

Statistics of Geometric Phase Curvature

Pragya Shukla

Formulation why needed Statistics N = 2 cas

Motivation

N=2 case

N=2 case

General N case

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localized dynamics

general ensemble

curvature distribution

Details of numerical result



Statistics of Geometric Phase Curvature

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(i) J. Phys A, 51, 475101, (2018)
(ii) J. Stat. Phys., Springer Nature, (2019)

Jan 23, 2020

Geometric Curvature



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Details of numerical result

- Geometric phase defined for a closed loop when the Hamiltonian goes around a closed loop $\mathbf{R}(T) = \mathbf{R}(0)$ in parameter space,
- circuit dependent in general
- need for a closed loop usually leads to technical issues
- often better to use "local phase": geometric curvature

$$\gamma_n(T) = i \oint_{\mathbf{R}(0)}^{\mathbf{R}(T)} \langle n, \mathbf{R}(\tau) | \nabla_R | n, \mathbf{R}(\tau) \rangle \, \mathrm{d}\mathbf{R} = \iint \mathbf{C}_n \cdot \mathrm{d}\mathbf{S}$$
G-Phase 2020

Geometric curvature

$$\mathbf{C}_n \equiv \nabla_{\mathbf{R}} \times i \langle n, \mathbf{R} | \nabla_R | n, \mathbf{R} \rangle$$

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 \blacksquare Geometric phase for a loop \rightarrow flux of the Geometric curvature

Curvature is better than phase !



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Details of numerical result Geometric phase always associated with a closed path
 Geometric curvature a local quantity
 provides a local description of the geometric properties of the parametric space.

both gauge-invariant, can act as observables

Geometric curvature: a geometric magnetic field
 Just as a magnetic field can affect the dynamic of an electron,
 curvature directly affects the dynamic of parameters (adiabatic).
 In this sense, curvature is more fundamental quantity than phase.

no closed loop needed for curvature analysis

 curvature has many applications: example: essential in a proper description of thr Bloch electrons which has various effects on transport and thermodynamics properties

 $C_{n}(\mathbf{R}) = \mathrm{Im} \nabla_{R} \langle n, \mathbf{R} | \times \nabla_{R} | n, \mathbf{R} \rangle$

in terms of eigenvalues and eigenfunctions



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$$\mathbf{C_n}(\mathbf{R}) = \mathbf{2} \operatorname{Im} \sum_{\mathbf{m} \neq \mathbf{n}} \frac{\langle \mathbf{n} | \nabla_\mathbf{R} \mathbf{H} | \mathbf{m} \rangle \times \langle \mathbf{m} | \nabla_\mathbf{R} \mathbf{H} | \mathbf{n} \rangle}{(\mathbf{E_n} - \mathbf{E_m})^2}$$

Hamiltonian $H(\mathbf{R})$ in 3-dimensional parameter space $\mathbf{R} = (x, y, z)$

$$\mathbf{C_n} = (\mathbf{C_{nx}}, \mathbf{C_{ny}}, \mathbf{C_{nz}})$$
 (in vector form)

$$\mathbf{C_{nz}(\mathbf{x},\mathbf{y})=2}\,\mathrm{Im}\sum_{\mathbf{m}\neq\mathbf{n}}\frac{\langle\mathbf{n}|\partial_{\mathbf{x}}\mathbf{H}|\mathbf{m}\rangle\langle\mathbf{m}|\partial_{\mathbf{y}}\mathbf{H}|\mathbf{n}\rangle}{(\mathbf{E_n}-\mathbf{E_m})^2}~2020$$

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what is geometric curvature for a complex system?

Curvature of a typical random state:

 $H(x, y) = H_0 + xH_x + yH_y$



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for the state n = 10 of a 20×20 Hamitonian with H_0, H_x, H_y sampled from the GUE.



Role of Complexity



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Details of numerical result

- Lack of detailed knowledge about interactions manifests itself by randomization (partial / full) of various operators of the system.
- Determination of some/ all matrix elements ⇒ within an uncertainty ⇒ matrix elements are at best described by a probability distribution.
- Uncertainty associated with various matrix element can be of different types ⇒ matrix elements can have different distributions.

- Hamiltonian ⇒ a random matrix (some/ all matrix elements randomly distributed)
- Distributions of the eigenfunctions and eigenvalues
- \blacksquare What is the distribution of geometric curvature $\mathbf{P_c}(\mathbf{C})$?

distribution of curvature



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Details of numerical result Complexity leads to sample to sample fluctuations in eigenvalues and eigenfunctions \to fluctuations of geometric curvature

