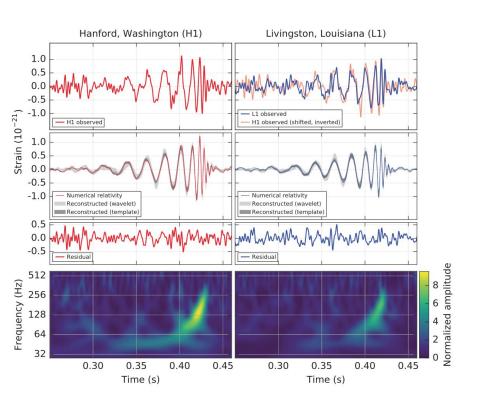
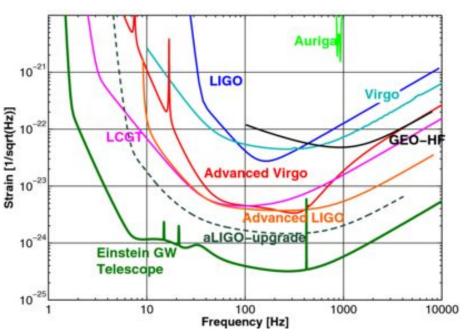
Gravitational waves from binary black holes

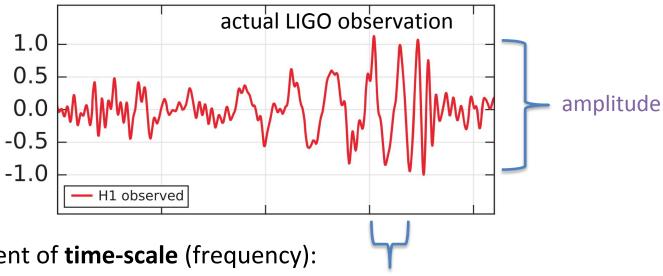




from ET conceptual design paper

Potential to detect a lot of massive binary (BH) mergers from far away

Gravitational wave observables



time scale

Measurement of time-scale (frequency):
 mass-redshift combination

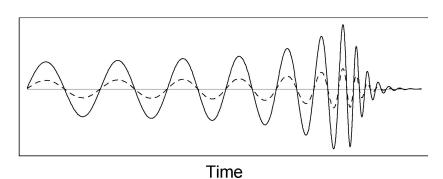
$$M(1+z)$$

Measurement of strain amplitude: (multiple detectors for orientation)
 Luminosity distance-magnification combination

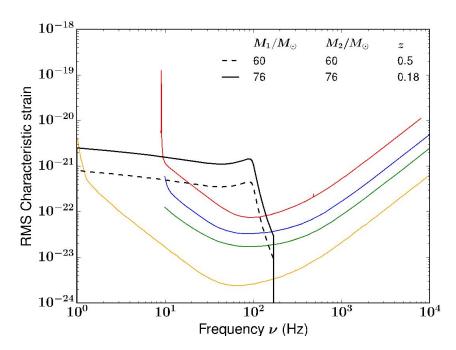
$$\frac{\sqrt{\mu}}{dL(z)} \left(\frac{dE}{df_s}\right)_{M,f_s=f_o(1+z)}^{1/2}$$

Detailed shape: mass ratio, spin, etc.

Gravitational lensing and GW parameter estimation



Consider an event with physical mass scale M, source redshift \mathcal{Z} , lensing magnification μ



Assume ignorance about magnification: Inferred mass scale \tilde{M} , inferred source redshift \tilde{z}

$$M(1+z) = \tilde{M}(1+\tilde{z})$$
$$d_L(\tilde{z}) = d_L(z)/\sqrt{\mu}$$

Availability of redshift information vs. lensing

w/o lensing (de-)magnification

w/ lensing(de-)magnification

w/ EM counterpart or host identification

w/o EM counterpart or host identification (probably BH-BH merger) Independently
measure M, z, d_L;
standard sirens for
measuring d_L(z)
(Holz & Hughes 05)

