# Fractional derivatives, boundary value problems and heavy particles in a viscous fluid

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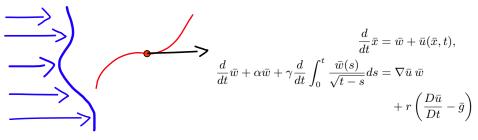


# Acknowledgements

The following is joint work with Rama Govindarajan and S Ganga Prasath (ICTS)

# The Maxey-Riley equation

(M&R 1983)



where  $\bar{u}$  is a given fluid velocity,  $\bar{w}$  is velocity of particle relative to fluid and  $\bar{x}$  is location of the particle

$$r = \left(\frac{3R}{2} - 1\right), \ \alpha = \mu, \ \gamma = \kappa \mu^{1/2}$$
 
$$R = \frac{2\rho_f}{\rho_f + \rho_p}, \ \mu = \frac{R}{St}, \ \kappa = \sqrt{\frac{9R}{2\pi}}, \ St = \frac{2}{9} \left(\frac{a}{L}\right)^2 Re$$

Faxén corrections may also be added.

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- Memory cost increases with time
- Computational cost increases with time
- Singular integrals
- Not a dynamical system

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All of this is really due to that nonlocal term

### Known results

- (F&H 2015; L, F&H 2015) Local and global existence-uniqueness of mild solutions
- Proof is involved and delicate. Does not lead to a numerical method
- Long time behaviour
- Numerical schemes: Daitche (2015, 2013)
- Does history matter?

# What can we say? V,GP&G 2018; GP,V&G 2018

- A simpler proof of global existence using standard arguments
- .....once we reformulate the problem!
- Smoothness of solutions
- A new efficient numerical method to simulate the trajectory of the particle

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#### Main message

Think of the Maxey-Riley equation as a nonlinear boundary condition to the heat equation

## Fractional derivatives

What makes MR hard?  $\equiv$  What is a half-derivative?

$$\frac{d^{1/2}}{dt^{1/2}}y = \frac{d}{dt} \int_0^t \frac{y(s)}{\sqrt{t-s}} ds = \int_0^t \frac{\dot{y}(s)}{\sqrt{t-s}} ds + \frac{y(0)}{\sqrt{t}}$$
$$\frac{d^{1/2}}{dt^{1/2}} \frac{d^{1/2}}{dt^{1/2}} y = \frac{d}{dt} y$$

- Above is called Riemann-Liouville half-derivative. We'll stick to this.
- Many other definitions of fractional derivatives: Caputo, Atangana-Baleanu, Riesz, Hadamard, Marchaud, Grünwald-Letnikov and many others

$$\left(\frac{d}{dt}\right)^{\alpha} y = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{ikx} |k|^{\alpha} \hat{y}(k) dk$$

 Fractional derivatives: Podlubny (1998). Equivalence of fractional Laplacians: Kwaśnicki (2017).

$$\frac{d^{1/2}}{dt^{1/2}} \frac{d^{1/2}}{dt^{1/2}} q = \frac{d}{dt} q$$
$$\frac{d^{1/2}}{dt^{1/2}} \to \frac{d}{dx}$$

to obtain

Formally replace

$$\frac{d^2}{dx^2}q = \frac{d}{dt}q$$

Does the 1/2 derivative have anything to do with the heat equation?

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Does the 1/2 derivative have anything to do with the heat equation?

$$q_t = q_{xx}, \quad x > 0, \ 0 < t < T,$$
 
$$q(x,0) = 0, \quad x > 0, t = 0, \quad q(0,t) = y(t), \quad 0 \le t \le T$$

Then

$$q_x(0,t) = \frac{d^{1/2}}{dt^{1/2}}y = \int_0^t \frac{\dot{y}(s)}{\sqrt{t-s}}ds + \frac{y(0)}{\sqrt{t}}$$

 $\begin{tabular}{ll} Dirichlet $\rightarrow$ Neumann map \\ Can be shown using UTM starting from the global relation \\ \end{tabular}$ 

