

A New Perspective on Holographic Entanglement

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1 How should one think about the minimal surface?

In semiclassical gravity, surface areas are related to entropies

Bekenstein-Hawking [74]:

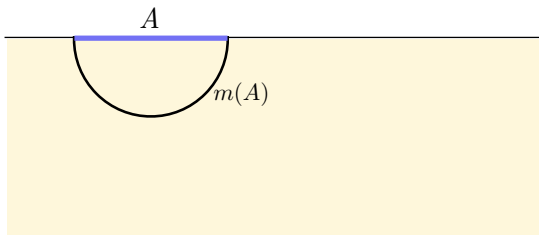
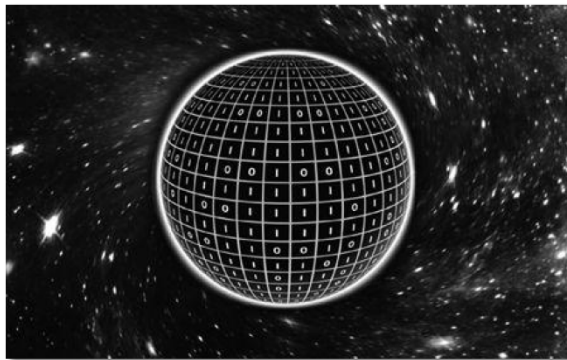
For black hole,

$$S = \frac{1}{4G_N} \text{area}(\text{horizon})$$

Why?

Possible answer:

Microstate bits “live” on horizon, 1 bit / 4 Planck areas



Ryu-Takayanagi [06]: For region in holographic field theory (classical Einstein gravity, static state)

$$S(A) = \frac{1}{4G_N} \text{area}(m(A))$$

$m(A)$ = bulk minimal surface homologous to A

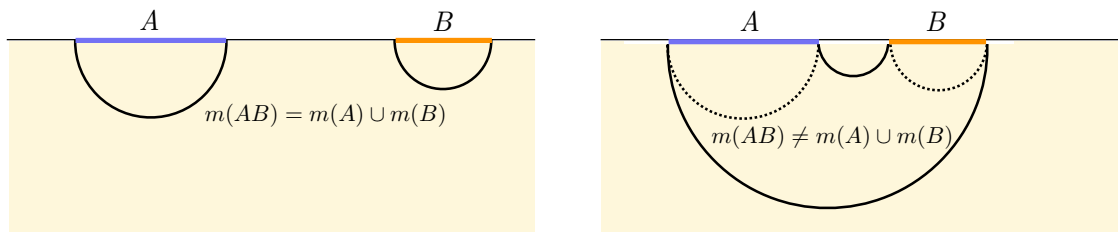
Do microstate bits of A “live” on $m(A)$?

Unlike horizon, $m(A)$ is not a special place; by choosing A , we can put $m(A)$ almost anywhere

Puzzles:

- Under continuous changes in boundary region, minimal surface can jump

Example: Union of separated regions A, B



- Information-theoretic quantities are given by differences of areas of surfaces passing through different parts of bulk:

Conditional entropy: $H(A|B) = S(AB) - S(B)$

Mutual information: $I(A : B) = S(A) + S(B) - S(AB)$

Conditional mutual information: $I(A : B|C) = S(AB) + S(BC) - S(ABC) - S(C)$

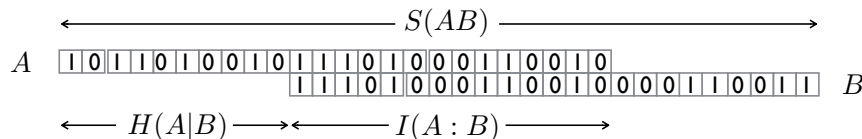
$$H(A|B) = S(AB) - S(B)$$

$$I(A : B) = S(A) + S(B) - S(AB)$$

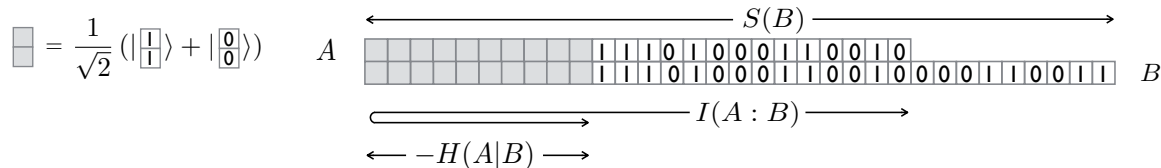
Information-theoretic meaning (heuristically):

