

Physical and evolutionary constraints *at the molecular scale*

Anne-Florence Bitbol



ICTS Program on “Living Matter” - Bangalore, India
April 2018

Introduction

■ Understanding proteins

- Heteropolymers made of 20 types of amino-acids (monomers) → $\sim 20^{100}$ possible proteins
 - A given natural protein folds into a compact and (almost) unique 3D **structure**
 - It has specific **interactions** with other molecules → **function**

 - Experiment: random proteins do not fold properly [Socolich et al. \(2005\)](#)
 - Theory: for a random protein, interactions between monomers are random (the potential depends on the amino-acids involved) → spin-glass like: frustration
→ many locally stable low energy states
[Bialek \(2012\)](#)
- Natural proteins are special

Introduction

■ Understanding proteins

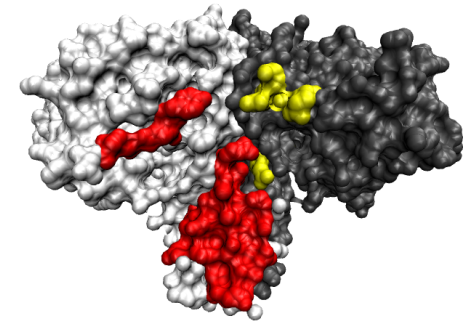
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Sequence
...ISHEL...

folding

Structure

evolution

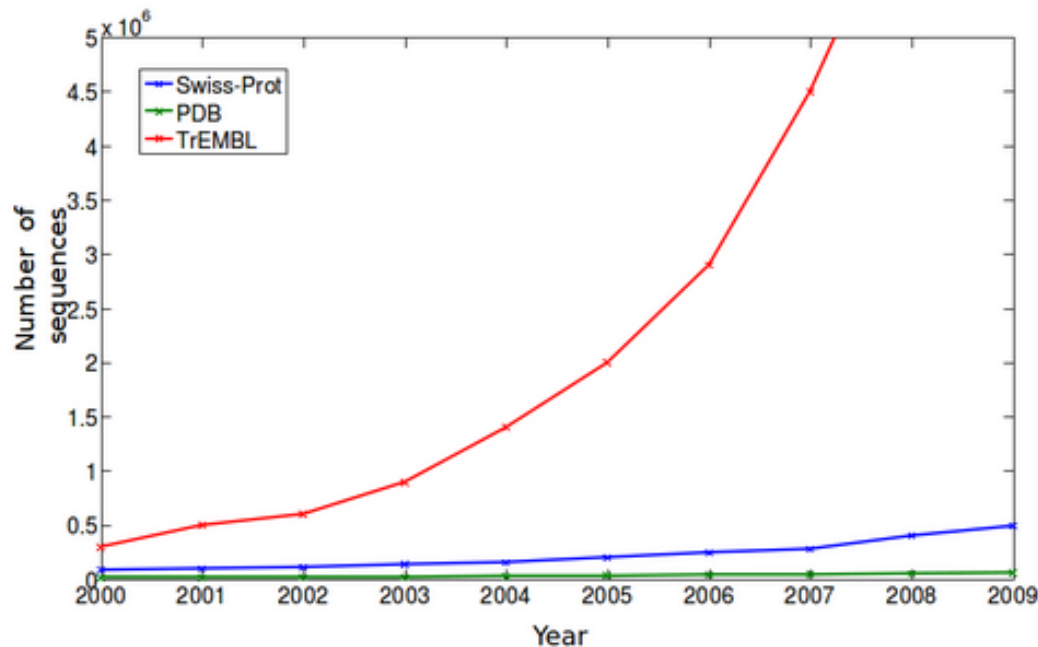


Function (including interactions)

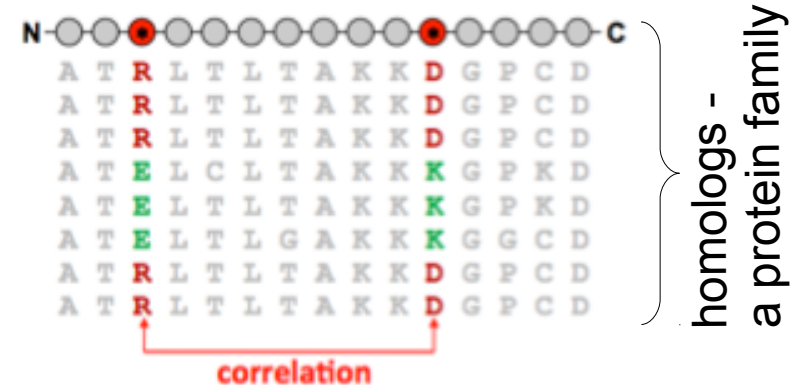
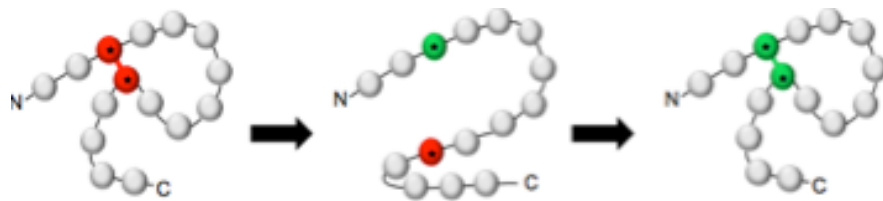
- Enzyme (histidine kinase)
- Phosphorylates another protein (response regulator)

Introduction

- Exploiting sequence data to understand natural proteins



Recent data-driven approaches to infer structure and function from sequences



Evolutionary coupling between interacting residues

→ correlations in homolog sequence data inform us about structure

BUT... observed correlations can be indirect $A \leftrightarrow B \leftrightarrow C$

Outline

I. Predicting protein structure from sequence data

Direct coupling analysis (DCA)

II. Inferring interaction partners from protein sequences

Iterative pairing algorithm (IPA)

Direct coupling analysis (DCA)

**Predicting protein structure
from sequence data**

Direct coupling analysis (DCA) *Weigt, White et al. (2009)*

▪ Statistical inference method (cf. tutorial)

• Goal: construct a global model for the protein family

L -site probability distribution (probability of observing a given sequence in the protein family considered): $P(\alpha_1, \alpha_2, \dots, \alpha_L)$

• Construct it from the data (data-driven approach)

Observations retained: one- and two-body frequencies (choice)

$$\begin{array}{l} \dots \text{ISHEL} \dots \\ \dots \text{VSHDI} \dots \\ \dots \text{VSHEL} \dots \\ \vdots \end{array} \rightarrow \begin{cases} f_i(\alpha) & i \in \{1, \dots, L\} \\ f_{ij}(\alpha, \beta) & \alpha \in \{A_1, \dots, A_{20}, A_{21} = -\} \\ C_{ij}(\alpha, \beta) = f_{ij}(\alpha, \beta) - f_i(\alpha)f_j(\beta) \end{cases}$$

Multiple choices are consistent with these observations...

• Maximum entropy principle

Maximize $S = - \sum_{\{\alpha_1, \dots, \alpha_L\}} P(\alpha_1, \dots, \alpha_L) \log [P(\alpha_1, \dots, \alpha_L)]$ (Shannon entropy) + constraints

Yields the least-structured model consistent with the observations

• Resulting global model

$$P(\alpha_1, \dots, \alpha_L) = \frac{1}{Z} \exp \left\{ - \left[\sum_{i=1}^L h_i(\alpha_i) + \sum_{i < j} e_{ij}(\alpha_i, \alpha_j) \right] \right\} \rightarrow \text{Potts model}$$

one-body terms - fields

two-body terms - (direct) couplings

Direct coupling analysis (DCA)

Statistical inference method (cf. tutorial)

$$\begin{array}{l} \dots \text{ISHEL} \dots \\ \dots \text{VSHDI} \dots \\ \dots \text{VSHEL} \dots \\ \vdots \end{array} \rightarrow \begin{cases} f_i(\alpha) & i \in \{1, \dots, L\} \\ f_{ij}(\alpha, \beta) & \alpha \in \{A_1, \dots, A_{20}, A_{21} = -\} \\ C_{ij}(\alpha, \beta) = f_{ij}(\alpha, \beta) - f_i(\alpha)f_j(\beta) \end{cases}$$

Pairwise maximum entropy model and direct couplings:

$$P(\alpha_1, \dots, \alpha_L) = \frac{1}{Z} \exp \left\{ - \left[\sum_{i=1}^L h_i(\alpha_i) + \sum_{i < j} e_{ij}(\alpha_i, \alpha_j) \right] \right\}$$

One needs to determine the fields and couplings consistent with the observations

$$\sum_{\alpha_k, k \neq i} P(\alpha_1, \dots, \alpha_L) = f_i(\alpha_i),$$

$$\sum_{\alpha_k, k \notin \{i, j\}} P(\alpha_1, \dots, \alpha_L) = f_{ij}(\alpha_i, \alpha_j).$$

→ very hard problem! (inverse problem - general)

→ many approximation methods

Cocco et al. (2017) - in the context of proteins

Mean-field approximation: $e_{ij}(\alpha, \beta) = C_{ij}^{-1}(\alpha, \beta)$
(20 L x 20 L matrix)

Morcos, Pagnani et al. (2011)
Marks, Colwell et al. (2011)

- Simplest approximation, can be derived through a small-coupling expansion
- Has proved rather good in the case of proteins

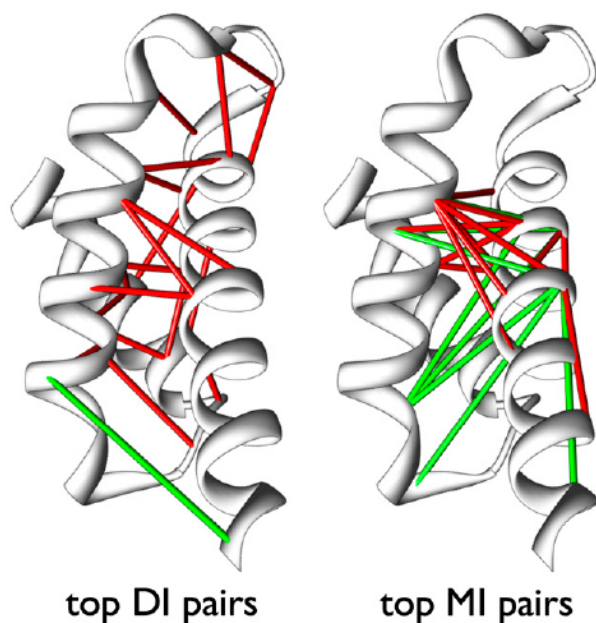
Direct coupling analysis (DCA)

■ Performance

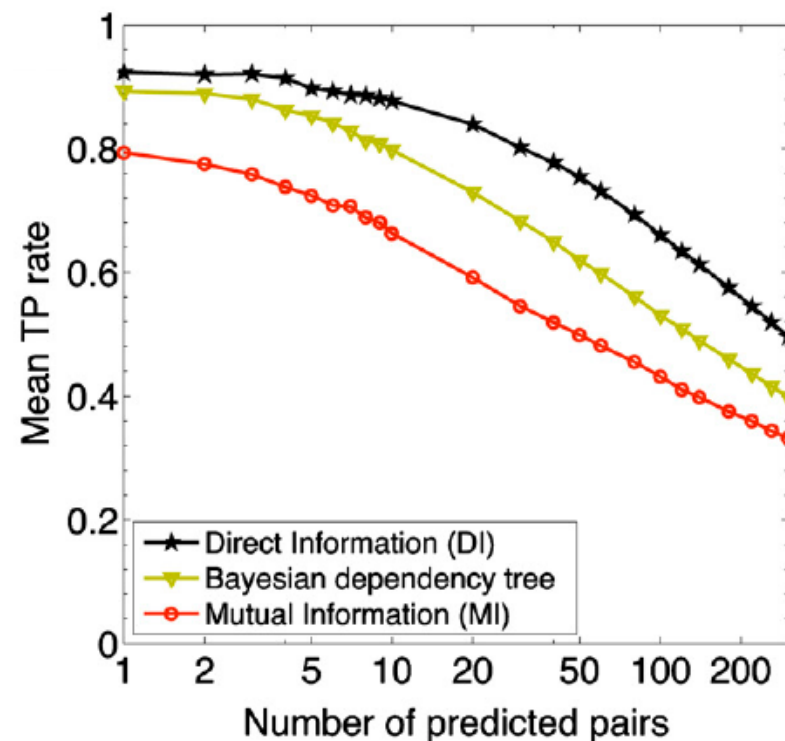
$e_{ij}(\alpha, \beta)$ much better predictor of 3D contact than $C_{ij}(\alpha, \beta)$
Mutual Information

Weigt, White et al. (2009)
Morcos, Pagnani et al. (2011)
Marks, Colwell et al. (2011)

Morcos, Pagnani et al. (2011):



Bacterial Sigma factor region 2.
Top 20 DI / MI predictions
(distance along the backbone > 4).
Red: distance < 8 Å; green: others.



