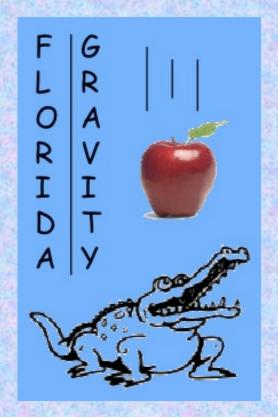
Gravity: Newtonian, post-Newtonian, Relativistic

Summer School on Gravitational Waves Indian Institute for Theoretical Sciences Bangaluru, India, 25 - 29 July 2016

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Outline of the Lectures

1. Newtonian gravity (3 lectures)

Foundations, Isolated gravitating bodies, Orbital dynamics

PW, Chapters 1, 3

2. Post-Minkowskian theory (1 lecture)

Formulation, Implementation PW, Chapters 6 - 7

3. Post-Newtonian theory: Near-zone physics (3 lectures)

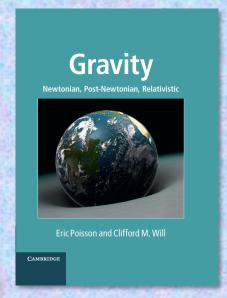
Implementation, PN celestial mechanics, astrometry & timekeeping PW, Chapters 8 - 10

4. Post-Newtonian theory: Far-zone physics (3 lectures)

Gravitational radiation, Radiation Reaction PW, Chapters 11 - 12

Textbook: Gravity: Newtonian, post-Newtonian, General Relativistic, by Eric Poisson and Clifford Will (Cambridge U Press, 2014)

Lecture slides (in pdf) and selected PW chapters available at www.phys.ufl.edu/~cmw/Gravity-Lectures/outline.html





Foundations of Newtonian Gravity

Newton's 2nd law and the law of gravitation:

$$m_I oldsymbol{a} = oldsymbol{F}$$
 $oldsymbol{F} = -G m_G M oldsymbol{r}/r^3$

The principle of equivalence:

$$\boldsymbol{a} = -\frac{m_G}{m_I} \frac{GM\boldsymbol{r}}{r^3}$$

If
$$m_G = m_I(1+\eta)$$

Then, comparing the acceleration of two different bodies or materials

$$\Delta \boldsymbol{a} = \boldsymbol{a}_1 - \boldsymbol{a}_2 = -(\eta_1 - \eta_2) \frac{GM\boldsymbol{r}}{r^3}$$



The Weak Equivalence Principle (WEP)

400 CE Ioannes Philiponus: "...let fall from the same height two weights of which one is many times as heavy as the

other the difference in time is a very small one"

1553 Giambattista Benedetti

proposed equality

1586 Simon Stevin

experiments

1589-92 Galileo Galilei

Leaning Tower of Pisa?

1670-87 Newton

pendulum experiments

1889, 1908 Baron R. von Eötvös

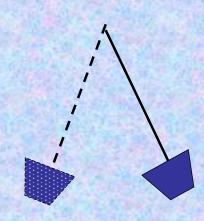
torsion balance experiments (10-9)

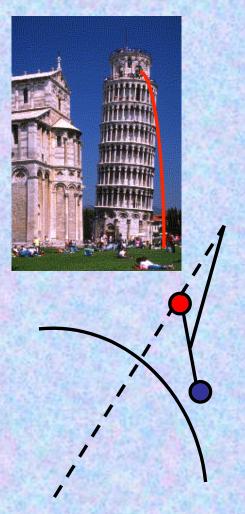
1990 - 2010 UW (Eöt-Wash)

