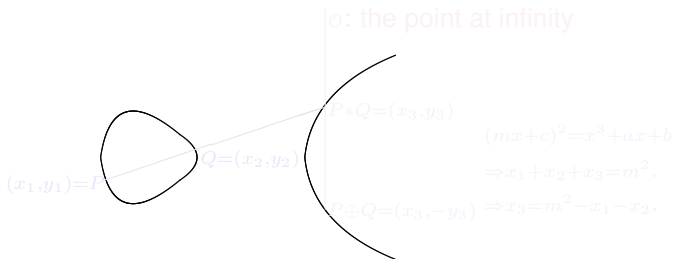
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Addition on Elliptic Curve: A Diagram

Introduction

The Point at Infinity

Group Structure



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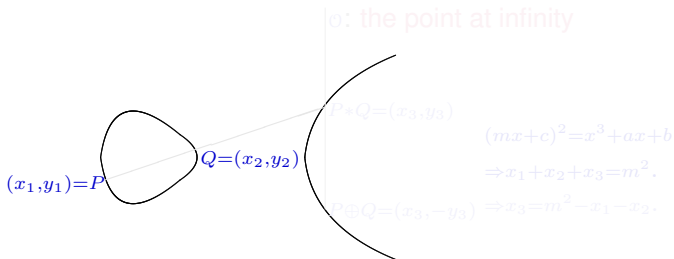
$$x(P \oplus Q) = \left(\frac{y(P) - y(Q)}{x(P) - x(Q)} \right)^2 - x(P) - x(Q).$$

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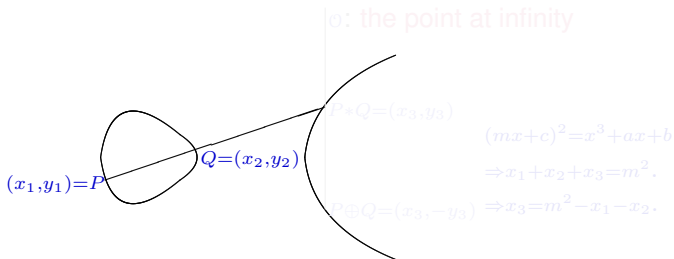
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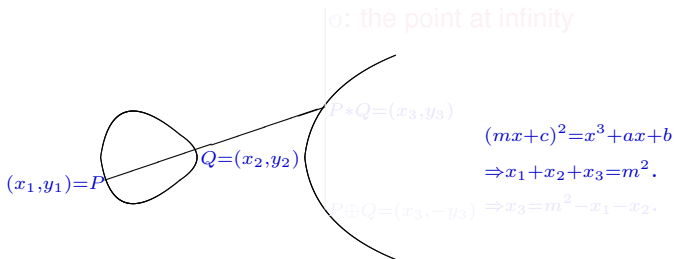
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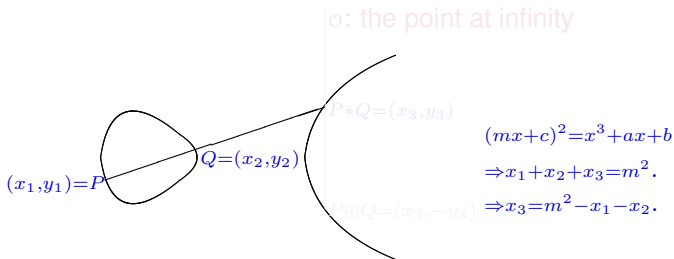
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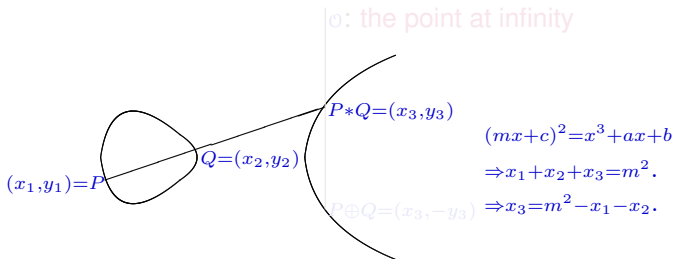
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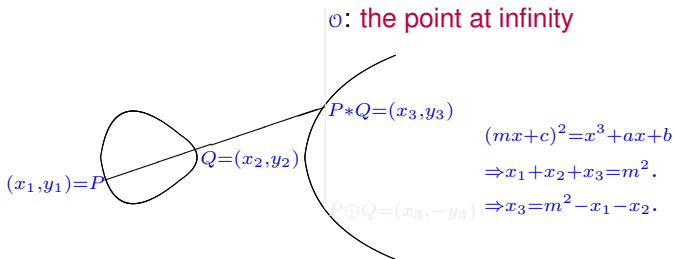
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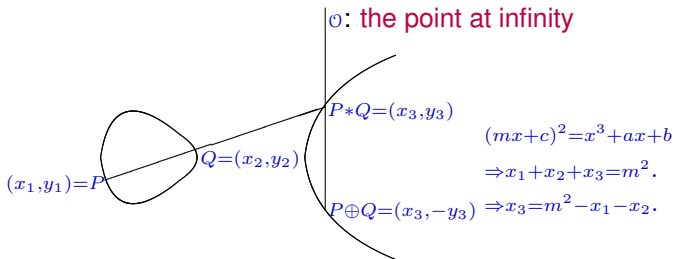
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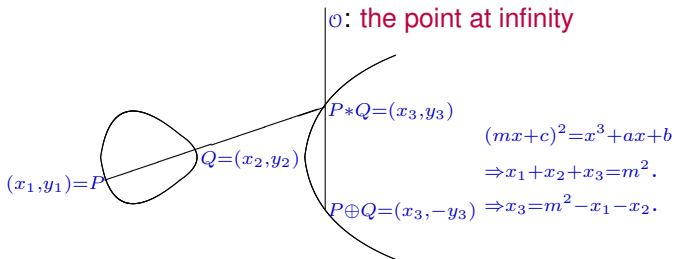
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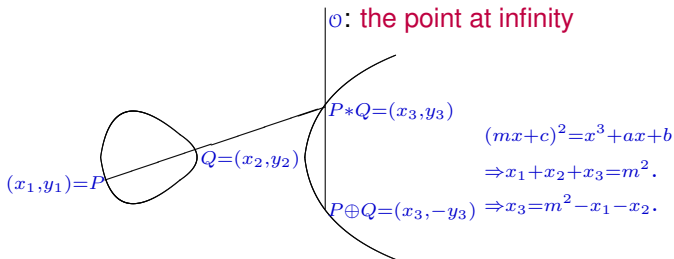
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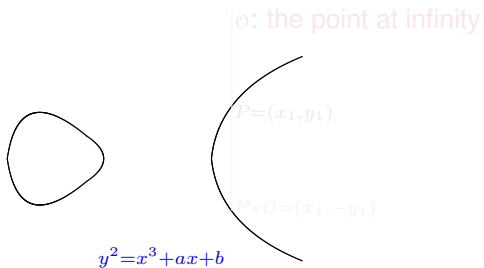
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\mathcal{O} is the Identity