Mean TP rate for 131 domain families
vs. number of top-ranked contacts

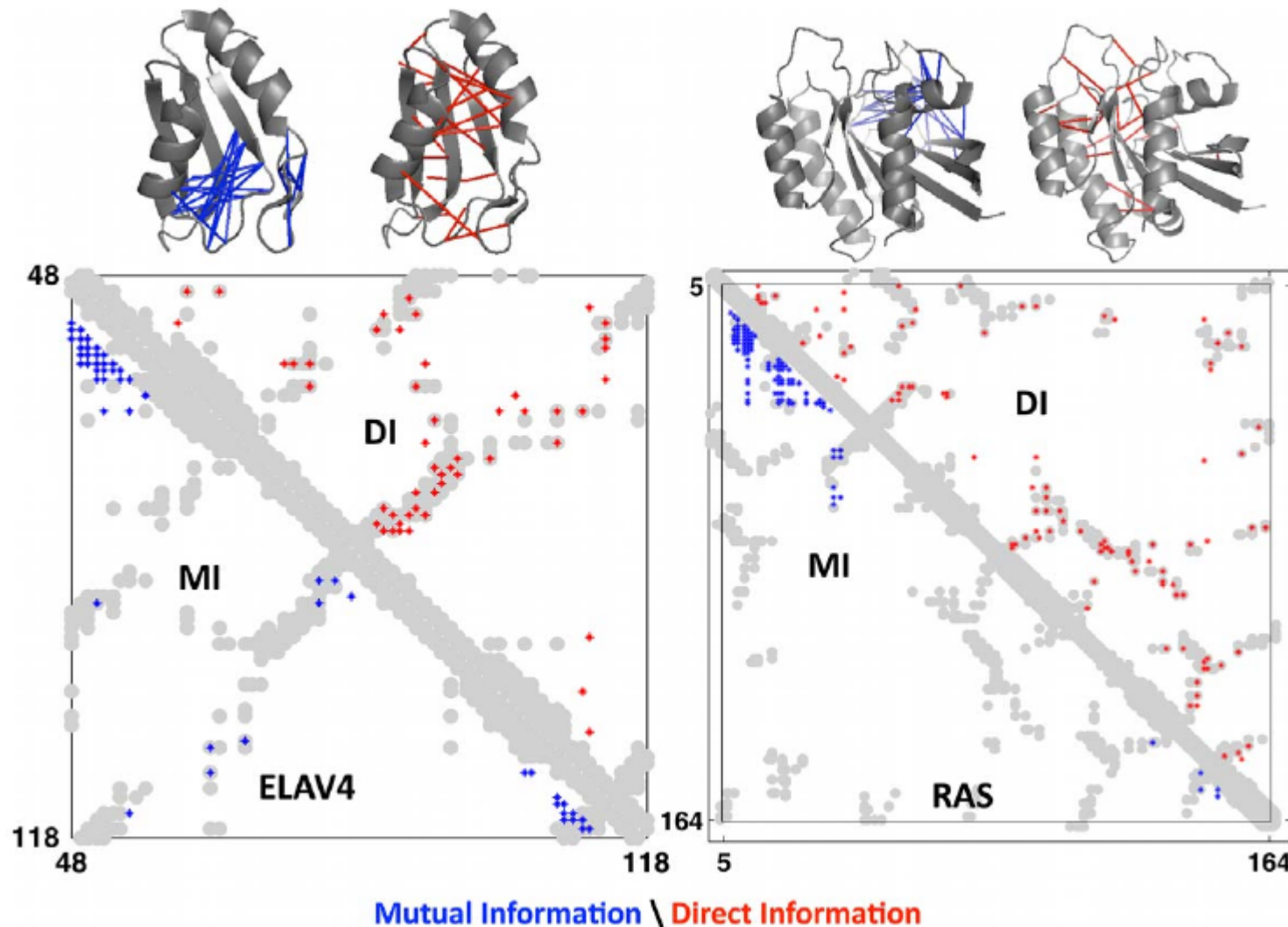
Direct coupling analysis (DCA)

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$e_{ij}(\alpha, \beta)$ much better predictor of 3D contact than $C_{ij}(\alpha, \beta)$
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Marks, Colwell et al. (2011):



Predicted contacts for DI (red) overlap more accurately with the contacts in the experimentally observed structure (grey), than those for MI (blue).

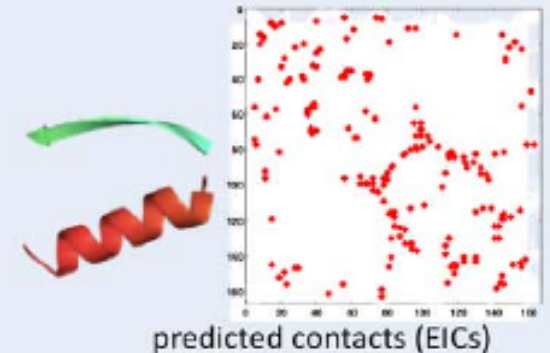
Direct coupling analysis (DCA)

- Full prediction of protein 3D structure from sequence data

Marks, Colwell et al. (2011):

Analyze the highest scoring pairs to produce ranked list of residue pairs which we predict to be close in 3D space. Use these pairs as predicted close “evolutionary inferred contacts”, EICs, in folding calculations

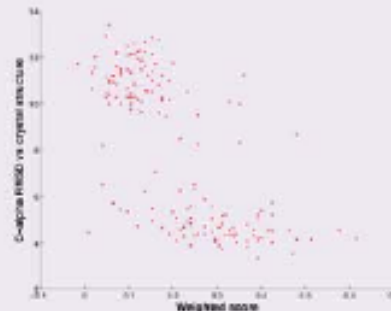
```
assign (resid 143 and name CA) (resid 123 and name CA) 4 4 3
assign (resid 16 and name CA) (resid 10 and name CA) 4 4 3
assign (resid 141 and name CA) (resid 82 and name CA) 4 4 3
assign (resid 129 and name CA) (resid 87 and name CA) 4 4 3
assign (resid 92 and name CA) (resid 11 and name CA) 4 4 3
assign (resid 116 and name CA) (resid 81 and name CA) 4 4 3
```



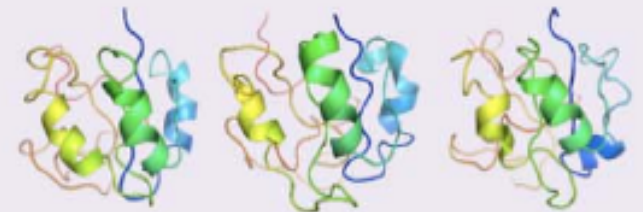
Start with extended structure
use **distance geometry** and **simulated annealing** with predicted constraints, EICs, to fold the chain



Rank predicted structures using quality measure of backbone alpha torsion and beta sheet twist



good scores



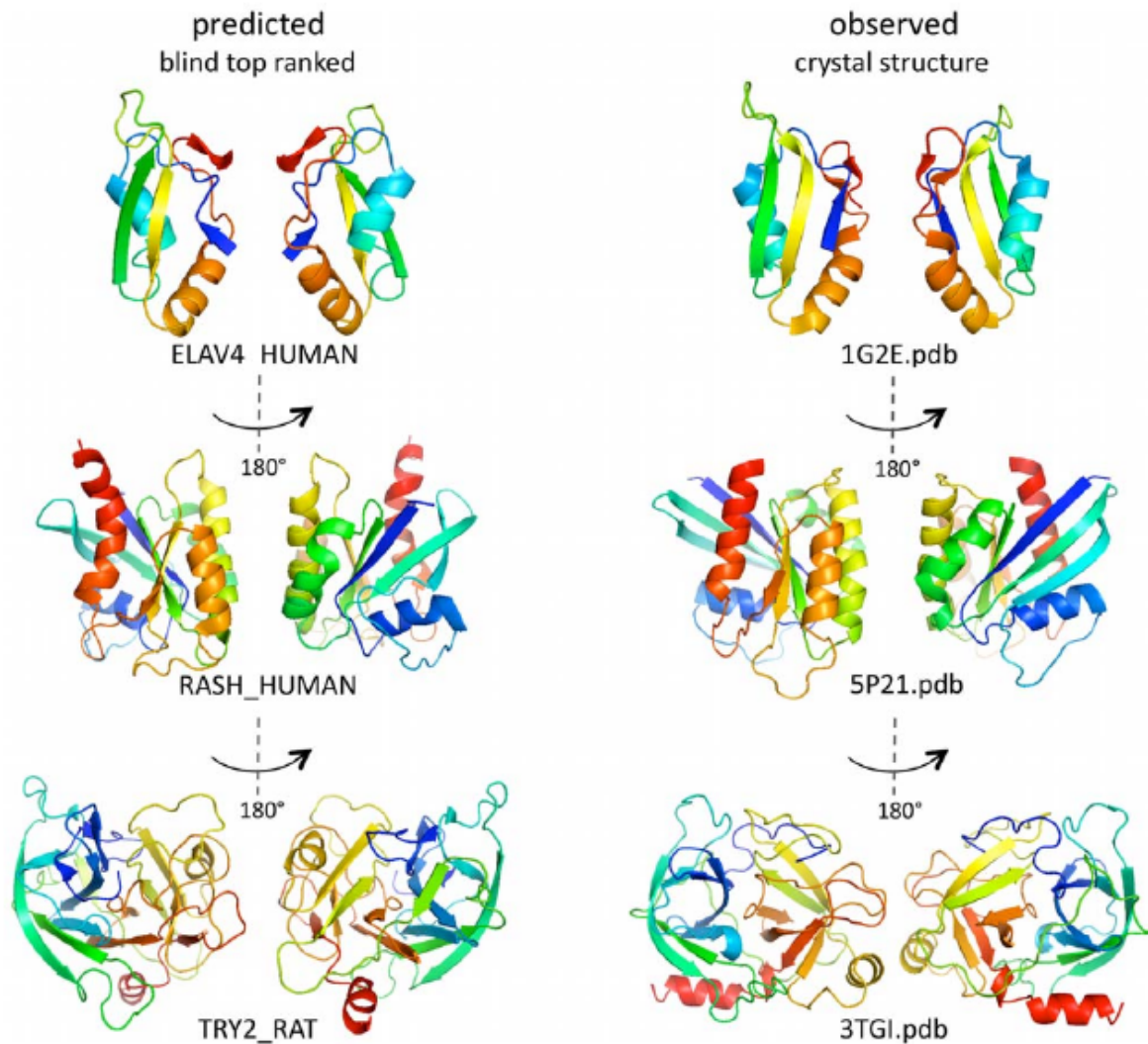
bad scores



Direct coupling analysis (DCA)

■ Full prediction of protein 3D structure from sequence data

Marks, Colwell et al. (2011):



Results for 3 proteins:
- predicted top ranked 3D structure (left)
- experimentally observed structure (right)
Each structure in front and back view

■ Limitations

- DCA requires large alignments of homologous proteins (~ a few hundreds)
- DCA requires a high diversity within these alignments

Inferring interaction partners from protein sequences

Anne-Florence Bitbol

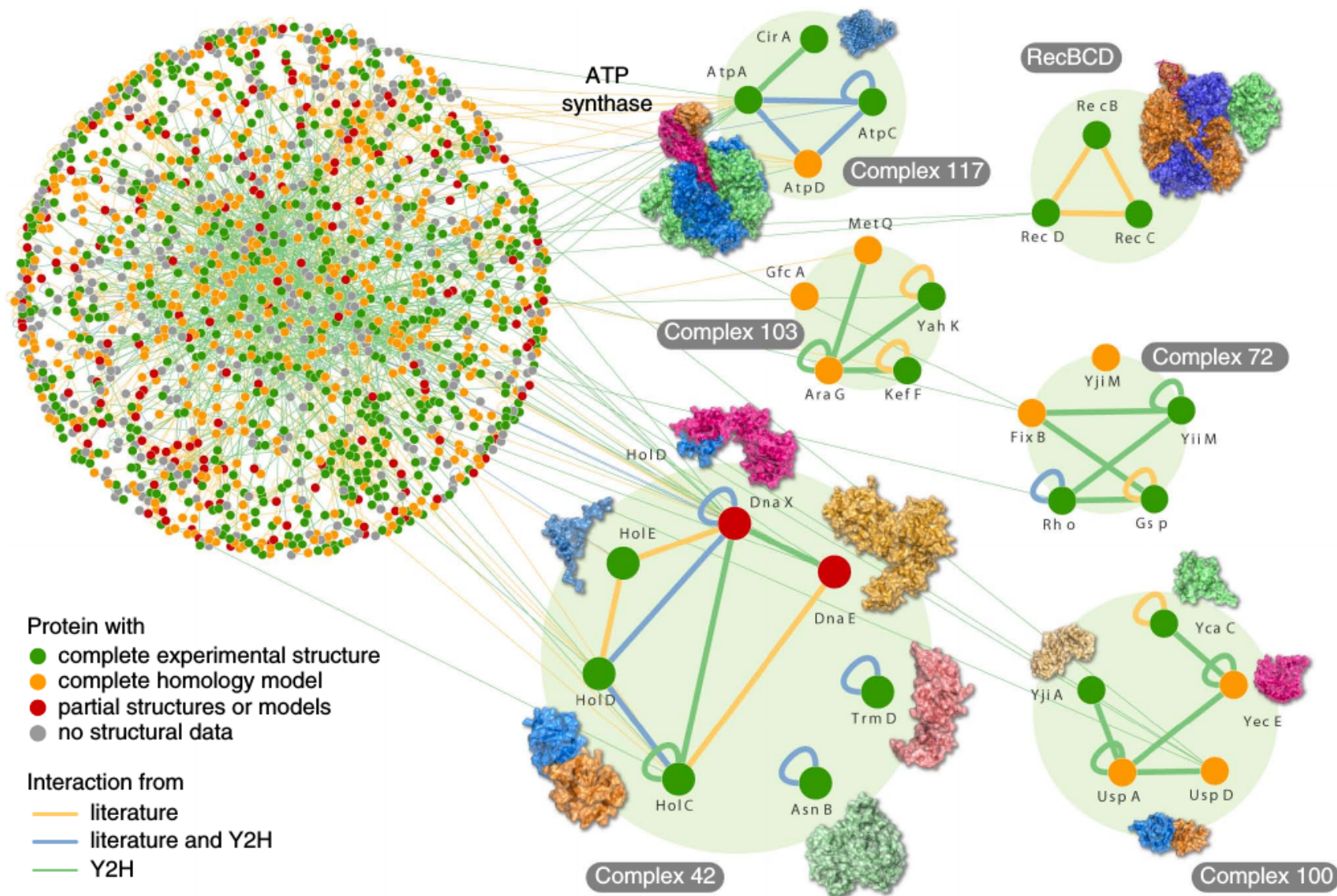
with Robert S. Dwyer, Lucy J. Colwell and Ned S. Wingreen



