

ICTS Dec 2016
Bangalore

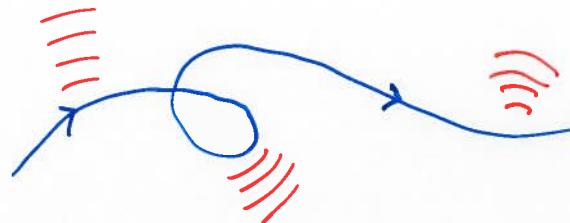
Landau-Lifshitz Equations of Radiative Friction

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1. The setting

- motion of charge coupled to radiation field



- charged particle charge e , mass m , q, p small size
- Maxwell field
 - dynamic F
 - external F^{ex}
- classical $\hbar = 0$
- temperature 0

↷ friction \ll effective hamiltonian motion

H.S. Dynamics of charged particles... , CUP 2004

Kunze, H.S. Post-Coulombian ... 2001 $v/c \ll 1$

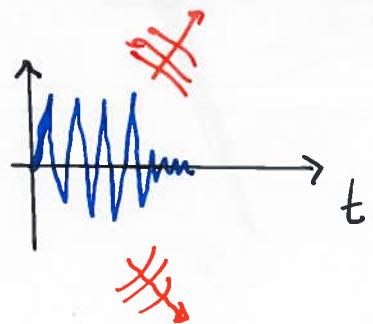
Komech, Imaikin, Kopylova, H.S. 1998 - now

$F^{ex} = 0$, asymptotic velocity
scattering theory

⇒ ultra strong laser sources

⇒ quantitative experimental confirmation

|||||
•
pulse



compare: scattered light
frictionless \Leftrightarrow radiative friction
theory

2. Effective equations of motion

Abraham 1903, von Laue 1909

world line $x(\tau)$

$$\underbrace{m_0 \ddot{x}}_{\text{model-dependent}} = \frac{e}{c} \vec{F}^{\text{ex}} \cdot \dot{\vec{x}} + \frac{e^2}{6\pi c^3} \left(\ddot{\vec{x}} - \frac{1}{c^2} (\vec{x} \cdot \ddot{\vec{x}}) \vec{x} \right)$$

\sim
small

universal

Maxwell linear, linear coupling \Rightarrow explicit memory equation

(nonlinear)

Taylor expansion

Dirac 1938

run away solutions

"physical solutions" are singled out by

$$\lim_{t \rightarrow \infty} \dot{v}(t) = 0$$

3. Singular perturbation theory

W.S. 1998

highest derivative with small parameter

Example

$$\dot{x} = f(x, y)$$

$$\varepsilon \dot{y} = y - h(x) \quad \varepsilon \ll 1, \quad x, y \in \mathbb{R}$$

$$\varepsilon = 0 \quad y = h(x) \quad \leftarrow \text{constrained motion}$$

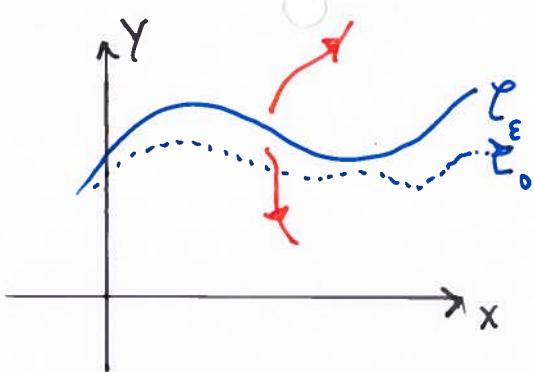
$$\Rightarrow \dot{x} = f(x, h(x))$$

$$\varepsilon \text{ small:} \quad \varepsilon \dot{y} = y - h(x_0) \quad \text{run away} \quad y(t) = (y_0 - h(x_0)) e^{t/\varepsilon} + h(x_0)$$

|| manifold $C_0 = \{y = h(x)\}$ is deformed to $C_\varepsilon = \{y = h_\varepsilon(x)\}$ ||