10-13

2010 Atom inteferometers

matter waves vs macroscopic object

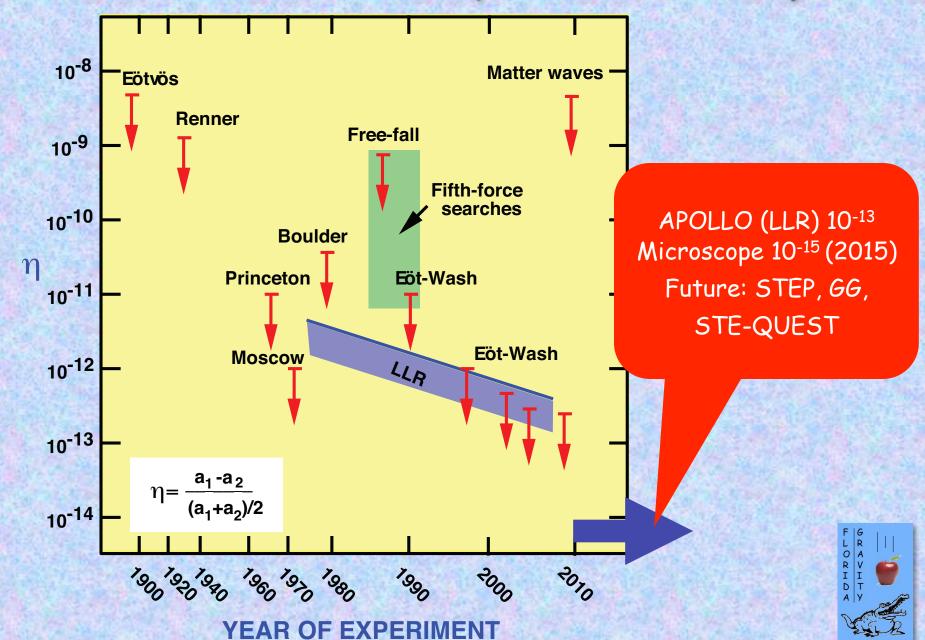




Bodies fall in a gravitational field with an acceleration that is independent of mass, composition or internal structure



Tests of the Weak Equivalence Principle



Newtonian equations of Hydrodynamics

 $moldsymbol{a}=moldsymbol{
abla}U\,,\;\;$ Equation of motion Writing U = GM/r, Field equation

Generalize to multiple sources (sum over M's) and continuous matter

$$\rho \frac{d\boldsymbol{v}}{dt} = \rho \boldsymbol{\nabla} U - \boldsymbol{\nabla} p \,,$$
 Euler equation of motion
$$\frac{\partial \rho}{\partial t} + \boldsymbol{\nabla} \cdot (\rho \boldsymbol{v}) = 0 \,,$$
 Continuity equation
$$\boldsymbol{\nabla}^2 U = -4\pi G \rho \,,$$
 Poisson field equation
$$\frac{d}{dt} := \frac{\partial}{\partial t} + \boldsymbol{v} \cdot \boldsymbol{\nabla} \,,$$
 Total or Lagrangian derivative

 $p = p(\rho, T, ...)$ Equation of state

Formal solution of Poisson's field equation:

Write
$$U(t, \boldsymbol{x}) = G \int G(\boldsymbol{x}, \boldsymbol{x}') \rho(t, \boldsymbol{x}') d^3x'$$
,

Green function
$$\nabla^2 G(\boldsymbol{x}, \boldsymbol{x}') = -4\pi\delta(\boldsymbol{x} - \boldsymbol{x}') \Rightarrow G(\boldsymbol{x}, \boldsymbol{x}') = 1/|\boldsymbol{x} - \boldsymbol{x}'|$$

$$U(t, \boldsymbol{x}) = G \int \frac{\rho(t, \boldsymbol{x'})}{|\boldsymbol{x} - \boldsymbol{x'}|} d^3x'$$



Rules of the road

Consequences of the continuity equation: for any f(x,t):

$$\frac{d}{dt} \int \rho(t, \boldsymbol{x}) f(t, \boldsymbol{x}) d^3 x = \int \left(\rho \frac{\partial f}{\partial t} + f \frac{\partial \rho}{\partial t} \right) d^3 x$$

$$= \int \left(\rho \frac{\partial f}{\partial t} - f \boldsymbol{\nabla} \cdot (\rho \boldsymbol{v}) \right) d^3 x$$

$$= \int \left(\rho \frac{\partial f}{\partial t} + \rho \boldsymbol{v} \cdot \boldsymbol{\nabla} f \right) d^3 x - \oint f \rho \boldsymbol{v} \cdot d\boldsymbol{S}$$

$$= \int \rho \frac{df}{dt} d^3 x.$$

Useful rules:

$$\frac{\partial}{\partial t} \int \rho(t, \mathbf{x'}) f(t, \mathbf{x}, \mathbf{x'}) d^3 x' = \int \rho' \left(\frac{\partial f}{\partial t} + \mathbf{v'} \cdot \nabla' f \right) d^3 x',$$

