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Institute of Mathematical Sciences and Physics

Multiscale Expansion Method for Periodic Homogenization

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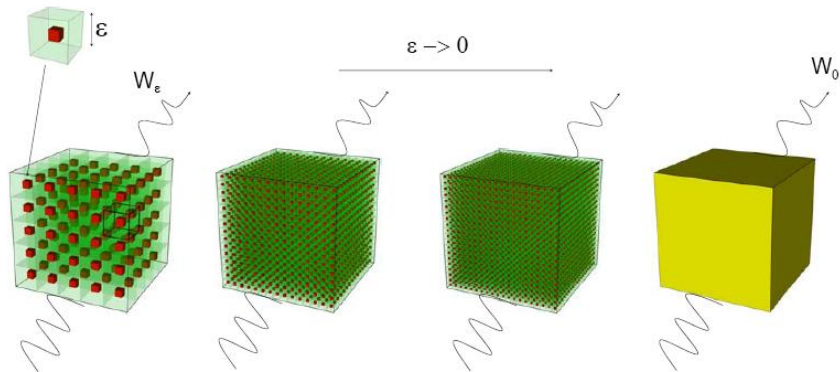
- 1 Introduction
- 2 The multiscale expansion method for periodic homogenization (one-dimensional case)
- 3 The multiscale expansion method for periodic homogenization (n -dimensional case)
- 4 The cell and the homogenized problems



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Homogenization



Reference: Meirmanov, Mathematical Methods Based on Homogenization Theory



Objectives of the Lecture

- 1 Show the multiscale expansion method in the one-dimensional and n -dimensional cases for a model diffusion problem.
- 2 Derive the corresponding cell and homogenized problems.
- 3 Examine the properties of the cell and homogenized problems.



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A **stationary** temperature field in a **non-homogeneous** rod with periodic structure:

$$\begin{cases} \frac{d}{dx} \left(a_\varepsilon(x) \frac{du}{dx} \right) = f(x), & x \in (0, 1) \\ u(0) = g_0, u(1) = g_1. \end{cases}$$



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Type 1



$$\begin{cases} \frac{d}{dx} \left(a_\varepsilon(x) \frac{du}{dx} \right) = f(x), & x \in (0, 1) \\ u(0) = g_0, u(1) = g_1. \end{cases}$$

Assumptions:

- 1 The rod is of periodic structure.
- 2 The thermal conductivity a_ε is periodic with period $\varepsilon = \frac{1}{n}$ where n is a large natural number.
- 3 $a_\varepsilon(x) = a\left(\frac{x}{\varepsilon}\right)$ and $a(y)$ is a 1-periodic function which is positive and differentiable.



Setting of the Problem

$$\begin{cases} \frac{d}{dx} \left(a_\varepsilon(x) \frac{du}{dx} \right) = f, & x \in (0, 1) \\ u(0) = g_0, u(1) = g_1. \end{cases}$$



$$\begin{cases} \frac{d}{dx} \left(a_\varepsilon(x) \frac{du}{dx} \right) = f, & x \in (0, 1) \\ u(0) = g_0, u(1) = g_1. \end{cases}$$

Our goal: Solve for u when $\varepsilon \rightarrow 0$.



Construct the solution u in the form (also called an ansatz):

$$u = u_0(x, y) + \varepsilon u_1(x, y) + \varepsilon^2 u_2(x, y) + \dots$$



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$$u = u_0(x, y) + \varepsilon u_1(x, y) + \varepsilon^2 u_2(x, y) + \dots$$

Notes:

- 1 slow (or macroscopic) variable x
- 2 fast (or microscopic) variable $y = \frac{x}{\varepsilon}$
- 3 $u_i(x, y)$ are periodic with respect to the variable y with period 1



Differentiation formula:

$$\frac{dF}{dx}(x, y) = \frac{\partial F}{\partial x}(x, y) + \frac{\partial F}{\partial y} \cdot \frac{dy}{dx} = \frac{\partial F}{\partial x} + \frac{1}{\varepsilon} \frac{\partial F}{\partial y}.$$