Introduction

■ Protein-protein interactions

- Crucial for functional multiprotein complexes, signaling pathways etc.
- Systematic experimental determination is tedious

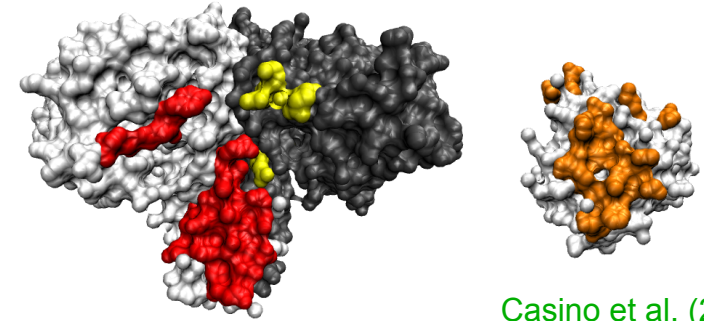
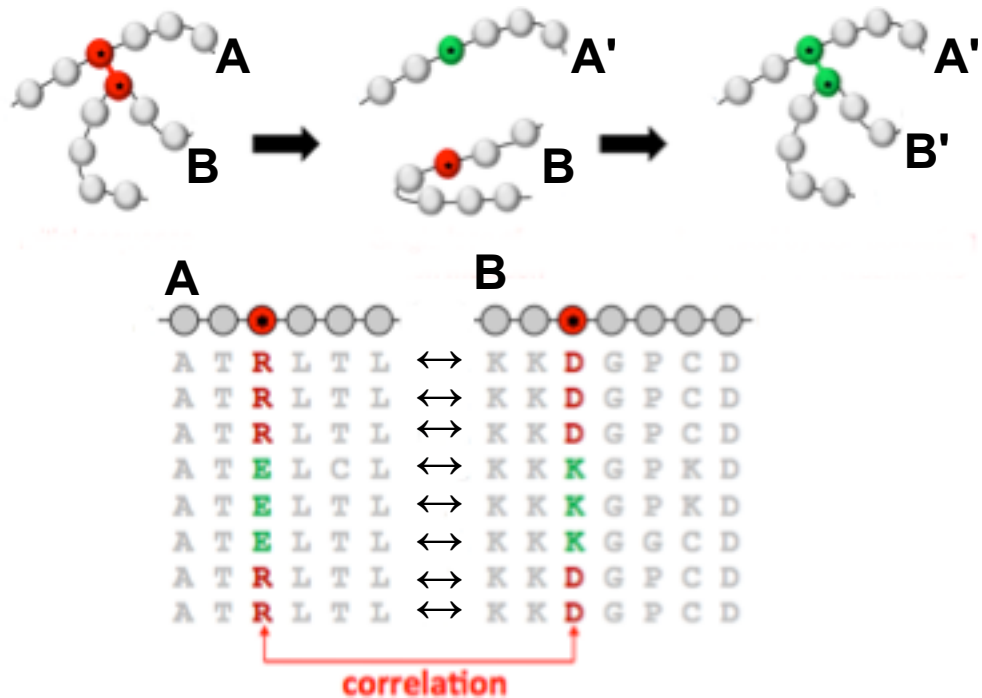


Binary PPI
in *E. coli*

Rajagopala et al. (2014)

Introduction

■ Co-evolution and correlations *between interacting partners*



Casino et al. (2009)

Often, several paralogs in each species

→ Can we use these patterns of correlations to infer specific interaction partners?

- (1) Do protein families A and B interact or not?
- (2) Within a species, which A interacts with which B?

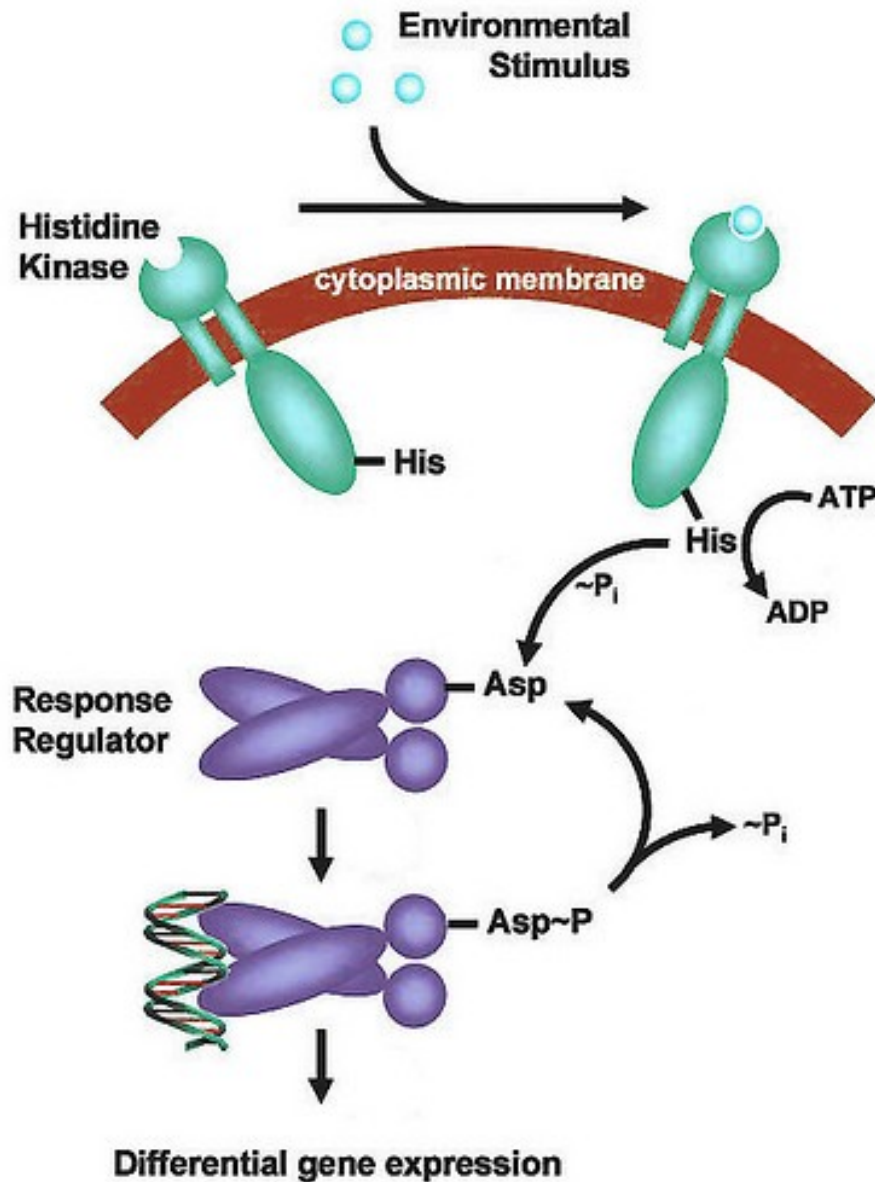
	A (HK)		B (RR)
Species 1	ISHEL	?	DGLPA
	VSHEL		NGLPV
	VSHDL		DGIEL
Species 2	ISHEI		NGLPL
	ISHDI		DGLPA
Species 3	ISHEL		NGLPA
	ISHDL		DGIEV
	VSHDI		DGIEA

(1) Do protein families A and B interact or not?

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Dataset

■ Bacterial two-component systems:

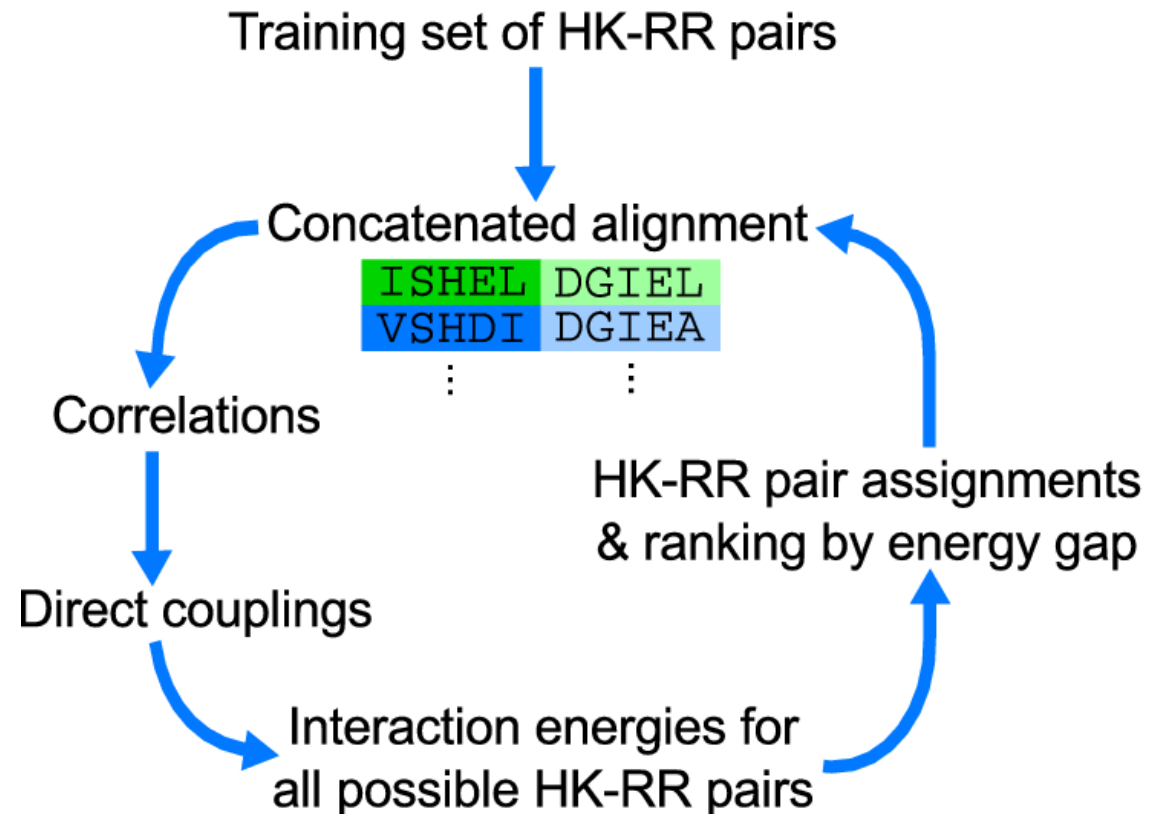
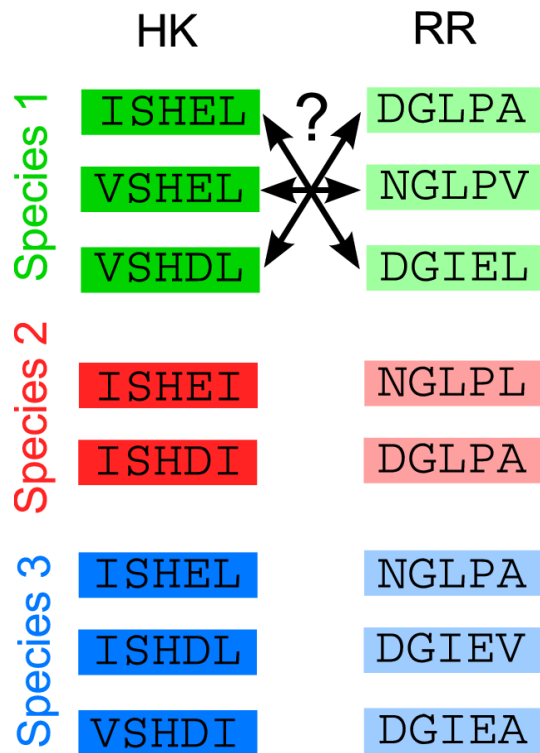


- Histidine kinase (HK)
- Response regulator (RR)

- Many fully-sequenced genomes (2,758 here)
 - Lots of known interaction partners
 - **Many paralogs** per species
- a **great benchmark**

Method

- Iterative pairing algorithm



Method

Correlations, direct couplings and interaction energies

ISHEL	DGLPA	→	{	$f_i(\alpha)$	$i \in \{1, \dots, L\}$
VSHDI	DGIEA			$f_{ij}(\alpha, \beta)$	$\alpha \in \{A_1, \dots, A_{20}, A_{21} = -\}$
⋮	⋮			$C_{ij}(\alpha, \beta) = f_{ij}(\alpha, \beta) - f_i(\alpha)f_j(\beta)$	

Pairwise maximum entropy model and direct couplings:

$$P(\alpha_1, \dots, \alpha_L) = \frac{1}{Z} \exp \left\{ - \left[\sum_{i=1}^L h_i(\alpha_i) + \sum_{i < j} e_{ij}(\alpha_i, \alpha_j) \right] \right\}$$

