



# Second order QCD corrections to SIDIS : Technicalities

---

Narayan Rana

NISER Bhubaneswar

Probing Hadron Structure at the Electron-Ion Collider

8th February 2024

in collaboration with S. Goyal, S. Moch, V. Pathak, V. Ravindran

## Electron Ion Collider

a machine to look inside the nucleus

EIC will take precision snapshots of the internal structures of the protons and neutrons, allowing us a better understanding of the strongest force in nature

A precise theoretical description of our current understanding (the Standard Model) is also necessary to find any agreement/disagreement with precise experimental data

The inclusive/semi-inclusive deep inelastic scattering (DIS/SIDIS) plays a crucial role.

Parton model connects the partonic cross-section to the hadronic one through PDFs & FFs. We compute the partonic cross-section using the framework of perturbative QCD order by order in  $\alpha_s$ .

Higher order corrections are essential to

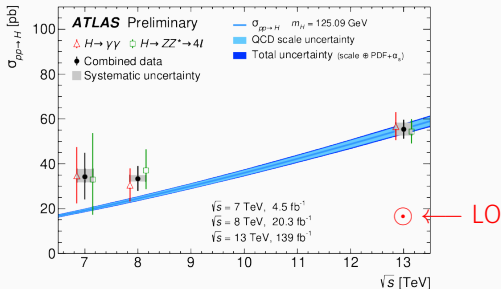
- achieve sufficiently/comparably precise theoretical estimates
- reduce the uncertainties arising from the factorization scales

detailed talk by V. Ravindran

## An example from the LHC : NNLO QCD for the SM Higgs

The NNLO QCD corrections played very important role in confirming the SM Higgs.

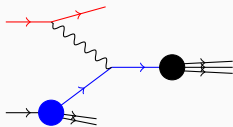
16.00 pb LO  
+ 20.84 pb NLO (EFT)  
- 2.05 pb ( $m_t$  exact NLO)  
+ 9.56 pb NNLO (EFT)  
+ 0.34 pb NNLO ( $1/m_t$ )  
+ 2.40 pb EW  
+ 1.49 pb N<sup>3</sup>LO (EFT)



If we had considered LO only, we would have never found the SM Higgs.

**For EIC also, higher order corrections will play important role!**

# SEMI-INCLUSIVE DIS



**SIDIS**

$$l + H \rightarrow l + H' + X$$

Phase-space:

Final state hadron is tagged!

Extra constrain on the phase-space

$$dPS|_{\text{SIDIS}} = dPS|_{\text{DIS}} \times \delta\left(z' - \frac{p_a \cdot p_b}{p_a \cdot q}\right)$$

**DIS**

$$l + H \rightarrow l + X$$

Phase-space:

All final states are fully integrated!

The hadronic part is characterized by two structure functions  $F_1$  &  $F_2$ .

## Parton model & perturbative expansion

$$F_i = x^{i-1} \sum_{a,b} \int_x^1 \frac{dx_1}{x_1} f_a(x_1, \mu_F^2) \int_z^1 \frac{dz_1}{z_1} D_b(z_1, \mu_F^2) \times \mathcal{F}_{i,ab} \left( \frac{x}{x_1}, \frac{z}{z_1}, Q^2, \mu_F^2 \right)$$

$\downarrow$

the finite coefficient functions which can be computed perturbatively

In QCD, we have a series expansion of the partonic cross sections in strong coupling constant  $\alpha_s$ :

$$\begin{aligned} \mathcal{F}_{ab}(z) &= \mathcal{F}_{ab}^{(0)} \sum_{m=0}^{\infty} \alpha_s^m \mathcal{F}_{ab}^{(m)}(z) \\ &= \mathcal{F}_{ab}^{(0)} \left[ 1 + \alpha_s \mathcal{F}_{ab}^{(1)}(z) + \alpha_s^2 \mathcal{F}_{ab}^{(2)}(z) + \alpha_s^3 \mathcal{F}_{ab}^{(3)}(z) + \dots \right] \end{aligned}$$