 \blacksquare distribution of curvature components $(\mathbf{C_x},\mathbf{C_y},\mathbf{C_z})$ of an arbitrary eigenstate

$$\mathbf{P}(\mathbf{C}_{\mathbf{x}}, \mathbf{C}_{\mathbf{y}}, \mathbf{C}_{\mathbf{z}}) = \langle \delta(\mathbf{C}_{\mathbf{x}} - \mathbf{C}_{\mathbf{nx}}) \delta(\mathbf{C}_{\mathbf{y}} - \mathbf{C}_{\mathbf{ny}}) \delta(\mathbf{C}_{\mathbf{z}} - \mathbf{C}_{\mathbf{nz}}) \rangle$$

with

$$\mathbf{C_{nz}} = \mathbf{2} \ \mathrm{Im} \sum_{\mathbf{m} \neq \mathbf{n}} \frac{\langle \mathbf{n} | \partial_{\mathbf{x}} \mathbf{H} | \mathbf{m} \rangle \langle \mathbf{m} | \partial_{\mathbf{y}} \mathbf{H} | \mathbf{n} \rangle}{(\mathbf{E_n} - \mathbf{E_m})^2} \textbf{(20)}$$

similarly

 $\mathbf{C_{nx}}, \mathbf{C_{ny}}$

needed: distribution of the eigenvalues and eigenfunctions of H

begin with a simple question



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Details of numerical resul Hamiltonian $H(\mathbf{R})$ in 2-dimensional parameter space $\mathbf{R} = (\mathbf{x}, \mathbf{y})$

For
$$H(x, y) = H_0 + x H_x + y H_y$$

$$\mathbf{C} \equiv \mathbf{C_n}(\mathbf{x}, \mathbf{y}) = 2 \operatorname{Im} \sum_{\mathbf{m} \neq \mathbf{n}} \frac{\langle \mathbf{n} | \mathbf{H_x} | \mathbf{m} \rangle \langle \mathbf{m} | \mathbf{H_y} | \mathbf{n} \rangle}{(\mathbf{E_n} - \mathbf{E_m})^2}$$

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2×2 Hamiltonian



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Details of numerical result \blacksquare only two states with curvature $\mathbf{C_1},\mathbf{C_2}$

$$\mathbf{C_1} = -\mathbf{C_2} = \mathbf{2} \operatorname{Im} \frac{\langle \mathbf{l} | \mathbf{H_x} | \mathbf{2} \rangle \; \langle \mathbf{2} | \mathbf{H_y} | \mathbf{1} \rangle}{(\mathbf{E_1} - \mathbf{E_2})^2} = \frac{-\mathbf{i} (\mathbf{F} - \mathbf{F}^*)}{\mathbf{S}^2}$$

E $_2 - E_1 \equiv S$: spacing between eigenvalues E_1, E_2

- Perturbation H_x, H_y measured in eigenfunction basis of H $F \equiv F_{12} \equiv \langle 1 | H_x | 2 \rangle \langle 2 | H_y | 1 \rangle = F_{21}^*$
- Desired Probability distribution

$$\begin{aligned} \mathbf{P_c}(\mathbf{C}) &= \langle \delta \left[\mathbf{C} - \mathbf{C_1} \right] \rangle \\ &= \frac{1}{2\pi} \int_{-\infty}^{\infty} \mathrm{d} \mathbf{t} \, \exp[\mathbf{i} \mathbf{C} \mathbf{t}] \, \langle \exp\left[-\mathbf{i} \mathbf{C_1} \mathbf{t}\right] \rangle \end{aligned}$$

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 $\langle . \rangle$: ensemble average

2×2 Hamiltonians



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$$\left\langle \exp\left[-i\mathbf{C_{1}t}\right]\right\rangle = \int \exp\left[\frac{\left(\mathbf{F}-\mathbf{F}^{*}\right)}{\mathbf{S}^{2}}\right] \ \mathbf{P}(\mathbf{F},\mathbf{F}^{*},\mathbf{S}) \ \mathrm{d}\mathbf{F} \ \mathrm{d}\mathbf{F}^{*} \ \mathrm{d}\mathbf{S}$$

matrix elements of H_x, H_y, H_0 correlated in eigenfunction basis of H

$$\mathbf{0} = \langle \mathbf{1} | \mathbf{H} | \mathbf{2}
angle = \langle \mathbf{1} | \mathbf{H}_{\mathbf{0}} | \mathbf{2}
angle + \mathbf{x} \langle \mathbf{1} | \mathbf{H}_{\mathbf{x}} | \mathbf{2}
angle + \mathbf{y} \langle \mathbf{1} | \mathbf{H}_{\mathbf{y}} | \mathbf{2}
angle$$

F, F* are correlated -Phase 2020

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is S uncorrelated with F, F*?

 \rightarrow eigenvalues and eigenfunctions of H uncorrelated?

H-matrix in site basis: ergodic limit



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In the basis associated with the space

- $\langle k | \mathbf{H} | l \rangle = \mathbf{H}_{kl}$: Similar Distribution about most probable value
 - : Indicator of determinstic uncertainty

If available information :

 $\langle \mathbf{H}_{kl}^2 \rangle$

$$\langle \mathbf{H}_{kl}^2 \rangle = \sigma^2, \quad \langle \mathbf{H}_{kl} \rangle = \mathbf{0}$$

$$\rho(H) = \exp\left[-\frac{1}{2\sigma^2}\sum_{k \le l} H_{kl}^2\right] = \exp\left[-\frac{1}{2\sigma^2}\operatorname{Tr} H^2\right]$$

Wigner-Dyson Ensembles

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extended eigenstates:

$$\mathbf{H}(\mathbf{x}, \mathbf{y}) = \mathbf{H}_{\mathbf{0}} + \mathbf{x} \ \mathbf{H}_{\mathbf{x}} + \mathbf{y} \ \mathbf{H}_{\mathbf{y}}$$