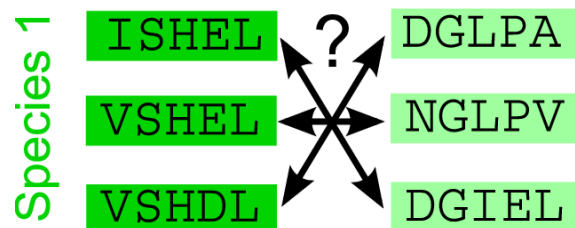
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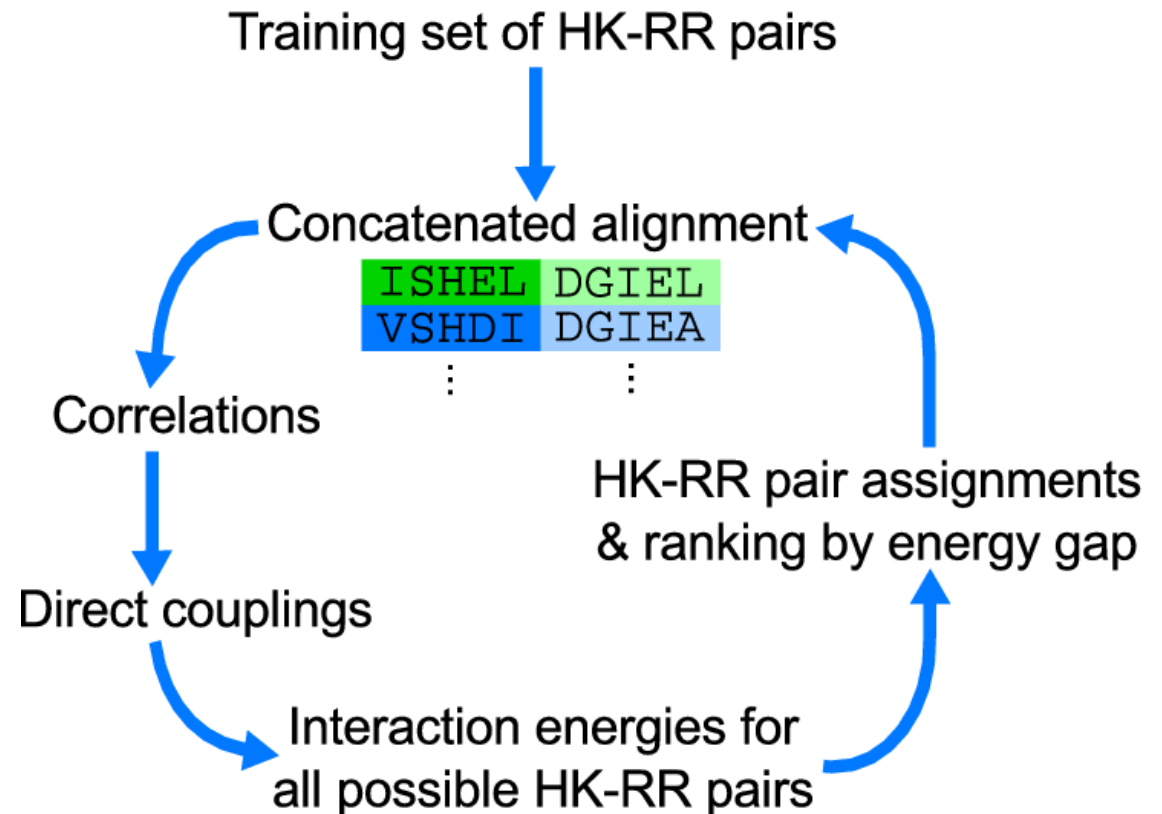
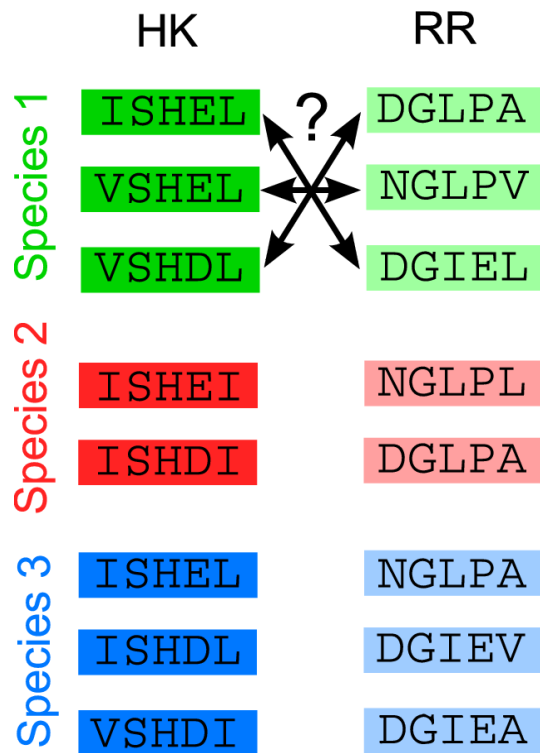
Interaction energies for all possible HK-RR pairs in each species:



$$E(\alpha_1, \dots, \alpha_{L_A}, \alpha_{L_A+1}, \dots, \alpha_L) = \sum_{i=1}^{L_A} \sum_{j=L_A+1}^L e_{ij}(\alpha_i, \alpha_j)$$

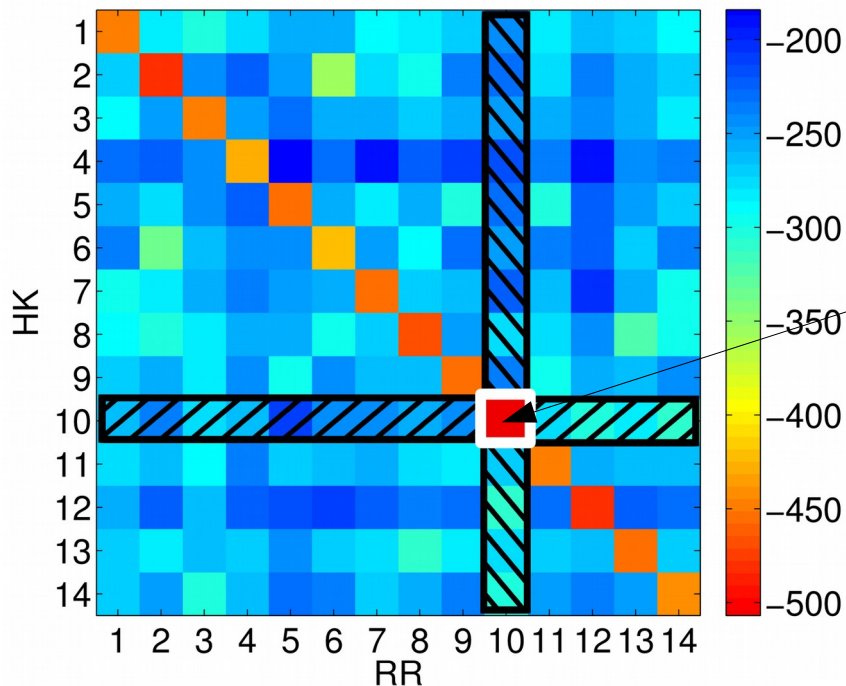
Method

- Iterative pairing algorithm



Method

■ HK-RR pair assignments and ranking by gap

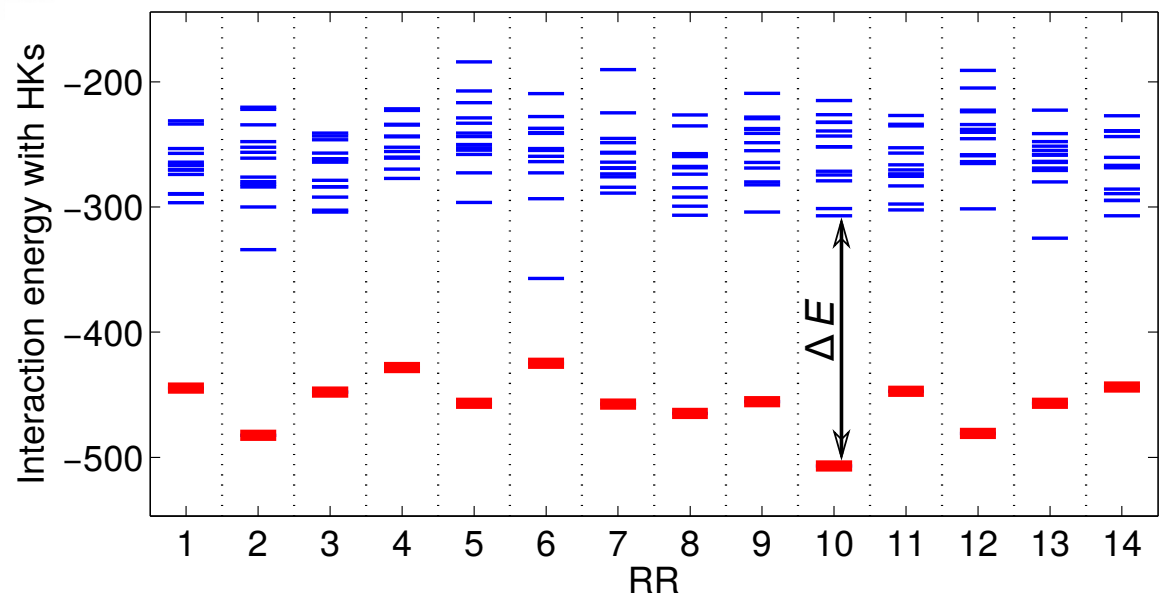


- Interaction energies between HK and RR from *E. coli* K-12 MG1655

Lowest energy
→ make this pair

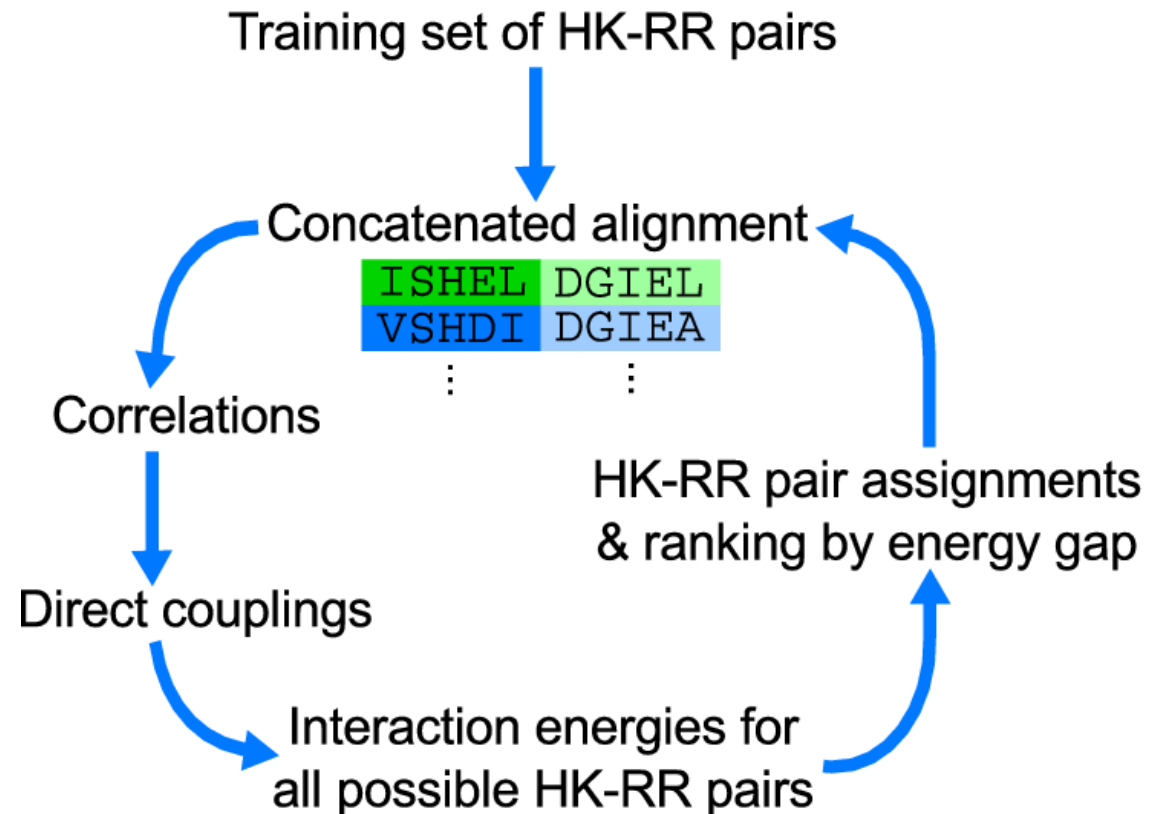
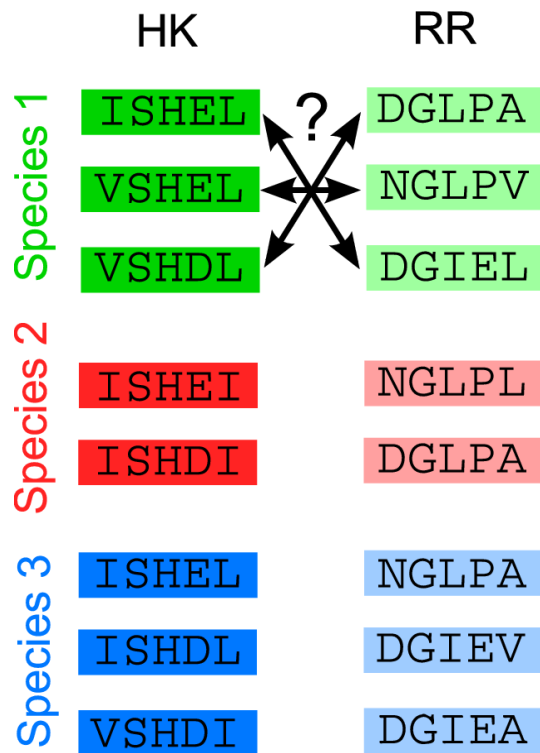
- Once a pair is made, suppress this HK and RR from further consideration (1 to 1 interactions)

