## Machine Learning Knowledge exchange : from LHC to EIC

## International School and Workshop on Probing Hadron Structure at the Electron-Ion Collider

ICTS



Sanmay Ganguly IIT-Kanpur sanmay@iitk.ac.in

**Sanmay Ganguly (IITK)** 

# The collider experimental program

## Simulation based approach :



# The collider experimental program

## Simulation based approach :



# The collider program flow-chain



**Sanmay Ganguly (IITK)** 

# The collider program flow-chain



3



1. Decide the right representation of the data (images/graphs/trees..)









Variation in data



figure out p(x) from which the data is drawn. e.g. VAE







**Sanmay Ganguly (IITK)** 



Sanmay Ganguly (IITK)

## Looking the problem through ML lens







## Sanmay Ganguly (IITK)

# We have time for a coffee together





## Sanmay Ganguly (IITK)

# We have time for a coffee together



## There will be a decade of overlap between LHC and EIC.

The probe of strong interaction program will have overlapping physics goals.

Through the ML lens the formulation of the problems will be closer.



Sanmay Ganguly (IITK)

# Calorimetery

#### Image from 1705.02355

 $f_{\{\theta\}} ($ 



## Calorimetry + ML early works J. Cogan et-al JHEP 02 (2015) 118



Sanmay Ganguly (IITK)

# A 3-D view for topoclusters only

#### 8 X 8 Low Res detector

32 X 32 High Res detector

Energy rel residuals [%]



**Sanmay Ganguly (IITK)** 

# When do intrinsic calorimeter sizes are limiting factors ?





The intrinsic detector resolution is a blocker



## An event display for super-res prediction





**Sanmay Ganguly (IITK)** 

# The mass distribution



**Sanmay Ganguly (IITK)** 

## Pion identification within ATLAS



A classification & regression task is tested on ATLAS samples. The calibrated topocluster cells are used to form images & P.C.

### ATL-PHYS-PUB-2020-040

$$\mathcal{L} = (1 - \alpha)\mathcal{L}_{\text{classification}} + \alpha \mathcal{L}_{\text{Regression}}$$



**Sanmay Ganguly (IITK)** 

# Pion identification within ATLAS



**Sanmay Ganguly (IITK)** 

# Pion identification within ATLAS



**Sanmay Ganguly (IITK)** 

# Electron identification within CMS



15

# Electron identification within CMS



**Sanmay Ganguly (IITK)** 

Tracking





**Sanmay Ganguly (IITK)** 

# Tracking & ML



Sanmay Ganguly (IITK)

# Tracking & ML : ATLAS

## ATL-ITK-PROC-2022-006



Sanmay Ganguly (IITK)



Sanmay Ganguly (IITK)



**Sanmay Ganguly (IITK)** 

# Full ML driven PFlow : MLPF



*Eur. Phys. J. C (2021) 81: 381* J. Pata et. al.

**PF** lepton, hadron, photon =  $\mathbf{F}_{PF}$  (track hits + calo cells)
# Combining track + calo for PFlow



MLPF arXiv : 2203.00330 J. Pata et. al.

Sanmay Ganguly (IITK)

#### What's the core data structure?



#### What's the core data structure?



Sanmay Ganguly (IITK)

#### The new networks we tried



# The network flow comparisons



Sanmay Ganguly (IITK)

# Design of the performance metrics



Sanmay Ganguly (IITK)

# Data complexity & sample output



HG-PFlow seems to be doing a better job among the compared methods



Sanmay Ganguly (IITK)

# Data complexity & sample output



**Sanmay Ganguly (IITK)** 



$$\{p_1, p_2, ..., p_n\}$$

Jet Algorithm (for CA, kT, anti-kT)

 $\{j_1, j_2, \dots, j_k\}$ 

 $\{p_1, p_2, \dots, p_n\} = F(q)$ 

The forward problem is not computable from first principle

The question of jet tagging is how do we define the inverse problem?  $q = F^{-1} \Big( \{ p_1, p_2, \dots, p_n \} \Big) ?$ 