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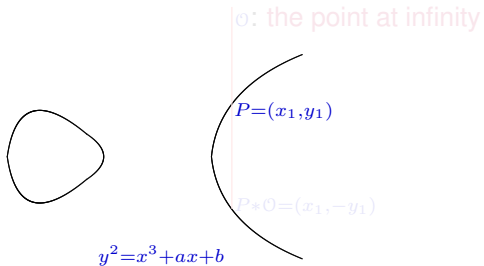
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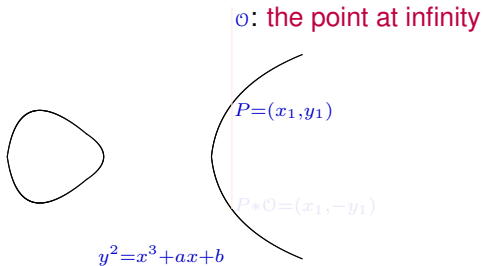
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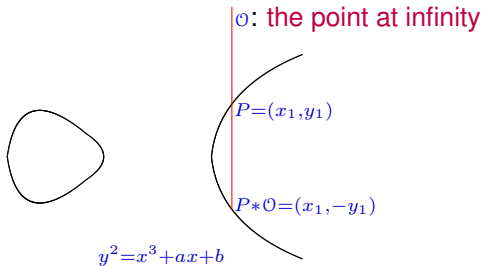
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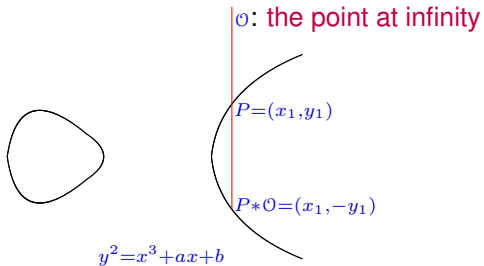
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\mathcal{O} is the Identity

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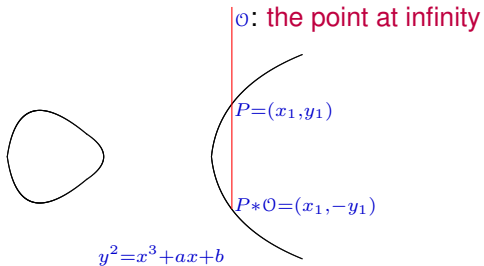
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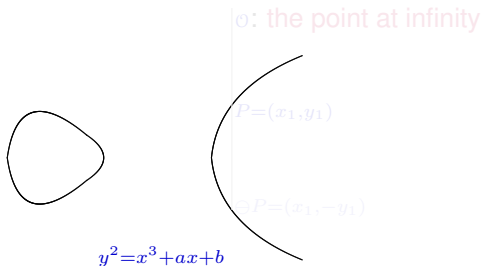
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The Inverse of a Point

