

NONEQUILIBRIUM RESPONSE -III

RECAP

- General response formula in Nonequilibrium from dynamical ensembles
- Decomposition according to time-reversal symmetry
- Consistent with Kubo and Green-Kubo around equilibrium
- Examples: Jump processes
- Random walk and boundary/bulk driven SEP

DIFFUSION PROCESSES

- Single particle/ many particles diffusing in potential
- Time evolution governed by Langevin equation: overdamped/ underdamped
- Response to external force
- General formalism remains same
- How to compute the path probability? Action?

OVERDAMPED DIFFUSION

- Single particle in a thermal bath of temperature T
- Nonconservative force field : out of equilibrium

- Overdamped regime $\dot{x} = \mu[f(x) + \varepsilon h_s \nabla V(x)] + \sqrt{2\mu T} \eta_t$

Nonconservative force ($d > 1$) Perturbation

- Discretise the trajectory to write the probability

$$\omega = \{x_s; 0 \leq s \leq t\} := \{x_{i\Delta t}\}_{i=0}^N \quad \text{With } t = N\Delta t$$

- Path-weight $P(\omega) = \lim_{N \rightarrow \infty} \prod_{i=0}^N P_{\Delta t}(x_i | x_{i-1})$ (Markov)

- Discretize Langevin equation:

$$\Delta x = \mu F(x) \Delta t + \sqrt{2D\Delta t} \xi \quad \text{Where}$$

$$F(x) = f(x) + \varepsilon h_t \nabla V(x)$$

$$D = \mu T$$

- Gaussian variable ξ from $N(0,1)$: $P(\xi) \propto \exp[-\xi^2/2]$

$$P_{\Delta t}(\Delta x_i) \propto \exp \left[-\frac{\Delta t}{4D} \left(\frac{\Delta x_i}{\Delta t} - \mu F(x_i) \right)^2 \right]$$

- Multiply and $\Delta t \rightarrow 0$

$$P(\omega) \propto \exp \left[-\frac{1}{4D} \int_0^t ds \left(\dot{x}_s - \mu F(x_s) \right)^2 \right]$$

Trajectory weight for an overdamped particle moving under force $F(x)$

- Reference process: pure diffusion

$$P_0(\omega) \propto \exp \left[-\frac{1}{4D} \int_0^t ds \dot{x}_s^2 \right]$$

- Action from the ratio

$$F(x) = f(x) + \varepsilon h_t \nabla V(x)$$

$$A_\varepsilon(\omega) = -\log \frac{P(\omega)}{P_0(\omega)} = -\frac{\beta}{2} \int_0^t dx_s F(x_s) + \frac{\beta\mu}{4} \int_0^t ds F(x_s)^2$$

- Response : excess wrt ε (around $\varepsilon = 0$)

Stochastic integrals

$$A'_0(\omega) = -\frac{\beta}{2} \int_0^t dx_s h_s \nabla V(x_s) + \frac{\beta\mu}{2} \int_0^t ds h_s f(x_s) \nabla V(x_s)$$

- Identify entropy and frenesy
- Time-reversal: protocol h_s also to be reversed $\theta h_s = h_{t-s}$

$$A'_0(\omega) = -\frac{\beta}{2} \int_0^t dx_s h_s \nabla V(x_s) + \frac{\beta\mu}{2} \int_0^t ds h_s f(x_s) \nabla V(x_s)$$

Not well defined symmetry

Symmetric

- Recast in terms of Stratonovich integral

$$\int_0^t dx_s h_s \nabla V(x_s) = \int_0^t dx_s \circ h_s \nabla V(x_s) - D \int_0^t ds h_s \nabla^2 V(x_s)$$