# UTM: Dirichlet to Neumann map

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Global relation

$$\begin{split} e^{k^2T} \hat{q}(k,T) &= ik \tilde{f}_0(k,0,T) + \tilde{f}_1(k,0,T), \quad k \in \mathbb{C}^- \\ \hat{q}(k,T) &= \int_0^\infty e^{-ikx} q(x,T) dx, \quad \tilde{f}_j(k,X,\tau) = \int_0^\tau e^{k^2s} \partial_x^j q(X,s) ds \end{split}$$

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- Multiply by  $ike^{-ik^2t}$  and integrate over  $\partial D^- = \{k \in \mathbb{C}^- \mid \operatorname{Re} k^2 = 0\}$
- Left-hand side drops out by Jordan's lemma
- Right most term  $k^2 \to il$ ,  $l \in \mathbb{R}$  and apply Fourier inversion theorem
- Integrate-by-parts first term on right and then apply Fubini's theorem

# Model equation

MR equation

$$\begin{split} \frac{d}{dt}\bar{x} &= \bar{w} + \bar{u}(\bar{x},t),\\ \frac{d}{dt}\bar{w} &+ \alpha\bar{w} + \gamma\frac{d}{dt}\int_0^t \frac{\bar{w}(s)}{\sqrt{t-s}}ds &= \bar{F}(\bar{w},\bar{x},t) \end{split}$$

Focus attention on the velocity equation and replace nonlinearity

$$\frac{d\bar{y}}{dt} + \alpha \bar{y} + \gamma \frac{d^{1/2}}{dt^{1/2}} \bar{y} = \bar{F}(\bar{y})$$

Linear version

$$\frac{d\bar{y}}{dt} + \alpha \bar{y} + \gamma \frac{d^{1/2}}{dt^{1/2}} \bar{y} = \bar{F}(t)$$

Q Can we solve this equation?

• F&H (2015) invert the d/dt and iterate over space of continuous functions

# Model equation

(scalar linear) Model MR 
$$\rightarrow$$
 Heat equation  $y(t) \rightarrow q(0,t)$ 

$$\begin{aligned} q_t &= q_{xx}, & x > 0, & 0 < t < T, \\ q(x,0) &= 0, & x > 0, t = 0, \\ \frac{d}{dt}q(0,t) + \alpha q(0,t) - \gamma q_x(0,t) &= F(t), & 0 \le t \le T, \\ \lim_{t \to 0} q(0,t) &= y_0 \end{aligned}$$

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Q What does 'solve' mean?

#### Local existence

Scalar model  $MR \rightarrow mild$  form

$$\frac{dy}{dt} + \alpha y + \gamma \frac{d^{1/2}}{dt^{1/2}} y = F(y) \longrightarrow y(t) = \varphi(t) y_0 + \int_0^t \varphi(t-s) F(y(s)) ds$$
 and Picard iterates converge in  $C[0,T]$  for  $F$  Lipschitz

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$$\frac{dy}{dt} + \alpha y + \gamma \frac{d^{1/2}}{dt^{1/2}}y = 0, \quad y(0) = y_0$$

in the sense

$$q_t = q_{xx}, \quad x > 0, \ 0 < t < T,$$
 
$$q(x,0) = 0, \quad x > 0, t = 0,$$
 
$$\frac{d}{dt}q(0,t) + \alpha q(0,t) - \gamma q_x(0,t) = 0, \quad 0 \le t \le T,$$
 
$$\lim_{t \to 0} q(0,t) = y_0$$

has a solution and  $\lim_{x\to 0} q(x,t) = \varphi(t)$ 

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h<sup>2</sup>t

$$\varphi(t) = \frac{i}{\pi} \int_{-\infty}^{\infty} \frac{ke^{-k^2t}}{\alpha - k^2 + ik\gamma} dk$$

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and Picard iterates converge in C[0,T] for F Lipschitz where

$$\varphi(t) = \frac{i}{\pi} \int_{-\infty}^{\infty} \frac{ke^{-k^2t}}{\alpha - k^2 + ik\gamma} dk$$