**QEICIII-2024** 

# Object tagging

#### Particle Net : 1902.08570 Huilin Qu, Loukas Gouskos



#### $\exists r \times iV > cs > arXiv:1801.07829$

**Computer Science > Computer Vision and Pattern Recognition** 

[Submitted on 24 Jan 2018 (v1), last revised 11 Jun 2019 (this version, v2)]

#### **Dynamic Graph CNN for Learning on Point Clouds**

Yue Wang, Yongbin Sun, Ziwei Liu, Sanjay E. Sarma, Michael M. Bronstein, Justin M. Solomon

**Sanmay Ganguly (IITK)** 



Sanmay Ganguly (IITK)

#### Anatomy of heavy-quark hadronization



# Set2Graph proposal for flavor-tagging



Target						
	1	0	0	0		
1		0	0	0		
0	0		1	1		
0	0	1		1		
0	0	1	1			

 $n_{\text{tracks}} \times (n_{\text{tracks}} - 1)$ edges Regular Article - Experimental Physics | Open Access | Published: 23 June 2021

Secondary vertex finding in jets with neural networks

Jonathan Shlomi <sup>I</sup>, Sanmay Ganguly, Eilam Gross, Kyle Cranmer, Yaron Lipman, Hadar Serviansky, Haggai Maron & Nimrod Segol

The European Physical Journal C 81, Article number: 540 (2021) Cite this article



# Set2Graph model within ATLAS FTAG-2023-001



Sanmay Ganguly (IITK)

#### Direct physics application of the taggers







# Generative models for calorimeter simulations



### Detector simulation using ML



CaloGAN 1705.02355 Michela Paganini, Luke de Oliveira, Benjamin Nachman



# 



Generator

#### Discriminator

### Detector simulation using ML



EPiC-GAN : SciPost Phys. 15, 130 (2023) Erik Buhmann, Gregor Kasieczka, Jesse Thaler



### The major gain





Sanmay Ganguly (IITK)

#### A generative model for Particle-flow



**Sanmay Ganguly (IITK)** 

#### The task of constrained set generation



**Sanmay Ganguly (IITK)** 

#### The task of constrained set generation





**Sanmay Ganguly (IITK)** 

QEICIII-2024

2

1<u>M</u>

0

100

75

# What's brewing now?

#### Major thrust in immediate future : Interpretability



Interpretability is a key issue and efforts are ongoing to map the NN explainability to first principle physics intuition

#### Interpretability : an example attempt

(3)

$$\mathbf{R}_{j}^{(l)} = \sum_{k} rac{x_{j}A_{jk}}{\sum_{m} x_{m}A_{mk}} \mathbf{R}_{k}^{(l+1)}$$

where  $\mathbf{R}_{j}^{(l)}$  represent the *R*-scores of the features of node *j* at layer *l*, while the quantity  $x_j A_{jk}$  models the extent to which node *j* at layer *l*, with activation  $x_j$ , contributes to the relevance of node *k* at layer *l* + 1, where *A* is the adjacency matrix.



#### Neur IPS 2021. F. Mokhtar, R. Kansal et al

**Explainability for MLPF** 

Figure 1: The flow of R-scores of node 1 across the different layers in MLPF. For MLP layers, the redistribution of R-scores follows the standard LRP rules [35, 36]. For the aggregation step in the message passing layer, the redistribution follows Equation 3. We only show three nodes for simplicity.

Feature correlation for top tagging.