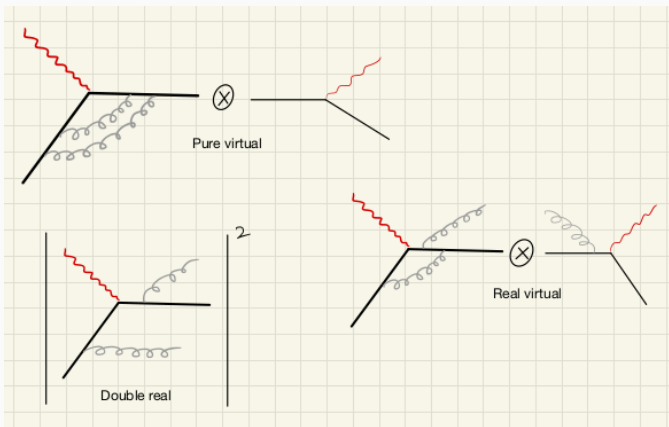


We are interested in the second order correction

## Goal of this talk

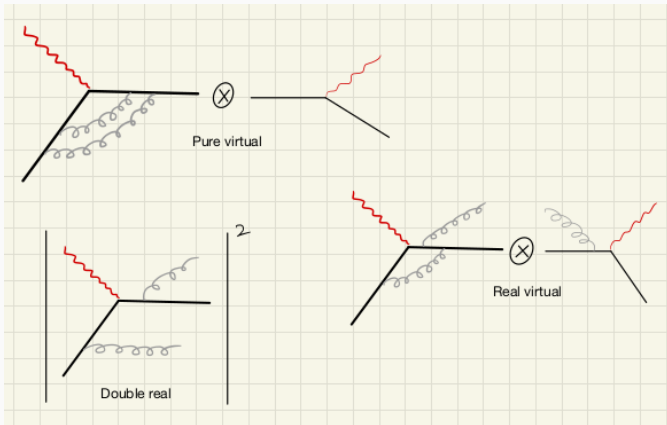
- Motivation, kinematics and the basics have been discussed on Monday  
talk by V. Ravindran
- In this talk, we discuss the details of the computational technology

## Schematic diagrams for NNLO contributions to SIDIS



Each individual contribution is divergent :  $\frac{1}{\epsilon}$  in dimensional regularization

## Schematic diagrams for NNLO contributions to SIDIS



Sum of all degenerate processes: KLN theorem & mass factorization



## Computational procedure

$$d = 4 - 2\epsilon$$

- Diagrammatic approach -> QGRAF to generate Feynman diagrams
- In-house **FORM** routines for algebraic manipulation : *Lorentz, Dirac and Color algebra*
- Reverse unitarity : phase-space integrals to loop integrals

$$\delta(k^2 - m^2) \sim \frac{1}{2\pi i} \left( \frac{1}{k^2 - m^2 - i0} - \frac{1}{k^2 - m^2 + i0} \right)$$

- Decomposition of the dot products to obtain scalar integrals

$$\frac{2l \cdot p}{l^2(l-p)^2} = \frac{l^2 - (l-p)^2 + p^2}{l^2(l-p)^2} = \frac{1}{(l-p)^2} - \frac{1}{l^2} + \frac{p^2}{l^2(l-p)^2}$$

- Identity relations among scalar integrals : **IBPs, LIs & SRs**
- Algebraic linear system of equations relating the integrals



Master integrals (MIs)

---

- Computation of MIs : **Method of differential equation** (generic & canonical)
- UV renormalization and mass factorization
- Numerical evaluation using suitable PDFs and FFs

## Computational procedure

$$d = 4 - 2\epsilon$$

- Diagrammatic approach -> QGRAF to generate Feynman diagrams
- In-house **FORM** routines for algebraic manipulation : *Lorentz, Dirac and Color algebra*
- **Reverse unitarity** : phase-space integrals to loop integrals

$$\delta(k^2 - m^2) \sim \frac{1}{2\pi i} \left( \frac{1}{k^2 - m^2 - i0} - \frac{1}{k^2 - m^2 + i0} \right)$$

- Decomposition of the dot products to obtain scalar integrals

$$\frac{2l \cdot p}{l^2(l-p)^2} = \frac{l^2 - (l-p)^2 + p^2}{l^2(l-p)^2} = \frac{1}{(l-p)^2} - \frac{1}{l^2} + \frac{p^2}{l^2(l-p)^2}$$

- **Identity relations among scalar integrals** : IBPs, LIs & SRs
- Algebraic linear system of equations relating the integrals



Master integrals (MIs)

---

- Computation of MIs : **Method of differential equation** (generic & canonical)
- UV renormalization and mass factorization
- Numerical evaluation using suitable PDFs and FFs

Loop computation procedure: Integration-by-parts identities

## Integration-by-parts identities

[Tkachov, Chetyrkin]