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what is P(C) when dynamics of the system represented by H is ergodic? eigenfunctions delocalized in basis of interest, H: metallic, chaotic

 ${\boldsymbol{H}}$: represented by Gaussian unitary ensembles

 $\rho(\mathbf{H}) = \mathcal{N} \exp\left[-\mathrm{Tr} \, \mathbf{H}^2\right]$

$$\begin{aligned} \mathbf{P}_{\mathbf{e},\mathbf{u}}(\mathbf{E},\mathbf{U}) &= \mathbf{J}(\mathbf{E},\mathbf{U}|\mathbf{H}) \ \rho(\mathbf{H}) \\ &= |\mathbf{E}_1 - \mathbf{E}_2|^2 \exp\left[-(\mathbf{E}_1^2 + \mathbf{E}_2^2)\right] \ \delta(\mathbf{U}^{\dagger}\mathbf{U} - \mathbf{I}) \end{aligned}$$

eigenvalues and eigenfunctions of H not correlated 2020

 \longrightarrow lack of correlations between $S=|E_1-E_2|$ and F

$$\mathbf{F} = \mathbf{H_{x;12}} \ \mathbf{H_{y;21}} = \sum_{k,l} \mathbf{U_{k1}^*} \ \mathbf{U_{l2}} \ \mathbf{U_{j2}^*} \ \mathbf{U_{r1}} \ \mathbf{H_{x;kl}} \ \mathbf{H_{y;jr}}$$

 $\mathbf{P}(\mathbf{F},\mathbf{F}^*,\mathbf{S}) = \mathbf{P}_{\mathbf{f}}(\mathbf{F},\mathbf{F}^*) \ \mathbf{P}_{\mathbf{s}}(\mathbf{S}) \quad \text{for all } \mathbf{F} \in \mathbf{F} \ \text{for all } \mathbf{F} \in \mathbf{F} \ \text{for all } \mathbf{F} \in \mathbf{F} \in \mathbf{F} \ \text{for all } \mathbf{F} \in \mathbf{F} \in \mathbf{F} \ \text{for all } \mathbf{F} \ \text{for all } \mathbf{F} \in \mathbf{F} \ \text{for all } \mathbf{F} \in \mathbf{F} \ \text{for all } \mathbf{F} \in \mathbf{F} \ \text{for all } \mathbf{F} \ \text{for all } \mathbf{F} \ \text{for all } \mathbf{F} \in \mathbf{F} \ \text{for all } \mathbf{F$

2×2 Hamiltonians



$$\mathbf{P_f}(\mathbf{F_x},\mathbf{F_y}) = \mathcal{N} \exp\left[-\frac{1}{2(1-K^2)}\left(\frac{\mathbf{F_x^2}}{\mathbf{V_x}} - \frac{2KF_xF_y}{\sqrt{\mathbf{V_x}\mathbf{V_y}}} + \frac{\mathbf{F_y^2}}{\mathbf{V_y}}\right)\right]$$

 $\label{eq:Vx} \begin{array}{l} V_x, V_y \text{: variances of } F_x, F_y, \text{ variances of real and imaginary parts of } F \equiv F_{12} \\ \hline \\ \text{normalization } \mathcal{N} = \frac{1}{2\pi \sqrt{V_x V_y (1-K^2)}} \\ \begin{array}{l} \text{Phase 2020} \end{array} \end{array}$

$$\begin{split} \langle \exp\left[-i\mathbf{C_1t}\right] \rangle &= \int \exp\left[\frac{(\mathbf{F}-\mathbf{F}^*)}{\mathbf{S}^2}\right] \, \mathbf{P}(\mathbf{F},\mathbf{F}^*) \, \mathbf{P_s}(\mathbf{S}) \, \mathrm{d}\mathbf{F} \, \mathrm{d}\mathbf{F}^* \, \mathrm{d}\mathbf{S} \\ &= \int \frac{\mathbf{S}^4}{\mathbf{S}^4 + 4t^2 \mathbf{V_x} \mathbf{V_y} (1-\mathbf{K}^2)} \, \mathbf{P_s}(\mathbf{S}) \, \mathrm{d}\mathbf{S} \end{split}$$



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$$\mathbf{P_c}(\mathbf{C}) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \mathrm{d}\mathbf{t} \, \exp[\mathbf{i}\mathbf{C}\mathbf{t}] \, \langle \exp\left[-\mathbf{i}\mathbf{C_1t}\right] \rangle$$

• H_0, H_x, H_y : $GUE \Rightarrow H GUE$

nearest neighbor spacing distribution for GUE

$$P_{s}(S) = \frac{32}{\pi^{2} \langle S \rangle^{3}} S^{2} \exp \left[-\frac{4S^{2}}{\pi \langle S \rangle^{2}} \right]$$

$$G - Phase 2020$$

$$\Rightarrow P_{c}(C) = \frac{3}{4A} \left(1 + \frac{|C|}{A} \right)^{-5/2}$$

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Rescaling by
$$A = \frac{8\sqrt{V_x V_y (1-K^2)}}{\pi \langle S \rangle^2} = \frac{1}{4(1+x^2+y^2)^{5/2}} \rightarrow$$
 universal form