\uparrow
locally smooth

$\Rightarrow C_\varepsilon$ can be complicated



on E_ϵ

$$\dot{x} = \underbrace{f(x, h(x))}_{\text{"hamiltonian"}^{\sim}} + \varepsilon \underbrace{\partial_y f(x, h(x)) h'(x)}_{\text{"friction"}^{\sim}} f(x, h(x))$$

apply to ALD

$$m_e \ddot{x} = \frac{e}{c} \vec{F}^{ex} \cdot \dot{x} + \frac{e^2}{6\pi c^3} \left(\left(\frac{e}{mc} \right)^2 \vec{F}^{ex} \cdot \vec{F}^{ex} \cdot x + \frac{e}{mc} \dot{x} \cdot \nabla \vec{F}^{ex} \cdot \dot{x} - \left(\frac{e}{mc} \right)^2 (\vec{F}^{ex} \cdot \vec{F}^{ex}) \dot{x} \right)$$

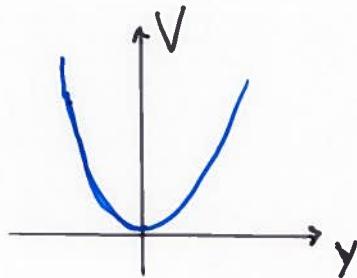
agrees with Landau+Lifshitz, Classical Theory of Fields, all editions ≈ 1950

4. Examples

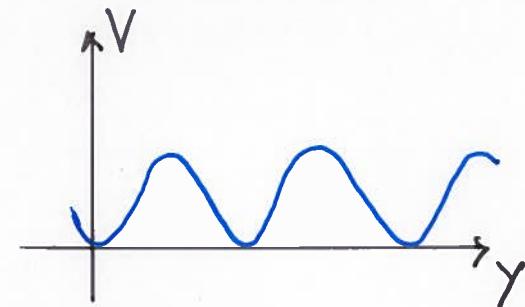
- dimension 1 , $B^{ex} = 0$, $E^{ex} = -\nabla V$

$$m \ddot{y} = -V'(y) - \frac{e^2}{6\pi c^3} \frac{1}{m} V''(y) \dot{y}$$

friction



+ anti friction



- Penning trap
- $e\phi(x) = \frac{1}{2}m\omega_z^2 \left(-\frac{1}{2}x_1^2 - \frac{1}{2}x_2^2 + x_3^2 \right)$
- uniform magnetic field \vec{B}
- ultra-relativistic
- numerical simulations

5. Microscopic theory

Abraham model

- rigid charge distribution

$$\epsilon \varphi(x) \quad \text{space scale } R$$

$$\text{time scale } R/c$$

Maxwell

$$\partial_t B = -\nabla \times E$$

$$\operatorname{div} B = 0$$

$$\rho = \epsilon \varphi(x - q(t))$$

$$\partial_t E = \nabla \times B - j$$

$$\operatorname{div} E = \rho$$

$$j = \dot{q}(t) \epsilon \varphi(x - q(t))$$

Lorentz force

$$m_0 \ddot{q} = e \int dx \varphi(x - q) \left(E(x, t) + \dot{q} \wedge B(x, t) + E_{ex}(x, t) + \dot{q} \wedge B_{ex}(x, t) \right)$$

bare

dynamic

external

Dirac 1938

point charge limit

$$\varphi(x) \sim R^{-3} \varphi(x/R) \quad R \rightarrow 0$$

→ $(m_0 + \frac{e^2}{6\pi c^2 R}) \ddot{q} = \text{forces}$

$m_0 + \frac{e^2}{6\pi c^2 R}$ fixe $m_0 \rightarrow -\infty$ motion is unstable
runaway