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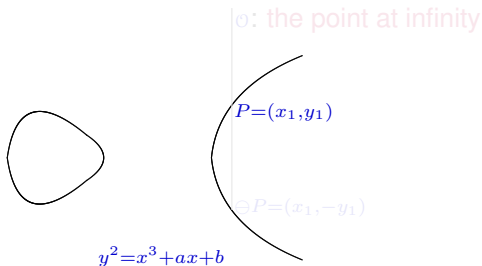
The Point at
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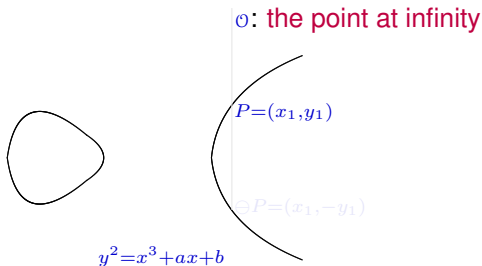
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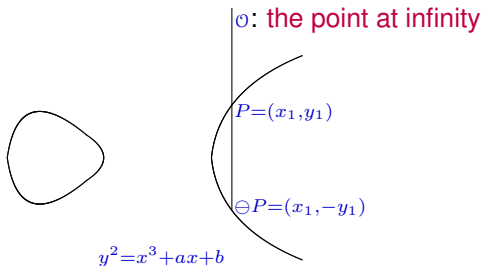
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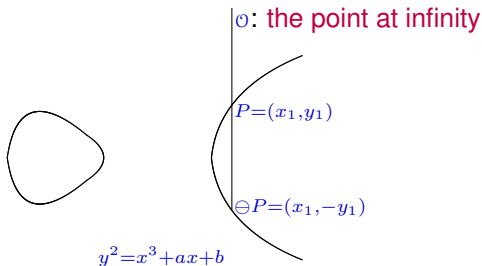
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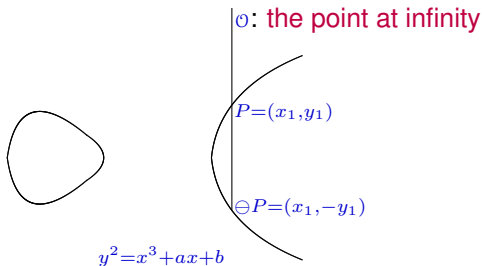
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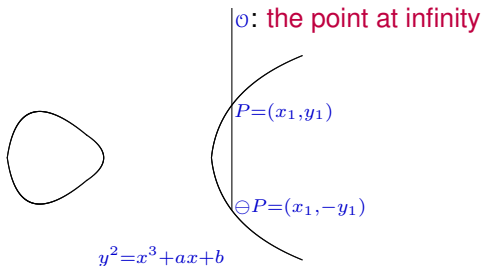
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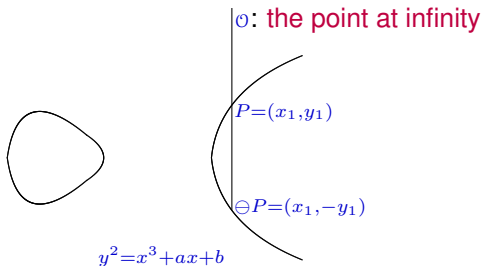
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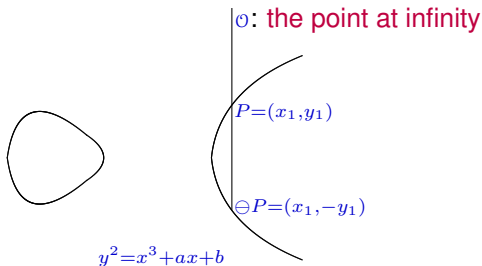
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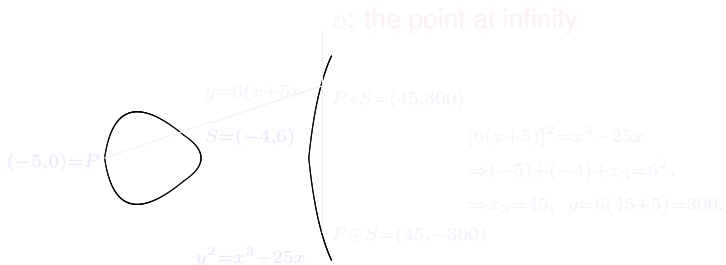
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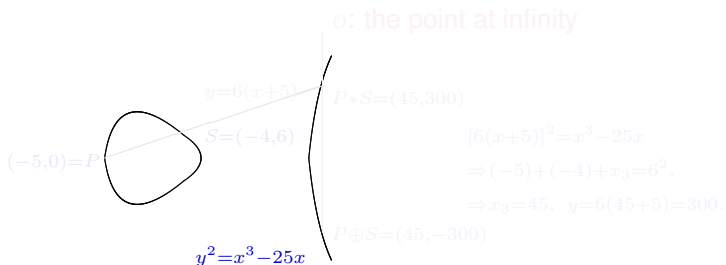
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Addition on E : an Example



