# Distribution of Values on Quadratic Surfaces 

## O. Sargent

Groups Geometry and Dynamics, 2012

## Motivation

Consider the following:

- $P: \mathbb{R}^{d} \rightarrow \mathbb{R}^{s}$ a polynomial map.
- $X \subseteq \mathbb{R}^{d}$ defined over $\mathbb{Q}$ such that $\left|X \cap \mathbb{Z}^{d}\right|=\infty$.


## Question

What can one say about $P\left(X \cap \mathbb{Z}^{d}\right) \subseteq \mathbb{R}^{s}$ ?

- When is it dense? (conditions on $P$ and $X$ ?)
- If it is dense, then exactly how dense?


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## Special Cases

## $X=\mathbb{R}^{d}, P=\left(L_{1}, \ldots, L_{s}\right)$ a linear map.

- If $s<d$ and $\alpha_{1} L_{1}+\cdots+\alpha_{s} L_{s} \notin \mathbb{Q}$ unless $\alpha_{i}=0$ for all $i$, then $\overline{P\left(\mathbb{Z}^{d}\right)}=\mathbb{R}^{s}$.
- Classical.


## $X=\mathbb{R}^{d}, P$ a quadratic form.

- If $d>2$ and $P$ is indefinite, non degenerate, not a multiple of a rational form, then $\overline{P\left(\mathbb{Z}^{d}\right)}=\mathbb{R}$.
- Oppenheim Conjecture, proved by G. Margulis in 1989.


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Today: Another Special Case (Density).

- $Q: \mathbb{R}^{d} \rightarrow \mathbb{R}$, indefinite quadratic form, non degenerate, rational coefficients.
- $M=\left(L_{1}, \ldots, L_{s}\right): \mathbb{R}^{d} \rightarrow \mathbb{R}^{s}$, linear map.
${ }^{-X_{a}}(\mathbb{K})=\left\{x \in \mathbb{K}^{d}: Q(x)=a\right\} .(\mathbb{K}=\mathbb{Z}$ or $\mathbb{R})$
- Take $a \in \mathbb{Q}$ such that $\left|X_{a}(\mathbb{Z})\right|=\infty$.


## Theorem (1. (O.S 2012))

If
(a) $d>2 s$ and $\operatorname{rank}\left(\left.Q\right|_{\operatorname{Ker}(M)}\right)>2$,
(2) $\left.Q\right|_{\operatorname{Ker}(M)}$ is indefinite,
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Then $M\left(X_{a}(\mathbb{Z})\right)=\mathbb{R}^{s}$.

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If
(1) $d>2 s$ and $\operatorname{rank}\left(\left.Q\right|_{\operatorname{Ker}(M)}\right)>2$,
(2) $\left.Q\right|_{\operatorname{Ker}(M)}$ is indefinite,
(3) $\alpha_{1} L_{1}+\cdots+\alpha_{s} L_{s} \notin \mathbb{Q}$ unless $\alpha_{i}=0$ for all $i$.

Then $\overline{M\left(X_{a}(\mathbb{Z})\right)}=\mathbb{R}^{s}$.

## Remarks about the conditions of Theorem 1.

- $d>2 s$ probably not necessary. $(d>s+2$ should work??)
- $\operatorname{rank}\left(\left.Q\right|_{\operatorname{Ker}(M)}\right)>2$ is probably necessary although so far no counterexamples?
- $\left.Q\right|_{\operatorname{Ker}(M)}$ is indefinite is possibly too strong but it implies that $X_{a}(\mathbb{R}) \cap\left\{x \in \mathbb{R}^{d}: M(x)=b\right\}$ is non compact which is necessary.
- $\alpha_{1} L_{1}+\cdots+\alpha_{s} L_{s} \notin \mathbb{Q}$ unless $\alpha_{i}=0$ for all $i$ is necessary.


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## Today: Another Special Case (Quantification).

## Theorem (2. (O.S 2012))

If
(1) $d>2 s$ and $\operatorname{rank}\left(\left.Q\right|_{\operatorname{Ker}(M)}\right)=d-s$,
(2) $\left.Q\right|_{\operatorname{Ker}(M)}$ has signature $\left(r_{1}, r_{2}\right)$ where $r_{1} \geq 1$ and $r_{2} \geq 3$,
(3) $\alpha_{1} L_{1}+\cdots+\alpha_{s} L_{s} \notin \mathbb{Q}$ unless $\alpha_{i}=0$ for all $i$.

Then there exists $C_{0}>0$ such that for all $\theta>0$ there exists $T_{0}>0$ such that for all $T>T_{0}$ and $R \subseteq \mathbb{R}^{s}$ - compact with smooth boundary

$$
\begin{aligned}
& (1-\theta) C_{0} \operatorname{Vol}(R) T^{d-s-2} \leq \\
& \left|\left\{v \in \mathbb{Z}^{d}: Q(v)=a, M(v) \in R,\|v\| \leq T\right\}\right| \leq \\
& (1+\theta) C_{0} \operatorname{Vol}(R) T^{d-s-2}
\end{aligned}
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## Remarks about the conditions of Theorem 2.

- $C_{0}$ is such that
$C_{0} \operatorname{Vol}(R) T^{d-s-2} \sim \operatorname{Vol}\left(X_{a}(\mathbb{R}) \cap\left\{v \in \mathbb{R}^{d}: M(v) \in R,\|v\| \leq T\right\}\right)$
evaluated w.r.t the Haar measure on $X_{a}(\mathbb{R})$.
- The condition that rank $\left(\left.Q\right|_{\operatorname{Ker}(M)}\right)=d-s$ should be able to be relaxed to $\operatorname{rank}\left(\left.Q\right|_{\operatorname{Ker}(M)}\right)>2$.
- The cases where $\left.Q\right|_{\operatorname{Ker}(M)}$ has signature $(1,2)$ or $(2,2)$ are 'exceptional and there are more integer points than expected by a factor of $\log T$.