Case N = 2: theory with numerics



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$N \times N$ Hamiltonians



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• (N-1) states contributing to curvature C_n

$$\begin{array}{lll} C_n & = & 2 \ \mathrm{Im} \sum_{m \neq n} \frac{\langle n | H_x | m \rangle \, \langle m | H_y | n \rangle}{(E_n - E_m)^2} \\ \\ & \approx & 2 \ \mathrm{Im} \left[\frac{\langle n | H_x | n + 1 \rangle \, \langle n + 1 | H_y | n \rangle}{(E_n - E_{n+1})^2} + \frac{\langle n | H_x | n - 1 \rangle \, \langle n - 1 | H_y | n \rangle}{(E_n - E_{n-1})^2} \right] \end{array}$$

 $(n|H_x|n+1) \equiv u_{x+} + iv_{x+}, \quad \langle n+1|H_y|n \rangle \equiv u_{y+} + iv_{y+}, \quad E_{n+1} - E_n \equiv S_+$ **G=Phase** 2020

Desired Probability distribution

$$\begin{aligned} \mathbf{P_c}(\mathbf{C}) &= \langle \delta \left[\mathbf{C} - \mathbf{C_n} \right] \rangle \\ &= \frac{1}{2\pi} \int_{-\infty}^{\infty} \mathrm{d} \mathbf{t} \, \exp[\mathbf{i} \, \mathbf{C} \mathbf{t}] \, \langle \exp\left[-\mathbf{i} \, \mathbf{C_n} \mathbf{t}\right] \rangle \end{aligned}$$

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$P_c(c)$: full form: $\mathbf{P}_{\mathbf{C}}(\mathbf{C}) = \frac{1}{\mathbf{A}} \mathbf{P}_{\mathbf{c}} \left(\frac{\mathbf{C}}{\mathbf{A}} \right)$

$$P_{c}(c) = \frac{27\sqrt{3}}{\left(1+4c^{2}\right)^{5}} \left(\frac{6f_{1}(|c|)\tan^{-1}\left(\sqrt{3+8|c|}\right)}{\pi\left(3+2c^{2}\right)^{5}\left(3+8|c|\right)^{9/2}} + \frac{3f_{2}(|c|)\log\left(1+2|c|\right)}{\pi\left(3+2c^{2}\right)^{5}} + \frac{f_{3}(|c|)}{2\pi\left(3+2c^{2}\right)^{4}\left(3+8|c|\right)^{4}} + 3\left(1-40c^{2}+80c^{4}\right) \right).$$

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$$f_{1}(c) = -33777 - 517914c - 2031912c^{2} + 8531280c^{3} + 106694400c^{4} + 420839296c^{5} + 818860032c^{6} + 596420096c^{7} - 755948800c^{8} - 2317539840c^{9} - 2585458688c^{10} - 1558491136c^{11} - 472834048c^{12} + 4341760c^{13} + 75366400c^{14} + 46137344c^{15} + 12320768c^{16} + 1572864c^{17}, f_{2}(c) = 1 + 2430c + 8120c^{2} - 8640c^{3} - 57440c^{4} - 76224c^{5} - 30720c^{6} + 15360c^{7} + 21760c^{8} + 7680c^{9} + 2048c^{10}, f_{3}(c) = (-41553 - 509328c - 1668384c^{2} + 3797712c^{3} + 44854416c^{4} + 163496512c^{5} + 381128320c^{6} + 630179840c^{7} + 631230720c^{8} + 166594560c^{9} - 372436992c^{1} - 457797632c^{11} - 216436736c^{12} - 44941312c^{13} + 6979584c^{14} + 1179648c^{14}.$$

Case N = 40: theory with numerics



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■ slight deviation from theory near *C* = 0: effect of neglecting non-neighbor levels

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localized/ partially localized eigenstates



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what happens when wave-dynamics is not ergodic?

H: represented by a system-dependent random matrix ensemble

how the distribution is sensitive to behavior of $\partial_x H, \partial_y H$?

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 $\partial_{\mathbf{x}} \mathbf{H}, \partial_{\mathbf{y}} \mathbf{H}:$ ensembles different from \mathbf{H}

H-matrix in site basis: $\mathbf{H} = \sum_{i,j} c_i \mathbf{c}_i^+ \cdot \mathbf{c}_i + \sum_{i,j} \mathbf{V}_{ij} \mathbf{c}_i^+ \cdot \mathbf{c}_j$



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Details of numerical result Localized Wave Dynamics:





In the basis associated with the space

- 1. $H_{kl} \neq 0$ if k = l or $k = l \pm L^{d-1}$
- a. H_{kk} : Randomly Distributed

$$\rho_{kk} = e^{-H_{kk}^2/2v_{kk}^2}$$

b. Nearest Neighbor interactions may be random or non random

If non-random

$$\rho_{kl} = \delta(\mathbf{H}_{kl} - \mathbf{b}_{kl})$$
$$\rho_{kl} = e^{-(\mathbf{H}_{kl} - \mathbf{b}_{kl})^2/2v_k^2}$$