Anti-symmetric

Symmetric

Calculate
explicitly

- Excess entropy

$$S'_0 = \beta \int_0^t dx_s \circ h_s \nabla V(x_s)$$

$$= \beta \left[V(x_t)h_t - V(x_0)h_0 - \int_0^t ds \dot{h}_s V(x_s) \right]$$

Work done by the perturbing
force
along the trajectory

Same as Kubo

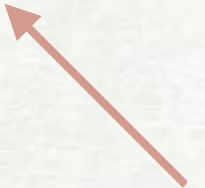
- Excess frenesy

$$D'_0 = \frac{\beta}{2} \int_0^t ds h_s [D \nabla^2 V(x_s) + \mu f(x_s) \nabla V(x_s)]$$

- Depends on diffusion constant and μ : medium dependent

- Equilibrium response can be obtained by just knowing the perturbation protocol
- In nonequilibrium medium property enters through frenesy
- Same perturbation in different medium results in different response

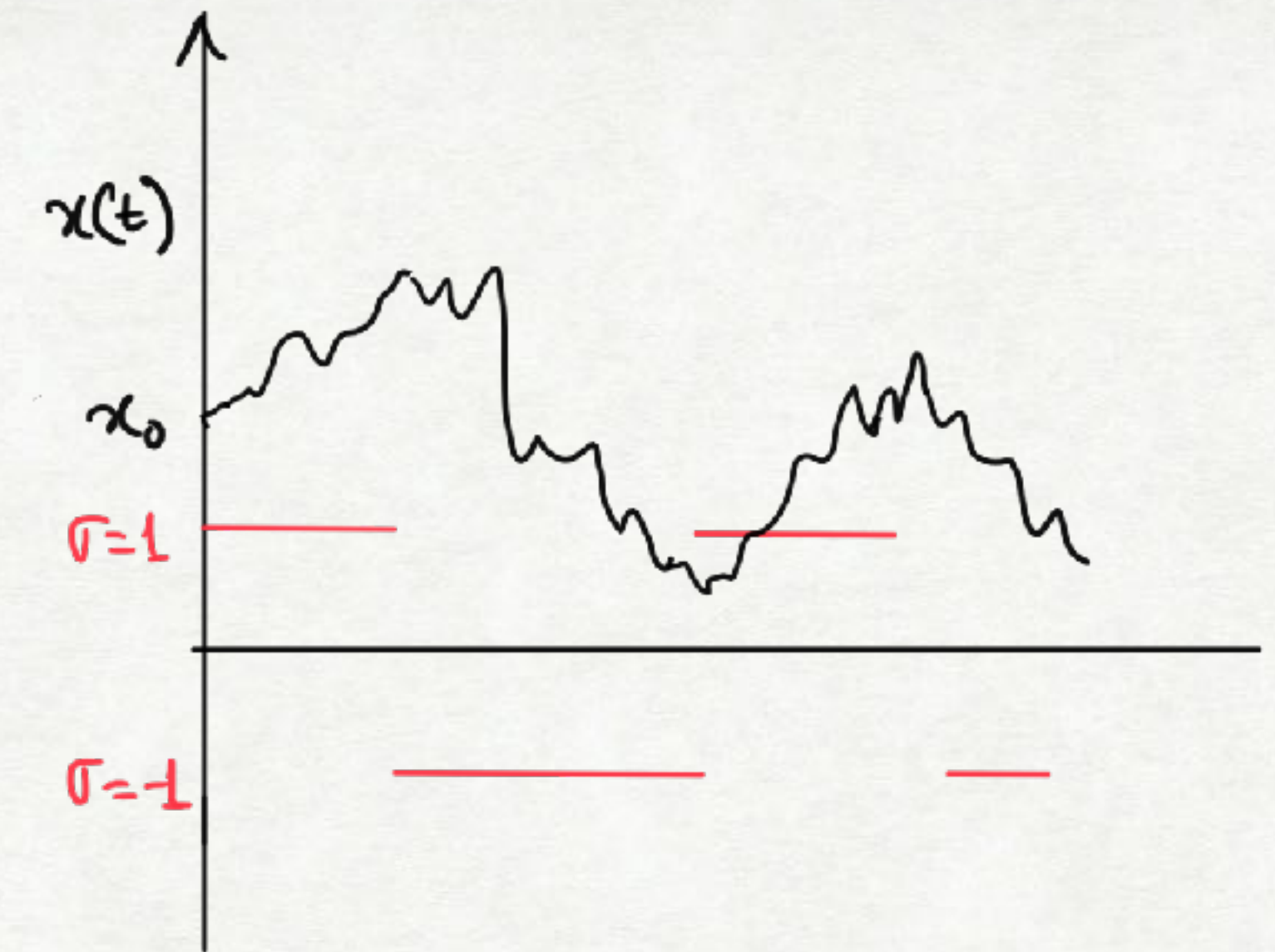
ACTIVE RUN-AND-TUMBLE PARTICLE (RTP)