- $\varphi(0) = 1$ ,  $\varphi'(t) < 0$  for t > 0 and  $\varphi(t) \to 0$  as  $t \to \infty$
- $\varphi(t)$  is bounded, 1/2–Hölder continuous at t=0 and smooth for all t>0
- If F is differentiable  $\Rightarrow$  strong solution for t > 0
- Grönwall's inequality implies uniqueness

#### Global existence

Classical argument

$$\frac{dy}{dt} = F(y) \longrightarrow y(t) = y_0 + \int_0^t F(y(s))ds$$

Local existence in C[0,T]. Restart the iteration process using  $y_0 = y(T)$ 

In our case  $\varphi(t+s) \neq \varphi(t)\varphi(s)$ . No semigroup property  $t \to t+s$  implies vector field at t+s depends on solution up to time s

Not a dynamical system!

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... But heat equation is!

## Linear model MR

#### Global existence

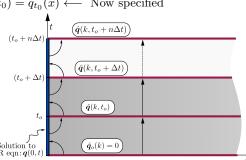
$$q_t = q_{xx}, \quad x > 0, t \in (t_0, t_0 + \Delta t),$$

$$\frac{d}{dt}q(0,t) + \alpha q(0,t) - \gamma q_x(0,t) = F(t), \quad t_0 \le t \le t_0 + \Delta t,$$

$$\lim_{t \to t_0} q(0,t) = y(t_0),$$

$$q(x,t_0) = q_{t_0}(x) \longleftarrow \text{ Now specified}$$

- 1) solve for Dirichlet condition in  $[t_0, t_0 + \Delta t]$
- 2) find  $q(x, t_0 + \Delta t)$  using Dirichlet boundary condition



Same idea works for nonlinear case

$$q_t = q_{xx}, \quad x > 0, t \in (t_0, t_0 + \Delta t),$$

$$\frac{d}{dt}q(0, t) + \alpha q(0, t) - \gamma q_x(0, t) = F(q(0, t)), \quad t_0 \le t \le t_0 + \Delta t,$$

$$\lim_{t \to t_0} q(0, t) = y(t_0),$$

$$q(x, t_0) = q_{t_0}(x) \longleftarrow \text{ Now specified}$$

- Only require  $\hat{q}(k, t_0)$  (no Fourier inversion required)
- If nonlinearity is uniformly Lipschitz ⇒ Global existence (usual ODE argument)
- $y(t), t \in [t_0, t_0 + \Delta t] \rightarrow \hat{q}(k, t_0 + \Delta t)$  is explicit

$$y(t) = \int_{-\infty}^{\infty} ke^{-k^2(t-t_0)} \hat{H}(k, t_0) dk + \int_{t_0}^{t} F(y(s)) \varphi(t-s) ds, \quad t_0 < t < t_0 + \Delta t$$

$$\hat{H}(k,t_0) = e^{-k^2 \Delta t} \, \hat{H}(k,t_0 - \Delta t) - e^{-k^2 t_0} \int_{t_0 - \Delta t}^{t_0} e^{k^2 s} y(s) ds$$
$$+ \frac{e^{-k^2 t_0}}{\alpha - k^2 + i\gamma k} \int_{t_0 - \Delta t}^{t_0} e^{k^2 s} F(y(s)) ds$$

with

$$\hat{H}(k,0) = \frac{y(0)}{(\alpha - k^2 + ik\gamma)}$$

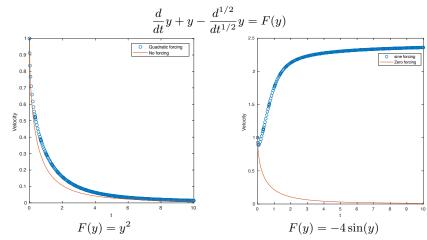
and

$$\varphi(t) = \frac{i}{\pi} \int_{-\infty}^{\infty} \frac{ke^{-k^2t}}{\alpha - k^2 + ik\gamma} dk$$