Hopping Strength $b_{kl} = 0$ if $k \neq 1$ or $k \neq 1 \pm L^{d-1}$

system-dependent random matrix ensembles



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Details of numerical result Complex systems represented by multi-parametric Gaussian ensemble

$$\rho(\mathbf{H}, \mathbf{v}, \mathbf{b}) = \mathbf{C} \mathrm{exp} \left[-\sum_{\mathbf{k} \leq \mathbf{l}} \sum_{\mathbf{s} = 1}^{2} \frac{1}{2 \mathbf{v}_{\mathbf{k} \mathbf{l}; \mathbf{s}}} (\mathbf{H}_{\mathbf{k} \mathbf{l}; \mathbf{s}} - \mathbf{b}_{\mathbf{k} \mathbf{l}; \mathbf{s}})^2 \right]$$

System information contained in parameter-sets ${\bf v}, {\bf b}$: $v_{kl;s}^2(x,y) = \langle H_{kl;s}(x,y)^2 \rangle - \langle H_{kl;s}(x,y) \rangle^2, \qquad b_{kl;s}(x,y) = \langle H_{kl;s}(x,y) \rangle$

$$\mathbf{P_{e,u}(E,U)} = \mathbf{J}(\mathbf{H}|\mathbf{E},\mathbf{U}) \ \rho(\mathbf{H}) = \prod_{\mathbf{m}\neq\mathbf{n}} |\mathbf{E_m} - \mathbf{E_n}|^2 \ \rho(\mathbf{E},\mathbf{U})$$

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eigenvalues and eigenfunctions of H now correlated !

curvature distribution for generic case



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$$\begin{split} \mathbf{C_b} &= \mathbf{2} \operatorname{Im} \sum_{\mathbf{a} \neq \mathbf{b}} \frac{\langle \mathbf{b} | \partial_\mathbf{x} \mathbf{H} | \mathbf{a} \rangle \langle \mathbf{a} | \partial_\mathbf{y} \mathbf{H} | \mathbf{b} \rangle}{(\mathbf{E_a} - \mathbf{E_b})^2} = \mathbf{2} \operatorname{Im} \sum_{\mathbf{a} \neq \mathbf{b}} \frac{\mathbf{F_{ab}}}{(\mathbf{E_a} - \mathbf{E_b})^2} \\ & \\ \mathbf{F_{ab}} &= (\partial_\mathbf{x} \mathbf{H})_{\mathbf{a} \mathbf{b}} \; \partial_\mathbf{y} \mathbf{H}_{\mathbf{b} \mathbf{a}} = \sum_{j, r, k, l} \mathbf{U_{ka}^*} \mathbf{U_{lb}} \mathbf{U_{jb}^*} \mathbf{U_{ra}} (\partial_\mathbf{x} \mathbf{H})_{kl} \; \partial_\mathbf{y} \mathbf{H_{jr}} \end{split}$$

$$\mathbf{P_{c}(C)} = \int \delta\left(\mathbf{C} - \mathbf{C_{b}}\right) \ \mathbf{P_{e,u}(U, U^{*}, E)} \ \rho_{\mathbf{x}}(\partial_{\mathbf{x}}\mathbf{H}) \ \rho_{\mathbf{y}}(\partial_{\mathbf{y}}\mathbf{H}) \ D\Gamma$$
G-Phase 2020

Integration measure $D\Gamma \equiv DU DU^* DE D(\partial_x H) D(\partial_y H)$

• $E \equiv \{E_1, \dots, E_N\}$ and $F_b \equiv \{F_{1b}, \dots, F_{Nb}\}$ correlated

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numerics: three different ensembles



perturbation ensemble has any role?



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Details of numerical result

AE, wf=256







BE,wf=256

0.008

0.008

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comparison: Anderson, Brownian, GUE ensembles



Statistics of Geometric Phase Curvature

Pragya Shuk

why needed Statistics

Motivation

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Details of numerical result

without rescaling



after rescaling





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Single parametric diffusion of ${}_{_{\rho\,\infty\,e}}-\sum\frac{(\mathbf{H}_{\mathbf{k}|\mathbf{s}}-\mathbf{b}_{\mathbf{k}|\mathbf{s}})^2}{^{2\mathbf{v}_{\mathbf{k}|\mathbf{s}}}}$



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Details of numerical result Changing complexity i.e. v, b leads to evolution of $\rho(\mathbf{H})$

possible to define a function Y such that (with $g_{kl} = 1 + \delta_{kl}$)

$$\frac{\partial \rho}{\partial \mathbf{Y}} = \sum_{\mathbf{k}, \mathbf{l}; \mathbf{s}} \frac{\partial}{\partial \mathbf{H}_{\mathbf{k} \mathbf{l}; \mathbf{s}}} \left[\frac{\mathbf{g}_{\mathbf{k} \mathbf{l}}}{2} \frac{\partial}{\partial \mathbf{H}_{\mathbf{k} \mathbf{l}; \mathbf{s}}} + \mathbf{H}_{\mathbf{k} \mathbf{l}; \mathbf{s}} \right] \rho$$

