Natural Swarms in 3.99 Dimensions







oh, btw – yes, we do experiments!









spatial correlations



equal-time velocity correlation function

 $C(r) = \langle \delta \vec{v}(x_0, t_0) \cdot \delta \vec{v}(x_0 + r, t_0) \rangle$



temporal correlations

space-time correlation function



 $C(r,t) = \langle \delta \vec{v}(x_0, t_0) \cdot \delta \vec{v}(x_0 + r, t_0 + t) \rangle$





$$\tau \sim \xi^z$$

dynamical critical exponent z

$$z = 1.37 \pm 0.11$$



key experimental facts about natural swarms:

- scale-free correlations, $\xi \sim L$
- critical slowing down, $\tau \sim \xi^z$
- dynamical critical exponent, $z = 1.37 \pm 0.11$

theory

ingredient #1

imitation aka ferromagnetism

simple ferromagnets



 $z \approx 2$

Wilson, Fisher (1972) Halperin, Hohenberg, Ma (1972)



RG - ferromagnetism



Halperin, Hohenberg, Ma (1972)

something is missing



what a low critical exponent is telling us?

$$\tau \sim \xi \bar{s} pace \sim time \omega \sim k^z$$

the smaller is z, the more effective is the transport of fluctuations across the system

$$z = 1.37$$
 vs $z \approx 2$

an exponent $z \ll 2$ implies that fluctuations propagate much more effectively than mere diffusion

ingredient #2 activity

active ferromagnets: the Vicsek model



$$\begin{pmatrix} \frac{d\boldsymbol{\sigma}_i}{dt} = J \sum_j n_{ij}(t) \,\boldsymbol{\sigma}_j + \boldsymbol{\zeta}_i \\ \frac{d\boldsymbol{r}_i}{dt} = v_0 \,\boldsymbol{\sigma}_i \end{pmatrix}$$

$$v_0 \sigma_i = v_i$$
 is the velocity

Model A meets Navier-Stokes: Toner-Tu field theory

Vicsek
$$\begin{cases} \frac{d\boldsymbol{\sigma}_{i}}{dt} = J \sum_{j} n_{ij}(t) \, \boldsymbol{\sigma}_{j} + \boldsymbol{\zeta}_{i} \\ \frac{d\boldsymbol{r}_{i}}{dt} = v_{0} \, \boldsymbol{\sigma}_{i} \end{cases} \text{ Toner-Tu} \begin{cases} D_{t} \boldsymbol{v}(x,t) = -\Gamma \frac{\delta \mathcal{H}}{\delta \boldsymbol{v}} - \nabla P + \boldsymbol{\theta}(x,t) \\ \frac{\partial \rho(x,t)}{\partial t} + \nabla(\rho \, \boldsymbol{v}(x,t)) = 0 \end{cases}$$

$$\mathcal{H} = \int d^d x \left\{ (\nabla \mathbf{v})^2 + r \mathbf{v}^2 + u \mathbf{v}^4 \right\}$$

material derivative $D_t \mathbf{v}(x, t) = \partial_t \mathbf{v} + \lambda(\mathbf{v} \cdot \nabla) \mathbf{v}$

- - -

incompressible case: $\rho(x, t) = \rho_0$

$$\begin{cases} D_t \mathbf{v}(x,t) = -\Gamma \frac{\delta \mathcal{H}}{\delta \mathbf{v}} - \nabla P + \boldsymbol{\theta}(x,t) \\ \nabla \cdot \mathbf{v} = 0 \end{cases}$$

Chen, Toner, Lee (2015)

see also Forster, Nelson, Stephens (1977)

activity brings the RG flow to a new fixed point



this RG exponent is also confirmed by simulations of the *compressible* case



let's go back to the experimental evidence

and remember:

a smaller exponent z suggests that

a more efficient propagation mechanism is at play

fact: temporal relaxation in natural swarms is underdamped



why this should help?

underdamping requires a real part of the frequency



because alignment requires a Laplacian, a real part of ω indicates there are *two* derivatives in time:

$$\frac{\partial}{\partial t} \sim \nabla^2 \longrightarrow i\omega \sim k^2 \longrightarrow z_{\text{naive}} \sim 2$$

$$\frac{\partial^2}{\partial t^2} \sim \nabla^2 \longrightarrow \omega^2 \sim k^2 \longrightarrow z_{\text{naive}} \sim 1 \quad \text{looks promising!}$$

we must go back to underdamped dynamics

conjugate variables and their Poisson relations



we need to restore the generator of the *rotations* of the polarization field ψ this is the *internal* angular momentum, aka **spin** *s*:

$$\{s_{\alpha}, s_{\beta}\} = \epsilon_{\alpha\beta\gamma} s_{\gamma} \qquad \left\{ \begin{array}{l} \dot{\psi} = \psi \times s \\ s_{\alpha}, \psi_{\beta}\} = \epsilon_{\alpha\beta\gamma} \psi_{\gamma} \end{array} \right\} \begin{pmatrix} \dot{\psi} = \psi \times s \\ \dot{s} = -\psi \times \frac{\partial H}{\partial \psi} - \eta s + \theta \end{pmatrix} \stackrel{\text{back to}}{\longleftarrow} \dot{\psi} = -\frac{\partial H}{\partial \psi} + \theta$$