Differentiation formula:

$$\frac{dF}{dx}(x, y) = \frac{\partial F}{\partial x}(x, y) + \frac{\partial F}{\partial y} \cdot \frac{dy}{dx} = \frac{\partial F}{\partial x} + \frac{1}{\varepsilon} \frac{\partial F}{\partial y}.$$

A series expansion in ε :

$$\begin{aligned} & \varepsilon^{-2} \left[\frac{\partial}{\partial y} \left(a(y) \frac{\partial u_0}{\partial y} \right) \right] + \varepsilon^{-1} \left[\frac{\partial}{\partial x} \left(a(y) \frac{\partial u_0}{\partial y} \right) + \frac{\partial}{\partial y} \left(a(y) \left(\frac{\partial u_0}{\partial x} + \frac{\partial u_1}{\partial y} \right) \right) \right] \\ & + \varepsilon^0 \left[\frac{\partial}{\partial x} \left(a(y) \left(\frac{\partial u_0}{\partial x} + \frac{\partial u_1}{\partial y} \right) \right) + \frac{\partial}{\partial y} \left(a(y) \left(\frac{\partial u_1}{\partial x} + \frac{\partial u_2}{\partial y} \right) \right) \right] \\ & + \varepsilon^1 [\dots] + \varepsilon^2 [\dots] + \dots = f. \end{aligned}$$



Multiscale asymptotic expansion method

For homogenization purposes, only the $\varepsilon^{-2}, \varepsilon^{-1}, \varepsilon^0$ terms are needed:

$$\frac{\partial}{\partial y} \left(a(y) \frac{\partial u_0}{\partial y} \right) = 0$$

$$\frac{\partial}{\partial x} \left(a(y) \frac{\partial u_0}{\partial y} \right) + \frac{\partial}{\partial y} \left(a(y) \left(\frac{\partial u_0}{\partial x} + \frac{\partial u_1}{\partial y} \right) \right) = 0$$

$$\frac{\partial}{\partial x} \left(a(y) \left(\frac{\partial u_0}{\partial x} + \frac{\partial u_1}{\partial y} \right) \right) + \frac{\partial}{\partial y} \left(a(y) \left(\frac{\partial u_1}{\partial x} + \frac{\partial u_2}{\partial y} \right) \right) = f$$

(A system of linear differential equations for u_0, u_1, u_2 with respect to y , considering x as a parameter)



The mean value (period-average) operator \mathcal{M} :

$$\mathcal{M}(F(x, y)) = \int_0^1 F(x, y) dy$$

with x and y considered as independent.



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Step 1:

$$\frac{\partial}{\partial y} \left(a(y) \frac{\partial u_0}{\partial y} \right) = 0 \Rightarrow u_0(x, y) = v_0(x).$$



Step 2:

$$\begin{aligned} \frac{\partial}{\partial x} \left(a(y) \frac{\partial u_0}{\partial y} \right) + \frac{\partial}{\partial y} \left(a(y) \left(\frac{\partial u_0}{\partial x} + \frac{\partial u_1}{\partial y} \right) \right) &= 0 \\ \Rightarrow \frac{\partial u_1}{\partial y} &= \left(\frac{\hat{a}}{a(y)} - 1 \right) \frac{dv_0}{dx} \\ \Rightarrow u_1(x, y) &= N_1(y) \frac{dv_0}{dx} + v_1(x), \end{aligned}$$

where $v_1(x)$ is an arbitrary function and

$$N_1(y) = \int_0^y \left(\frac{\hat{a}}{a(t)} - 1 \right) dt,$$

with $\hat{a} = \frac{1}{\mathcal{M}(a(y))^{-1}}$.



Step 3:

$$\begin{aligned} \frac{\partial}{\partial x} \left(a(y) \left(\frac{\partial u_0}{\partial x} + \frac{\partial u_1}{\partial y} \right) \right) + \frac{\partial}{\partial y} \left(a(y) \left(\frac{\partial u_1}{\partial x} + \frac{\partial u_2}{\partial y} \right) \right) &= f \\ \Rightarrow \int_0^1 \left[\frac{\partial}{\partial x} \left(a(y) \frac{\partial u_1}{\partial y} \right) + \frac{\partial}{\partial x} \left(a(y) \frac{\partial u_0}{\partial x} \right) \right] dy &= \int_0^1 f(x) dy \end{aligned}$$