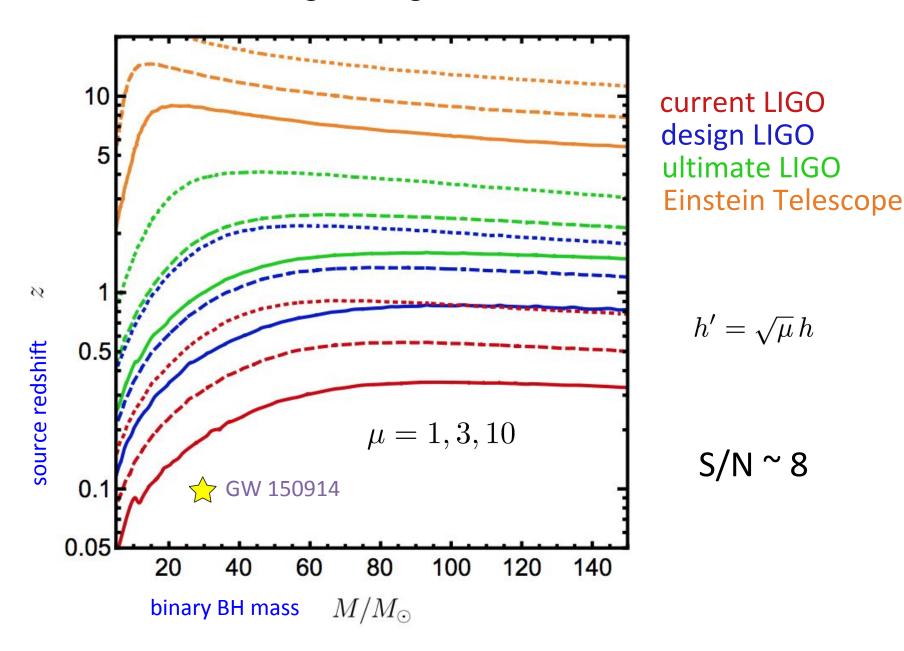
assuming fiducial cosmology d_L(z); still able to fix M, z (e.g. GW 150914)

assuming fiducial cosmology d_L(z); measure M, z and magnification µ

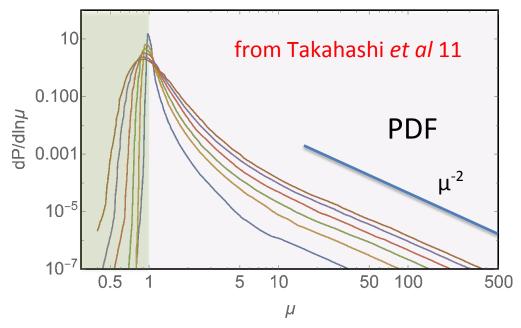
Cannot uniquely determine M, z, µ

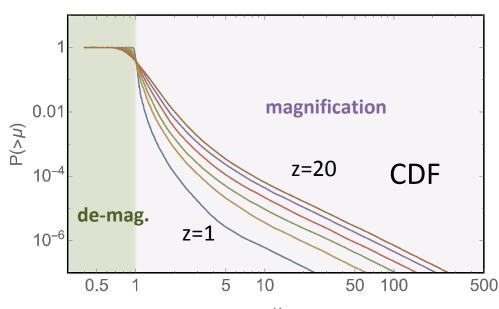
DEGENERACY

High magnification tail



Lensing probability in ACDM





normalization

$$\int d\ln \mu \, \frac{dP(\mu, z)}{d\ln \mu} \, = 1$$

conservation of solid angle

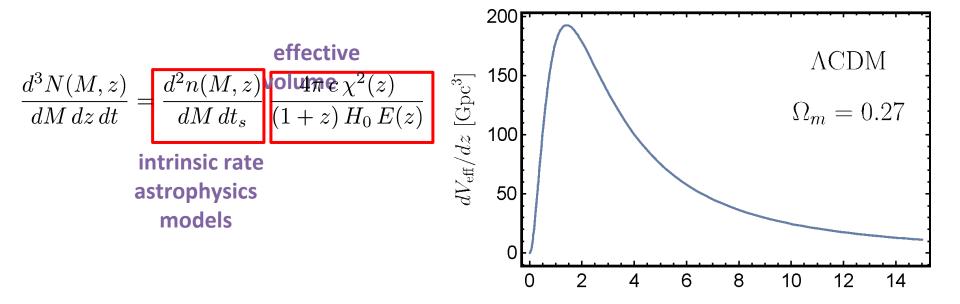
$$<\mu> = \int d \ln \mu \, \frac{dP(\mu, z)}{d \ln \mu} \, \mu = 1$$