HERE external fields vary slowly on scale $R, R/c$

electron $R = 10^{-14} \text{ m}, R/c = 10^{-23} \text{ sec}$

φ fixed, $m_0 > 0$ stable motion

modified energy-momentum

initial conditions $q, \dot{q} = v, E, B$ adjusted local Coulomb

TRUE SOLUTION

$$q_\varepsilon(t) \quad v_\varepsilon(t)$$

ε parameter for slow variation

$$E_{ex}(\varepsilon x, \varepsilon t), B_{ex}(\varepsilon x, \varepsilon t)$$

$$q_\varepsilon(t) \approx \varepsilon^{-1} \tau(\varepsilon t)$$

$$v_\varepsilon(t) \approx u(\varepsilon t) + \Theta(1)$$

a priori bounds

rescale $t = \varepsilon^{-1} \tau + \Theta(1)$

to order ε^0 : effective hamiltonian $E(p)$

to order ε^1 : friction error bound ε^2

$\| \text{initial slip} \|$

6. Sommerfeld - Page

$|v| \ll 1$, linearized memory term

$$g(x) = \frac{1}{4\pi R^2} \delta(|x| - R)$$

$E^{ex} = 0$, $B^{ex} = (0, 0, B_0)$ in plane motion

$$\Rightarrow m_0 \ddot{v} = e B_0 v^\perp + \frac{e^2}{12\pi R^2} (v(\cdot - 2R) - v) \quad (v_1, v_2)^\perp = (-v_2, v_1)$$

delay

gyration frequency $\omega = \frac{e B_0}{m_0}$, delay $\tau = \frac{2R}{c}$, friction $\alpha = \frac{e^2}{3\pi m_0 \tau^2}$

$$\approx \ddot{v} = \omega v^\perp + \alpha(v(\cdot - \tau) - v)$$

given

electron, $B_0 = 10$ Tesla, $R = 10^{-13}$ cm

$\alpha\tau = 10^{-5}$

$\omega\tau = 10^{-8}$

10 cm $\rightarrow 1\mu\text{m}$

10^{14} revolutions, 1 sec

$$v(t) = u(t), 0 \leq t \leq \tau$$

Taylor expansion in \mathbb{R}

$$(m_0 + \frac{e^2}{6\pi c^2 R}) \dot{w} = \frac{eB_0}{c} w^\perp + \frac{e^2}{6\pi c^3} \ddot{w}$$

Dirac: $R \rightarrow 0$ $m_{\text{eff}} = m_0 + \frac{e^2}{6\pi c^2 R} > 0$

limit has runaway, except for constrained initial conditions

slow variation (small B_0) time $\varepsilon^{-1} t$

$$\varepsilon \frac{d}{dt} v(t) = \varepsilon \omega v(t)^\perp + \alpha (v(t-\varepsilon\tau) - v(t))$$

$$\Leftrightarrow (1+\alpha\tau) \frac{d}{dt} v(t) = \omega v(t)^\perp + \frac{1}{2} \alpha \tau^2 \varepsilon \frac{d^2}{dt^2} v(t)$$

comparison dynamics

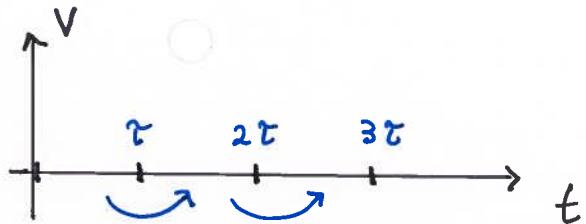
center manifold

LL

$$\boxed{(1+\alpha\tau)\dot{w} = \omega w^\perp - \frac{1}{2} \varepsilon \alpha \left(\frac{\omega\tau}{1+\omega\tau}\right)^2 w}$$

solution map

linear



spectral analysis

initial slip , $B_0 = 0$, $v(t) \rightarrow \bar{v}$ exponentially fast

comparison dynamics $w(t)$ with $w(0) = \bar{v}$, $\epsilon = 1$,



$$|v(t) - w(t)| \leq O((\omega\tau)^2) \quad \text{for } t/\tau \gg \log(\omega\tau)^2$$

\approx LL units $|v(t) - w_\epsilon(t)| \leq c_0 \epsilon^2$ uniform in t .

Conclusions

- radiative friction
 - Landau-Lifshitz equations
 - 2nd order in t
 - stable
 - simple numerics
- microscopic model
 - smeared charge
 - slow variation of external fields
- Sommerfeld-Page ✓
 - Abraham model
 - error bounds too weak