Step 3:

$$\begin{aligned} \frac{\partial}{\partial x} \left(a(y) \left(\frac{\partial u_0}{\partial x} + \frac{\partial u_1}{\partial y} \right) \right) + \frac{\partial}{\partial y} \left(a(y) \left(\frac{\partial u_1}{\partial x} + \frac{\partial u_2}{\partial y} \right) \right) &= f \\ \Rightarrow \int_0^1 \left[\frac{\partial}{\partial x} \left(a(y) \frac{\partial u_1}{\partial y} \right) + \frac{\partial}{\partial x} \left(a(y) \frac{\partial u_0}{\partial x} \right) \right] dy &= \int_0^1 f(x) dy \end{aligned}$$

Substituting the value of u_0 and $\frac{\partial u_1}{\partial y}$ into the preceding equation gives

$$\hat{a} \frac{d^2 v_0}{dx^2} = f(x)$$

with the boundary conditions $v_0(0) = g_0$ and $v_0(1) = g_1$.



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A model problem of conductivity reads:

$$\begin{cases} -\operatorname{div}(A_\varepsilon(x)\nabla u_\varepsilon) = f(x), & \text{in } \Omega, \\ u_\varepsilon = 0, & \text{on } \partial\Omega, \end{cases}$$

where $A_\varepsilon(x)$ and $u_\varepsilon(x)$ are the conductivity and unknown function modeling electric potential or temperature, respectively.



Setting of the problem

$$\begin{cases} -\operatorname{div}(A_\varepsilon(x)\nabla u_\varepsilon) = f, & \text{in } \Omega, \\ u_\varepsilon = 0, & \text{on } \partial\Omega. \end{cases}$$

Assumptions:

- 1 $\Omega \subseteq \mathbb{R}^N$, is a bounded, periodic domain with period ε (very small positive number)
- 2 $Y = (0, 1)^N$ is the rescaled unit periodic cell.
- 3 The conductivity varies periodically with period ε and will be the matrix $A(y)$ where $y = \frac{x}{\varepsilon} \in Y$. A is assumed to be bounded and positive definite, that is, for all $\xi \in \mathbb{R}^N$ and at any point $y \in Y$,

$$\alpha|\xi|^2 \leq \sum_{i,j=1}^N a_{ij}(y)\xi_i\xi_j \leq \beta|\xi|^2.$$

for some positive constants $\beta \leq \alpha > 0$.

- 4 $A_\varepsilon(x) = A\left(\frac{x}{\varepsilon}\right)$



Setting of the problem

$$\begin{cases} -\operatorname{div}(A_\varepsilon(x)\nabla u_\varepsilon) = f, & \text{in } \Omega, \\ u_\varepsilon = 0, & \text{on } \partial\Omega, \end{cases}$$

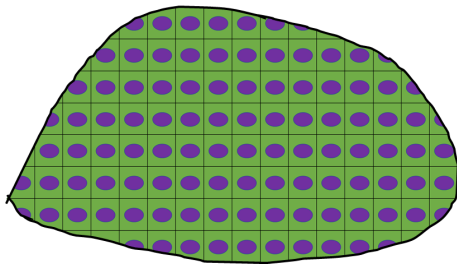


Figure: A periodic domain Ω

$$\begin{cases} -\operatorname{div}(A_\varepsilon(x)\nabla u_\varepsilon) = f, & \text{in } \Omega, \\ u_\varepsilon = 0, & \text{on } \partial\Omega. \end{cases}$$



$$\begin{cases} -\operatorname{div}(A_\varepsilon(x)\nabla u_\varepsilon) = f, & \text{in } \Omega, \\ u_\varepsilon = 0, & \text{on } \partial\Omega. \end{cases}$$

The PDE can be written in the form:

$$-\sum_{i,j=1}^N \frac{\partial}{\partial x_i} \left(a_{ij} \left(\frac{x}{\varepsilon} \right) \frac{\partial u}{\partial x_j} \right) = f(x).$$



$$\begin{cases} -\operatorname{div} (A_\varepsilon(x) \nabla u_\varepsilon) = f, & \text{in } \Omega, \\ u_\varepsilon = 0, & \text{on } \partial\Omega. \end{cases}$$

The PDE can be written in the form:

$$-\sum_{i,j=1}^N \frac{\partial}{\partial x_i} \left(a_{ij} \left(\frac{x}{\varepsilon} \right) \frac{\partial u}{\partial x_j} \right) = f(x).$$

Our goal: Solve the above problem as the period $\varepsilon \rightarrow 0$ and derive some global or average behavior of the domain Ω .