*Generalization of Gauss's theorem in  $d$  dimension*

Within **dimensional regularization**, all integrals in  $d$  dimension are well-defined and convergent  $\Rightarrow$  integrand must be zero at boundary

$$\int \prod_{i=1}^l \mathcal{D}^d l_i \frac{d}{dl_j^\mu} \left( \frac{v^\mu}{D_1^{n_1} \dots D_m^{n_m}} \right) = 0 \quad \Big|_{v \equiv l, p}$$

A very simple example 1:

$$\mathcal{I}(n) = \int \frac{d^d l}{(2\pi)^{d/2}} \frac{1}{(l^2 - m^2)^n}$$

The identity for  $v \equiv l$  gives a recursion relation for  $\mathcal{I}(n+1) \Rightarrow \mathcal{I}(n)$

$$\mathcal{I}(n+1) = \frac{(d-2n)}{2nm^2} \mathcal{I}(n)$$

The relation can be represented as



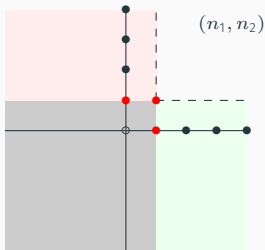
## Integration-by-parts identities

[Tkachov, Chetyrkin]

Another simple example 2:

$$\mathcal{I}(n_1, n_2) = \int \frac{d^d l}{(2\pi)^{d/2}} \frac{1}{(l^2 - m_1^2)^{n_1} ((l - q)^2 - m_2^2)^{n_2}}$$

The relations now depend on  $n_1$  and  $n_2$  and whether they are **positive** or **non-positive**.



- The relations are like translations from one point to another.
- The first goal is to choose the red points (the MIs).
- The second goal is to find an efficient path (IBP reduction rules) with minimal translation.

## Integration-by-parts identities

[Tkachov, Chetyrkin]

Integral families with 7 propagators.

$$\mathcal{I}(n_1, n_2, \dots, n_7)$$

For NNLO, it's not difficult! Thousands of Feynman integrals can be written in terms of only a few! However for three-loop onward, it becomes extremely challenging.

Scalar integrals form a 'vector space'  $\Rightarrow$  IBP reduction is a 'projection' to basis vectors

---

Several technical advances have been made in recent years by improving system-solving strategy, either due to novel algorithms or to the development of software.

- **LiteRed** : Symbolical recursion relation
- **FIRE, Reduze, Kira** : Laporta algorithm; Solves for specific integer values

Loop computation procedure: Solving remaining integrals

## The method of differential equations

A Feynman integral is a function of spacetime dimension  $d$  and kinematic invariants  $x, z$ .

$$J_i = \mathcal{N} \int \frac{d^d l_1}{(2\pi)^d} \frac{d^d l_2}{(2\pi)^d} \frac{1}{l_1^2 l_2^2 ((l_1 - l_2)^2 - m^2) (l_1 - q)^2 (l_2 - q)^2} \equiv f(d, x, z)$$

The idea is to obtain a differential eqn. for the integral *w.r.t.*  $x, z$  and solve it.



## The method of differential equations

A Feynman integral is a function of spacetime dimension  $d$  and kinematic invariants  $x, z$ .

$$J_i = \mathcal{N} \int \frac{d^d l_1}{(2\pi)^d} \frac{d^d l_2}{(2\pi)^d} \frac{1}{l_1^2 l_2^2 ((l_1 - l_2)^2 - m^2) (l_1 - q)^2 (l_2 - q)^2} \equiv f(d, x, z)$$

The idea is to obtain a differential eqn. for the integral *w.r.t.*  $x, z$  and solve it.

$$\frac{d}{dz} J_i = \text{some combinations of integrals}$$

↓ IBP identities/reduction

$$= \sum_{j=1}^n c_{ij} J_j$$

$c_{ij}$ 's are rational function of  $d, x$  and  $z$ .