- Energy gap → confidence score used to rank pairs
- Those with largest score are **included in the concatenated alignment (training set) at the next iteration**



Method

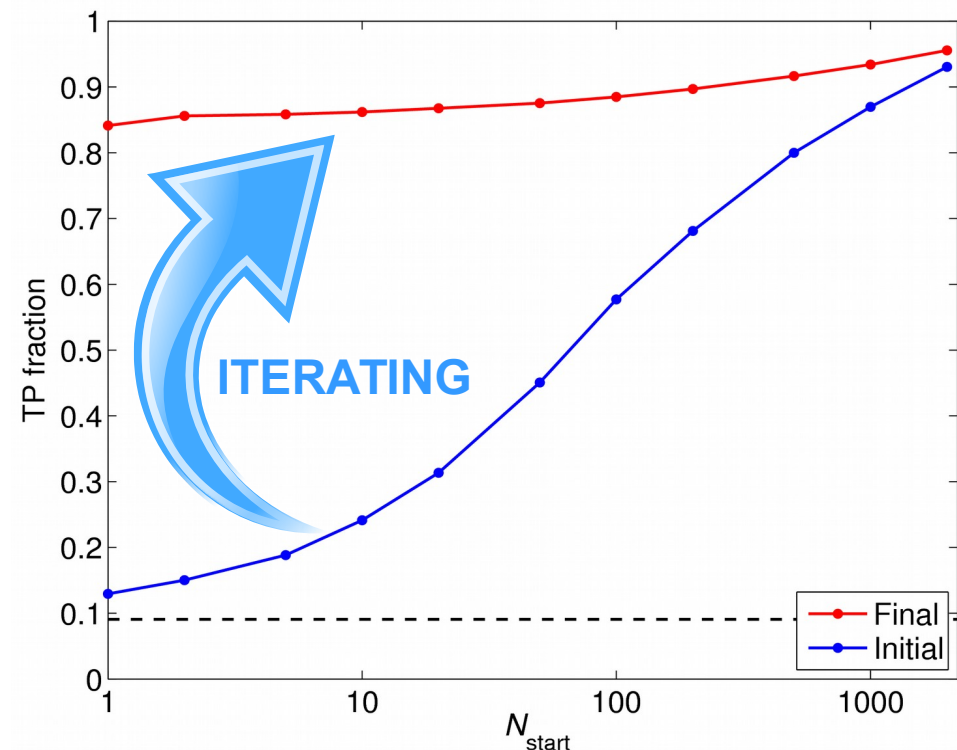
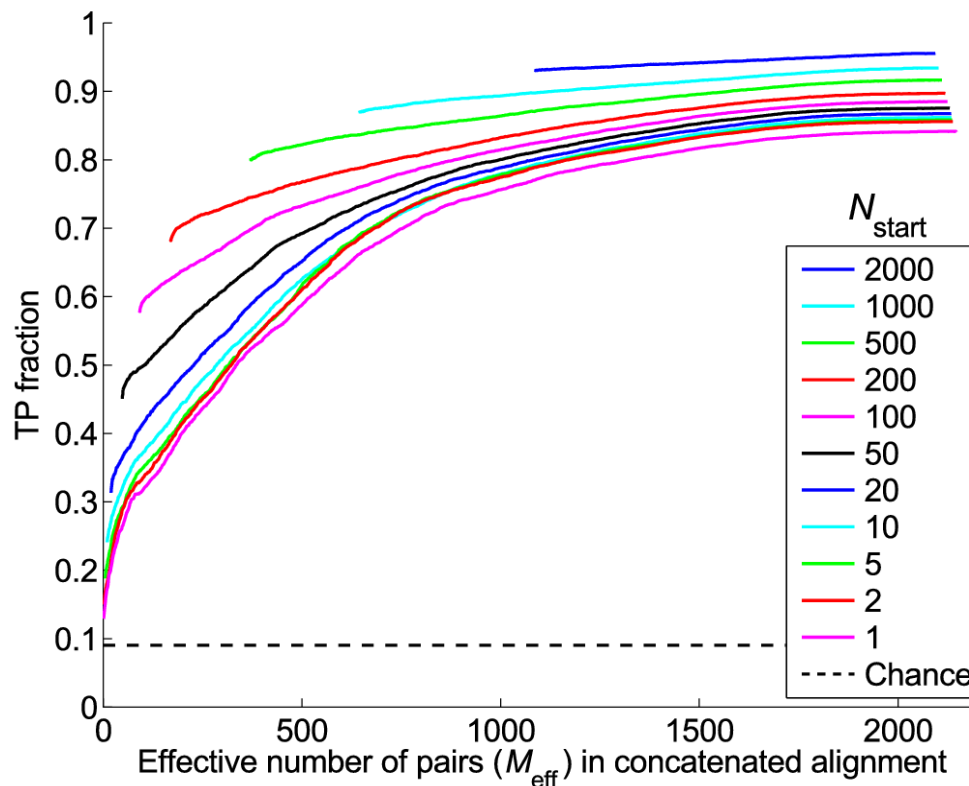
- Iterative pairing algorithm



Effect of training set size (Nstart)

■ Progression of TP fraction and final value vs. Nstart

Dataset: **5064** pairs, mean **11.0 /species**; $M_{eff}=2091$ (from full dataset with 23,424 pairs)
Nincrement=6; different Nstart (number of training HK-RR pairs)
Results averaged over 50 replicates, with different random choices of training pairs

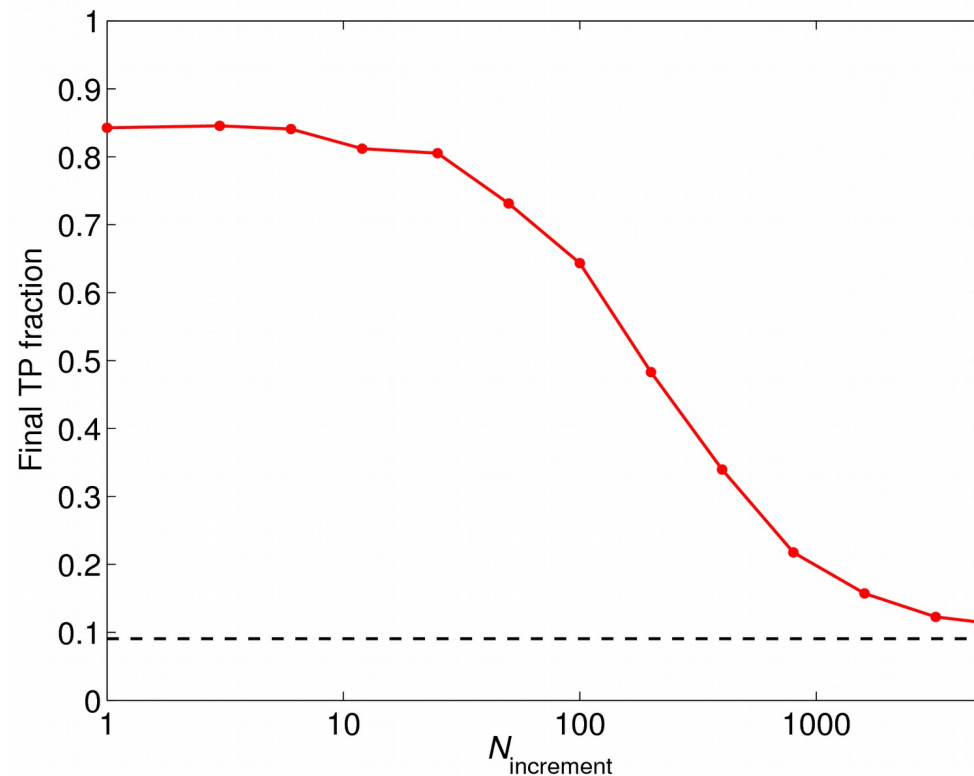
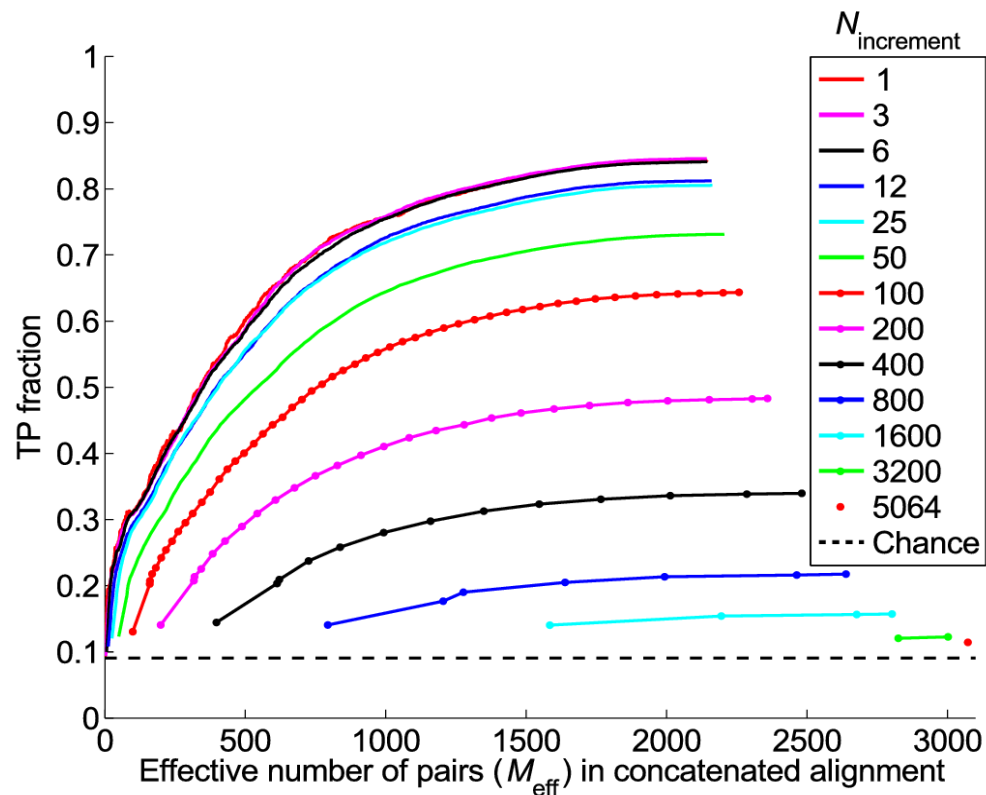


- High final TP fractions thanks to iterating
 - Weak dependence of the final TP fraction on Nstart
- **Can we do without a training set?**

Starting from random pairings

■ Progression of TP fraction and final value vs. $N_{\text{increment}}$

Starting from random within-species pairings; different $N_{\text{increment}}$
Results averaged over 50 replicates, with different initial random pairings

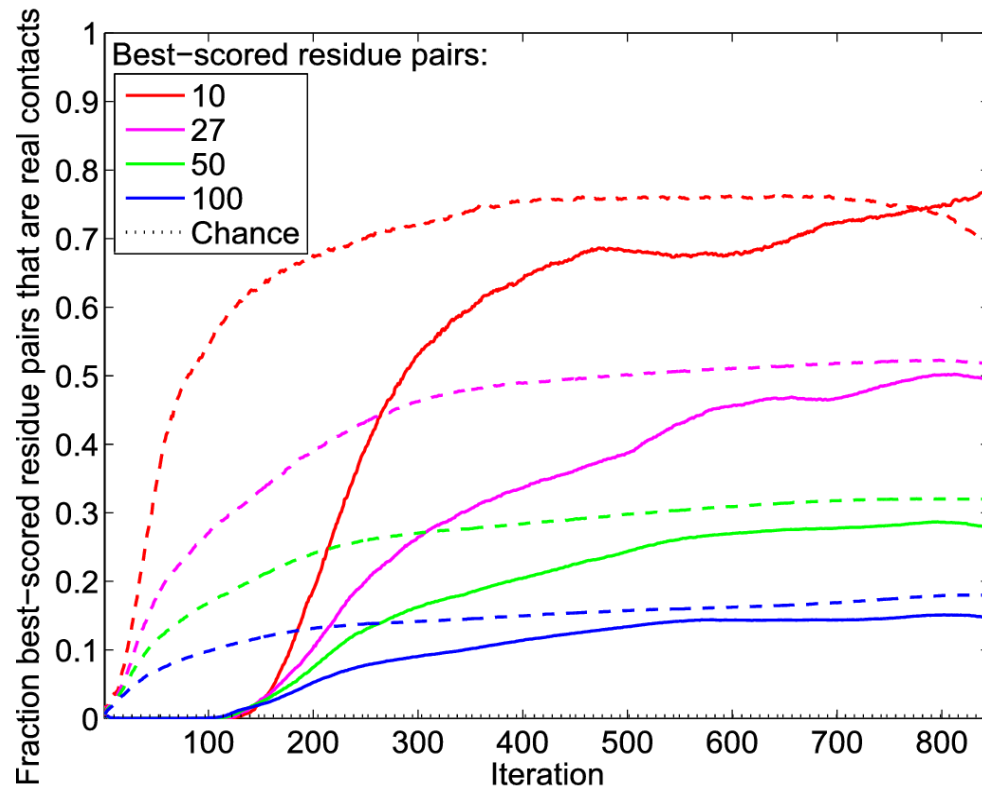


- Performance increases as $N_{\text{increment}}$ decreases
- With **no training set**, TP fraction **0.84** for $N_{\text{increment}}=6$ and lower; **robust**: std 0.04
- How does the TP fraction increase at early stages (in the concatenated alignment)?