- Strong lensing dominated by galaxies; cluster lensing subdominant. Li & Ostriker 03
- Stellar lens population: diffraction regime. Takahashi 03

Observed merger distribution

Only inferred mass and redshift are observable

$$\frac{d^3N\left(\tilde{M},\tilde{z}\right)}{d\tilde{M}\,d\tilde{z}\,dt} = \int d\ln\mu \frac{dP\left(\mu,z\right)}{d\ln\mu} \frac{d^3N\left(M,z\right)}{dM\,dz\,dt} \left[\frac{\partial\left(M,z\right)}{\partial\left(\tilde{M},\tilde{z}\right)}\right]_{\mu}$$
 Observed rate in terms of M' and z' unlensed rate in probability terms of M and z



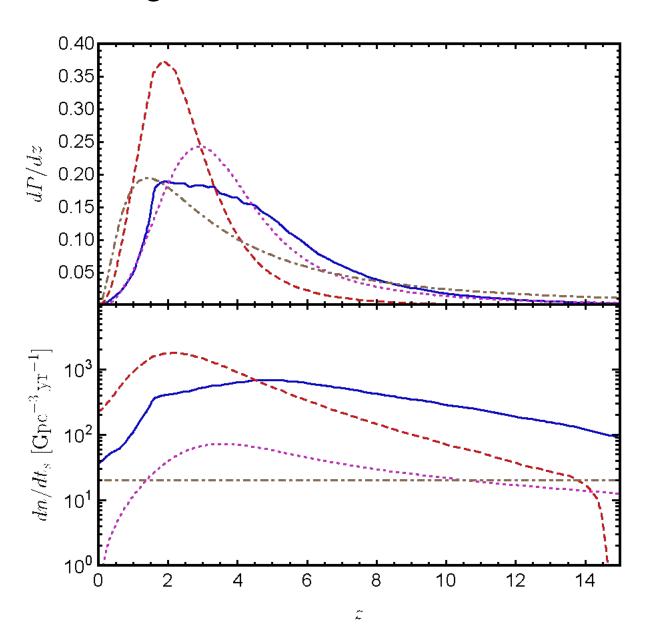
z

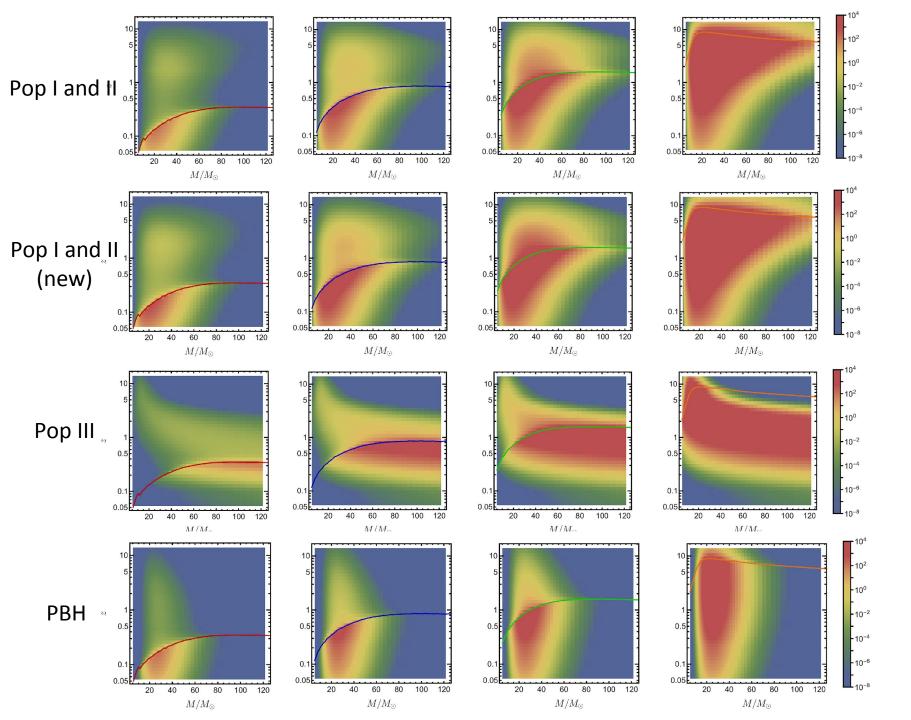
Amplification bias

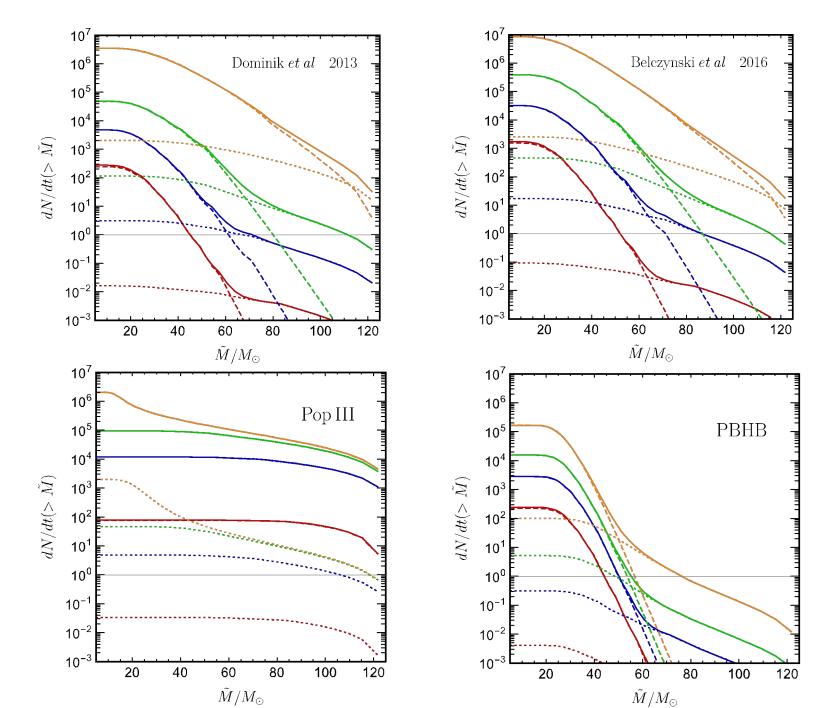
Sensitivity cut