- Overdamped particle with an internal 'orientation' $\sigma = \pm 1$
- Flips with rate α
$$\dot{x} = v_0 \sigma_t + \sqrt{2T} \eta_t + \varepsilon \quad \text{and } \sigma \xleftrightarrow{\alpha} -\sigma$$


Perturbation
- Two sources of stochasticity: σ and η
- White noise $\langle \eta_t \rangle = 0, \quad \langle \eta_t \eta_{t'} \rangle = \delta(t - t')$
- Dichotomous noise $\langle \sigma_t \rangle = 0, \quad \langle \sigma_t \sigma_{t'} \rangle = \exp[-2\alpha |t - t'|] : \text{coloured (memory)}$
- Position: non-Markov evolution

TRAJECTORY

- Trajectory $\omega = \{x_s, \sigma_s; 0 \leq s \leq t\}$
- Joint $x - \sigma$ process is Markov
- σ evolution independent of position
- Weight $P(\omega) = P(\{x_s\} | \{\sigma_s\})P(\{\sigma_s\})$
- σ trajectory: 2 state jump process $\rightarrow \{(\sigma_0, t_0), (\sigma_1, t_1), \dots, (\sigma_n, t_n)\}$



- $$P(\{\sigma_s\}) \propto \rho(\sigma_0) e^{-\alpha \sum t_i} \alpha^n$$

With $\rho(\sigma_0) = \frac{1}{2}$

P denotes probability generically,
not the specific function

- Position trajectory weight- piecewise:

$$P(\{x_s\} | \{\sigma_s\}) = \prod_{i=0}^n P(\{x_s; 0 \leq s \leq t_i\} | \sigma_i)$$

- Each segment evolves following an overdamped equation

$$P(\{x_s; 0 \leq s \leq t_i\} | \sigma_i) \propto \exp \left[-\frac{1}{4T} \int_0^{t_i} ds (\dot{x}_s - v_0 \sigma_i + \varepsilon)^2 \right]$$

- Full trajectory probability

$$P_\varepsilon(\omega) \propto \alpha^n e^{-\alpha t} \exp \left[-\frac{1}{4T} \int_0^t ds (\dot{x}_s - v_0 \sigma_s + \varepsilon)^2 \right]$$

- Reference process: $\varepsilon = 0$

- Weight

$$P_0(\omega) \propto \alpha^n e^{-\alpha t} \exp \left[-\frac{1}{4T} \int_0^t ds (\dot{x}_s - v_0 \sigma_s)^2 \right]$$

- Action

$$A_\varepsilon(\omega) = \frac{1}{4T} \int_0^t ds [\varepsilon^2 + \varepsilon(\dot{x} - v_0 \sigma_s)]$$

- Excess action (around $\varepsilon = 0$)

$$A'_0(\omega) = \frac{1}{2T} \int_0^t ds (\dot{x} - v_0 \sigma_s) = \frac{1}{2T} \left[x_t - x_0 - v_0 \int_0^t ds \sigma_s \right]$$

DECOMPOSITION

- Identify time-symmetric and anti-symmetric components

$$A'_0(\omega) = \frac{1}{2T} \left[x_t - x_0 - v_0 \int_0^t ds \sigma_s \right]$$