Classical: $H(A|B) = \# \text{ of (independent) bits belonging purely to } A$

$I(A : B) = \# \text{ shared with } B$



Quantum: Entangled (Bell) pair contributes 2 to $I(A : B)$, -1 to $H(A|B)$; can lead to $H(A|B) < 0$



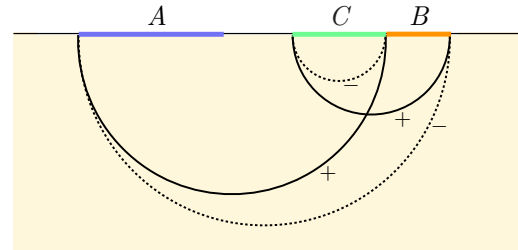
$I(A : B|C) = S(AB) + S(BC) - S(ABC) - S(C) = \text{correlation between } A \text{ \& } B, \text{ conditioned on } C$

What do differences between areas of surfaces, passing through different parts of bulk, have to do with these measures of information?

- RT obeys strong subadditivity [Headrick-Takayanagi '07]

$$I(A : BC) \geq I(A : C)$$

What does proof (by cutting & gluing minimal surfaces) have to do with information-theoretic meaning of SSA (monotonicity of correlations)?



To try to answer these questions, I will present a new formulation of RT

- Does not refer to minimal surfaces (demoted to a calculational device)
- Suggests a new way to think about the holographic principle & about the connection between spacetime geometry and information

2 Reformulation of RT

Consider a Riemannian manifold with boundary

Flow: vector field v obeying $\nabla \cdot v = 0$, $|v| \leq 1$

Think of flow as a set of oriented threads (flow lines) beginning & ending on boundary,
transverse density = $|v| \leq 1$

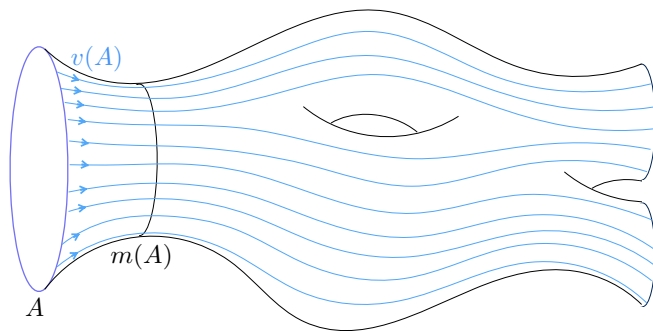
Let A be a subset of boundary

Max flow-min cut theorem (originally on graphs; Riemannian version: [Federer '74, Strang '83, Nozawa '90]):

$$\max_v \int_A v = \min_{m \sim A} \text{area}(m)$$

Note:

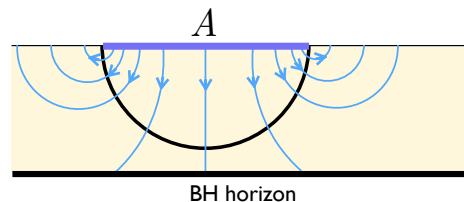
- Max flow is highly non-unique
(except on $m(A)$, where $v = \text{unit normal}$)
Let $v(A)$ denote *any* max flow
- Finding max flow is a convex optimization problem



RT version 2.0:

$$S(A) = \max_v \int_A v \quad (4G_N = 1)$$

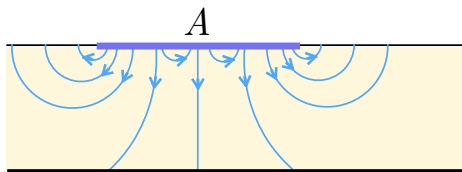
$$= \max \# \text{ of threads beginning on } A$$



Threads can end on A^c or horizon

Each thread has cross section of 4 Planck areas & is identified with 1 (independent) bit of A

Automatically incorporates homology & global minimization conditions of RT



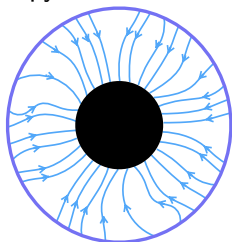
Threads are “floppy”: lots of freedom to move them around in bulk & move where they attach to A