$J_i$  is a basis 'vector'  $\Rightarrow \frac{d}{dz}$  is a 'rotation'  $\Rightarrow$  IBP reduction is a 'projection' to basis vectors

## The method of differential equations

A Feynman integral is a function of spacetime dimension  $d$  and kinematic invariants  $x, z$ .

$$J_i = \mathcal{N} \int \frac{d^d l_1}{(2\pi)^d} \frac{d^d l_2}{(2\pi)^d} \frac{1}{l_1^2 l_2^2 ((l_1 - l_2)^2 - m^2) (l_1 - q)^2 (l_2 - q)^2} \equiv f(d, x, z)$$

The idea is to obtain a differential eqn. for the integral *w.r.t.*  $x, z$  and solve it.

$$d_z \begin{pmatrix} J_1 \\ J_2 \\ J_3 \\ J_4 \\ \vdots \\ J_n \end{pmatrix} = \begin{bmatrix} \bullet & \bullet & \bullet & \bullet & \cdots & \bullet \\ \bullet & \bullet & \bullet & \bullet & \cdots & \bullet \\ \bullet & \bullet & \bullet & \bullet & \cdots & \bullet \\ \bullet & \bullet & \bullet & \bullet & \cdots & \bullet \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ \bullet & \bullet & \bullet & \bullet & \cdots & \bullet \end{bmatrix} \begin{pmatrix} J_1 \\ J_2 \\ J_3 \\ J_4 \\ \vdots \\ J_n \end{pmatrix}$$

$$d_z \mathbb{J} = \mathbb{A}(d, z) \mathbb{J}$$

## The method of differential equations

A Feynman integral is a function of spacetime dimension  $d$  and kinematic invariants  $x, z$ .

$$J_i = \mathcal{N} \int \frac{d^d l_1}{(2\pi)^d} \frac{d^d l_2}{(2\pi)^d} \frac{1}{l_1^2 l_2^2 ((l_1 - l_2)^2 - m^2) (l_1 - q)^2 (l_2 - q)^2} \equiv f(d, x, z)$$

The idea is to obtain a differential eqn. for the integral *w.r.t.*  $x, z$  and solve it.

$$d_z \begin{pmatrix} J_1 \\ J_2 \\ J_3 \\ J_4 \\ \vdots \\ J_{n-1} \\ J_n \end{pmatrix} = \begin{bmatrix} \bullet & \bullet & \bullet & \bullet & \cdots & \bullet & \bullet \\ 0 & \bullet & \bullet & \bullet & \cdots & \bullet & \bullet \\ 0 & \bullet & \bullet & \bullet & \cdots & \bullet & \bullet \\ 0 & 0 & 0 & \bullet & \cdots & \bullet & \bullet \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & 0 & \cdots & \bullet & \bullet \\ 0 & 0 & 0 & 0 & \cdots & 0 & \bullet \end{bmatrix} \begin{pmatrix} J_1 \\ J_2 \\ J_3 \\ J_4 \\ \vdots \\ J_{n-1} \\ J_n \end{pmatrix}$$

The bullets (●) indicate a non-zero rational function of  $d, x$  and  $z$ .

To solve such a system, it would be best to organize it in such a way that it diagonalizes, or at least it takes a block-triangular form. Then, it can be solved using bottom-up approach.

## The method of differential equations

- However, even a small  $2 \times 2$  sub-system is difficult to solve in  $d$ -dimension.
- The solution is to expand the sub-system in  $\epsilon$  and solve order-by-order in  $\epsilon$ .

$$\frac{d}{dz} J_n(z, \epsilon) = \mathcal{C}_{nm}(z, \epsilon) J_n(z, \epsilon) + \mathcal{R}_n(z, \epsilon)$$

Taylor expansion in  $\epsilon$

$$J_n(z, \epsilon) = \sum_{k=-2}^{\infty} J_n^{(k)}(z) \epsilon^k, \quad \mathcal{C}_n(z, \epsilon) = \sum_{k=0}^{\infty} \mathcal{C}_n^{(k)}(z) \epsilon^k, \quad \mathcal{R}_n(z, \epsilon) = \sum_{k=-2}^{\infty} \mathcal{R}_n^{(k)}(z) \epsilon^k$$

The leading pole is fixed for a topology (process).

$$\frac{d}{dz} J_n^{(k)}(z) = \mathcal{C}_{nm}^{(0)}(z) J_n^{(k)}(z) + \sum_{p=1}^{k+2} \mathcal{C}_{nm}^{(p)}(z) J_n^{(k-p)}(z) + \mathcal{R}_n^{(k)}(z)$$

## The method of differential equations

- However, even a small  $2 \times 2$  sub-system is difficult to solve in  $d$ -dimension.
- The solution is to expand the sub-system in  $\epsilon$  and solve order-by-order in  $\epsilon$ .

$$\frac{d}{dz} J_n(z, \epsilon) = \mathcal{C}_{nm}(z, \epsilon) J_n(z, \epsilon) + \mathcal{R}_n(z, \epsilon)$$