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## Ideas about the proof of Theorem 1: Strategy.

- Use Ratner's Theorem.


## Theorem (Ratner's Orbit closure Theorem, 1990)

G - connected Lie group. $U<G$, generated by 1-pararneter unipotent subgroups. $\Gamma \leq G$ a lattice. Then for all $x \in G / \Gamma, \overline{U x}=F x$ for $F$ a closed connected subgroup $U \leq F \leq G$.

- For our purpose, set:

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\begin{aligned}
& \text { - } G_{Q}=S O(Q)^{\circ}=\left\{g \in S L_{d}(\mathbb{R}): Q(g x)=Q(x)\right\}^{\circ} \text { - connected Lie group. } \\
& \text { - } \Gamma_{Q}=G_{Q} \cap S L_{d}(\mathbb{Z}) \text { - lattice because } Q \text { is rational. } \\
& \text { - } H_{Q, M}=\left\{g \in G_{Q}: M(g x)=M(x)\right\} .
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- Look at $H_{Q, M} \curvearrowright G_{Q} / \Gamma_{Q}$, if $H_{Q, M}$ is generated by 1-p unip. s.g then use Ratner!


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## Canonical Form

- An equivalence relation:

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& (Q M) \sim\left(Q^{\prime} M^{\prime}\right) \Longleftrightarrow g_{d} \in G L_{d}(\mathbb{R}), g_{s} \in G L_{s}(\mathbb{R}) \text { such that } \\
& \forall x \in \mathbb{R}^{d}\left(Q\left(g_{d} x\right), g_{s} M\left(g_{d} x\right)\right)=\left(Q^{\prime}(x), M^{\prime}(x)\right)
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- To simplify, from now on take $M=M: \mathbb{R}^{d} \rightarrow \mathbb{R}^{s}$ such that $s=1$ or $\operatorname{rank}\left(\left.Q\right|_{\operatorname{Ker}(M)}\right)=d-s$.


## Theorem (Canonical Form )

(a) $\operatorname{rank}\left(\left.O\right|_{\text {Ker }(M)}\right)=d-s$ and $(Q, M)$

$$
\left(Q^{\prime}\left(x_{1}, \ldots, x_{s}\right)+\sum_{i=s+1}^{p} x_{i}^{2}-\sum_{i=p+1}^{d} x_{i}^{2},\left(x_{1}, \ldots, x_{s}\right)\right)=\left(Q_{1}, M_{1}\right)
$$

(2) $s=1$ and $(Q, M) \sim\left(2 x_{1} x_{d}+\sum_{i=2}^{p} x_{i}^{2}-\sum_{i=p+1}^{d-1} x_{i}^{2}, x_{1}\right)=\left(Q_{2}, M_{2}\right)$

- Note that in case 2. $\operatorname{rank}\left(\left.Q\right|_{\operatorname{Ker}(M)}\right)=d-2$.


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- An equivalence relation:
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## What is $H_{Q, M}$ ?

- Notation: $I_{n}-n \times n$ identity matrix, $I_{n_{1}, n_{2}}=\left(\begin{array}{cc}I_{n_{1}} & 0 \\ 0 & -I_{n_{2}}\end{array}\right)$
- In case 1.
$=H_{Q_{1}, M_{1}}=\left(\begin{array}{cc}I_{S} & 0 \\ 0 & S O\left(p-r_{1}, q-r_{2}\right)\end{array}\right)$.
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$\begin{aligned} & D \\ & =\left(\begin{array}{ccc}1 & 0 & 0 \\ 0 & S O(p-1, q-1) & 0 \\ 0 & 0 & 1\end{array}\right) \leq H_{Q_{2}, M_{2}} . \\ & U=\left\{\left(\begin{array}{ccc}1 & 0 & 0 \\ t & l_{d-2} & 0 \\ t^{\top} /_{p-1 q-1} t / 2 & -t^{\top} /_{p-1, q-1} & 1\end{array}\right): t \in \mathbb{R}^{d-2}\right\} \leq H_{Q_{2}, M_{2}} .\end{aligned}$
- $U$ is normalised by $D$ and $U D=H_{Q_{2}, M_{2}}$.
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## Intermediate Subgroups.

- The task now is to determine closed connected subgroups, $F$ such that $H_{Q, M} \leq F \leq G_{Q}$.
- In case 1, if s is relatively large there are quite a few possibilities for $F$.
- In case 2. Let $A=\left\{\left(\begin{array}{ccc}a & 0 & 0 \\ 0 & I_{d-2} & 0 \\ 0 & 0 & a^{-1}\end{array}\right): a \in \mathbb{R} \backslash\{0\}\right\}$.
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## F invariant subspaces.

- Show that, if $V$ is an $F$ invariant subspace of dimension smaller than $d-s$, then $V$ is defined over $\mathbb{Q}$.
- This works, by using the fact that $H_{Q, M} \leq F$ and so any $F$ invariant subspace must be $H_{Q, M}$ invariant.
- Leads to two types of F invariant subspaces:
$\star$ those contained in $\left\langle x_{1}, \ldots, x_{s}\right\rangle$
$\star$ those that contain $\left\langle x_{s+1}, \ldots, x_{d}\right\rangle$
- The assumption that $d>2 s$ means the latter type have dimension larger than $d-s$.
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## Thanks!

Thank you for listening!