where

$$\mathbf{P} = -\frac{1}{N(N+1)} \ln \left[\prod_{\mathbf{k} \le \mathbf{l}} \prod_{\mathbf{s} = 1}^{2} |\mathbf{g}_{\mathbf{k}\mathbf{l}} - 2\mathbf{v}_{\mathbf{k}\mathbf{l};\mathbf{s}}| \ |\mathbf{b}_{\mathbf{k}\mathbf{l};\mathbf{s}}|^2 \right]$$

multi-parametric diffusion of $\rho(H)$ can be reduced to a single parameter Y= average distribution parameter, a measure of average uncertainty of system

$$\bullet \text{ moments } \quad \langle \delta \mathbf{H_{kl;s}} \rangle = -\mathbf{H_{kl;s}} \ \delta \mathbf{Y}, \quad \langle |\delta \mathbf{H_{kl;s}}|^2 \rangle = \mathbf{g_{kl}} \ \delta \mathbf{Y}$$

(P.S.: Phys. Rev. (2001), J. Phys. C (2005), J. Phys. A.(2008) 0 9 9

2nd order perturbation theory



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$$\delta \mathbf{e_n} = \delta \mathbf{H_{nn}} + \sum_{m \neq n} \frac{|\delta \mathbf{H_{mn}}|^2}{\mathbf{e_n} - \mathbf{e_m}} + \mathbf{o}((\delta \mathbf{H_{mn}})^3)$$

$$\delta \mathbf{U_{jn}} = \sum_{\mathbf{m} \neq \mathbf{n}} \left(\frac{\delta \mathbf{H_{mn}} \mathbf{U_{jm}}}{\mathbf{e_n} - \mathbf{e_m}} + \sum_{\mathbf{m}'}^{\mathbf{N}} \frac{\delta \mathbf{H_{mn}} \delta \mathbf{H_{m'n}} \mathbf{U_{jm}}}{(\mathbf{e_n} - \mathbf{e_m})(\mathbf{e_n} - \mathbf{e_{m}'})} - \frac{\delta \mathbf{H_{mn}} \delta \mathbf{H_{nn}}}{(\mathbf{e_n} - \mathbf{e_m})^2} \mathbf{U_{jm}} + \frac{\delta \mathbf{H_{mn}} \delta \mathbf{U_{nm}}}{2 (\mathbf{e_n} - \mathbf{e_m})^2} \mathbf{U_{jm}} + \frac{\delta \mathbf{H_{mn}} \delta \mathbf{U_{mm}}}{2 (\mathbf{e_n} - \mathbf{e_m})^2} \mathbf{U_{jm}} + \frac{\delta \mathbf{H_{mn}} \delta \mathbf{U_{mm}}}{2 (\mathbf{e_m} - \mathbf{e_m})^2} \mathbf{U_{jm}} + \frac{\delta \mathbf{H_{mn}} \delta \mathbf{U_{mm}}}{2 (\mathbf{e_m} - \mathbf{e_m})^2} \mathbf{U_{jm}} + \frac{\delta \mathbf{H_{mn}} \delta \mathbf{U_{mm}}}{2 (\mathbf{e_m} - \mathbf{e_m})^2} \mathbf{U_{mm}} + \frac{\delta \mathbf{U_{mm}} \delta \mathbf{U_{mm}}}{2 (\mathbf{e_m} - \mathbf{e_m})^2} \mathbf{U_{mm}} + \frac{\delta \mathbf{U_{mm}} \delta \mathbf{U_{mm}}}{2 (\mathbf{e_m} - \mathbf{e_m})^2} \mathbf{U_{mm}} + \frac{\delta \mathbf{U_{mm}} \delta \mathbf{U_{mm}}}{2 (\mathbf{e_m} - \mathbf{e_m})^2} \mathbf{U_{mm}} + \frac{\delta \mathbf{U_{mm}} \delta \mathbf{U_{mm}}}{2 (\mathbf{e_m} - \mathbf{e_m})^2} \mathbf{U_{mm}} + \frac{\delta \mathbf{U_{mm}} \delta \mathbf{U_{mm}}}{2 (\mathbf{e_m} - \mathbf{e_m})^2} \mathbf{U_{mm}} + \frac{\delta \mathbf{U_{mm}} \delta \mathbf{U_{mm}}}{2 (\mathbf{e_m} - \mathbf{e_m})^2} \mathbf{U_{mm}} + \frac{\delta \mathbf{U_{mm}} \delta \mathbf{U_{mm}}}{2 (\mathbf{e_m} - \mathbf{e_m})^2} \mathbf{U_{mm}} + \frac{\delta \mathbf{U_{mm}} \delta \mathbf{U_{mm}}}{2 (\mathbf{e_m} - \mathbf{e_m})^2} \mathbf{U_{mm}} + \frac{\delta \mathbf{U_{mm}} \delta \mathbf{U_{mm}}}{2 (\mathbf{e_m} - \mathbf{e_m})^2} \mathbf{U_{mm}} + \frac{\delta \mathbf{U_{mm}} \delta \mathbf{U_{mm}}}{2 (\mathbf{e_m} - \mathbf{e_m})^2} \mathbf{U_{mm}} + \frac{\delta \mathbf{U_{mm}} \delta \mathbf{U_{mm}}}{2 (\mathbf{e_m} - \mathbf{e_m})^2} \mathbf{U_{mm}} + \frac{\delta \mathbf{U_{mm}} \delta \mathbf{U_{mm}}}{2 (\mathbf{e_m} - \mathbf{e_m})^2} \mathbf{U_{mm}} + \frac{\delta \mathbf{U_{mm}} \delta \mathbf{U_{mm}}}{2 (\mathbf{e_m} - \mathbf{e_m})^2} \mathbf{U_{mm}} + \frac{\delta \mathbf{U_{mm}} \delta \mathbf{U_{mm}}}{2 (\mathbf{e_m} - \mathbf{e_m})^2} \mathbf{U_{mm}} + \frac{\delta \mathbf{U_{mm}} \delta \mathbf{U_{mm}}}{2 (\mathbf{e_m} - \mathbf{e_m})^2} \mathbf{U_{mm}} + \frac{\delta \mathbf{U_{mm}} \delta \mathbf{U_{mm}}}{2 (\mathbf{e_m} - \mathbf{e_m})^2} \mathbf{U_{mm}} + \frac{\delta \mathbf{U_{mm}} \delta \mathbf{U_{mm}}}{2 (\mathbf{e_m} - \mathbf{e_m})^2} \mathbf{U_{mm}} + \frac{\delta \mathbf{U_{mm}} \delta \mathbf{U_{mm}}}{2 (\mathbf{e_m} - \mathbf{e_m})^2} \mathbf{U_{mm}} + \frac{\delta \mathbf{U_{mm}} \delta \mathbf{U_{mm}}}{2 (\mathbf{e_m} - \mathbf{e_m})^2} \mathbf{U_{mm}} + \frac{\delta \mathbf{U_{mm}} \delta \mathbf{U_{mm}}}{2 (\mathbf{e_m} - \mathbf{e_m})^2} \mathbf{U_{mm}} + \frac{\delta \mathbf{U_{mm}} \delta \mathbf{U_{mm}}}{2 (\mathbf{e_m} - \mathbf{e_m})^2} \mathbf{U_{mm}} + \frac{\delta \mathbf{U_{mm}} \delta \mathbf{U_{mm}}}{2 (\mathbf{e_m} - \mathbf{e_m})^2} \mathbf{U_{mm}} + \frac{\delta \mathbf{U_{mm}} \delta \mathbf{U_{mm}}}{2 (\mathbf{e_m} - \mathbf{e_m})^2} \mathbf{U_{mm}} + \frac{\delta \mathbf{U_{mm}} \delta \mathbf{U_{mm}}}{2 (\mathbf{e_m} - \mathbf{e_m})^2} \mathbf{U_{mm}} + \frac{\delta \mathbf{U_{mm}}$$