$$\frac{d}{dt} \int \rho(t, \mathbf{x'}) f(t, \mathbf{x}, \mathbf{x'}) d^3 x' = \int \rho' \left(\frac{\partial f}{\partial t} + \mathbf{v} \cdot \nabla f + \mathbf{v'} \cdot \nabla' f \right) d^3 x'$$

$$= \int \rho' \frac{df}{dt} d^3 x'$$

Global conservation laws

$$M := \int \rho(t, \boldsymbol{x}) d^3 x = \text{constant}$$

 $\boldsymbol{P} := \int \rho(t, \boldsymbol{x}) \boldsymbol{v} d^3 x = \text{constant}$

$$E := \mathcal{T}(t) + \Omega(t) + E_{\rm int}(t) = {\rm constant}$$

$$\boldsymbol{J} := \int \rho \boldsymbol{x} \times \boldsymbol{v} \, d^3 x = \text{constant}$$

$$R(t) := \frac{1}{M} \int \rho(t, x) x d^3 x = \frac{P}{M} (t - t_0) + R_0$$

$$d(\epsilon \mathcal{V}) + pd\mathcal{V} = 0$$
$$\nabla \cdot \mathbf{v} = \mathcal{V}^{-1} d\mathcal{V} / dt$$

$$\mathcal{T}(t) := \frac{1}{2} \int \rho v^2 d^3 x$$

$$\Omega(t) := -\frac{1}{2} G \int \frac{\rho \rho'}{|\boldsymbol{x} - \boldsymbol{x'}|} d^3 x' d^3 x,$$

$$E_{\text{int}}(t) := \int \epsilon d^3 x$$

$$\frac{d}{dt} \int \rho \mathbf{v} d^3 x = \int (\rho \nabla U - \nabla p) d^3 x$$

$$= -G \int \int \rho \rho' \frac{\mathbf{x} - \mathbf{x}'}{|\mathbf{x} - \mathbf{x}'|^3} d^3 x d^3 x' - \oint p \mathbf{n} d^2 S$$

$$= 0$$



Spherical and nearly spherical bodies

Spherical symmetry

$$\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial U}{\partial r} \right) = -4\pi G \rho(t, r)$$

$$\frac{\partial U}{\partial r} = -\frac{Gm(t,r)}{r^2} \qquad m(t,r) := \int_0^r 4\pi \rho(t,r') r'^2 dr'$$

$$U(t,r) = \frac{Gm(t,r)}{r} + 4\pi G \int_{r}^{R} \rho(t,r')r' dr'.$$

Outside the body U = GM/r



Spherical and nearly spherical bodies

Non-spherical bodies: the external field |x'| < |x|

Taylor expansion:

$$\frac{1}{|\boldsymbol{x} - \boldsymbol{x'}|} = \frac{1}{r} - x'^{j} \partial_{j} \left(\frac{1}{r}\right) + \frac{1}{2} x'^{j} x'^{k} \partial_{j} \partial_{k} \left(\frac{1}{r}\right) - \cdots$$
$$= \sum_{\ell=0}^{\infty} \frac{(-1)^{\ell}}{\ell!} x'^{L} \partial_{L} \left(\frac{1}{r}\right)$$

Then the Newtonian potential outside the body becomes

$$U_{\text{ext}}(t, \boldsymbol{x}) = G \sum_{\ell=0}^{\infty} \frac{(-1)^{\ell}}{\ell!} I^{\langle L \rangle} \partial_{\langle L \rangle} \left(\frac{1}{r}\right) ,$$
$$I^{\langle L \rangle}(t) := \int \rho(t, \boldsymbol{x'}) x'^{\langle L \rangle} d^3 x'$$

$$x^{L} := x^{i}x^{j} \dots (L \text{ times})$$

$$\partial_{L} := \partial_{i}\partial_{j} \dots (L \text{ times})$$

$$\langle \dots \rangle := \text{symmetric tracefree product}$$



Symmetric tracefree (STF) tensors

 $A^{\langle ijk...
angle}$ Symmetric on all indices, and $\delta_{ij}A^{\langle ijk...
angle}=0$