arXiv 2210.04371 Ayush Khot, Mark S. Neubauer, Avik Roy



-10		-10
110	$\tau_1^{0.5}$ -1.0 1.00.9 0.5 0.4 0.4 0.3 0.2 0.1 0.3 0.2 0.1 0.3 0.2 0.1 0.3 0.1 0.0 0.3 0.1 0.0 0.2 0.1 0.0 0.1 0.3	110
	τ <sup>1</sup> <sub>1</sub> - <mark>1.0 1.0 1.0</mark> 0.4 0.4 0.4 0.2 0.2 0.1 0.2 0.1 0.1 0.2 0.1 0.1 0.2 0.1 0.0 0.2 0.1 0.0 0.1 0.1 0.0-0.00.1	
	τ <sub>1</sub> <sup>2</sup> - <mark>0.9 1.0 1.0</mark> 0.4 0.4 0.4 0.2 0.2 0.1 0.1 0.1 0.1 0.1 0.1 0.0 0.1 0.1 0.0 0.1 0.1	
	τ2 <sup>.5</sup> -0.5 0.4 0.4 <mark>1.0 0.9 0.8 0.6 0.5 0.3 0.5</mark> 0.4 0.2 0.5 0.3 0.2 0.5 0.3 0.1 0.5 0.3 0.1 0.4 0.3 0.1-0.00.4	
	τ <sup>1</sup> / <sub>2</sub> -0.4 0.4 0.4 <mark>0.9 1.0 1.0</mark> 0.4 0.5 0.4 0.3 0.3 0.2 0.2 0.2 0.2 0.2 0.2 0.1 0.2 0.2 0.1 0.2 0.2 0.1 0.2 0.2 0.1-0.00.2	- 0.8
- 0.8	τ <sub>2</sub> <sup>2</sup> -0.4 0.4 0.4 <mark>0.8 1.0 1.0</mark> 0.3 0.4 0.4 0.2 0.2 0.2 0.1 0.2 0.2 0.1 0.2 0.1 0.1 0.1 0.1 0.1 0.1 0.1 0.1 0.0 0.1	0.0
	τ <sub>3</sub> <sup>0.5</sup> -0.3 0.2 0.2 0.6 0.4 0.3 1.0 0.8 0.6 0.8 0.6 0.4 0.8 0.5 0.3 0.7 0.5 0.2 0.7 0.5 0.2 0.7 0.5 0.1-0.00.5	
	τ <sup>1</sup> / <sub>3</sub> -0.2 0.2 0.2 0.5 0.5 0.4 0.8 1.0 1.0 0.5 0.6 0.6 0.4 0.5 0.4 0.4 0.4 0.3 0.4 0.4 0.3 0.3 0.3 0.3 0.2 0.00.2	
	τ <sub>3</sub> <sup>2</sup> -0.10.10.1 0.3 0.4 0.4 0.6 1.0 1.0 0.3 0.6 0.6 0.2 0.5 0.5 0.2 0.4 0.4 0.2 0.3 0.3 0.1 0.2 0.2 0.0 0.1	
	τ <sup>0.5</sup> -0.3 0.2 0.1 0.5 0.3 0.2 <mark>0.8 0.5 0.3 1.0 0.7 0.5 0.9 0.6 0.4 0.9 0.6 0.3 0.8 0.6 0.2 0.8 0.6 0.2-0.1</mark> 0.5	- 0.6
- 0.6	τ <sup>1</sup> / <sub>4</sub> -0.2 0.1 0.1 0.4 0.3 0.2 0.6 0.6 0.6 0.7 1.0 0.9 0.6 0.8 0.7 0.5 0.7 0.6 0.5 0.6 0.4 0.4 0.5 0.3-0.00.2	
	τ <sup>2</sup> / <sub>4</sub> -0.1 0.1 0.1 0.2 0.2 0.2 0.4 0.6 0.6 0.5 0.9 1.0 0.3 0.8 0.8 0.3 0.6 0.6 0.2 0.4 0.5 0.2 0.3 0.4 0.0 0.1	
	τ <sub>2</sub> .5 -0.3 0.2 0.1 0.5 0.2 0.1 0.8 0.4 0.2 0.9 0.6 0.3 1.0 0.7 0.4 0.9 0.6 0.3 0.9 0.6 0.3 0.9 0.6 0.2-0.1 0.5	