$$\frac{dN_{\mathcal{D}}}{dt} \left(\tilde{M} > M_{\min} \right) = \int_{M_{\min}}^{+\infty} d\tilde{M} \int d\tilde{z} \, \Theta \left(\mathcal{S}_{\mathcal{D}}(\tilde{M}, \tilde{z}) - \mathcal{S}_{0} \right) \\ \times \int d \ln \mu \, \frac{dP(\mu; z)}{d \ln \mu} \, \frac{d^{3}N(M, z)}{dM \, dz \, dt} \, \left| \frac{\partial(M, z)}{\partial(\tilde{M}, \tilde{z})} \right|_{\mu}.$$

- Detector-dependent
- Increases the strongly lensed fraction for given parameters

Origin of massive BH binaries?

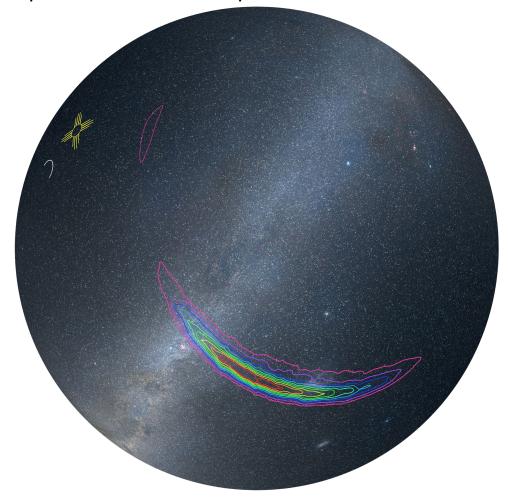






What can we learn from multiple images?

With two detectors, localization is a function of orientation. Multiple orientations -> improved location.



GW150914 Localization