

# On a Local Lyapunov function for the McKean-Vlasov Dynamics

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August 2017

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- ▶  $\eta(t) := \text{Law}(X(t))$  for  $t \geq 0$ ; column vector.
- ▶ Forward equation (FE):

$$\dot{\eta}(t) = L^* \eta(t), \quad t \geq 0, \text{ with } \eta(0) = \nu_0.$$

# A Lyapunov function for the dynamics

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- ▶ The dynamics is not necessarily reversible.
- ▶ Well-known: Relative entropy with respect to the invariant measure  $I(\cdot|\nu)$  is a Lyapunov function for the dynamics, i.e.,

$$I(\eta(t)|\nu) \leq I(\eta(s)|\nu) \text{ for } t > s \geq 0.$$

- ▶  $I(\mu|\nu) = \sum_{i \in S} \mu_i \log(\mu_i/\nu_i).$

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- ▶ Mean-field interactions: The transition rate of a particle depends on its state, and on the states of the other particles, but only through the empirical measure.
- ▶  $L_{\eta_N(t)}(i, j)$  = rate of an  $i \rightsquigarrow j$  transition at time  $t$  for a particle  $n$  in state  $X_n(t) = i$ .

# Assumptions and a limit theorem



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## Theorem

*Under the above assumptions, we have the following convergence (uniform over compacts) in probability:*

$$\eta_N(\cdot) \rightarrow \nu(\cdot),$$

*where  $\nu(\cdot)$  is the solution to the MVE with initial condition  $\nu_0$ .*

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  - ▶ Asymptotically, the particle evolutions decouple; “propagation of chaos”.
  - ▶ If  $\nu$ , the rest point for the MVE, is globally asymptotically stable, then the equilibrated distribution of  $k$  tagged particles is  $\nu^{\otimes k}$ .

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- ▶ The rate matrix of this Markov process is

$$\mathcal{L}_N(\xi, \xi^{i,j}) = N\xi_i L_\xi(i, j).$$

Also it is irreducible if  $\underline{L}$  is so.

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or equivalently, after division by  $N$ ,

$$\frac{1}{N} \sum_{\xi \in \Delta_N(S)} p_N(t)(\xi) \log \left( \frac{p_N(t)(\xi)}{p_N(\xi)} \right) \leq \frac{1}{N} \sum_{\xi \in \Delta_N(S)} p_N(s)(\xi) \log \left( \frac{p_N(s)(\xi)}{p_N(\xi)} \right)$$

# Manipulating the prelimit Lyapunov function

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$J_{N,t}(\cdot) \rightarrow J_t(\cdot)$ , and  $J_N(\cdot) \rightarrow J(\cdot)$ , and the convergences are uniform.  
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Consequences:

- Thanks to uniform convergence, the prelimit Lyapunov function is as close to

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- ▶ Thanks to continuity of  $J_t$ ,  $J$ , and  $p_N(t) \xrightarrow{w} \delta_{\nu(t)}$ , we get

$$J(\nu(t)) - J_t(\nu(t)) = J(\nu(t))$$

is nonincreasing with  $t$  and thus a Lyapunov function for the MVE.

# The main result

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  - ▶ By contraction, LDP of the flow of empirical measure  $(\eta_N(t), t \in [0, T])$ . Rate function  $S_{[0, T]}(\eta(\cdot))$ . Rate function for state at terminal time  $J_T$ .

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  - ▶ By techniques similar to the previous talk, LDP for the invariant measure  $p_N$ . Rate function  $J$ .
- ▶ While we could naturally establish that  $J_t$  and  $J$  are l.s.c., we had not established continuity of these functions.

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  4.  $\text{osc}(\log p_N(\cdot)) \leq \text{osc}(\log \mu_N(\cdot)) + c \log N.$
- ▶ By Arzela-Ascoli, limit of  $-\frac{1}{N} \log p_N(\cdot)$  (which we know exists from before) must be continuous.

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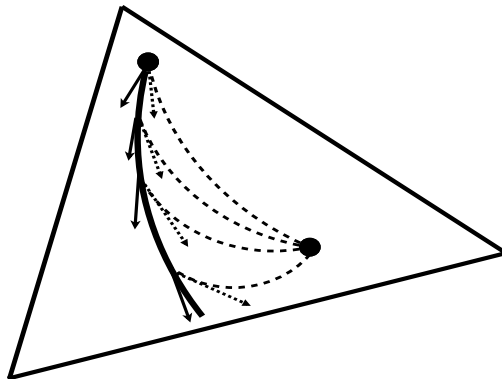
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  - ▶ Finally follow Freidlin-Wentzell to analyse the invariant measure.