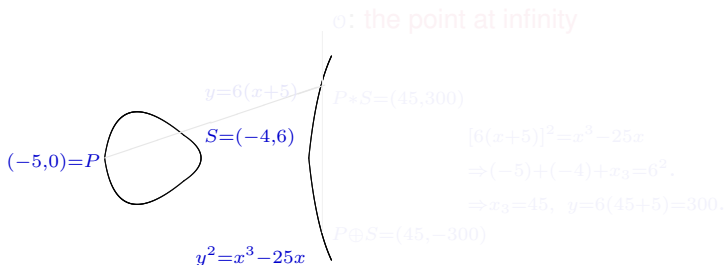
- The coefficient of x^2 will be the negative of the sum of the three roots. Thus $36 = (-5) + (-4) + x$, or $x(P * S) = 45$, and $y(P * S) = 6(45 + 5) = 300$.
- Note that the vertical line through $P * S = (45, 300)$ (and 0) hits the curve at the point $(45, -300)$.
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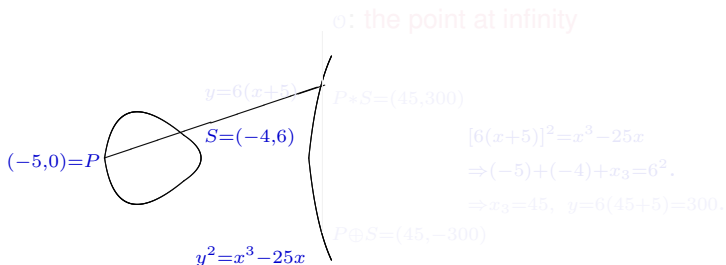
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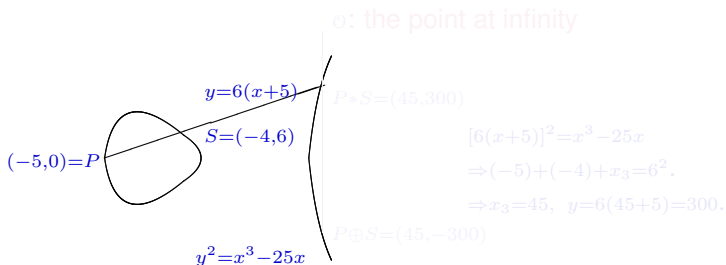
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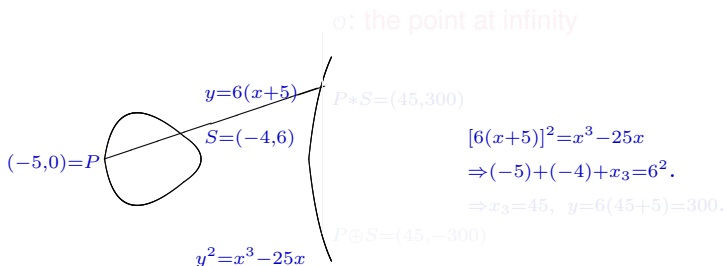