Attanasi et al 2014, Cavagna et al 2015

Theory of dynamic critical phenomena

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Halperin-Hohenberg's Model G

Model G



the rotational symmetry of the dynamics implies that the spin s(x, t) is a conserved quantity

spin conservation law $\implies \omega = iDk^2 \pm ck$ and z = 1.5 fix this!

Emmy Noether Seminar Room

ingredient #3

underdamping - inertia - spin conservation

(but this is not your regular inertia!)

promoting Model G to an active field theory

Equilibrium Model G:

$$\begin{pmatrix} \frac{\partial v(x,t)}{\partial t} = +g \, v \times \frac{\delta \mathcal{H}}{\delta s} - \Gamma \frac{\delta \mathcal{H}}{\delta v} + \, \theta_v(x,t) \\ \frac{\partial s(x,t)}{\partial t} = -g \, v \times \frac{\delta \mathcal{H}}{\delta v} - \Lambda \frac{\delta \mathcal{H}}{\delta s} + \, \theta_s(x,t) \end{cases}$$
go active:
$$\begin{cases} \partial_t v \to D_t v = \partial_t v + \gamma_v \left(v \cdot \nabla \right) v \\ \partial_t s \to D_t s = \partial_t s + \gamma_s \left(v \cdot \nabla \right) s \end{cases}$$

Self-Propelled Model G (or Active Model G) - our theory:

$$\begin{cases} D_t \mathbf{v}(x,t) = +g \, \mathbf{v} \times \frac{\delta \mathcal{H}}{\delta s} - \Gamma \frac{\delta \mathcal{H}}{\delta v} - \nabla P + \, \boldsymbol{\theta}_v(x,t) \\ D_t s(x,t) = -g \, \mathbf{v} \times \frac{\delta \mathcal{H}}{\delta v} - \Lambda \frac{\delta \mathcal{H}}{\delta s} + \, \boldsymbol{\theta}_s(x,t) \end{cases}$$
to be studied in the swarm phase

4 dynamical fields and 5 non-linear couplings



all coupling constants have RG scaling dimension equal to $\varepsilon = 4 - d$, hence:

expansion for $d = 4 - \varepsilon$

a handful of 1-loop diagrams



a novel fixed point emerges





numerical simulations

numerical simulations - Inertial Spin Model

$$\begin{cases} \frac{d\boldsymbol{v}_i}{dt} = \frac{1}{\chi} \boldsymbol{s}_i \times \boldsymbol{v}_i & \text{Sriram, notice this... and yet spin cannot be eliminated!} \\ \frac{d\boldsymbol{s}_i}{dt} = \boldsymbol{v}_i \times \frac{J}{n_i} \sum_j n_{ij}(t) \boldsymbol{v}_j \boxed{-\frac{\eta}{\chi} \boldsymbol{s}_i} + \boldsymbol{v}_i \times \boldsymbol{\zeta}_i & \langle \boldsymbol{\zeta}_i(t) \cdot \boldsymbol{\zeta}_j(t') \rangle = 2dT \ \eta \ \delta_{ij} \delta(t-t') \\ \frac{d\boldsymbol{r}_i}{dt} = \boldsymbol{v}_i & \text{Cavagna et al 2015} \end{cases}$$

0.1

logξ

0.2

0.3

0

final comparison



summary: experiments - simulations - RG theory



too good to be true?

$$z_{\text{RG},1-\text{loop}} = 1.35 \qquad z_{\text{sim}} = 1.35 \pm 0.04$$
$$z_{\text{RG},2-\text{loop}} = ? \qquad \text{will the 2-loop corrections be just zero ?!?}$$

$$z_{\text{RG}}^{\text{Model G}} = 1.5 \qquad \delta z_{1-\text{loop}} = 0.15$$
$$\delta z_{2-\text{loop}} = ?$$
$$\delta z_{2-\text{loop}}^{\text{Ising}} = 0.02$$

it's not to good to be true – we are in line with standard calculations

RG crossover

spin dynamics:

$$\dot{s} = -\Lambda s + \dots$$

conservative:

$$\Lambda = \lambda k^2$$

non - conservative:

$$\Lambda = \lambda k^2 + \eta$$

 η is an RG-relevant variable



temporal relaxation in natural swarms is clearly underdamped



Vicsek swarms - simulations



RG crossover



RG crossover





the 3.99 group



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