Example: gradients of 1/r

$$\partial_{j} r^{-1} = -n_{j} r^{-2},$$

$$\partial_{jk} r^{-1} = (3n_{j} n_{k} - \delta_{jk}) r^{-3},$$

$$\partial_{jkn} r^{-1} = -\left[15n_{j} n_{k} n_{n} - 3(n_{j} \delta_{kn} + n_{k} \delta_{jn} + n_{n} \delta_{jk})\right] r^{-4}$$

$$\partial_L r^{-1} = \partial_{\langle L \rangle} r^{-1} = (-1)^{\ell} (2\ell - 1)!! \frac{n_{\langle L \rangle}}{r^{\ell+1}}$$

General formula for not:

$$n^{\langle L \rangle} = \sum_{p=0}^{[\ell/2]} (-1)^p \frac{(2\ell - 2p - 1)!!}{(2\ell - 1)!!} \left[\delta^{2P} n^{L - 2P} + \operatorname{sym}(q) \right]$$

$$q := \ell!/[(\ell-2p)!(2p)!!]$$



Symmetric tracefree (STF) tensors

Link between n'l' and spherical harmonics

$$e_{\langle L \rangle} n^{\langle L \rangle} = \frac{\ell!}{(2\ell - 1)!!} P_{\ell}(\boldsymbol{e} \cdot \boldsymbol{n})$$

$$n^{\langle L \rangle} := \frac{4\pi\ell!}{(2\ell + 1)!!} \sum_{m = -\ell}^{\ell} \mathcal{Y}_{\ell m}^{\langle L \rangle} Y_{\ell m}(\theta, \phi)$$

$$\mathcal{Y}_{10}^{\langle z\rangle} = \sqrt{\frac{3}{4\pi}}, \qquad \mathcal{Y}_{11}^{\langle x\rangle} = -\sqrt{\frac{3}{8\pi}}, \qquad \mathcal{Y}_{11}^{\langle y\rangle} = i\sqrt{\frac{3}{8\pi}},$$

$$\mathcal{Y}_{20}^{\langle xx\rangle} = -\sqrt{\frac{5}{16\pi}}, \qquad \mathcal{Y}_{20}^{\langle yy\rangle} = -\sqrt{\frac{5}{16\pi}}, \qquad \mathcal{Y}_{20}^{\langle zz\rangle} = 2\sqrt{\frac{5}{16\pi}},$$

Average of n'l' over a sphere:

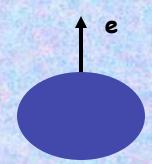
$$\langle \langle n^L \rangle \rangle := \frac{1}{4\pi} \oint n^L d\Omega = \begin{cases} \frac{1}{(\ell+1)!!} \left(\delta^{L/2} + \text{sym}[(\ell-1)!!] \right) & \ell = \text{even} \\ 0 & \ell = \text{odd} \end{cases}$$



Spherical and nearly spherical bodies

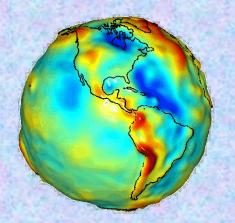
Example: axially symmetric body

$$I_A^{\langle L \rangle} = -m_A R_A^{\ell} (J_{\ell})_A e^{\langle L \rangle}$$



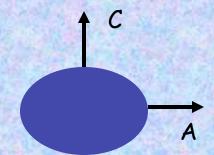
$$J_{\ell} := -\sqrt{\frac{4\pi}{2\ell + 1}} \frac{1}{MR^{\ell}} \int \rho(t, \boldsymbol{x}) r^{\ell} Y_{\ell 0}^{*}(\theta, \phi) d^{3}x$$

$$U_{\mathrm{ext}}(t, \boldsymbol{x}) = \frac{GM}{r} \left[1 - \sum_{\ell=2}^{\infty} J_{\ell} \left(\frac{R}{r} \right)^{\ell} P_{\ell}(\cos \theta) \right]$$



Note that:

$$J_2 = \frac{C - A}{MR^2}$$





Measuring the Earth's Newtonian hair

Gravity Recovery And Climate Experiment (GRACE)



Earth: $j_2 = -4.841 \times 902^4 (5) \times 10^{-4}$

 $j_3 = 9.57 \times 10^{17}$, $\times 10^{-7}$

 $j_4 = 5.89990^{-7}(4). \times 10^{-7}$

.....

 $j_{360,0} = 3.2 (5) \times 10^{-10}$