Also lots of room near boundary to add extra threads that begin & end on A (don't contribute to $S(A)$)

Role of minimal surface: bottleneck, where threads are maximally packed, hence counted by area

Holographic principle: entropy \propto area because bits are carried by one-dimensional objects

Bekenstein-Hawking:



3 Threads & information

Now we address conceptual puzzles with RT raised before

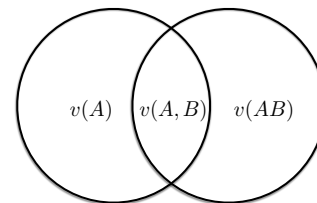
First: even when $m(A)$ jumps, $v(A)$ changes continuously with A

Next, consider two regions A, B

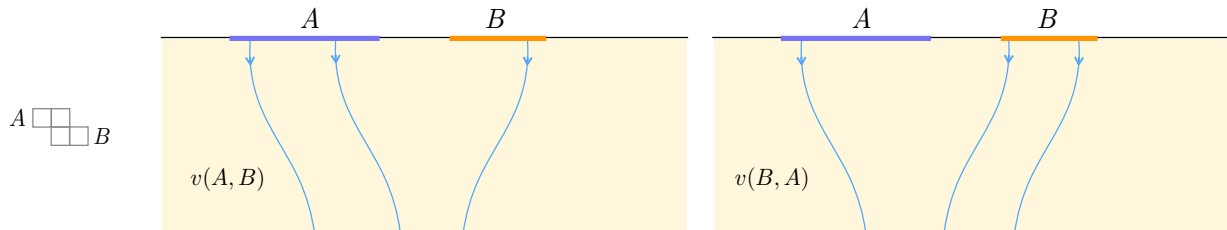
We can maximize flux through A *or* B , not in general both

But we *can* always maximize through A *and* AB (nesting property)

Call such a flow $v(A, B)$



Example 1: $S(A) = S(B) = 2, S(AB) = 3 \Rightarrow I(A : B) = 1, H(A|B) = 1$



Lesson 1:

- Threads that are stuck on A represent bits unique to A
- Threads that can be moved between A & B represent correlated pairs of bits

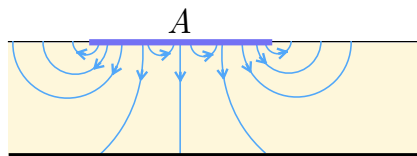
Example 2: $S(A) = S(B) = 2$, $S(AB) = 1 \Rightarrow I(A : B) = 3$, $H(A|B) = -1 \Rightarrow$ entanglement!

One thread leaving A *must* go to B , and vice versa



Lesson 2:

- Threads that connect A & B (switching orientation) represent entangled pairs of bits



Apply lessons to single region:

- freedom to move beginning points around reflects correlations within A
- freedom to add threads that begin & end on A reflects entanglement within A

In equations:

Conditional entropy:

$$\begin{aligned} H(A|B) &= S(AB) - S(B) \\ &= \int_{AB} v(AB) - \int_B v(B) \\ &= \int_{AB} v(B, A) - \int_B v(B, A) \\ &= \int_A v(B, A) \\ &= \text{min flux on } A \text{ (maximizing on } AB) \end{aligned}$$

Mutual information:

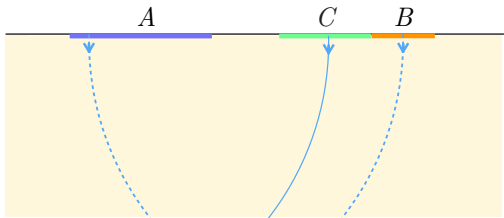
$$\begin{aligned} I(A : B) &= S(A) - H(A|B) \\ &= \int_A v(A, B) - \int_A v(B, A) \\ &= \text{max} - \text{min flux on } A \text{ (maximizing on } AB) \\ &= \text{flux movable between } A \text{ and } B \text{ (maximizing on } AB) \end{aligned}$$

Max flow can be defined even when flux is infinite: flow that cannot be augmented