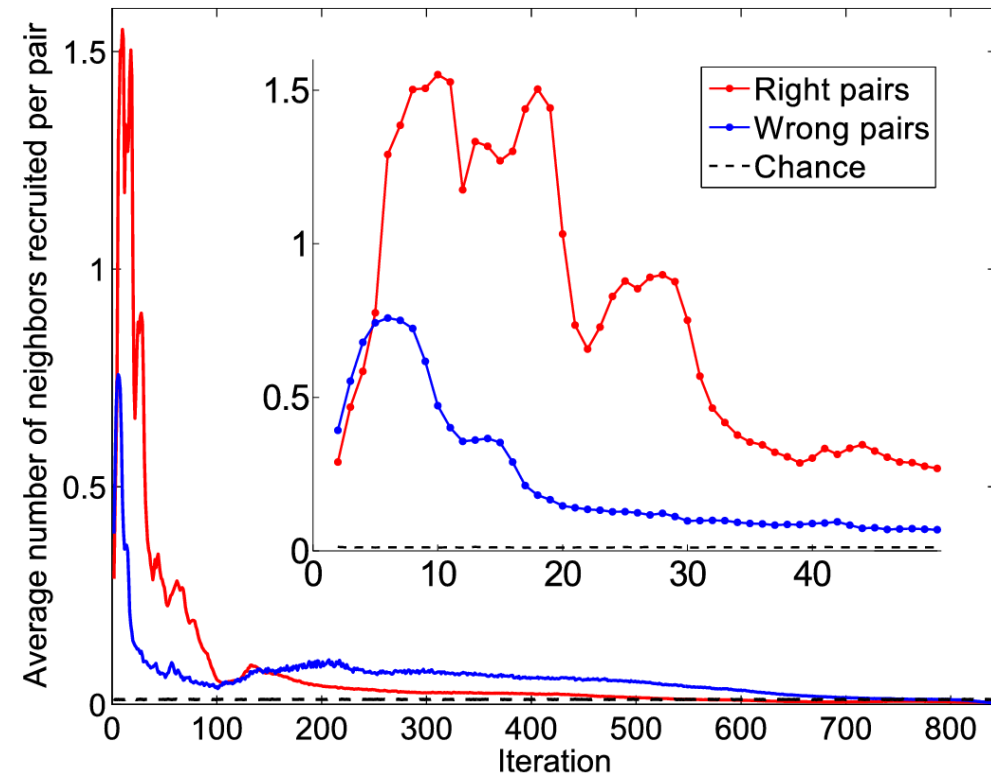
Training process

■ Evolution of the couplings and of the concatenated alignment

HK-RR residue pairs with highest Frobenius norm vs. actual contacts [Casino et al. \(2009\)](#)



Impact of sequence similarity in recruitment into the concatenated alignment



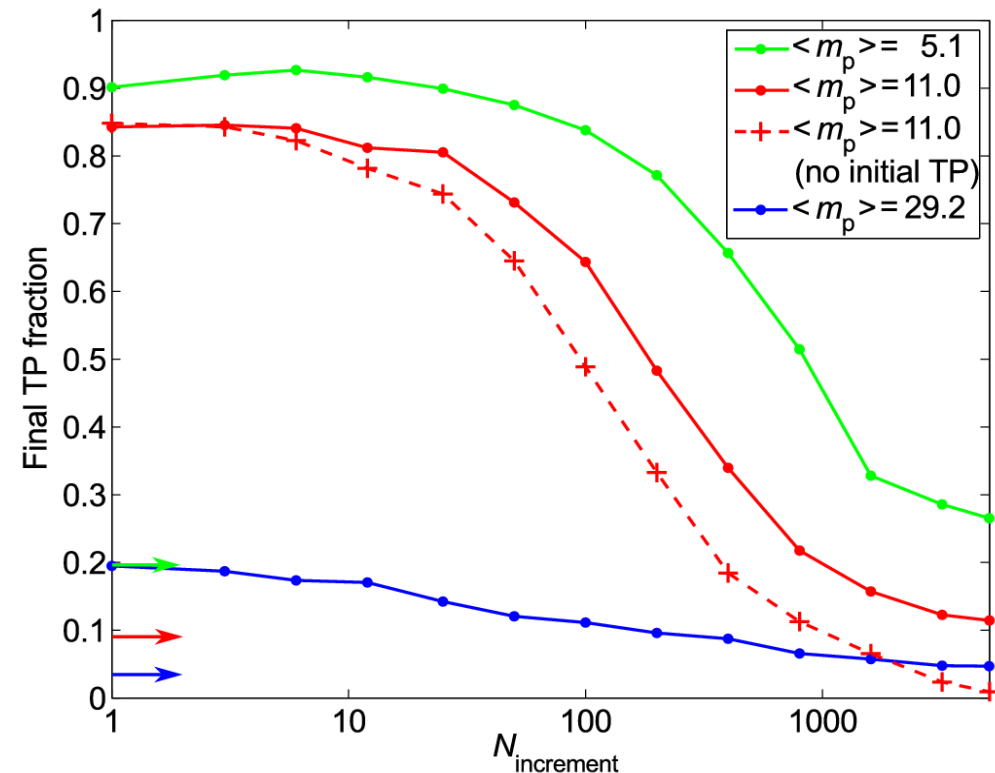
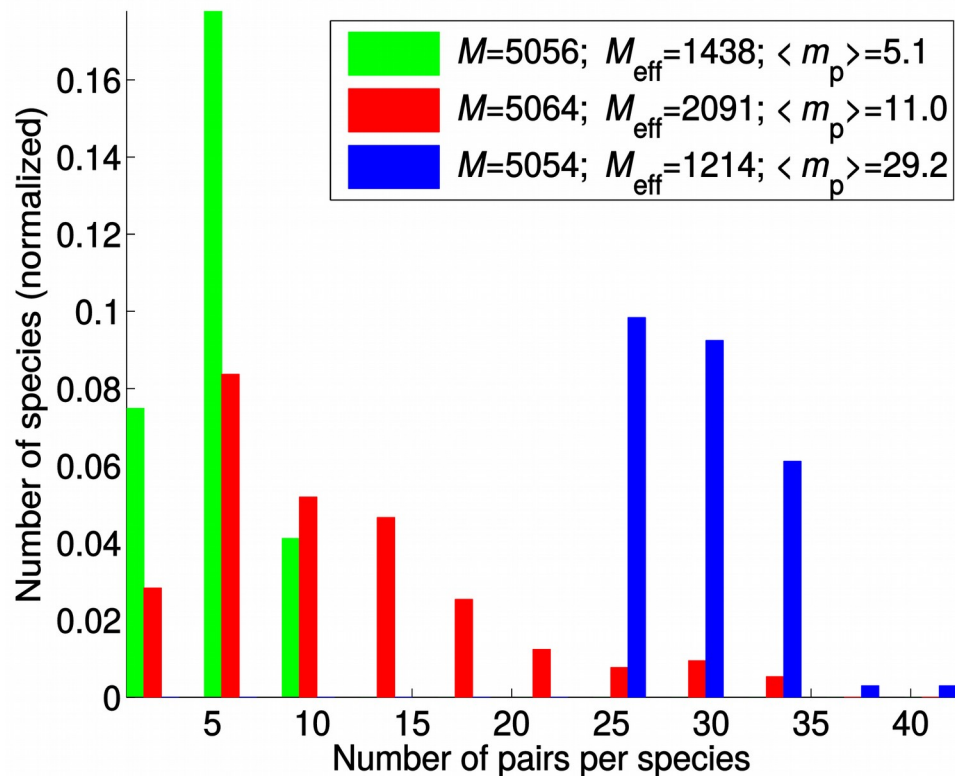
- Initially, models are no better than chance, but they improve a lot upon iterating
- Initially, **sequence similarity** is crucial to recruitment into the concatenated alignment
→ **Favors correct pairs, which have ~2x more neighbors**

Impact of the number of pairs per species

- Consider 3 datasets with the same number of sequences

- Standard (random) extract from the full dataset
- Extracts with fewer / more pairs per species

→ Starting from random pairings:
final TP fraction vs. $N_{\text{increment}}$



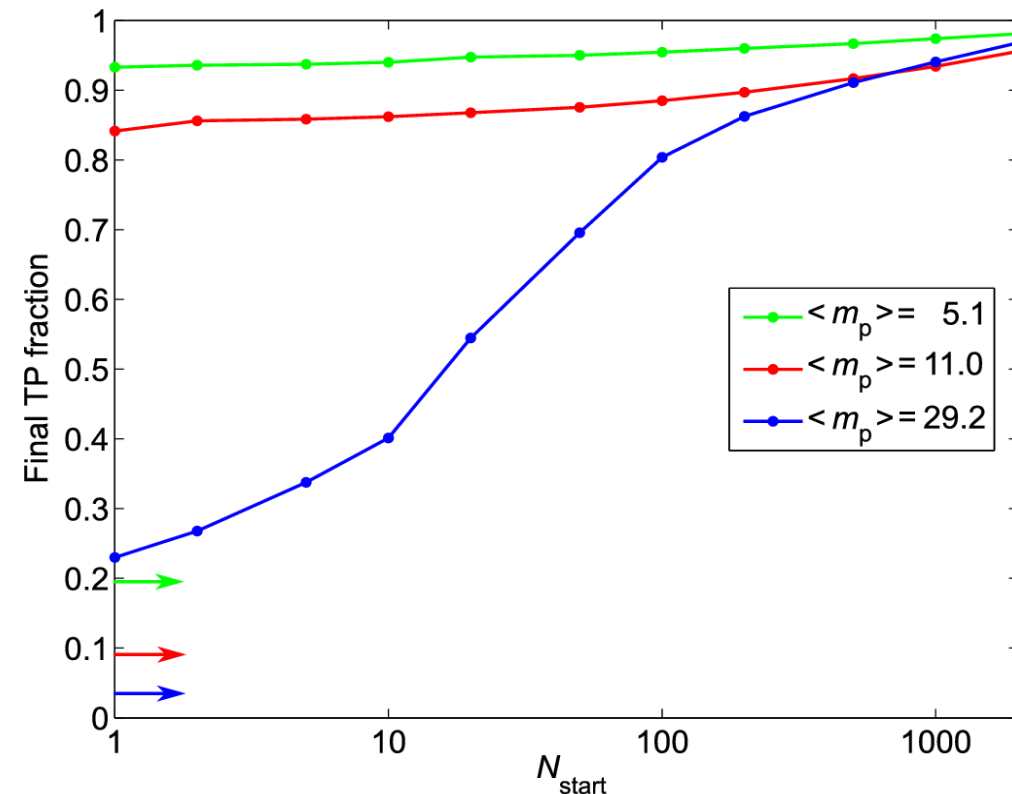
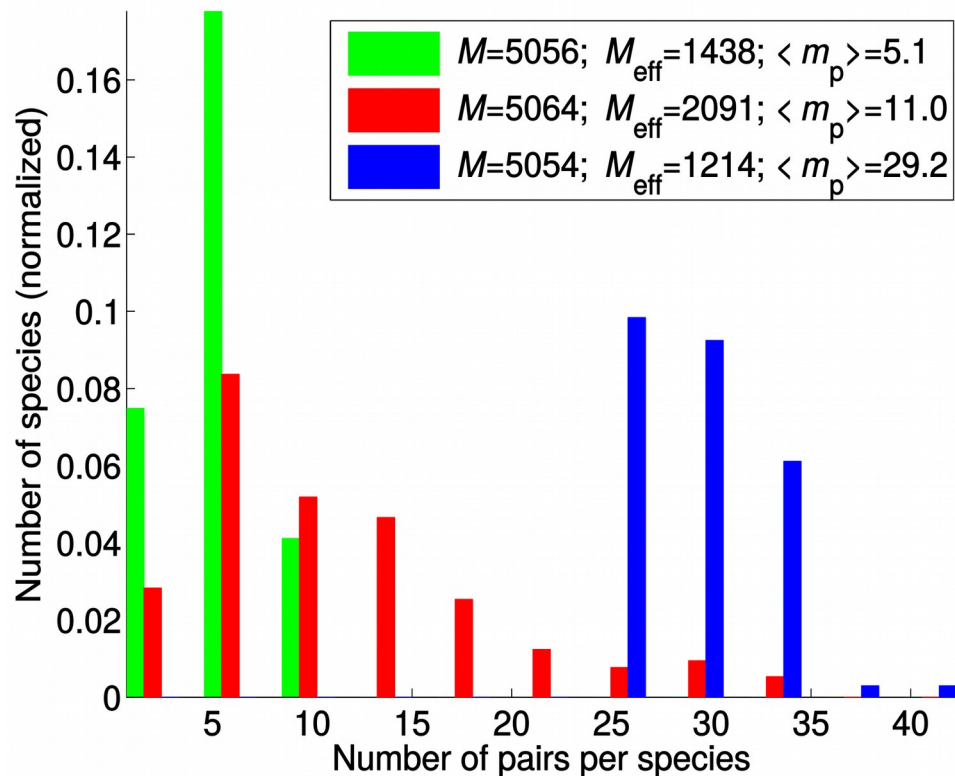
→ Species with few pairs are important

Impact of the number of pairs per species

- Consider 3 datasets with the same number of sequences

- Standard (random) extract from the full dataset
- Extracts with fewer / more pairs per species