The solution u_ε as a power series in ε (ansatz):

$$u_\varepsilon(x) = \sum_{i=0}^{\infty} \varepsilon^i u_i \left(x, \frac{x}{\varepsilon} \right)$$

where $u_i(x, y)$ is a Y -periodic function with respect to y .



The solution u_ε as a power series in ε (ansatz):

$$u_\varepsilon(x) = \sum_{i=0}^{\infty} \varepsilon^i u_i \left(x, \frac{x}{\varepsilon} \right)$$

where $u_i(x, y)$ is a Y -periodic function with respect to y .

Differentiation formula:

$$\nabla \left(u_i \left(x, \frac{x}{\varepsilon} \right) \right) = \left(\frac{1}{\varepsilon} \nabla_y u_i + \nabla_x u_i \right) \left(x, \frac{x}{\varepsilon} \right)$$

where ∇_y and ∇_x denote the partial derivative with respect to the first and second variable of $u_i(x, y)$.



A series expansion in ε :

$$\begin{aligned} & - \varepsilon^{-2} (\operatorname{div}_y A \nabla_y u_0) \left(x, \frac{x}{\varepsilon} \right) \\ & - \varepsilon^{-1} [\operatorname{div}_y A (\nabla_x u_0 + \nabla_y u_1) + \operatorname{div}_x (A \nabla_y u_0)] \left(x, \frac{x}{\varepsilon} \right) \\ & - \varepsilon^0 [\operatorname{div}_x A (\nabla_x u_0 + \nabla_y u_1) + \operatorname{div}_y A (\nabla_x u_1 + \nabla_y u_2)] \left(x, \frac{x}{\varepsilon} \right) \\ & - \sum_{i=1}^{\infty} \varepsilon^i [\operatorname{div}_x A (\nabla_x u_i + \nabla_y u_{i+1}) + \operatorname{div}_y A (\nabla_x u_{i+1} + \nabla_y u_{i+2})] \left(x, \frac{x}{\varepsilon} \right) \\ & = f(x). \end{aligned}$$



Order ε^{-2} equation:

$$-\operatorname{div}_y A(y) \nabla_y u_0(x, y) = 0$$

Order ε^{-1} equation:

$$-\operatorname{div}_y (A(y) (\nabla_x u_0 + \nabla_y u_1))(x, y) - \operatorname{div}_x (A(y) \nabla_y u_0)(x, y) = 0$$

Order ε^0 equation:

$$\begin{aligned} & -\operatorname{div}_x (A(y) (\nabla_x u_0 + \nabla_y u_1))(x, y) \\ & -\operatorname{div}_y (A(y) (\nabla_x u_1 + \nabla_y u_2))(x, y) = f(x) \end{aligned}$$



Step 1:

$$-\operatorname{div}_y A(y) \nabla_y u_0(x, y) = 0 \Rightarrow u_0(x, y) = u_0(x)$$

where u_0 does not depend on y .



Step 2:

$$-\operatorname{div}_y(A(y)(\nabla_x u_0 + \nabla_y u_1))(x, y) - \operatorname{div}_x(A(y)\nabla_y u_0)(x, y) = 0$$



Step 2:

$$-\operatorname{div}_y(A(y)(\nabla_x u_0 + \nabla_y u_1))(x, y) - \operatorname{div}_x(A(y)\nabla_y u_0)(x, y) = 0$$

Finding u_1 in terms of u_0 :

$$u_1(x, y) = \sum_{i=1}^N \frac{\partial u_0}{\partial x_i}(x) \omega_i(y).$$

where $\omega_i(y) \in H_{per}^1(Y)$ (unique up to an additive constant)
the solution to

$$-\operatorname{div}_y(A(y)\nabla_y \omega_i(y)) = \operatorname{div}_y(A(y)e_i)$$

with e_i the i^{th} basis vector of \mathbb{R}^N .