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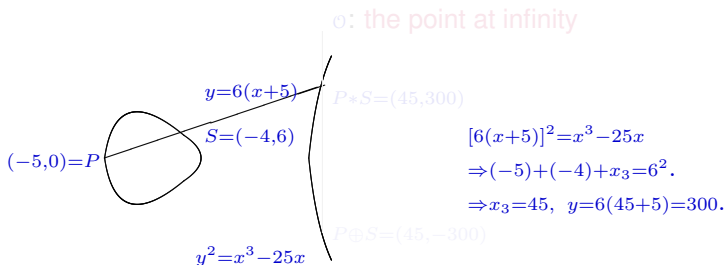
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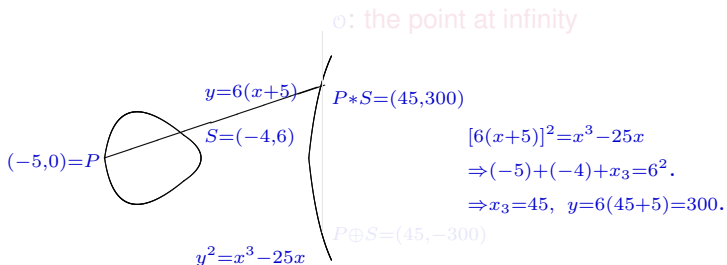
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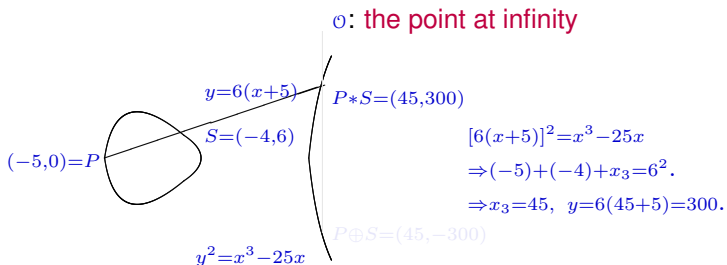
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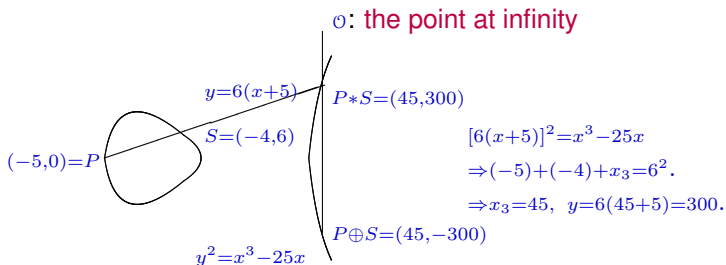
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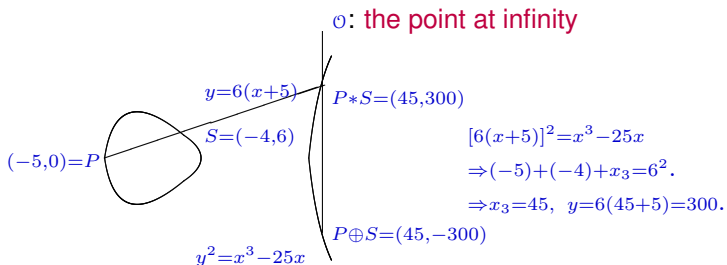
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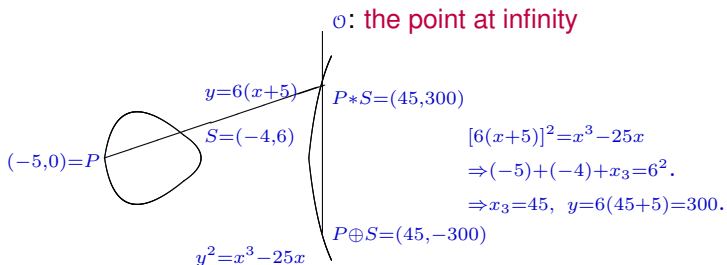
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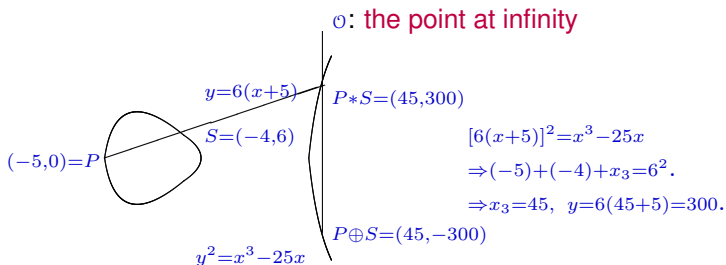
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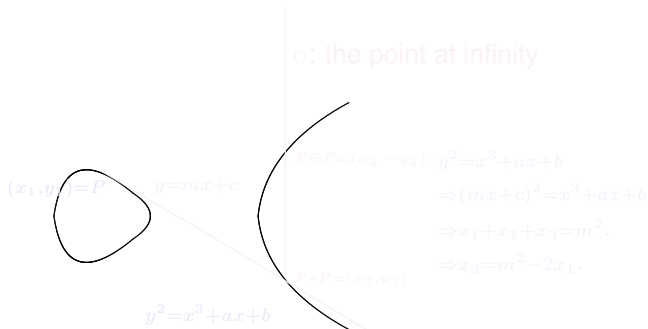
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Doubling of a Point