$$\langle \delta \mathbf{e_n}
angle = \langle \delta \mathbf{H_{nn}}
angle + \sum_{\mathbf{m} \neq \mathbf{n}}^{\mathbf{N}} \frac{\langle |\delta \mathbf{H_{mn}}|^2
angle}{\mathbf{e_n} - \mathbf{e_m}} = \left[\gamma \mathbf{e_n} + \sum_{\mathbf{m} \neq \mathbf{n}}^{\mathbf{N}} \frac{1}{\mathbf{e_n} - \mathbf{e_m}} \right] \delta \mathbf{Y}$$

$$\langle \delta \mathbf{e_n} \delta \mathbf{e_m} \rangle = \langle \delta \mathbf{H_{nn}} \delta \mathbf{H_{mm}} \rangle = (\mathbf{2f})^{-1} \delta_{\mathbf{nm}} \delta \mathbf{Y}$$

$$\langle \delta \mathbf{U_{jn}}
angle = -rac{1}{2} \sum_{\mathbf{m=1, m \neq n}} rac{\mathbf{U_{jn}}}{(\mathbf{e_n} - \mathbf{e_m})^2} \delta \mathbf{Y}$$

$$\langle \delta \mathbf{U_{jr}} \delta \mathbf{U_{kl}} \rangle = - \frac{\mathbf{U_{jl} U_{kr}}}{(\mathbf{e_r} - \mathbf{e_l})^2} (\mathbf{1} - \delta_{\mathbf{rl}}) \ \delta \mathbf{Y}$$

$$\langle \delta \mathbf{U_{jr}} \delta \mathbf{U_{kl}^*} \rangle = \sum_{\mathbf{m} \neq \mathbf{n}}^{\mathbf{N}} \frac{\mathbf{U_{jm}U_{km}^*}}{(\mathbf{e_r} - \mathbf{e_m})^2} \ \delta_{\mathbf{rl}} \delta \mathbf{Y}$$

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Diffusion Equation for $P_{e,u}(e_1,...,e_N;U_1,...,U_N;Y)$



Statistics of Geometric Phase Curvature

Pragya Shukla

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Details of numerical result Using standard second order perturbation theory for Hermitian operators, the second order change due to a small change δY