	$\tau_{5}^{1}$ - 0.2 0.1 0.1 0.3 0.2 0.2 0.5 0.5 0.5 0.6 0.8 0.8 0.7 1.0 0.9 0.6 0.8 0.7 0.5 0.7 0.5 0.4 0.6 0.4 0.00.2	
	τ <sup>2</sup> <sub>5</sub> -0.1 0.1 0.0 0.2 0.2 0.2 0.3 0.4 0.5 0.4 0.7 0.8 0.4 0.9 1.0 0.3 0.7 0.8 0.2 0.5 0.6 0.1 0.4 0.4 0.0 0.0	- 0.4
- 0.4	τ <sup>0.5</sup> - 0.3 0.2 0.1 0.5 0.2 0.1 0.7 0.4 0.2 0.9 0.5 0.3 0.9 0.6 0.3 1.0 0.7 0.3 1.0 0.7 0.3 0.9 0.7 0.2 0.1 0.5	
	$\tau_{6}^{1}$ - 0.1 0.1 0.1 0.3 0.2 0.2 0.5 0.4 0.4 0.6 0.7 0.6 0.6 0.8 0.7 0.7 1.0 0.9 0.6 0.8 0.7 0.5 0.7 0.5 0.00.2	
	τ <sub>6</sub> <sup>2</sup> -0.0 0.0 0.0 0.1 0.1 0.1 0.2 0.3 0.4 0.3 0.6 0.6 0.3 0.7 0.8 0.3 0.9 1.0 0.2 0.7 0.7 0.2 0.5 0.6 0.0 0.0	
	τ <sub>9</sub> .5 -0.3 0.2 0.1 0.5 0.2 0.1 0.7 0.4 0.2 0.8 0.5 0.2 0.9 0.5 0.2 1.0 0.6 0.2 1.0 0.7 0.3 1.0 0.7 0.2-0.1 0.5	
	τ <sup>1</sup> / <sub>7</sub> -0.1 0.1 0.1 0.3 0.2 0.1 0.5 0.4 0.3 0.6 0.6 0.4 0.6 0.7 0.5 0.7 0.8 0.7 0.7 1.0 0.9 0.6 0.8 0.7 0.00.3	- 0.2
- 0.2	τ <sup>2</sup> / <sub>7</sub> -0.0 0.0 0.0 0.1 0.1 0.1 0.2 0.3 0.3 0.2 0.4 0.5 0.3 0.5 0.6 0.3 0.7 0.7 0.3 0.9 1.0 0.2 0.7 0.8 0.0 0.0	
	τ <sup>0.5</sup> - 0.2 0.1 0.1 0.4 0.2 0.1 0.7 0.3 0.1 0.8 0.4 0.2 0.9 0.4 0.1 0.9 0.5 0.2 1.0 0.6 0.2 1.0 0.7 0.3 0.1 0.5	
	τ <sup>1</sup> / <sub>8</sub> -0.10.10.10.30.20.10.50.30.20.60.50.30.60.60.40.70.70.50.70.80.70.71.00.90.00.3	
	τ <sub>8</sub> - 0.0 0.0 0.0 0.1 0.1 0.1 0.1 0.2 0.2 0.2 0.3 0.4 0.2 0.4 0.4 0.2 0.5 0.6 0.2 0.7 0.8 0.3 0.9 1.0 0.0 0.0	0.0
	<b>P</b> <sub>T,J</sub> -0.10.00.00.00.00.00.00.00.00.0-0.10.00.0-0.10.00.0-0.10.00.0-0.10.00.001.00.001.00.001.000000	- 0.0
- 0.0	<i>m</i> j -0.3 0.1 0.1 0.4 0.2 0.1 0.5 0.2 0.1 0.5 0.2 0.1 0.5 0.2 0.0 0.5 0.2 0.0 0.5 0.3 0.0 0.5 0.3 0.0 0.1 1.0	
	$c_{1}^{c_{1}}$ $r_{1}$ $c_{2}^{c_{1}}$ $r_{1}$ $c_{2}^{c_{1}}$ $r_{1}$ $c_{2}^{c_{1}}$ $r_{1}$ $c_{2}^{c_{1}}$ $r_{1}$ $c_{2}^{c_{1}}$ $r_{1}$ $c_{2}^{c_{1}}$ $r_{1}$ $r_{2}^{c_{2}}$ $r_{1}$ $r_{2}^{c_{2}}$ $r_{1}$ $r_{2}^{c_{2}}$ $r_{2$	

