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Plan of Talks:

Talk 1: Hyperbolic geometry, ideal tetrahedra, hyperbolic 3-manifolds

Talk 2: Hyperbolic knots, ideal triangulations, Example, SnapPy

Further reading: https://www.math.csi.cuny.edu/abhijit/hypknots-reading.html



Aug 27th 2018



1) Geometries 2-dim - 1E2, 52 H2 - hypeobolic geometry

In geometry, the **parallel postulate**, also called **Euclid's fifth postulate** because it is the fifth postulate in Euclid's *Elements*, is a distinctive axiom in Euclidean geometry. It states that, in two-dimensional geometry:

If a line segment intersects two straight lines forming two interior angles on the same side that sum to less than two right angles, then the two lines, if extended indefinitely, meet on that side on which the angles sum to less than two right angles.

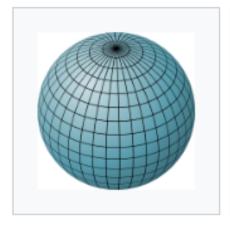
Probably the best known equivalent of Euclid's parallel postulate, contingent on his other postulates, is Playfair's axiom, named after the Scottish mathematician John Playf

In a plane, given a line and a point not on it, at most one line parallel to the given line can be drawn through the point. [4]

The parallel postulate seems natural enough, but it's the kind of statement that seems like it should be a theorem—something we prove using other axioms and postulates—rather than a postulate. For 2000 years, mathematicians tried to prove this, to show that the parallel postulate could be derived from the other axioms and postulates. (For the

The resulting geometries were later developed by Lobachevsky, Riemann and Poincaré into hyperbolic geometry (the acute case) and elliptic geometry (the obtuse case). The independence of the parallel postulate from Euclid's other axioms was finally demonstrated by Eugenio Beltrami in 1868.











genus 0

genus 1

genus 2

genus 3

Uniformization of Surfaces - closed orient surface Mg genus g

\$ 0 \$

5 susface

$$X(S)$$
  $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$   $= 0$ 

most surfaces are hyp.

3-dim 8 Geometries:

Geometrization of 3-mfds (Thurston, Perelman) \$\frac{1}{5^2} \text{IE} & H\square X\text{E} products

Nil & SL2 & +wisted products

understood in terms of Surfaces

as Seifert fibered spaces (SFS)

or toxus semi-bundles

Most interesting geometry is H3.

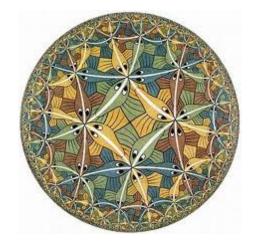
## 2) Hxp. plane H2



Upper half-plane



Poincare disk



Crochet by Diana Tiamina





Thorocycle Upper half plane

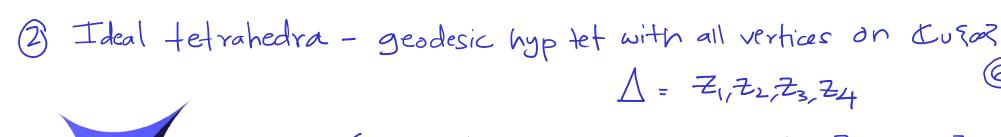
Cx Geodesics - verticle half lines or semi-circles centered on x-axis

Circle at 00 = 1RU303 |Som+(H) = PSL(Z/R) acts as Möbius toansf. = 3 az+b / a,b,c,d & R?

H3= \(\times(\times)/t\) / t\> 07 Upper half space Hi3- hyp 3-space géodesics T lines & circles on 10503 horosphores xy-plane v 7027 = Sphere at infinity = (1363)

Loom (H13) = PSL(2,4) acts as Middle transfon & 1903

Horospheres - scaled Euclidean planes, centered at  $\infty$   $ds_{H}^{2} = dx_{+}^{2} + dy_{-}^{2} + dt_{-}^{2}$  t = fixedHorospheres - scaled Euclidean planes, centered at  $\infty$  t = fixed





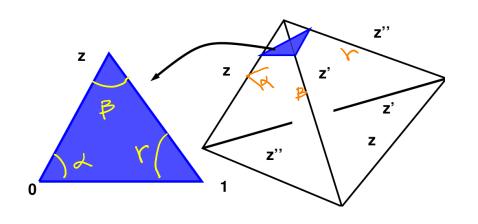
An Ideal Tetrahedron in Poincare ball model Cross ratio: [Z1, Z2, Z3, Z4] = Z4-Z1 Z3-Z2

a "geometric invariant" of ideal tet.

> (0: (Z1, Z2, Z3, Zu) + ) (0,00,1,Z) Mobius bank Z = Cross ratio

edge parameters for ideal tet. Z, 艺=上, 艺= 型

cross vatio charges like this when you change order of vert reeping orient.



dip, r are dihedral angles of A

(>) Isom classes of (>) \(\frac{7}{2}\)\[\tau\_{(\frac{1}{2})}\[\tag{7}\] ideal tet

Volume of ideal tet.

Lobachevsky fn  $\Lambda(\Theta) = -\int_{0}^{\Theta} \log |2 \sin t| dt$ 

Thm Let Tapp be ideal tet with dinedral angles  $\alpha, \beta, \gamma$ . The  $vol(T_{a,\beta,\gamma}) = \Lambda(\alpha) + \Lambda(\beta) + \Lambda(\gamma)$ 

Eg. i) Ideal tet of max volume = T = reg. ideal tet

Vol = 3 / (173) × 1.0149 ... = Vtet

Dilogarithm:  $L_{12}(z) = \sum_{n \geq 1} \frac{z^n}{n^2}$ 

(Kummer)  $Im(Li_2(z)) = \Lambda(argz) + \Lambda(argz') + \Lambda(argz'')$ - 109 121 arg (1-2)

Block-Wigner dilog: D(Z) = Im(Liz(Z)) + log(Zlarg(1-Z) = vol(A(Z))

## **Motivation**



In 1980s, the discovery of two different types of knot invariants revolutionized research in knot theory.

Vaughan Jones used representation theory and discovered the Jones polynomial, which resulted in the theory of quantum invariants of knots.



Bill Thruston used hyperbolic geometry to introduce geometric invariants, which resulted in geometric invariants of knots.



Relating quantum knot invariants to geometric invariants of knots is a very active area of research.

Hyp 3-mfds

M be fin vol., complete, orient hyp 3-mfd

M hyp:

(2) P: H3 > M covering map + local isometry

(3) So: TI, M -> PSL(2, C) discrete + faithful

Tomorrow - Structure on hyperbolic 3-manifolds, Hyperbolic knots, Thurston's gluing equations, Examples, SnapPy