Anti-symmetric



- Second term: depends on time-reversal behaviour of σ
- Symmetric if $\sigma_{t-s} = \sigma_s$, anti-symmetric if $\sigma_{t-s} = -\sigma_s$ (like velocity)

Generalized reversible

- If $\sigma_{t-s} = \sigma_s$

- Excess entropy

$$S'(\omega) = \frac{1}{T}(x_0 - x_t)$$

- Excess frenesy

$$D'(\omega) = -\frac{v_0}{2T} \int_0^t ds \sigma_s$$

- If $\sigma_{t-s} = -\sigma_s$

- Whole action is anti-symmetric

$$S'_0(\omega) = -\frac{1}{T} \left[x_t - x_0 - v_0 \int_0^t ds \sigma_s \right]$$

- No excess frenesy $D'(\omega) = 0$

- Response of displacement (same irrespective of choice)

$$\langle (x_t - x_0) \rangle_\varepsilon = \varepsilon \left[\frac{1}{2T} \langle (x_t - x_0)^2 \rangle_0 - \frac{v_0}{2T} \int_0^t \langle \sigma_s (x_t - x_0) \rangle_0 \right]$$

- Can be verified explicitly
- Equilibrium limit : $v_0 = 0$
- Physical interpretation: response entropic if σ reverses sign under time-reversal
- Also generalised reversible then...

VIOLATION OF EINSTEIN-SUTHERLAND RELATION

$$\dot{x} = v_0 \sigma_t + \sqrt{2T} \eta_t + \varepsilon$$

- Mobility and diffusion are related in equilibrium $\mathcal{D} = \mu T$

- For RTP, mobility $\mu = \lim_{t \rightarrow \infty} \frac{1}{\varepsilon t} \langle (x_t - x_0) \rangle_\varepsilon = 1$

- Diffusion $\mathcal{D} = \lim_{t \rightarrow \infty} \frac{1}{2t} \langle (x_t - x_0)^2 \rangle_0 = T + \frac{v_0^2}{2\alpha} > \mu T$

- Diffusion even when no temperature
- Additive violation of Einstein relation

EFFECTIVE TEMPERATURE

- Enforce Kubo-formula with a modified prefactor
- Example: RTP $\mathcal{D} = \mu T_{eff}$ with $T_{eff} = T + \frac{v_0^2}{2\alpha}$
- Strategy: Incorporate the deviation from Kubo-formula via effective temperature
- Does the same temperature work for all observable?

- Recast the Nonequilibrium response formula (around $\varepsilon = 0$):

$$\begin{aligned}
 \frac{1}{\varepsilon}[\langle O(t) \rangle_\varepsilon - \langle O(t) \rangle_0] &= \frac{1}{2} \langle S'_0 O(t) \rangle_0 - \langle D'_0 O(t) \rangle_0 \\
 &= \langle S'_0 O(t) \rangle_0 - \left\langle [D'_0 + \frac{1}{2} S'_0] O(t) \right\rangle_0 \\
 &= \langle S'_0 O(t) \rangle_0 \left[1 - \frac{\langle [D'_0 + \frac{1}{2} S'_0] O(t) \rangle_0}{\langle S'_0 O(t) \rangle_0} \right] \\
 &= \beta \left[1 - \frac{\langle [D'_0 + \frac{1}{2} S'_0] O(t) \rangle_0}{\langle S'_0 O(t) \rangle_0} \right] \int_0^t ds \, h_s \frac{d}{ds} \langle V(s) O(t) \rangle_0
 \end{aligned}$$

Effective temperature

$$= \beta_{eff} \chi_{\text{Kubo}}$$

- Generally time-dependent : late time limit is often taken
- Multiplicative correction instead of additive
- Obviously depends on the observable
- Successful in certain scenarios

Ref: Cugliandolo, J Phys A 2011