Taylor expansion in  $\epsilon$

$$J_n(z, \epsilon) = \sum_{k=-2}^{\infty} J_n^{(k)}(z) \epsilon^k, \quad \mathcal{C}_n(z, \epsilon) = \sum_{k=0}^{\infty} \mathcal{C}_n^{(k)}(z) \epsilon^k, \quad \mathcal{R}_n(z, \epsilon) = \sum_{k=-2}^{\infty} \mathcal{R}_n^{(k)}(z) \epsilon^k$$

The leading pole is fixed for a topology (process). **The homogeneous part is same for all  $k$ !**

$$\frac{d}{dz} J_n^{(k)}(z) = \mathcal{C}_{nm}^{(0)}(z) J_n^{(k)}(z) + \sum_{p=1}^{k+2} \mathcal{C}_{nm}^{(p)}(z) J_n^{(k-p)}(z) + \mathcal{R}_n^{(k)}(z)$$

## Algorithm : to solve a system of linear first order diff. eqns.

- First step is to reduce the sub-system to a higher order eqn in a single unknown

$$dz \begin{pmatrix} J_1 \\ J_2 \end{pmatrix} = \begin{bmatrix} \bullet & \bullet \\ \bullet & \bullet \end{bmatrix} \begin{pmatrix} J_1 \\ J_2 \end{pmatrix} + \begin{pmatrix} R_1 \\ R_2 \end{pmatrix} \Rightarrow \begin{aligned} a \frac{d^2 J_1}{dz^2} + b \frac{dJ_1}{dz} + cJ_1 + d &= 0 \\ J_2 &= a' \frac{dJ_1}{dz} + b' J_1 + c' \end{aligned}$$

- Start with the leading pole ( $\epsilon^{-2}$ ) - find the homogeneous solutions ( $h_i(z)$ ) and best uncoupling procedure - solve for the nonhomogeneous part using the method of variation of constant
- Structure of **homogeneous part is same at each order** in  $\epsilon$ -expansion. Hence the homogeneous solutions and uncoupling procedure are unique for any order
- Now at each order in  $\epsilon$ , find the nonhomogeneous part ( $r(y)$ ) keeping the uncoupling structure fixed and solve using variation of constant

$$g(z) = \sum_{i=1}^m h_i(z) \int dy \frac{r(y)W_i(y)}{W(y)}$$

---

The results are obtained in terms of iterated integrals (HPLs/GPLs).

---

## Iterated integrals

From Feynman integrals to iterated integrals : What do we gain?

Direct numerical integration of Feynman integrals is tedious, unstable and challenging to obtain precise results.

## Iterated integrals

From Feynman integrals to iterated integrals : What do we gain?

Direct numerical integration of Feynman integrals is tedious, unstable and challenging to obtain precise results.

---

Iterated integrals are one-dimensional. They can be computed with great precision in a short amount of time. Besides, they have the following properties:

- (a) **Shuffle algebra** : Allows to obtain a basis for a set of iterated integrals. Reduction to such a basis is extremely effective to reduce the computation time by few times.
- (b) **Scaling invariance** : Allows to convert the limit of these integrals from kinematical variables ( $z$ ) to constants (1). This makes the integration really precise.



## Iterated integrals

From Feynman integrals to iterated integrals : What do we gain?

Direct numerical integration of Feynman integrals is tedious, unstable and challenging to obtain precise results.

---

Iterated integrals are one-dimensional. They can be computed with great precision in a short amount of time. Besides, they have the following properties:

(a) **Shuffle algebra** : Allows to obtain a basis for a set of iterated integrals. Reduction to such a basis is extremely effective to reduce the computation time by few times.

(b) **Scaling invariance** : Allows to convert the limit of these integrals from kinematical variables ( $z$ ) to constants (1). This makes the integration really precise.

---

Till date, most of the MIs were solved in terms of GPLs



the iterative kernel is a simple polynomial  $\int_0^x \frac{dt}{a+t} \int_0^t \dots$

What happens when we have (multiple) square-roots?!

## Rationalization

### Rationalizable

- Find a suitable transformation

Let's consider  $\sqrt{4m^2 - s}$ .

We can use Landau transformation

$s = -m^2 \frac{(1-x)^2}{x}$  for this.

### Non-rationalizable

- A **single** transformation can not rationalize all square-roots **simultaneously**.