Step 3:

$$\begin{aligned} & - \operatorname{div}_x(A(y)(\nabla_x u_0 + \nabla_y u_1))(x, y) \\ & - \operatorname{div}_y(A(y)(\nabla_x u_1 + \nabla_y u_2))(x, y) = f(x) \end{aligned}$$



Step 3:

$$\begin{aligned} & -\operatorname{div}_x(A(y)(\nabla_x u_0 + \nabla_y u_1))(x, y) \\ & -\operatorname{div}_y(A(y)(\nabla_x u_1 + \nabla_y u_2))(x, y) = f(x) \end{aligned}$$

Integration and using the periodic boundary condition of u_1 and u_2 give:

$$-\operatorname{div}_x(A^* \nabla_x u_0) = f(x),$$



Step 3:

$$\begin{aligned} & -\operatorname{div}_x(A(y)(\nabla_x u_0 + \nabla_y u_1))(x, y) \\ & -\operatorname{div}_y(A(y)(\nabla_x u_1 + \nabla_y u_2))(x, y) = f(x) \end{aligned}$$

Integration and using the periodic boundary condition of u_1 and u_2 give:

$$-\operatorname{div}_x(A^* \nabla_x u_0) = f(x),$$

where A^* is known as the effective diffusion tensor and is given by

$$A_{j,k}^* = \int_Y \left(A_{j,k}(y) + \sum_{l=1}^N A_{j,l} \frac{\partial \omega_k}{\partial y_l}(y) \right) dy.$$



Using the Dirichlet boundary condition, the limit u_0 satisfies the boundary value problem:

$$\begin{cases} -\operatorname{div}_x (A^* \nabla_x u_0) = f(x), & \text{in } \Omega, \\ u_0 = 0, & \text{on } \partial\Omega. \end{cases}$$



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The cell problem:

$$-\operatorname{div}_y(A(y)\nabla_y\omega_i(y)) = \operatorname{div}_y(A(y)e_i)$$



The cell problem:

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The homogenized problem:

$$\begin{cases} -\operatorname{div}_x(A^*\nabla_x u_0) = f(x), & \text{in } \Omega, \\ u_0 = 0, & \text{on } \partial\Omega. \end{cases}$$



The cell and homogenized problems

The cell problem:

$$-\operatorname{div}_y(A(y)\nabla_y\omega_i(y)) = \operatorname{div}_y(A(y)e_i)$$

The homogenized problem:

$$\begin{cases} -\operatorname{div}_x(A^*\nabla_x u_0) = f(x), & \text{in } \Omega, \\ u_0 = 0, & \text{on } \partial\Omega. \end{cases}$$

Remarks:

- 1 The **cell problem** allows us to solve u_1 in terms of u_0 .
- 2 The **homogenized problem** gives the equation solved by u_0 .
- 3 The diffusion tensor A^* does not depend on x .
- 4 The functions ω_i in the cell problem are known as the **correctors**.



Questions about the cell and homogenized problems



- 1 Is the homogenized problem well-posed? What can be said of A^* ?
- 2 Is the cell problem well-posed?
- 3 What do the correctors mean?



$$\begin{aligned}u_\varepsilon(x) &\approx u_0(x) + \varepsilon u_1\left(x, \frac{x}{\varepsilon}\right) \\ &\approx u_0(x) + \varepsilon \sum_{i=1}^N \frac{\partial u_0}{\partial x_i}(x) \omega_i\left(\frac{x}{\varepsilon}\right).\end{aligned}$$



$$\begin{aligned}u_\varepsilon(x) &\approx u_0(x) + \varepsilon u_1\left(x, \frac{x}{\varepsilon}\right) \\ &\approx u_0(x) + \varepsilon \sum_{i=1}^N \frac{\partial u_0}{\partial x_i}(x) \omega_i\left(\frac{x}{\varepsilon}\right).\end{aligned}$$

Remarks:

- 1 The correctors ω_i measures the difference of the heterogeneous solution and the homogenized solution.
- 2 The solution u_ε oscillates with an amplitude ε and with a profile ω_i scaled by $\frac{\partial u_0}{\partial x_i}(x)$.