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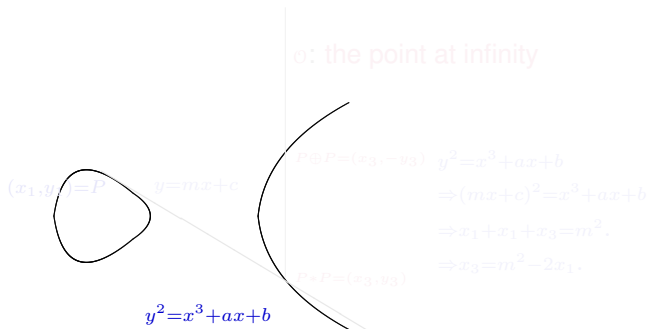
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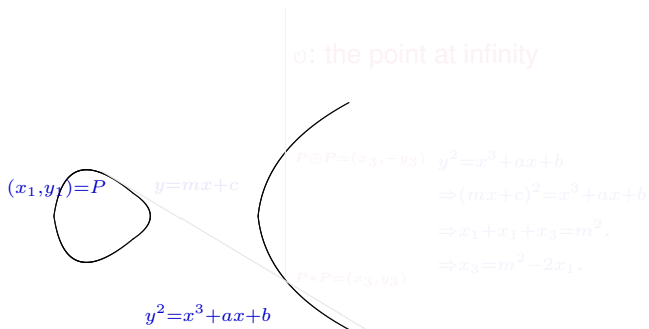
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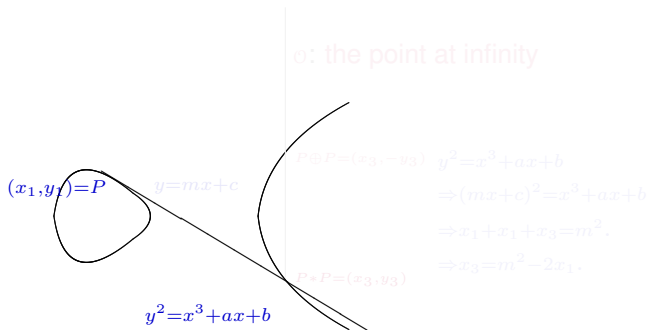
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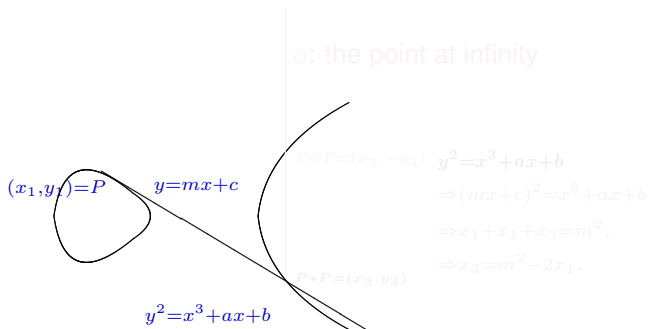
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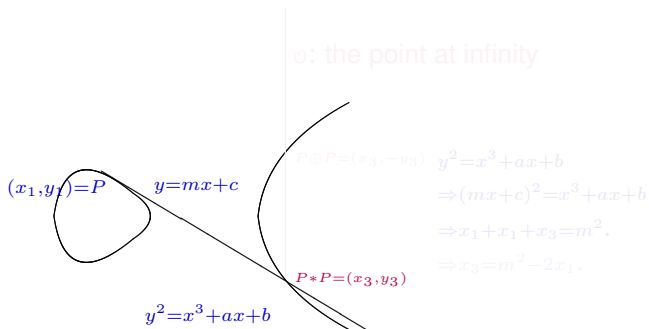
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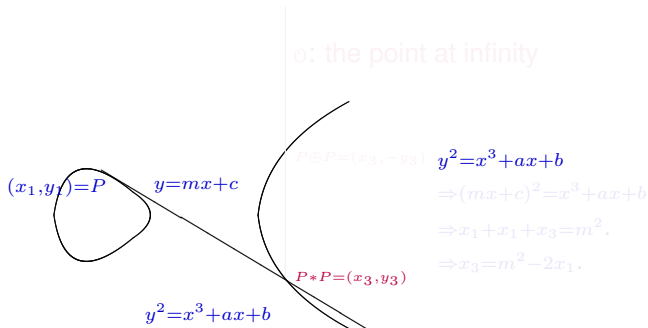
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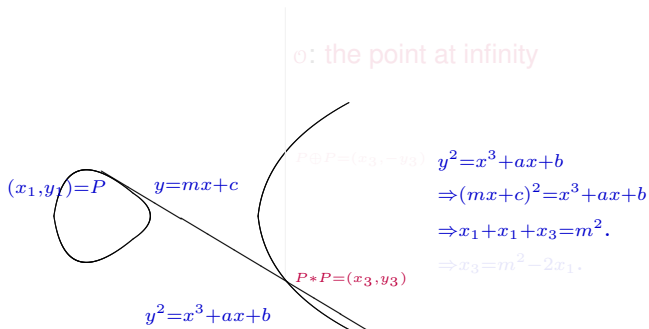
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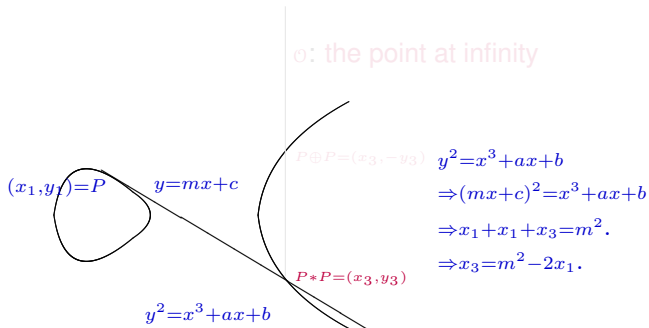
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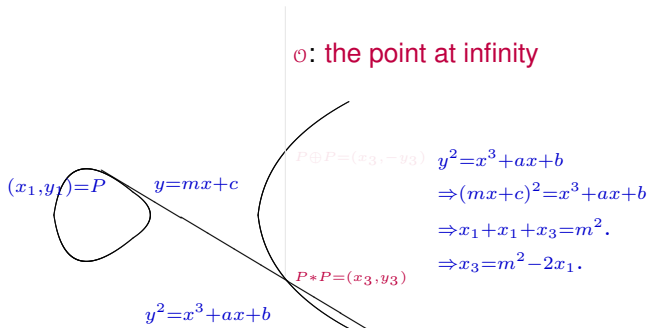
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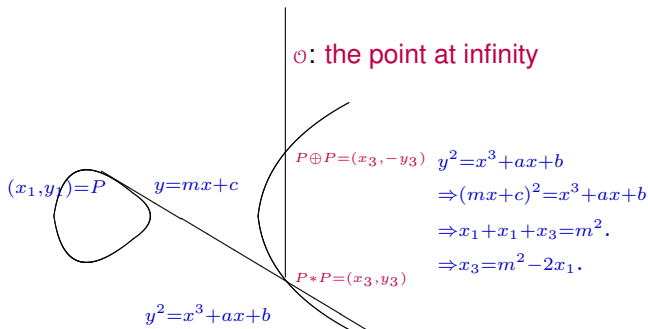
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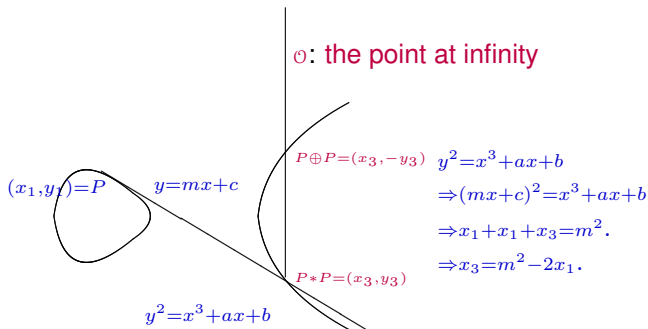
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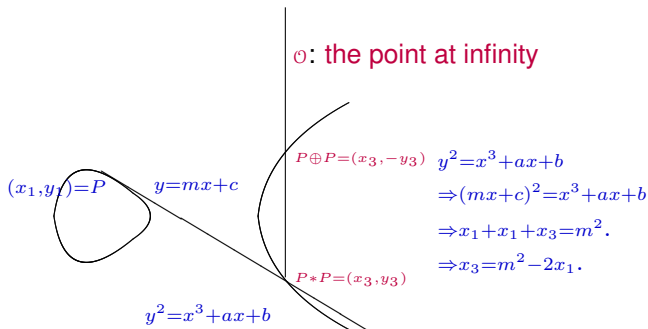
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Doubling a Point: an example