→ with a training set: final TP fraction vs. N_{start} ($N_{\text{increment}}=6$)

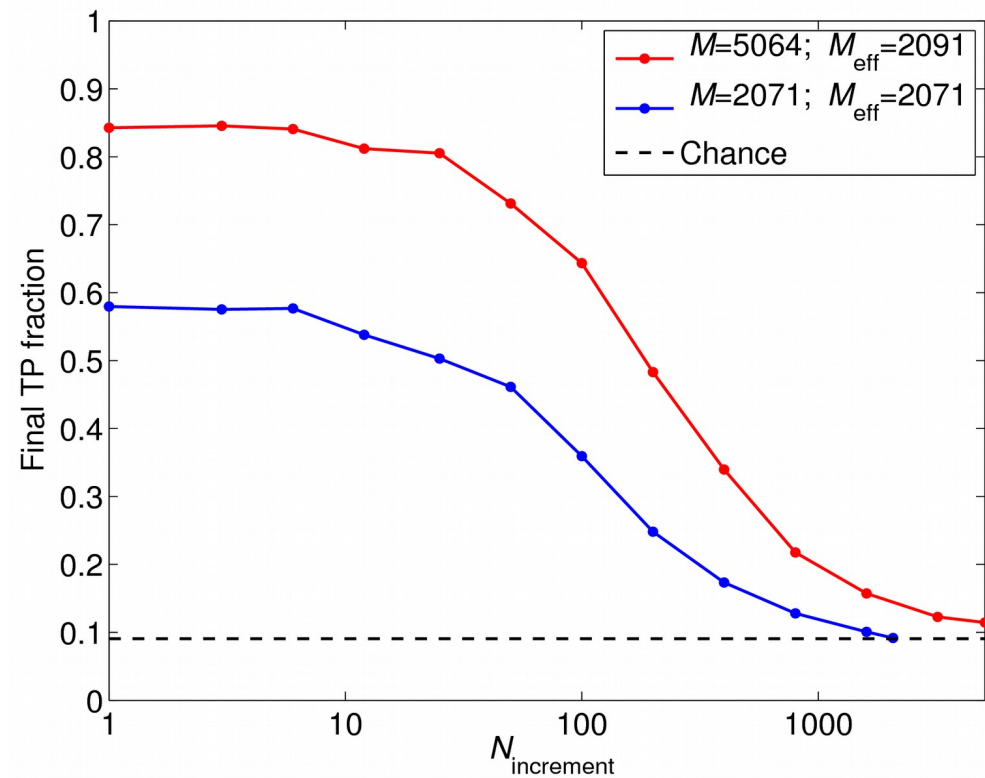
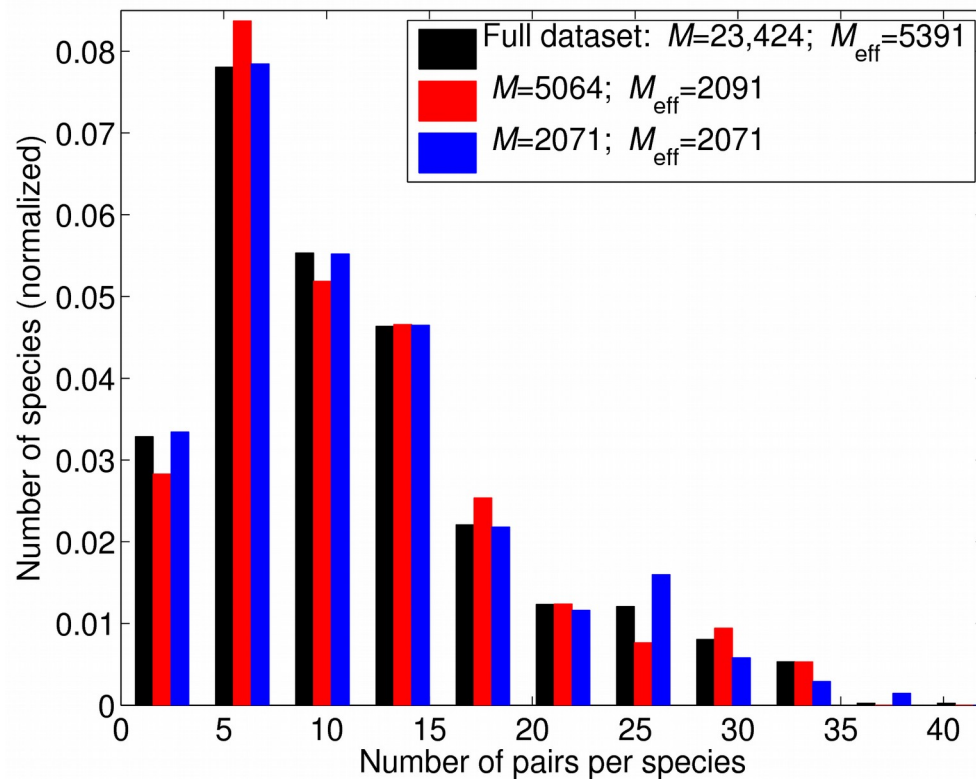


→ **Species with few pairs are important**
... but if there are none, a (sufficiently large) training set yields good final TP fractions

Impact of sequence similarity

Consider two datasets

- Standard (random) extract
- Extract with **distant sequences** (Hamming distance ≥ 0.3); same numbers of pairs / species

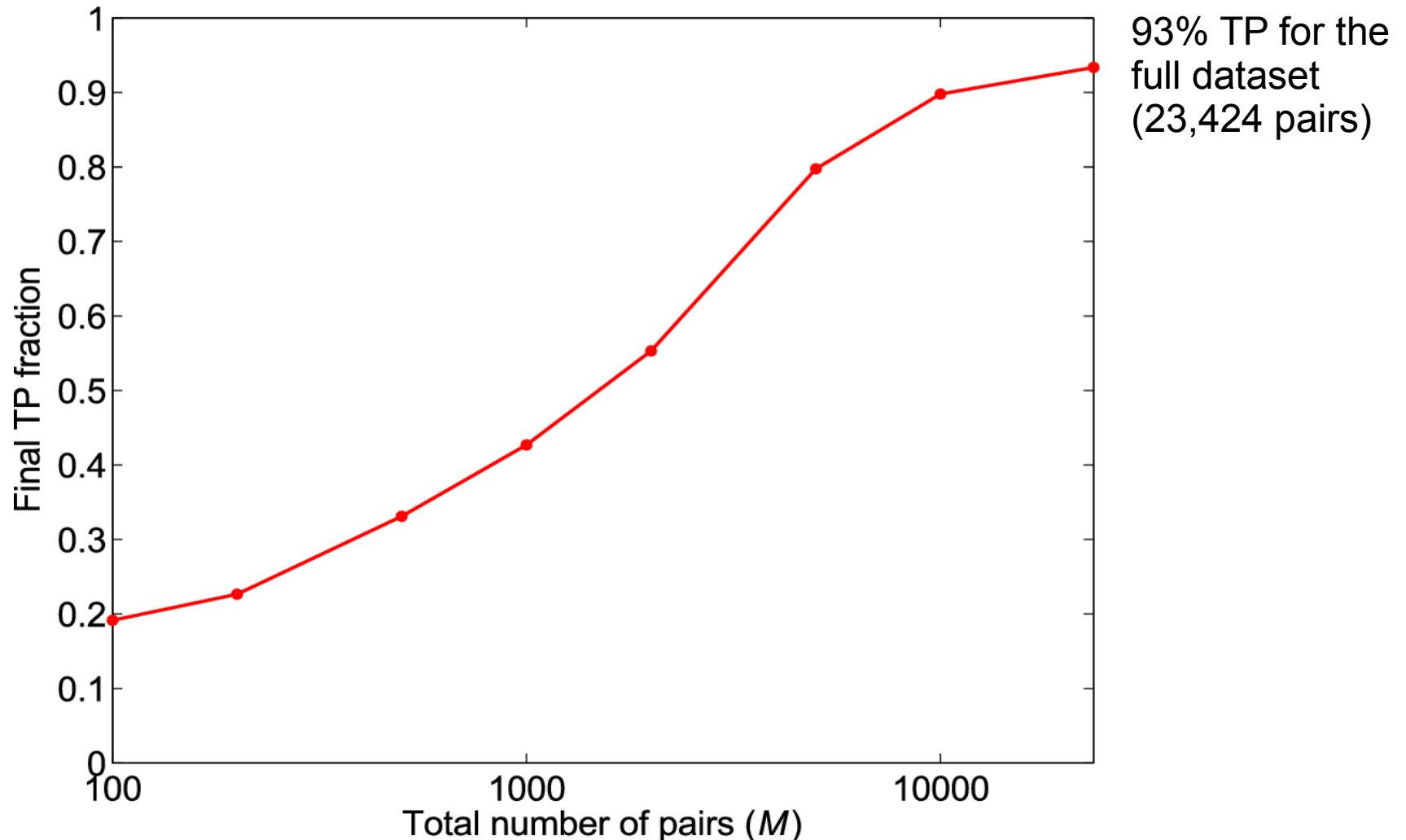


- Sequence similarity does help
- However, the TP fraction remains quite high

Impact of the dataset size

- Starting from random pairings: final TP fraction vs. alignment size

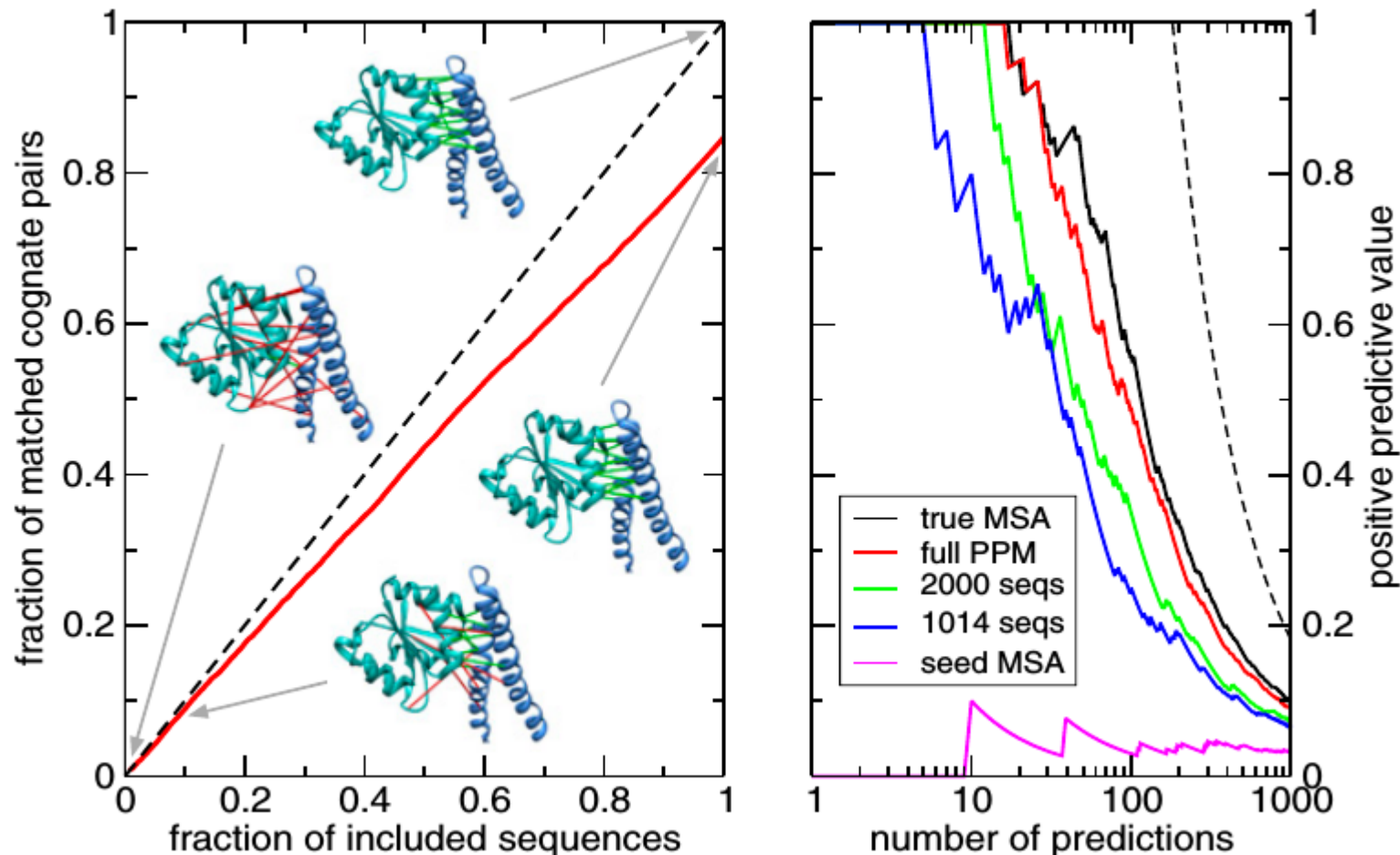
Different dataset sizes (from different numbers of picked species); **small N** increment
Results averaged over 50-500 replicates with different random pickings of species



Simultaneous prediction of complex structure

- Top inter-protein couplings = inter-protein contacts

Gueudre et al. 2016 (published back-to-back with currently presented work)