Joint probability distribution of eigenfunction components $P_{e,u}$

$$\frac{\partial \mathbf{P_{e,u}}}{\partial \mathbf{Y}} = (\mathbf{L_e} + \mathbf{L_u} + \mathbf{L_u^*}) \mathbf{P_{e,u}}$$

$$\begin{split} \mathbf{L}_{\mathbf{e}} \, \delta \mathbf{Y} &= \sum_{\mathbf{n}} \frac{\partial}{\partial \mathbf{e}_{\mathbf{n}}} \left[\frac{1}{2} \frac{\partial}{\partial \mathbf{e}_{\mathbf{n}}} \langle (\delta \mathbf{e}_{\mathbf{n}})^{2} \rangle - \langle \delta \mathbf{e}_{\mathbf{n}} \rangle \right] \\ \mathbf{L}_{\mathbf{u}} \, \delta \mathbf{Y} &= \sum_{\mathbf{k}, \mathbf{l}, \mathbf{j}, \mathbf{r}} \frac{\partial}{\partial \mathbf{U}_{\mathbf{j}\mathbf{r}}} \left[\frac{1}{2} \frac{\partial}{\partial \mathbf{U}_{\mathbf{k}\mathbf{l}}} \langle \delta \mathbf{U}_{\mathbf{j}\mathbf{r}} \delta \mathbf{U}_{\mathbf{k}\mathbf{l}} \rangle + \frac{1}{2} \frac{\partial}{\partial \mathbf{U}_{\mathbf{k}\mathbf{l}}^{*}} \langle \delta \mathbf{U}_{\mathbf{j}\mathbf{r}} \delta \mathbf{U}_{\mathbf{k}\mathbf{l}}^{*} \rangle - \langle \delta \mathbf{U}_{\mathbf{j}\mathbf{r}} \rangle \right] \end{split}$$

single parametric diffusion of curvature



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Details of numerical result

$$\mathbf{P_c}(\mathbf{C}) = \int \delta\left(\mathbf{C} - \mathbf{C_b}\right) \ \mathbf{P_{e,u}}(\mathbf{U}, \mathbf{U}^*, \mathbf{E}) \ \rho_{\mathbf{x}}(\partial_{\mathbf{x}} \mathbf{H}) \ \rho_{\mathbf{y}}(\partial_{\mathbf{y}} \mathbf{H}) \ \mathrm{D}\Gamma$$

$$\frac{\partial \mathbf{P_c}(\mathbf{C})}{\partial \mathbf{Y}} = \int \delta \left(\mathbf{C} - \mathbf{C_b} \right) \; \frac{\partial \mathbf{P_{e,u}}}{\partial \mathbf{Y}} \; \rho_{\mathbf{x}}(\partial_{\mathbf{x}} \mathbf{H}) \; \rho_{\mathbf{y}}(\partial_{\mathbf{y}} \mathbf{H}) \; \mathrm{D} \mathbf{\Gamma}$$

$$\frac{\partial \mathbf{P_c}(\mathbf{C})}{\partial \mathbf{Y}} = \int \delta \left(\mathbf{C} - \mathbf{C_b} \right) \, \left(\mathbf{L_e} + \mathbf{L_u} + \mathbf{L_u^*} \right) \, \mathbf{P_{e,u}} \, \rho_{\mathbf{x}}(\partial_{\mathbf{x}} \mathbf{H}) \, \rho_{\mathbf{y}}(\partial_{\mathbf{y}} \mathbf{H}) \, \mathrm{D}\Gamma$$

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single parametric diffusion of curvature



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Details of numerical result

$$ho(\mathbf{H}) \propto e^{-\sum \frac{(\mathbf{H}_{\mathbf{kl};\mathbf{s}} - \mathbf{b}_{\mathbf{kl};\mathbf{s}})^2}{2\mathbf{v}_{\mathbf{kl};\mathbf{s}}}}$$

$$\mathbf{Y} = -\frac{1}{N(N+1)} \; \ln \left[\prod_{\mathbf{k} \leq l; \mathbf{s}} |\mathbf{g}_{\mathbf{k}\mathbf{l}} - 2\mathbf{v}_{\mathbf{k}\mathbf{l}; \mathbf{s}}| \quad |\mathbf{b}_{\mathbf{k}\mathbf{l}; \mathbf{s}}|^2 \right]$$

For 2×2 *H*-matrix

$$\frac{\partial \mathbf{P}_{\mathbf{c}}(\mathbf{C})}{\partial \mathbf{Y}} = \frac{1}{2} \frac{\partial}{\partial \mathbf{C}} \left[\alpha \frac{\partial}{\partial \mathbf{C}} + \eta \mathbf{C} \right] \mathbf{P}_{\mathbf{c}}$$
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a single parametric formulation of curvature distribution for multi-parametric Gaussian ensemble ($\alpha, \eta =$ function(mean level spacing))





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Details of numerical result we analyzed distribution of the geometric curvature for the eigenstates of complex systems represented by a multi-parametric Gaussian ensembles.

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Details of numerical result

- we analyzed distribution of the geometric curvature for the eigenstates of complex systems represented by a multi-parametric Gaussian ensembles.
- such ensembles can appear whenever system is ergodic/ non-ergodic resulting in a full/ sparse matrix in a physically motivated basis.

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role of fluctuations in systems where phase is topologically invariant?

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Details of numerical result

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Thank you

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