↓

Square-roots will be present in the iterated integrals.

1) We can accept 'the fact' and evaluate them with appropriate analytic continuation.

or

2) Instead of using a single transformation rule to rationalize them, we write the system (each MI) as sum of functions of dependent variables and treat them separately. As a result, each sub-system has alphabet with 'good' letters with different argument.

Phase-space computation procedure: Reverse unitarity

## Reverse unitarity

- The IBP identities and method of differential equations are state-of-the-art tools. They only depend on the 'form' of the object (Feynman integrals) and its variables.
- The phase-space integrals are challenging, specially the angular integration.

$$\mathcal{N} \int d^d l_1 d^d l_2 d^d p_b \frac{1}{(p_a - l_1)^2 \dots} \delta(l_1^2) \delta(l_2^2) \delta(p_b^2) \delta^d(p_a + q - l_1 - l_2 - p_b) \delta\left(z' - \frac{p_a \cdot p_b}{p_a \cdot q}\right)$$

- The idea is to write the phase-space integrals in the loop-integral format and apply the methods (IBP & DE).

## Reverse unitarity

- The IBP identities and method of differential equations are state-of-the-art tools. They only depend on the 'form' of the object (Feynman integrals) and its variables.
- The phase-space integrals are challenging, specially the angular integration.

$$\mathcal{N} \int d^d l_1 d^d l_2 d^d p_b \frac{1}{(p_a - l_1)^2 \dots} \delta(l_1^2) \delta(l_2^2) \delta(p_b^2) \delta^d(p_a + q - l_1 - l_2 - p_b) \delta\left(z' - \frac{p_a \cdot p_b}{p_a \cdot q}\right)$$

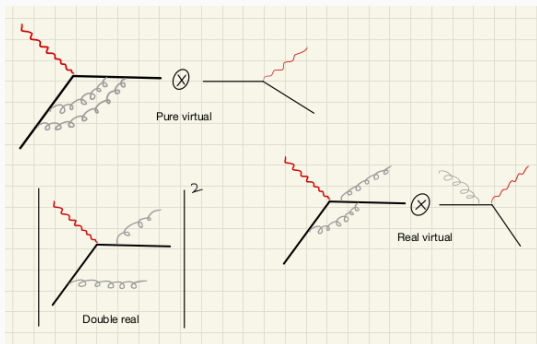
- The idea is to write the phase-space integrals in the loop-integral format and apply the methods (IBP & DE).
- **Reverse unitarity**

$$\delta(k^2 - m^2) \sim \frac{1}{2\pi i} \left( \frac{1}{k^2 - m^2 - i0} - \frac{1}{k^2 - m^2 + i0} \right)$$


- We can consider only the first term, as the differential equation is independent of the sign of  $i0$ . Of course, we need a boundary conditions to solve differential equations and that is where the actual physics information (phase-space integrals) goes in!

To obtain the finite partonic cross-section

## Compute & combine everything and mass factorization



- We compute relevant Feynman diagrams & corresponding Feynman integrals analytically.
- We combine them appropriately, perform mass factorization and obtain the finite partonic cross-section.

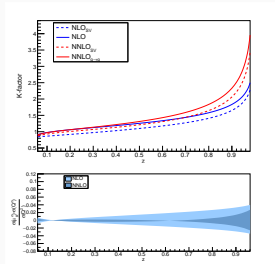


Results!




## Results

We have computed the non-singlet contributions to the quark initiated process with quark fragmenting to hadrons. The finite partonic cross-section has been convoluted with PDFs and FFs to obtain the hadronic cross-section through a FORTRAN code.



## Checks

- The master integrals were computed using different methods!
- Mass factorization (universal) removes all remaining infrared singularities!
- Successful checks with available results in the threshold limit!
- The constraint ( $z'$ ) can be integrated in our analytic result. We found perfect agreement with the fully inclusive result.



Concluding remarks!

- EIC will unravel the mysteries of strong force.
- Theoretical precision studies are extremely necessary to fully exploit the EIC data.
- Our current (well-tested) theoretical understanding (the SM) is constrained by its perturbative nature and hence, higher order perturbative corrections are necessary to achieve precise theoretical predictions.

-----

- In this talk, we have presented the computational details to obtain the first results on NNLO QCD corrections to SIDIS.
- The technicalities are impressive and generic.

-----

- Aside the phenomenological impact of the result, it also sets a milestone for the computational technique.

*Thank you for your attention!*