Regulator-free definition of mutual information:

$$I(A : B) = \int_A (v(A, B) - v(B, A))$$

Conditional mutual information:



$$\begin{aligned}
 I(A : B|C) &= H(A|C) - H(A|BC) \\
 &= \int_A v(C, A, B) - \int_A v(C, B, A) \\
 &= \text{max} - \text{min flux on } A \text{ (maximizing on } C \text{ \& } ABC) \\
 &= \text{flux movable between } A \text{ \& } B \text{ (maximizing on } C \text{ \& } ABC) \\
 &= (\text{flux movable between } A \text{ \& } BC) - (\text{movable between } A \text{ \& } C) \\
 &= I(A : BC) - I(A : C)
 \end{aligned}$$

Strong subadditivity ($I(A : B|C) \geq 0$) is clear

In each case, clear connection to information-theoretic meaning of quantity/property

Open problem: Use flows to prove “monogamy of mutual information” property of holographic EEs

[Hayden-Headrick-Maloney '12]:

$$I(A : BC) \geq I(A : B) + I(A : C)$$

(and generalizations to more parties [Bao et al '15])

Flow-based proof may illuminate the information-theoretic meaning of these inequalities

4 Extensions

4.1 Emergent geometry

Metric \longrightarrow Set of thread configurations allowed by $\nabla \cdot v = 0$, $|v| \leq 1$

Set of thread configurations \longrightarrow metric:

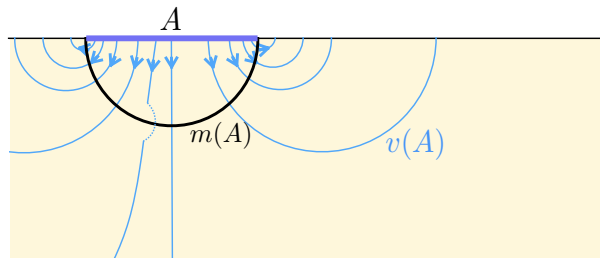
Given set $\{w\}$ of closed $(d-1)$ -forms, find $g_{\mu\nu}$ with pointwise smallest det such that $|w| \leq 1 \ \forall w$

4.2 Quantum corrections

Faulkner-Lewkowycz-Maldacena [13]:

Quantum (order G_N^0) correction to RT is from entanglement of bulk fields

May be reproduced by allowing threads to jump from one point to another (or tunnel through microscopic wormholes, à la ER = EPR [Maldacena-Susskind '13])



4.3 Covariant bit threads

With Veronika Hubeny (to appear)

Hubeny-Rangamani-Takayanagi [07] covariant entanglement entropy formula:

$$S(A) = \text{area}(m(A))$$

$m(A)$ = minimal extremal surface homologous to A

Need generalization of max flow-min cut theorem to Lorentzian setting

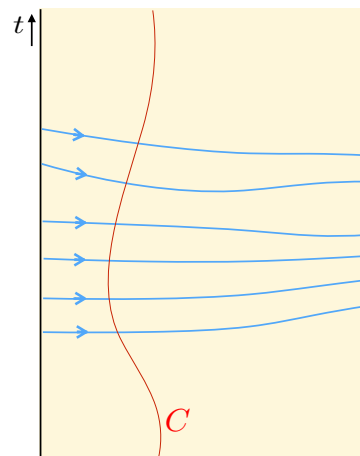
Define a *flow* as a vector field v (in full Lorentzian spacetime) obeying

- $\nabla \cdot v = 0$
- no flux into or out of singularities
- integrated norm bound: \forall timelike curve C ,

$$\int_C ds |v_\perp| \leq 1 \quad (v_\perp = \text{projection of } v \text{ orthogonal to } C)$$

Any observer counts, over her lifetime, total of at most 1 thread
/ 4 Planck areas

(Can be expressed as local constraint)



Theorem (assuming NEC, using results of Wall [12] & Headrick-Hubeny-Lawrence-Rangamani [14]):

$$\max_v \int_{D(A)} v = \text{area}(m(A)) \quad D(A) = \text{boundary causal domain of } A$$

Linearizes problem of finding extremal surface area

HRT version 2.0:

$$S(A) = \max_v \int_{D(A)} v$$

To maximize flux, threads seek out $m(A)$, automatically confining themselves to entanglement wedge

Threads can lie on common Cauchy slice (equivalent to Wall's [12] maximin by standard max flow-min cut) or spread out in time