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- Consider the elliptic curve $E : y^2 = x^3 + x + 1$ over the finite field $\mathbb{F}_{23} = \{0, 1, \dots, 22\}$. Note that $4.1^3 + 27.1^3 \neq 0$ in \mathbb{F}_{23} .

- $P = (3, 10)$ is a point on E as $3^3 + 3 + 1 = 31 = 10^2$ in \mathbb{F}_{23} .

- To compute $P * P = (x_3, y_3)$, the slope of the tangent at P is

$$m = \frac{3x^2 + 1}{2y} = \frac{3 \cdot 3^2 + 1}{2 \cdot 10} = \frac{7}{5} = \frac{7 \times 9}{5 \times 9} = \frac{63}{-1} = 6 \in \mathbb{F}_{23}.$$

- The tangent at $P = (3, 10)$ is

$$y - 10 = 6(x - 3), \text{ i.e., } y = 6x - 8.$$

$$(6x_3 - 8)^2 = x_3^3 + x_3 + 1$$

$$\implies x_3 = 36 - (3 + 3) = 30 = 7 \in \mathbb{F}_{23},$$

$$y_3 = 6 \times 7 - 8 = 11 \in \mathbb{F}_{23},$$

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Doubling a Point: an example

Introduction

The Point at
Infinity

Group Structure

- Consider the elliptic curve $E : y^2 = x^3 + x + 1$ over the finite field $\mathbb{F}_{23} = \{0, 1, \dots, 22\}$. Note that $4.1^3 + 27.1^3 \neq 0$ in \mathbb{F}_{23} .
- $P = (3, 10)$ is a point on E as $3^3 + 3 + 1 = 31 = 10^2$ in \mathbb{F}_{23} .
- To compute $P * P = (x_3, y_3)$, the slope of the tangent at P is

$$m = \frac{3x^2 + 1}{2y} = \frac{3 \cdot 3^2 + 1}{2 \cdot 10} = \frac{7}{5} = \frac{7 \times 9}{5 \times 9} = \frac{63}{-1} = 6 \in \mathbb{F}_{23}.$$

- The tangent at $P = (3, 10)$ is
 $y - 10 = 6(x - 3)$, i.e., $y = 6x - 8$.

$$(6x_3 - 8)^2 = x_3^3 + x_3 + 1$$

$$\implies x_3 = 36 - (3 + 3) = 30 = 7 \in \mathbb{F}_{23},$$

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Multiplication by Integers

Introduction

The Point at
Infinity

Group Structure

- We can add P to itself and get another point $2P = P \oplus P$, and in general,

$$[n]P = nP = \underbrace{P \oplus P \oplus \dots \oplus P}_{n\text{-times}}, \quad n = 1, 2, 3, \dots$$

- For a negative integer n , we can define nP as

$$nP = \ominus[(-n)P],$$

where $\ominus Q$ denoted the inverse of a point Q on the elliptic curve.