The cell problem:

$$-\operatorname{div}_y(A(y)\nabla_y\omega_i(y)) = \operatorname{div}_y(A(y)e_i)$$



The cell problem:

$$-\operatorname{div}_y(A(y)\nabla_y\omega_i(y)) = \operatorname{div}_y(A(y)e_i)$$

The variational formulation of the cell problem:

$$\int_Y (A(y)\nabla_y\omega_i(y), \nabla_y\varphi(y)) dy = - \int_Y (A(y)e_i, \nabla_y\varphi(y)) dy,$$

where $\varphi \in H_{per}^1(Y)$.



The cell problem:

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The variational formulation of the cell problem:

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where $\varphi \in H_{per}^1(Y)$.

Using the assumption on A and the Lax-Milgram Theorem, the preceding equation has a **unique solution** in the Hilbert space

$$V = \{\psi \in H_{per}^1(Y) \text{ such that } \int_Y \psi(y) dy = 0\}.$$



The diffusion tensor A^*

$$\int_Y (A(y) \nabla_y \omega_i(y), \nabla_y \varphi(y)) dy = - \int_Y (A(y) e_i, \nabla_y \varphi(y)) dy,$$



The diffusion tensor A^*

$$\int_Y (A(y) \nabla_y \omega_i(y), \nabla_y \varphi(y)) dy = - \int_Y (A(y) e_i, \nabla_y \varphi(y)) dy,$$

Let $\varphi = \omega_k$ in the variational formulation, that is, ω_k is a test function. Then

$$\int_Y (A(y)(e_i + \nabla_y \omega_i(y)), \nabla_y \omega_k(y)) dy = 0.$$



The diffusion tensor A^*

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Let $\varphi = \omega_k$ in the variational formulation, that is, ω_k is a test function. Then

$$\int_Y (A(y)(e_i + \nabla_y \omega_i(y)), \nabla_y \omega_k(y)) dy = 0.$$

It can be shown that:

$$\begin{aligned} A_{j,k}^* &= \int_Y \left(A_{j,k}(y) + \sum_{l=1}^N A_{j,l} \frac{\partial \omega_k}{\partial y_l}(y) \right) dy \\ &= \int_Y (A(y)(e_k + \nabla_y \omega_k(y)), e_j + \nabla_y \omega_j) dy \end{aligned}$$



The diffusion tensor A^*

If $\xi \in \mathbb{R}^N$ then

$$\begin{aligned}(A^*\xi, \xi) &= \sum_{j,k=1}^N A^* \xi_j \xi_k \\ &= \int_Y \left(A(y) \left(\xi + \sum_{k=1}^N \xi_k \nabla_y \omega_k(y) \right), \xi + \sum_{j=1}^N \xi_j \nabla_y \omega_j(y) \right) dy \\ &\geq \left\| \xi + \sum_{k=1}^N \xi_k \nabla_y \omega_k(y) \right\|_{L^2(Y)}^2,\end{aligned}$$



The diffusion tensor A^*

If $\xi \in \mathbb{R}^N$ then

$$\begin{aligned}(A^*\xi, \xi) &= \sum_{j,k=1}^N A^* \xi_j \xi_k \\ &= \int_Y \left(A(y) \left(\xi + \sum_{k=1}^N \xi_k \nabla_y \omega_k(y) \right), \xi + \sum_{j=1}^N \xi_j \nabla_y \omega_j(y) \right) dy \\ &\geq \left\| \xi + \sum_{k=1}^N \xi_k \nabla_y \omega_k(y) \right\|_{L^2(Y)}^2,\end{aligned}$$

showing that A^* is a positive definite matrix.



The solvability of the homogenized problem

Using the property of A^* and the Lax-Milgram Theorem, the homogenized problem:

$$\begin{cases} -\operatorname{div}_x (A^* \nabla_x u_0) = f(x), & \text{in } \Omega, \\ u_0 = 0, & \text{on } \partial\Omega. \end{cases}$$





has a unique solution in the Hilbert space $H_0^1(\Omega)$.



The multiscale expansion method

This method is a heuristic one which allows us to find the homogenized problem but not a rigorous one. It may not be optimal and perfect. The next methods will justify our result.



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Dhanyahvaad!