Major thrust in immediate future : Uncertainty



Reliable uncertainty estimation on ML based predictions are crucial for HEP Only few Bayesian methods have been tested naively.

Can we decompose and correlate the aleatoric and epistemic uncertainties with the underlying physics?

#### Major thrust in immediate future : Uncertainty



Sanmay Ganguly (IITK)

# Differential programming in HEP





generate  $p p > t t^{\sim}$ , t > b udsc udscx ,  $t^{\sim} > b^{\sim}$  udsc udscx



output madjax generated\_ttbar

```
set auto_update 0
2. Evaluation:
```

**31** (1V > hep-ph > arXiv:2203.00057 High Energy Physics – Phenomenology

[Submitted on 28 Feb 2022] Differentiable Matrix Elements with MadJax Lukas Heinrich, Michael Kagan

```
import madjax
```

```
mj = madjax.MadJax('generated_ttbar')
E_cm = 14000 \ \#GeV
process = 'Matrix_1_gg_ttx_t_budx_tx_bxdux'
matrix_element = mj.matrix_element(E_cm,process)
```

```
parameters = ('mass',6): 173.0 #set top mass
phasespace_coords = [0.1]*14 #14D phasespace
```

val, grad = matrix\_element(parameters, phasespace\_coords) grad[('mass', 6)] #gradient wrt top mass

#### Symmetry equivariant networks

<u>arXiv:2203.06153</u> : SG et al

#### Invariance

$$f(\rho_g(x)) = f(x)$$

#### Equivariance

 $f(\rho_g(x)) = \rho_g'\left(f(x)\right)$ 



#### Symmetry equivariant networks



 $m_{ij}^l = \phi_e\left(h_i^l, h_j^l, \psi(\|x_i^l - x_j^l\|^2), \psi(\langle x_i^l, x_j^l 
angle)
ight)$  $h_{i}^{l+1} = h_{i}^{l} + \phi_{h}(h_{i}^{l}, \sum w_{ij}m_{ij}^{l}),$ 

> LG equivariant GNN : arXiv 2201.08187

### ML on FPGA



Sanmay Ganguly (IITK)

# Take away

**ML** is here to stay with HEP.

**When looked through the lens of ML, LHC and EIC are not that far.** 

**Interpretability and uncertainty estimations are two key aspects where we the HEP-ML people need to emphasize.** 

**Need** to keep a close connection with the comp-sc/math community with the latest developments and contribute if possible.

**Symmetry equivariance and geometric DL methods might play a key role in this field.** 

**I** Didn't want to talk about an elephant entering the room : QML ( but should track it ).

Sanmay Ganguly (IITK)

**QEICIII-2024** 

53





Image: FermiLab

**ML** is here to stay with HEP.

**When looked through the lens of ML, LHC and EIC are not that far.** 

**Interpretability and uncertainty estimations are two key aspects where we the HEP-ML people need to emphasize.** 

Image: FermiLab



- **Need** to keep a close connection with the comp-sc/math community with the latest developments and contribute if possible.
- Symmetry equivariance and geometric DL methods might play a key role in this field.
- **I** Didn't want to talk about an elephant entering the room : QML ( but should track it ).

https://iml-wg.github.io/HEPML-LivingReview/

#### THANK YOU





Sanmay Ganguly (IITK)

# The COCOA



Mach. Learn.: Sci. Technol. 4 035042

https://cocoa-hep.readthedocs.io/en/latest/





#### **<u>COnfigurable CalOrimeter</u>** simulation for <u>AI</u>

**M** A complete hermetic geometry with full GEANT simulation.

**PYTHIA-8** based ME/PS & Hadronization

**FASTJET** integration is inbuilt.

**Comes with an ATLAS style pPFlow.** 

Sanmay Ganguly (IITK)
## Event construction using NN



$$\sigma_{t\bar{t}t\bar{t}} = 22.5^{+4.7}_{-4.3}$$
(stat)  $^{+4.6}_{-3.4}$ (syst) fb = 22.5  $^{+6.6}_{-5.5}$  fb.

Eur. Phys. J. C 83 (2023) 496



**Sanmay Ganguly (IITK)** 

QEICIII-2024