- A point P on E is called a **torsion point** if $[n]P = \mathcal{O}$ for some non-zero integer n .

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K -Rational Points on Elliptic Curve

Introduction

The Point at
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Group Structure

- Let K be a field, and E be an elliptic curve defined over K .
- The points (x, y) on E where $x, y \in K$ are called K -rational points on E and denoted by $E(K)$.
- If we start with two points on E with K -rational co-ordinates, their sum also has K -rational co-ordinates:

The straight line $y = mx + c$ joining $(x_1, y_1), (x_2, y_2) \in E(K)$ has slope $c, m = \frac{y_2 - y_1}{x_2 - x_1} \in K$. The third point of intersection (x_3, y_3) of this line with $y^2 = x^3 + ax + b$ is obtained as

$$\begin{aligned}(mx + c)^2 &= x^3 + ax + b \\ \implies x_1 + x_2 + x_3 &= m^2 \\ \implies x_3 &= m^2 - x_1 - x_2 \in K, \\ y_3 &= mx_3 + c \in K.\end{aligned}$$

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The Mordell-Weil Group

Introduction

The Point at
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Group Structure

- Let $E(K) = \{(x, y) \mid x, y \in K, y^2 = x^3 + ax + b\} \cup \{\mathcal{O}\}$. Then

$$P, Q \in E(K) \implies P \oplus Q \in E(K).$$

- The abelian group $E(K)$ is called the **Mordell-Weil group** of E/K .
- **Mordell-Weil Theorem:** For any finite extension K of \mathbb{Q} , $E(K)$ is a finitely generated abelian group, i.e.,

$$E(K) \cong \mathbb{Z}^{r_E(K)} \oplus E(K)_{tors}.$$

The integer $r_E(K)$ is called the (algebraic) **rank of E over K** .

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The Torsion Subgroup

Introduction

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Group Structure

- **Lutz-Nagell Theorem:** Let $E : y^2 = x^3 + ax + b$ be an elliptic curve with $a, b \in \mathbb{Z}$. If $(x, y) \in E(\mathbb{Q})$ is a non-zero torsion point, then $x, y \in \mathbb{Z}$, and $y = 0$ or $y^2 \mid (4a^3 + 27b^2)$.

- **Mazur's Theorem:** Let E/\mathbb{Q} be an elliptic curve. Then the torsion subgroup $E_{tors}(\mathbb{Q})$ is isomorphic to one of the following 15 groups:

$$\mathbb{Z}/N\mathbb{Z}, \quad \text{with } 1 \leq N \leq 10 \text{ or } N = 12,$$

$$\mathbb{Z}/2\mathbb{Z} \times \mathbb{Z}/2N\mathbb{Z}, \quad \text{with } 1 \leq N \leq 4.$$

Further, each of these subgroup occurs as $E_{tors}(\mathbb{Q})$ for infinitely many elliptic curves E/\mathbb{Q} . (*Conjectured by Levi 1906*)

- **Merel:** For every integer $d \geq 1$, there is a constant $N(d)$ such that for all number fields $[K : \mathbb{Q}] \leq d$ and all elliptic curves E/K ,

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Points of Infinite Order

Introduction

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Group Structure

- Bhargava and Shankar showed that at least 83% of elliptic curves have rank either 0 or 1.
- We have example of $E(\mathbb{Q})$ with the highest possible rank 28.
- Conjecture: There exist elliptic curves E/\mathbb{Q} of arbitrarily large rank.
- Mordell's Conjecture (for plane curves): Let C be a non-singular curve over \mathbb{Q} of degree strictly greater than 3. Then the set $C(\mathbb{Q})$ of rational point on C is finite. Faltings proved the conjecture in the 1980's.
- There is no effective algorithm to compute the rank of $E(\mathbb{Q})$.
- The first part of the BSD Conjecture connects the rank of $E(\mathbb{Q})$ to an analytic object, called the Hasse-Weil L -function of the elliptic curve.

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Points of Infinite Order

Introduction

The Point at
Infinity

Group Structure

- Bhargava and Shankar showed that at least 83% of elliptic curves have rank either 0 or 1.
- We have example of $E(\mathbb{Q})$ with the highest possible rank 28.
- **Conjecture:** There exist elliptic curves E/\mathbb{Q} of arbitrarily large rank.
- Mordell's Conjecture (for plane curves): Let C be a non-singular curve over \mathbb{Q} of degree strictly greater than 3. Then the set $C(\mathbb{Q})$ of rational point on C is finite. Faltings proved the conjecture in the 1980's.
- There is no effective algorithm to compute the rank of $E(\mathbb{Q})$.
- The first part of the BSD Conjecture connects the rank of $E(\mathbb{Q})$ to an analytic object, called the Hasse-Weil L -function of the elliptic curve.

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THANK YOU