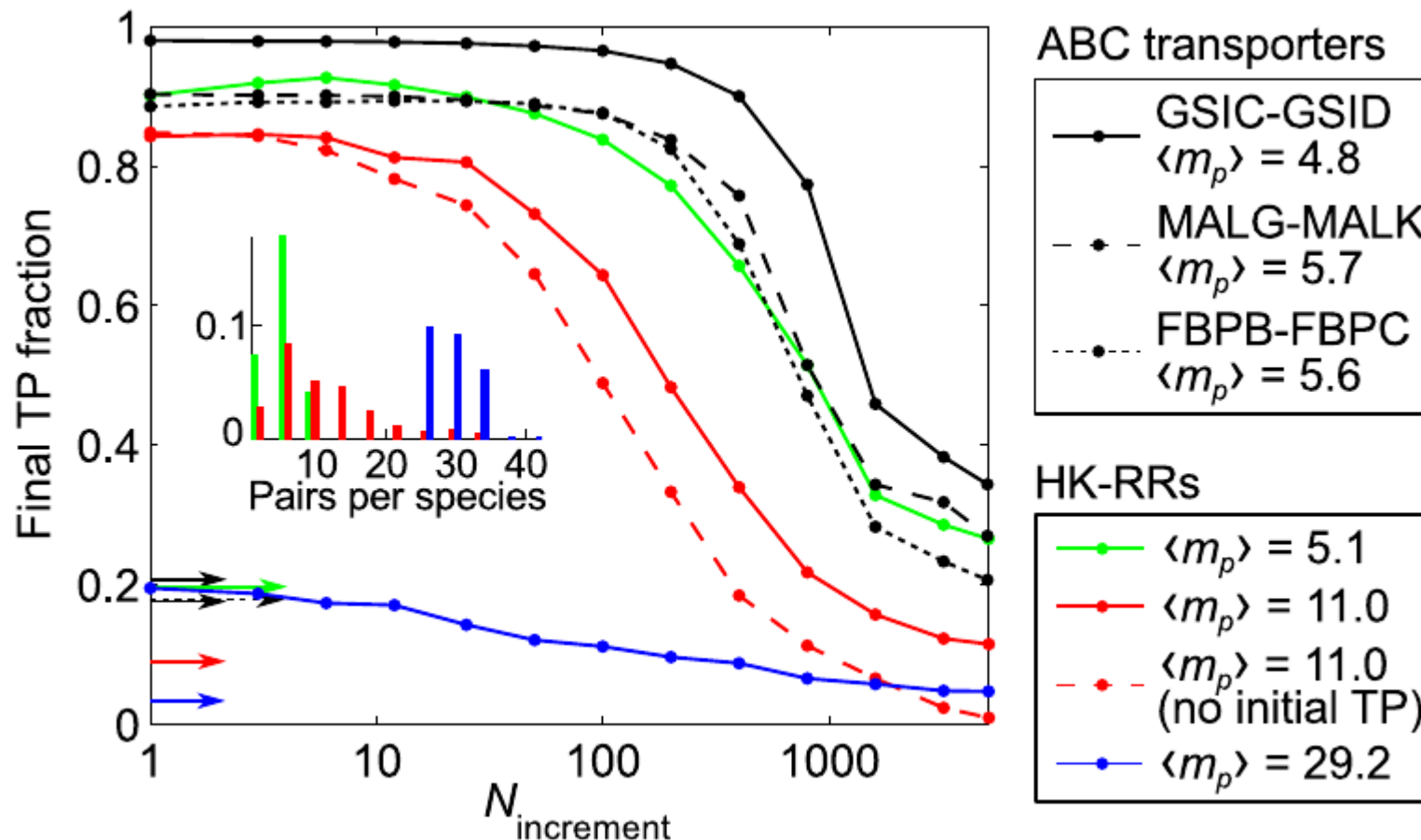
(1) Do protein families A and B interact or not?

(2) Within a species, which A interacts with which B?

Beyond HKs and RRs: ABC transporters

Very good performance in this case too

(starting from random pairings; 50 replicates)



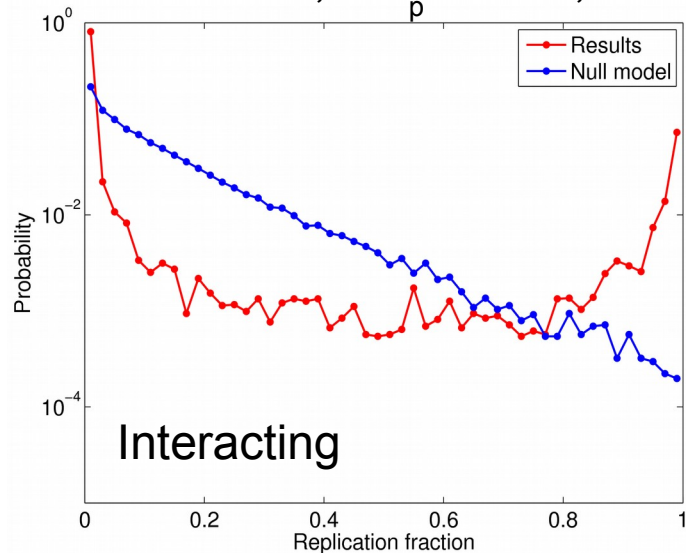
A very different biological case

→ The IPA should be widely applicable

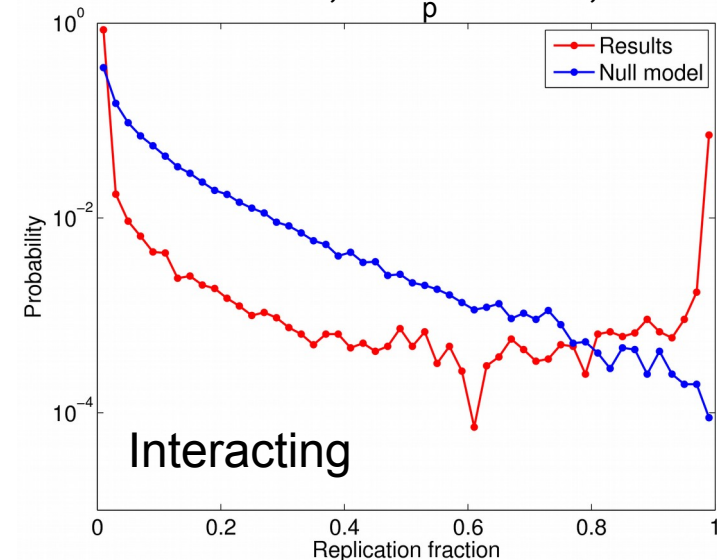
Do protein families A and B interact?

- Exploiting different random initializations
→ Distribution of the replication fraction - HK-RRs + ABC transporters

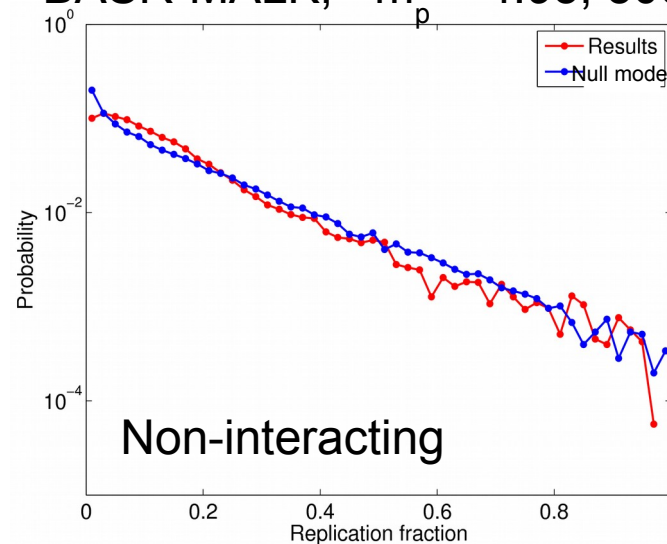
BASS-BASR, $\langle m_p \rangle = 5.50$, 5012 pairs



MALG-MALK, $\langle m_p \rangle = 5.69$, 5004 pairs



BASR-MALK, $\langle m_p \rangle = 4.95$, 5001 pairs



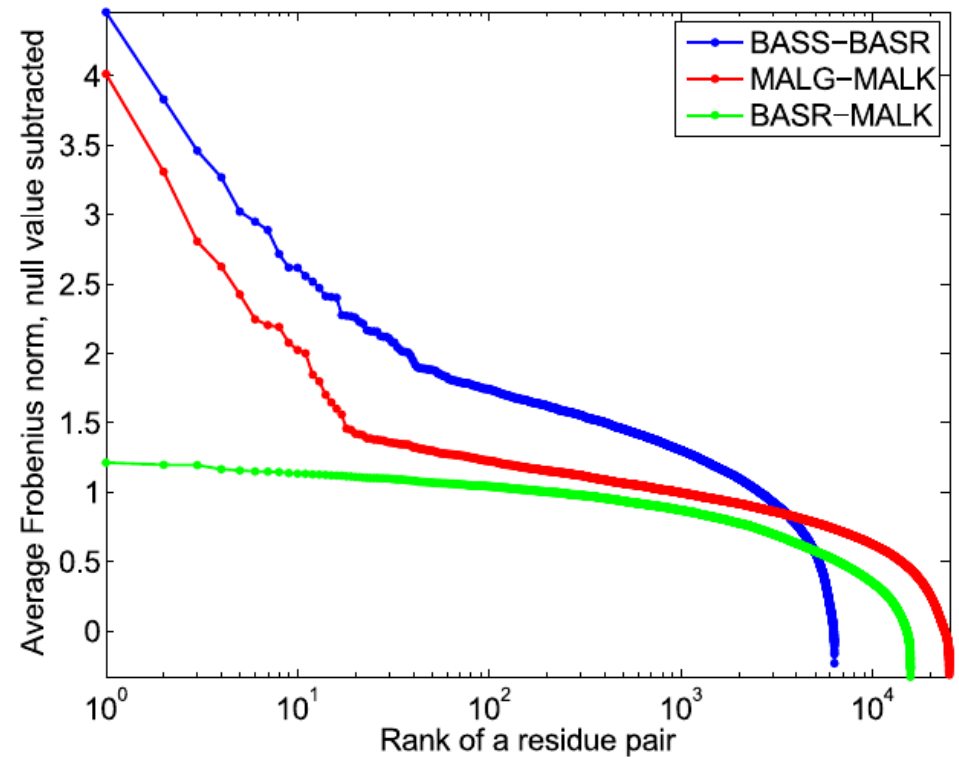
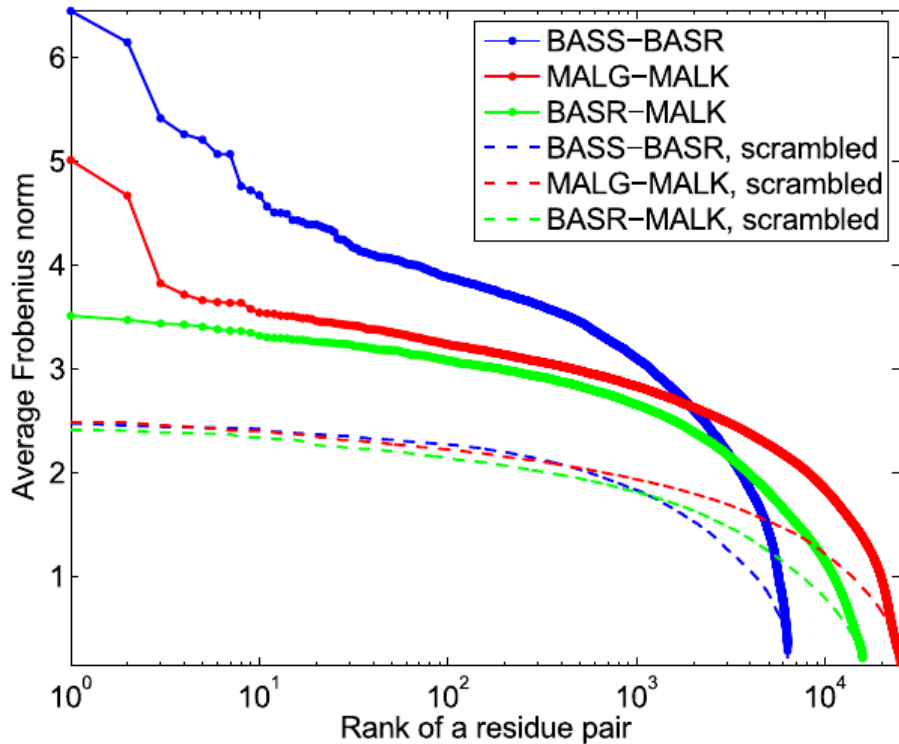
→ Bimodal distribution:
a signature of interactions

(Nincrement=50, 500 replicates)

Do protein families A and B interact?

■ Importance of the couplings for the same datasets

(Nincrement=50, 500 replicates)



→ The strongest couplings are outliers for interacting pairs, not for non-interacting ones

Conclusion

■ Summary

- Iterative method
- High performance even with **no initial training set**

■ Perspectives

- **Partnership prediction for orphan HK and RR**
→ current work with Mohamed Barakat, Philippe Ortet & Ned Wingreen
- Choosing among paralogs in other protein families
- Improving complex structure prediction
- **Prediction of novel protein-protein interactions**
→ current work with Yaakov Kleeorin & Ned Wingreen
- **Understand better how the algorithm “starts from nothing”**
→ current work with Pierre Mergny & Martin Weigt

■ Acknowledgements

Ned Wingreen, Princeton University
Lucy Colwell, Cambridge University
Rob Dwyer, Princeton University

Mohamed Barakat & Philippe Ortet, CEA Cadarache (P2CS)



■ Reference

Bitbol AF, Dwyer RS, Colwell LJ, Wingreen NS, PNAS 113 (43), 12180-12185 (2016)

Thanks!