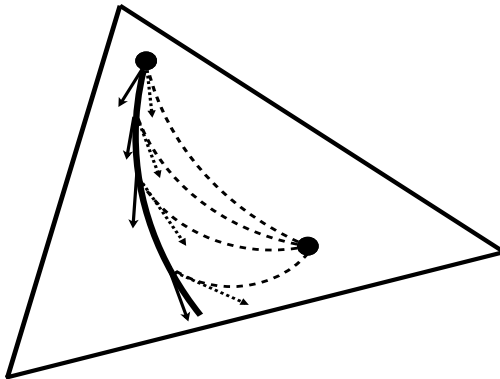
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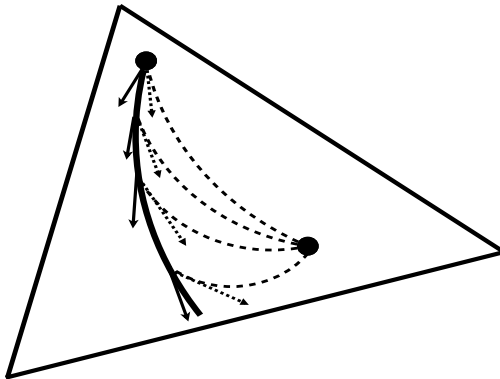
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- ▶ Sum over  $i$  and  $j$  and integrate over  $[0, T]$  to get the action functional:

$$\int_0^T \mathcal{L}(\eta(t), \dot{\eta}(t)) dt.$$

# The case of a globally asymptotically stable equilibrium $\nu$

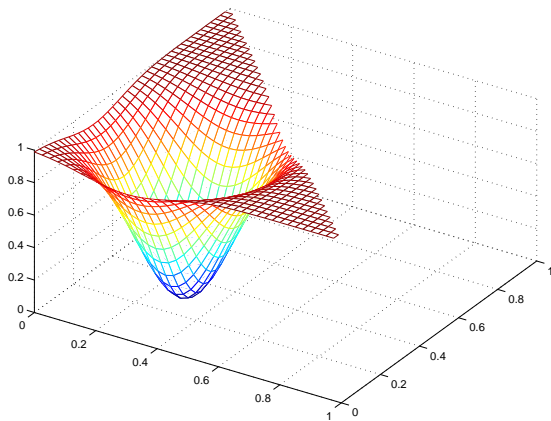
## Theorem

$J(\xi)$  is given by

$$J(\xi) = \inf \left\{ \int_0^T \mathcal{L}(\eta(t), \dot{\eta}(t)) \, dt \mid \eta(0) = \nu, \eta(T) = \xi, T \in (0, \infty) \right\}.$$

- ▶ Any deviation that puts the system at  $\xi$  must have started its effort from  $\nu$ .
- ▶  $J(\nu) = 0$ .

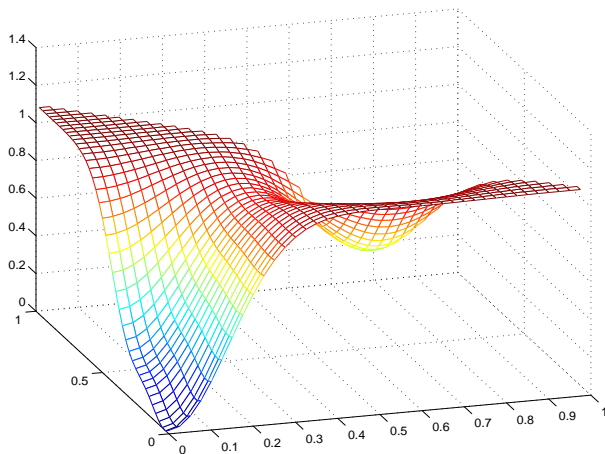
## The path to $\xi$



Can specify not only exponent  $J(\xi)$  of the probability, but also the path.

Any deviation that puts the system near  $\xi$  must have started from  $\nu$ , and must have taken the least cost path.

## When there are multiple stable limit sets



The case of two stable equilibria is easy to describe.

- ▶  $V_{12}$  = cost of moving from  $\nu^{(1)}$  to  $\nu^{(2)}$ .
- ▶  $V_{21}$  = cost of the reverse move.
- ▶ If  $V_{12} > V_{21}$ , then  $v_1 = 0$  and  $v_2 = V_{12} - V_{21}$ .

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## Theorem

$J(\xi)$  is given by

$$J(\xi) = \inf \left\{ v_i + \int_0^T \mathcal{L}(\eta(t), \dot{\eta}(t)) dt \mid \eta(0) = \nu^{(i)}, i = 1, 2, \eta(T) = \xi, T > 0 \right\}.$$

- ▶ Start from the global minimum  $\nu^{(1)}$  and move to the attractor in the basin in which  $\xi$  lies along the least cost path.
- ▶ Then move to  $\xi$  from there along the least cost path.
- ▶ A similar result when there are more than two, but finite, number of stable limit sets.

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- ▶ It is local Lyapunov if the dynamics has multiple stable rest points.