Rewriting history along the way

## Numerical method

- Approximate y(t) in Chebyshev polynomials over interval  $[t_0, t_0 + \Delta t]$
- Use mapped Chebyshev polynomials for  $\hat{H}(k, t_0)$
- Newton's method to solve for y(t). Convergence follows from existence of local solution



# Back to the MR equations

#### Component-wise

$$\frac{dx_i}{dt} = w_i + u_i(\bar{x}, t),$$

$$\frac{dw_i}{dt} + \alpha w_i + \gamma \frac{d^{1/2}}{dt^{1/2}} w_i = F_i(\bar{x}, \bar{w}, t)$$

- This leads to a system of model equations
- Linear equations are decoupled, solved using UTM
- Three heat equation BVPs (but effectively all are same)

#### Theorem

If  $\bar{u}$  is sufficiently smooth, then for any initial condition the MR equations has a mild solution for all time t>0

- Velocities are differentiable except possibly at t = 0 (when  $w_i(0) \neq 0$ )
- Fluid velocity  $\bar{u}(\bar{x},t)$  has three continuous uniformly bounded derivatives and partial derivatives are uniformly Lipschitz (same as F&H 2015)

# Why stick to only half-derivatives?

Rational derivatives

$$\frac{d}{dt}y + \alpha y + \gamma \frac{d^{1/3}}{dt^{1/3}}y = 0, \quad y(0) = y_0$$

rewritten as

$$q_{t} = -q_{xxx}, \quad x > 0, \ t \in (0, T),$$
 
$$q(x, 0) = 0, \quad x > 0,$$
 
$$\frac{d}{dt}q(0, t) + \alpha q(0, t) + \gamma q_{x}(0, t) = 0, \quad t \in [0, T],$$
 
$$\lim_{t \to 0} q(0, t) = y_{0}$$

since

$$\frac{d^{1/3}}{dt^{1/3}}y = \int_0^t \frac{\dot{y}(s)}{(t-s)^{1/3}} ds + \frac{y_0}{t^{1/3}} = q_x(0,t) = DN[q(0,t)]$$

where DN[f] is the Dirichlet to Neumann map for the third order PDE.

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where DN[f] is the Dirichlet to Neumann map for the third order PDE. also

$$\frac{d^{2/3}}{dt^{2/3}}y = q_{xx}(0,t)$$

## Rational derivatives

a general recipe

$$q_t = \partial_x^n q, \quad x > 0, \ 0 < t < T$$
 $q(0,t) = y(t), \quad t \in [0,T]$ 

$$\partial_x^m q(0,t) = \frac{d^{m/n}}{dt^{m/n}} y$$
 $\mathcal{L}q = \partial_x^n q, \quad q(x,t) : \mathbb{R}^+ \times \Omega \to \mathbb{R}, \ \Omega \subset \mathbb{R}^n$ 
 $q(0,t) = y(t), \quad t \in \Omega$ 

$$\partial_x^m q(0,t) = \mathcal{L}^{m/n} y$$

e.g.  $\mathcal{L}$  could be negative Laplacian or even wave operator. Compare elliptic extension due to Cafarelli and Sylvestre (2007)

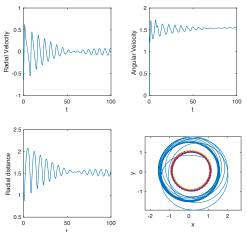
$$\Delta_t \tilde{u} + \frac{1 - \alpha}{x} \partial_x \tilde{u} + \tilde{u}_{xx} = 0,$$
  
$$\tilde{u}(t, 0) = u(t).$$

Then

$$(-\Delta_t)^{\alpha/2}u = c \lim_{t \to 0} \frac{\tilde{u}(x,t) - u(t)}{r^{\alpha}}.$$

## Conclusions

- A new way to consider rational derivatives
- Simpler wellposedness proof for MR equations
- Efficient numerical method for MR equations with fixed memory cost



Particle amongst three point-vortices

#### What remains?

- Explicit time integrators
- Integration with DNS of Navier-Stokes
- ...Does history matter?